FROM DATABASES TO ARCHITECTURES FOR BIG DATA MANAGEMENT

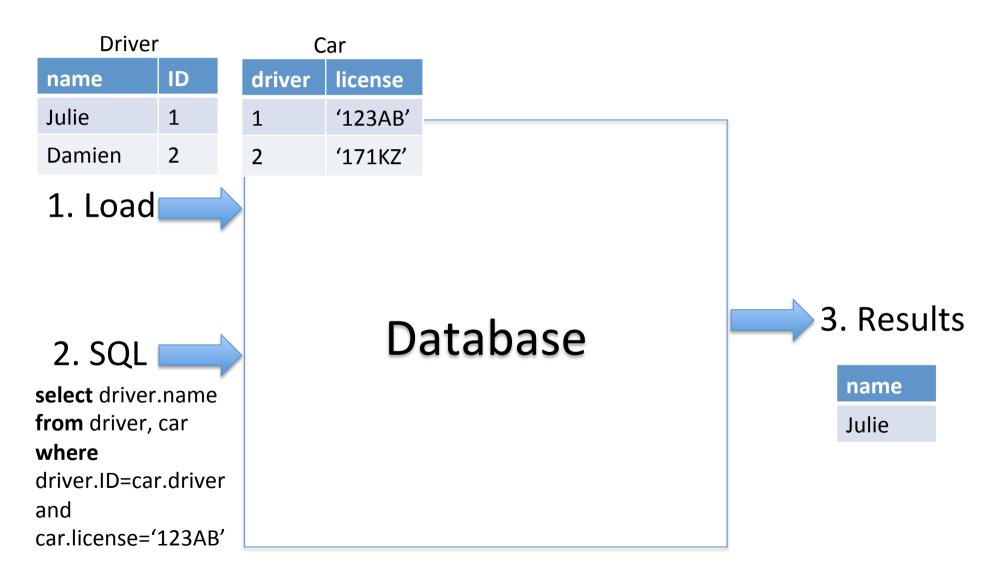
DATABASE FUNDAMENTALS (RECALL/CRASH COURSE)

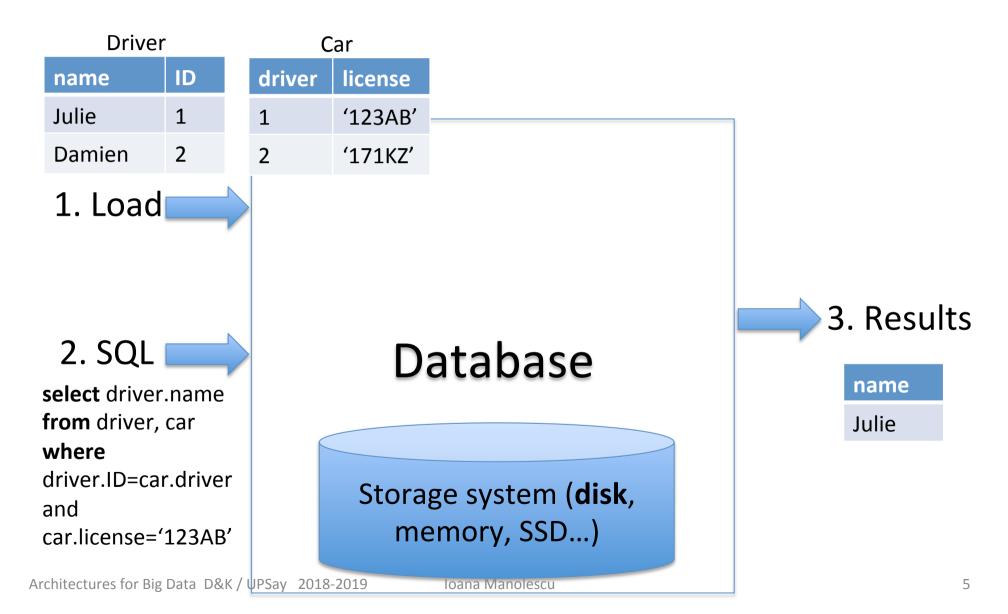
DATABASE FUNDAMENTALS (RECALL/INTRODUCTION)

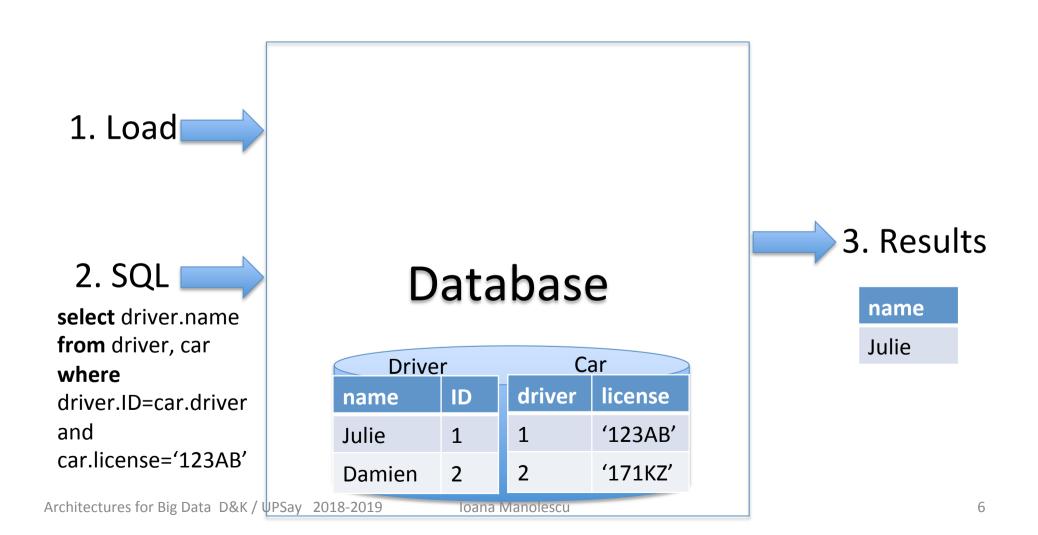
Database internals

(We illustrate for relational databases, as they are the most mature)









SQL

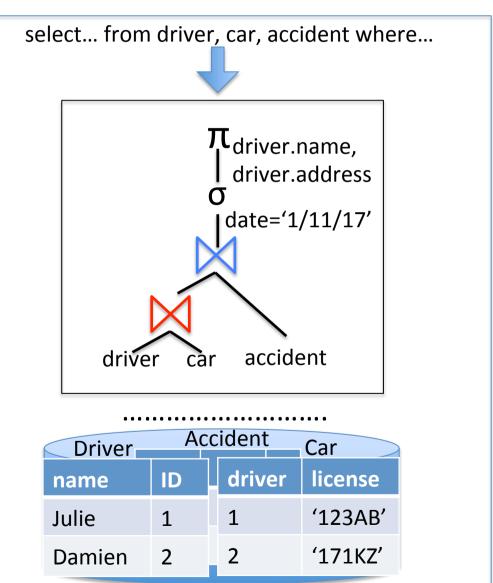
select driver.name,
driver.address
from driver, car,
accident

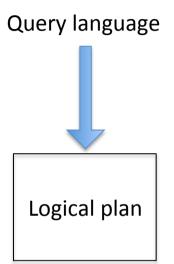
where

/17'

driver.ID=car.driver and car.license=accident .carLicense and

accident.date='1/11







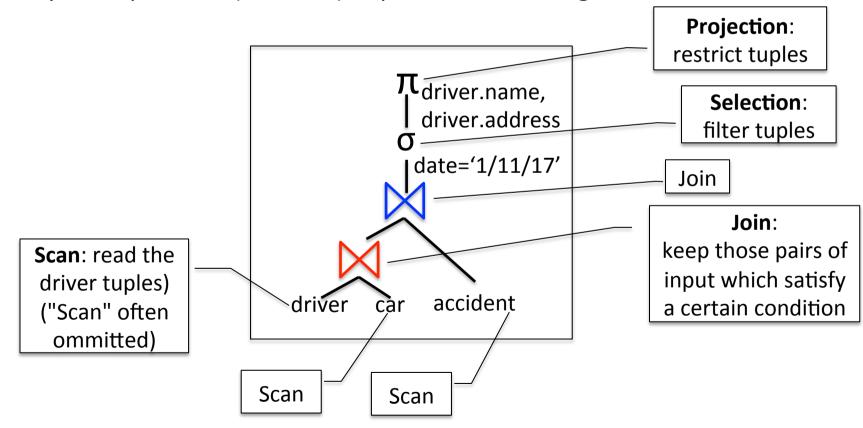
Logical query plans

 Trees made of logical operators, each of which specializes in a certain task

SQL: **select** driver.name. **Projection**: driver address restrict tuples from driver, car, accident where Πdriver.name, Selection: driver.ID=car.driver and driver.address filter tuples car.license=accident.carLi date='1/11/17' cense and Join accident.date='1/11/17' Join: keep those pairs of **Scan**: read the input which satisfy driver tuples) accident driver car a certain condition ("Scan" often ommitted) Scan Scan

Logical query plans

- Trees made of logical operators, each of which specializes in a certain task
- Logical operators: they are defined by their result, not by an algorithm
- Physical operators (see next) implement actual algorithms

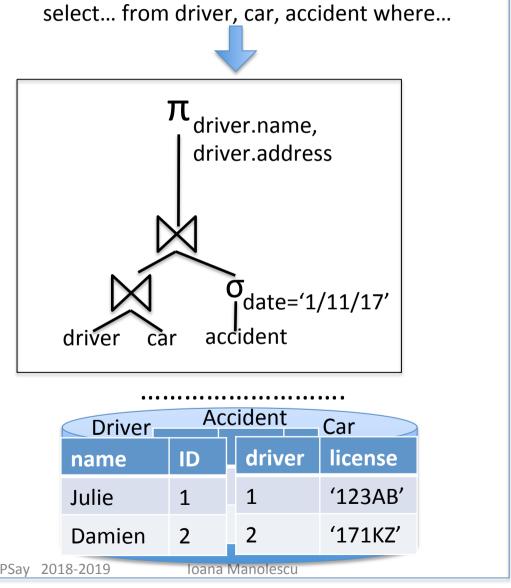


SQL

select driver.name,
driver.address
from driver, car,
accident

where

driver.ID=car.driver and car.license=accident .carLicense and accident.date='1/11 /13'



Query language



Logical plan 2

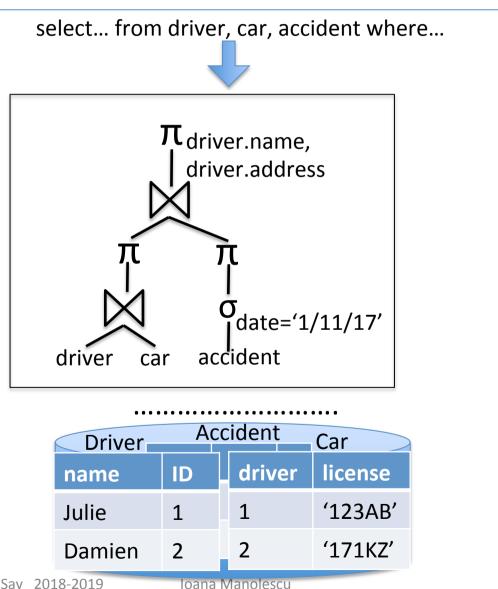


SQL

select driver.name, driver.address from driver, car, accident

where

driver.ID=car.driver and car.license=accident .carLicense and accident.date='1/11 /17'



Query language



Logical plan 2

Logical plan 3

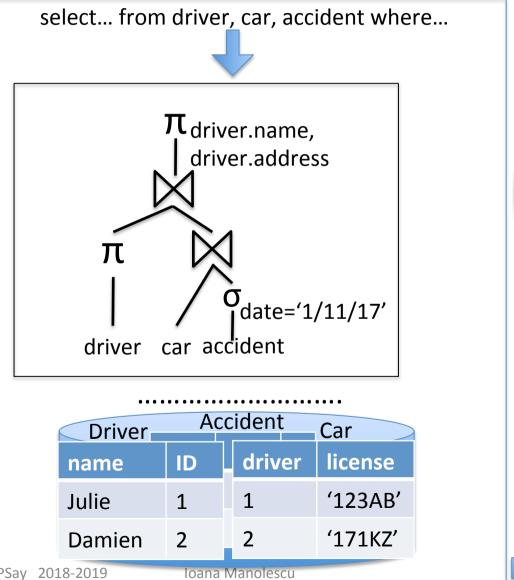


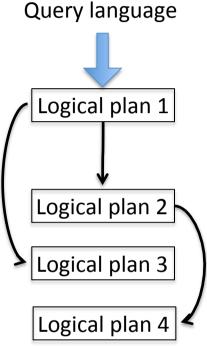
SQL

select driver.name,
driver.address
from driver, car,
accident

where

driver.ID=car.driver and car.license=accident .carLicense and accident.date='1/11 /17'



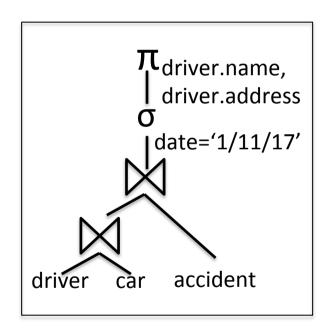


Logical query optimization

- Enumerates logical plans
- All logical plans compute the query result
 - They are equivalent
- Some are (much) more efficient than others
- Logical optimization: moving from a plan to a more efficient one
 - Pushing selections
 - Pushing projections
 - Join reordering: most important source of optimizations

1.000.000 cars, 1.000.000 drivers, 1.000 accidents, 2 cars per accident, 10 accidents on 1/11/17

« Name and address of drivers in accidents on 1/11/2017? »



Cost of an operator: depends on the number of tuples (or tuple pairs) which it must process e.g. c_disk x number of tuples read from disk e.g. c_cpu x number of tuples compared

Cardinality of an operator's output: how many tuples result from this operator

The cardinality of one operator's output determines the cost of its parent operator

Plan **cost** = the sum of the costs of all operators in a plan

1.000.000 cars, 1.000.000 drivers, 1.000 accidents, 2 cars per accident, 10 accidents on 1/11/17

« Name and address of drivers in accidents on 1/11/2017? »

Pessimi stic (worstcase) estim.

π_{driver.name,}

driver.name, driver.address o date='1/11/17'

accident

cs, cj, cf constant

driver

Scan costs: cs x $(10^6 + 10^6 + 10^3)$

Scan cardinality estimations: 10^6 , 10^6 , 10^3

Driver-car join cost estimation: cj x $(10^6 \times 10^6 = 10^{12})$

Driver-car join cardinality estimation: 10⁹

Driver-car-accident join cost estim.: cj x $(10^9 \text{ x } 10^3 = 10^{12})$ Driver-car-accident join cardinality estimation: 2 x 10^3

Selection cost estimation: cf x (2×10^3)

Selection cardinality estimation: 10

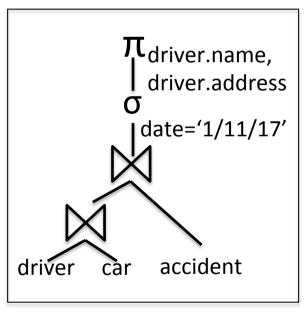
Projection (similar), negligible

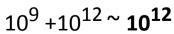
Total cost estimation: $10 + 3x10^3 + 2x10^6 + 10^{12} \sim 10^{12}$

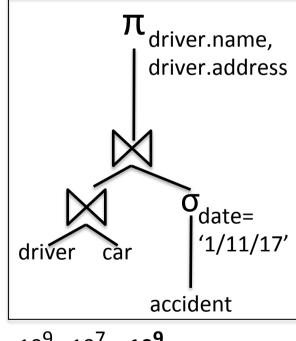
1.000.000 cars, 1.000.000 drivers, 1.000 accidents, 2 cars per accident, 10 accidents on 1/11/17

« Name and address of drivers in accidents on 1/11/2017? »

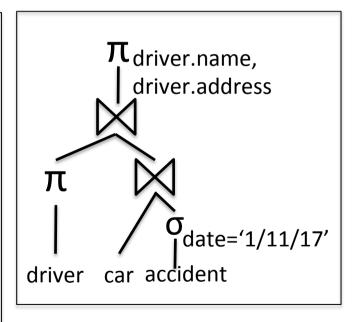
Three plans, same scan costs (neglected below); join costs dominant







$$10^9 + 10^7 \sim 10^9$$



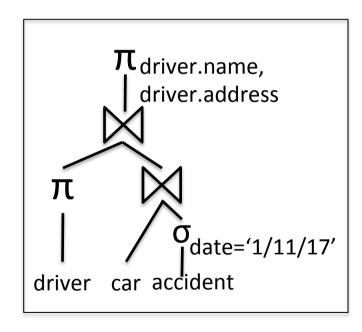
$$10^7 + 2*10^7 \sim 3*10^7$$

1.000.000 cars, 1.000.000 drivers, 1.000 accidents, 2 cars per accident, 10 accidents on 1/11/17

« Name and address of drivers in accidents on 1/11/2017? » Three plans, same scan costs (neglected below); join costs dominant

The best plan reads only the accidents that have to be consulted

- Selective data access
- Typically supported by an index
 - Auxiliary data structure, built on top of the data collection
 - Allows to access directly objects satisfying a certain condition



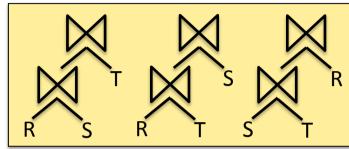
$$10^7 + 2*10^7 \sim 3*10^7$$

Join ordering is the main problem in logical query optimization

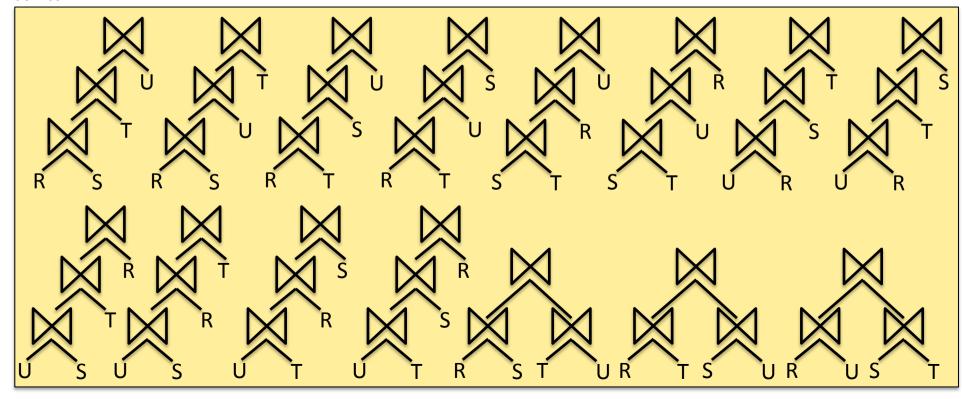








N=4:



Join ordering is the main problem in logical query optimization

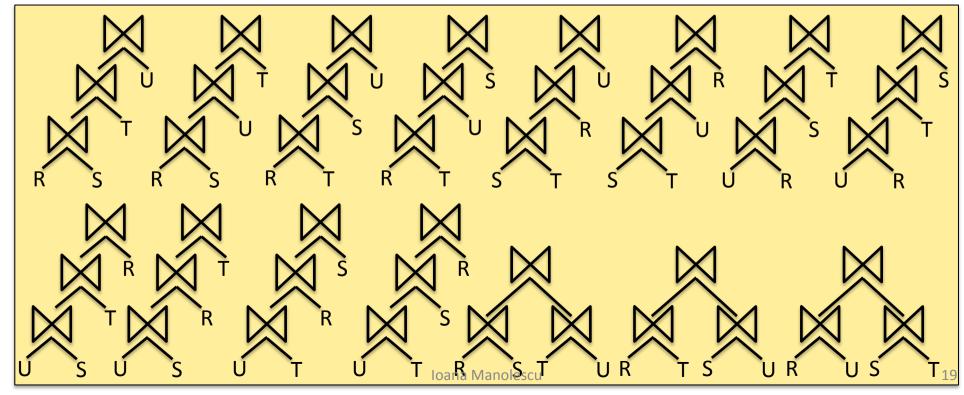
Plans(n+1) = (n+1) * Plans(n) + $\frac{1}{2}$ * $\Sigma_{i=1}$ (n/2) Plans(i)*Plans(n+1-i)



High (exponential) complexity → many heuristics

Exploring only left-linear plans etc.

N=4:



Logical query optimization needs statistics

Exact statistics (on base data):

- 1.000.000 cars, 1.000.000 drivers, 1.000 accidents

Approximate / estimated statistics (on intermediary results)

— "1.75 cars involved in every accident"

Statistics are gathered

- When loading the data: take advantage of the scan
- **Periodically** or upon **request** (e.g. analyze in the Postgres RDBMS)
- At **runtime**: modern systems may do this to change the data layout

Statistics on the base data vs. on results of operations not evaluated (yet):

- « On average 2 cars per accident »
- For each column R.a, store:

|R|, |R.a| (number of distinct values), min{R.a}, max{R.a}

- Assume uniform distribution in R.a
- Assume independent distribution
 - of values in R.a vs values in R.b;
 of values in R.a vs values in S.c
- + simple probability computations

More on statistics

- For each column R.a, store:
 - |R|, |R.a| (number of distinct values), min{R.a}, max{R.a}
- Assume uniform distribution in R.a
- Assume independent distribution
 - of values in R.a vs values in R.b;
 of values in R.a vs values in S.c
- The uniform distribution assumption is frequently wrong
 - Real-world distribution are skewed (popular/frequent values)
- The independent distribution assumption is sometimes wrong
 - « Total » counter-example: functional dependency
 - Partial but strong enough to ruin optimizer decisions: correlation
- Actual optimizers use more sophisticated statistic informations
 - Histograms: equi-width, equi-depth
 - Trade-offs: size vs. maintenance cost vs. control over estimation error

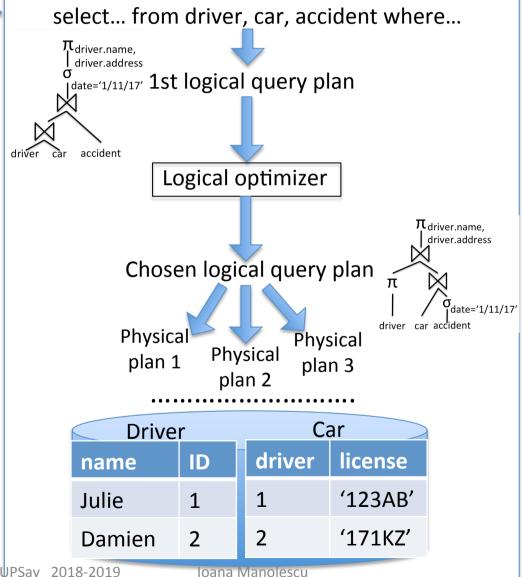
Database internal: query optimizer

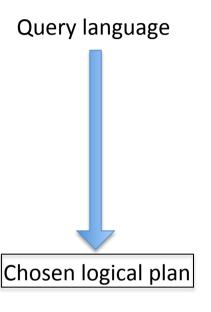
SQL

select driver.name, driver.address from driver, car, accident

where

driver.ID=car.driver and car.license=accident .carLicense and accident.date='1/11 /17'







Physical query plans

Made up of **physical operators** =

algorithms for implementing logical operators

Example: equi-join (R.a=S.b)

```
Nested loops join:
foreach t1 in R{
  foreach t2 in S {
    if t1.a = t2.b then output (t1 | | t2)
  }
}
```

```
Merge join: // requires sorted inputs
repeat{
  while (!aligned) { advance R or S };
  while (aligned) { copy R into topR, S into topS };
  output topR x topS;
} until (endOf(R) or endOf(S));
```

```
Hash join: // builds a hash table in memory
While (!endOf(R)) { t ← R.next; put(hash(t.a), t); }
While (!endOf(S)) { t ← S.next;
matchingR = get(hash(S.b));
output(matchingR x t);

Architectures for Big Data D&K / UPSay 2018-2019 loana Manolescu
```

Physical query plans

Made up of **physical operators** =

algorithms for implementing logical operators

Example: equi-join (R.a=S.b)

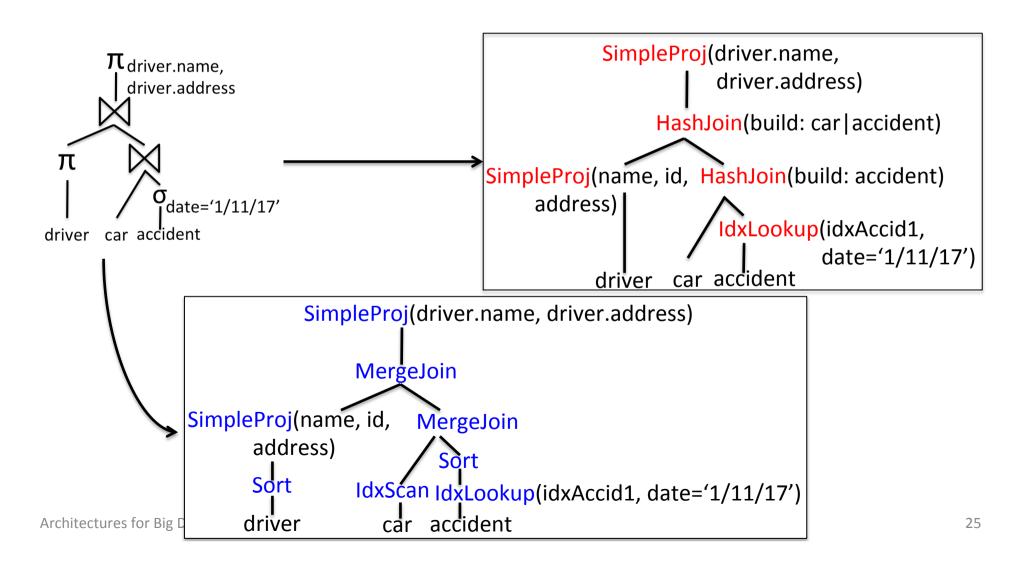
```
Nested loops join:
foreach t1 in R{
  foreach t2 in S {
    if t1.a = t2.b then output (t1 || t2)
  }
}
```

Also:
Block nested loops join
Index nested loops join
Hybrid hash join
Hash groups / teams

• • •

Physical optimization

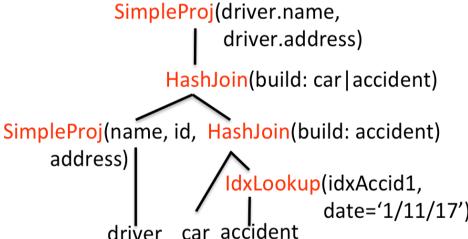
Possible physical plans produced by physical optimization for our sample logical plan:



Physical plan performance

Metrics characterizing a physical plan

- Response time: between the time the query starts running to the we know it's end of results
- Work (resource consumption)
 - How many I/O calls (blocks read)
 - Scan, IdxScan, IdxAccess; Sort;
 HybridHash (or spilling HashJoin)
 - How much CPU
 - All operators
 - Distributed plans: network traffic
- Total work: work made by all operators



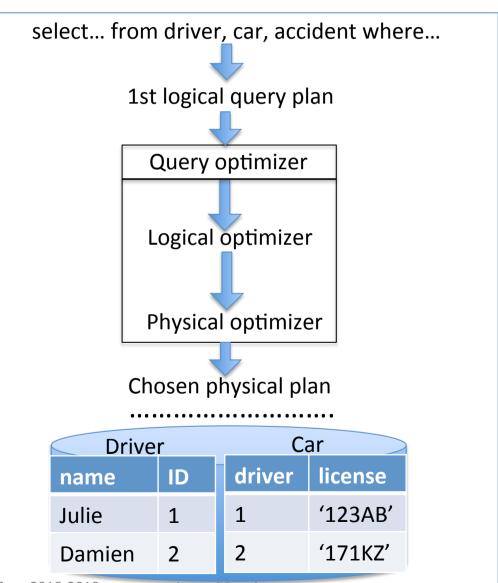
Query optimizers in action

Most database management systems have an « explain » functionality → physical plans. Below sample Postgres output:

Database internal: physical plan

SQL

select driver.name from driver, car where driver.ID=car.driver and car.license='123AB'

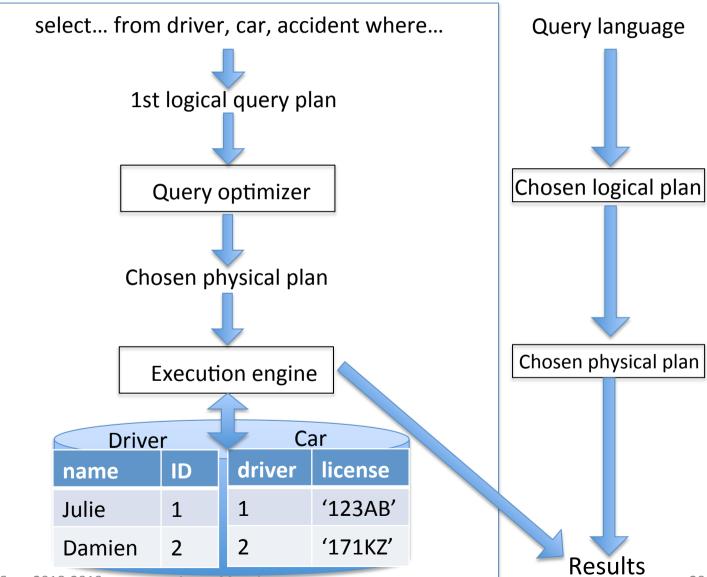


Query language Chosen logical plan Chosen physical plan Results 28

Database internals: query processing pipeline

SQL

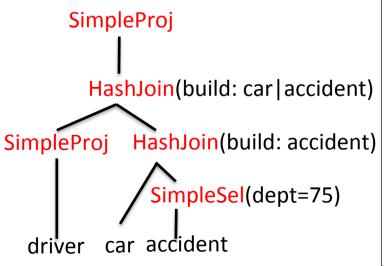
select driver.name from driver, car where driver.ID=car.driver and car.license='123AB'



Advanced query optimization techniques: Dynamic Query Optimization

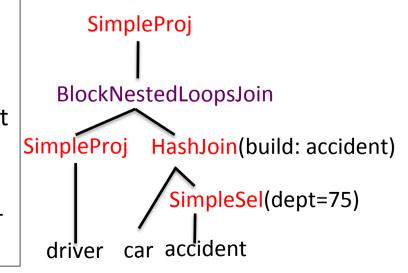
- Sizes (cardinalities) of intermediary results are estimated, which may lead to estimation errors
- A cardinality estimation error may lead to chosing a logical plan and a set of physical operators that perform significantly different from expectation (especially for the worse)

Initially chosen plan:



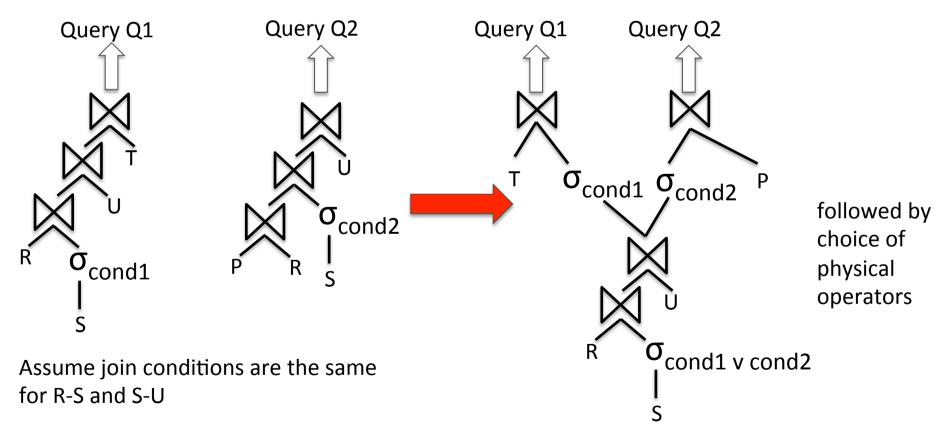
At execution time, we see that the lower HashJoin output is larger than expected: memory insufficient to build

Modified plan:



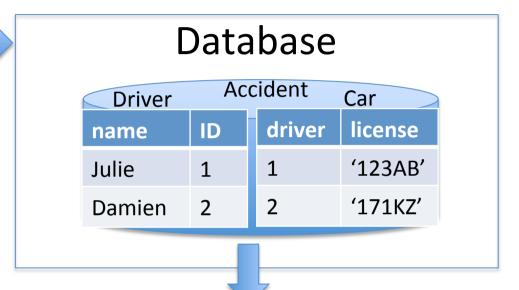
Advanced query optimization techniques: Multi-Query Optimization

Multiple queries sharing sub-expressions can be optimized together into a single plan with **shared subexpressions**





insert into driver
values ('Thomas',
3);
update car set
driver=3 where
license='123AB';



Database				
	Driver Accident Car			Car
	name	ID	driver	license
	Julie	1	3	'123AB'
	Damien	2	2	'171KZ'
	Thomas	3		

Database updates

- A set of operations atomically executed (either all, or none) is called a transaction
- There may be some dependencies between the operations of a transaction
 - First read the bank account balance
 - Then write that value reduced by 50€
- A total order over the operations of several concurrent transaction is called a **scheduling**
- The DB component that receives all incoming transactions and decides what operation will be executed when (i.e., <u>global</u> <u>order</u> over the operations of all transactions) is called a <u>scheduler</u>

Database updates

 The scheduler is in charge of ordering all operations so that they will appear executed one after the other (serially)

```
T1: BEGIN A=A+100, B=B-100 END
```

T2: BEGIN A=1.06*A, B=1.06*B END

T2: A=1.06*A, B=1.06*B

ARCHITECTURES FOR BIG DATA:

WHAT NEEDS TO CHANGE?

What is the impact of Big Data properties on database architectures?

指数据库事务正确执行的四个基本要素的缩写。包含:原子性(Atomicity)、一致性(Consistency)、隔离性(Isolation)、持久性(Durability)

- Volume requires distribution
 - Of the data storage; of query evalution
 - Distribution makes ACID difficult (CAP theorem) ✓
 - Complicates concurrency control
 - Replication, eventual consistency
 - Distribution requires efficient, easy-to-use parallelism
 - Distribution raises issues of control which can lead to single point of failure → decentralization
- Velocity requires efficient algorithms
 - Optimize for throughput (rather than response time)
 - Stream processing, in-memory architectures
 - Process-then-store (or process-then-discard)

What is the impact of Big Data properties on database architectures?

- Variety requires support for
 - flexible data models: key-values, JSON, graphs...
 - different schemas, and translation mechanisms
 between the schemas
 - Data integration
 - several data models being used together
 - Mediators, Data lakes
- Veracity requires support for reconciliation, data cleaning etc.
 - Similar to single-database setting, but adding source, source confidence, and provenance information

Roadmap for the rest of the course

- 1. Analysis of large-scale (in particular, distributed) Big Data platforms
 - Focus on: distribution of data and query processing, concurrency control
- 2. A selection of NoSQL platforms
 - Choice of most popular ones in their class
 - To illustrate variety of data models, and some distribution choices