

view_frames Result

Recorded at time: 1307320323.236

/odom_combined

Broadcaster: /robot_pose_ekf
Average rate: 19.896 Hz
Most recent transform: 0.042 sec old
Buffer length: 4.926 sec

/base_footprint

Broadcaster: /base_to_base_tf
Average rate: 1.250 Hz
Most recent transform: -0.395 sec old
Buffer length: 4.001 sec

/base_link

Broadcaster: /laser_to_base_tf
Average rate: 10.193 Hz
Most recent transform: -0.014 sec old
Buffer length: 4.807 sec

/base_laser

Broadcaster: /odomwheel_to_base_tf
Average rate: 10.189 Hz
Most recent transform: -0.017 sec old
Buffer length: 4.809 sec

/odom_wheel_frame

Broadcaster: /posewheel_to_base_tf
Average rate: 10.190 Hz
Most recent transform: -0.017 sec old
Buffer length: 4.809 sec

/pose_wheel_frame

