

Inference of proto-neutron star properties from gravitational wave data in core-collapse supernovae.

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Core collapse supernovae are very important phenomena in the Universe and their expected gravitational waves emission is a promising tool to study the onset of the supernova explosion mechanism. The complexity of the gravitational wave signal due to matter effects and the large degrees of freedom of the phenomena makes the source parameter inference problem very challenging. In this paper, we have considered the proto neutron star oscillation modes that carry out a large fraction of the gravitational wave signal and whose frequency time evolution is linked to the radius and the mass of the proton neutron star through universal relations demonstrated in [1]. We have developed a simple algorithm to extract from the gravitational wave data the frequency evolution of the gravity mode. We have used a set of 1D core collapse supernova simulations to build a model of evolution of the proto neutron star properties with the gravity mode frequency. The model is then used to infer the time evolution of a combinaison of the radius and mass of the proto neutron star. We have then estimated the performance of the method by performing simulations with 2D core collapse supernova waveforms covering a progenitor mass range between 11 and 40 solar mass and different equation of state. We have shown that for Advanced LIGO and Advanced Virgo detectors at design sensitivity it will be possible to infer poroton neutron star properties for a galactic source, while third generation detectors Einstein Telescope and Cosmic Explorer will allow to test distances of several hundreds of kiloparsec.

I. INTRODUCTION

The life of massive stars (those born with masses between $\sim 8 M_{\odot}$ and $\sim 120 M_{\odot}$) ends with the collapse of the iron core under its own gravity, leading to the formation of a neutron star (NS) or a black hole (BH), and followed (typically but not necessarily in the BH case) by a supernova explosion. Nearby core-collapse supernova (CCSN) explosions are expected to be sources of gravitational waves (GWs) and are one of the main candidates for the next great discovery by current ground-based observatories. However, these are relative rare events. A neutrino-driven explosion [2] is the most likely outcome in the case of slow rotating cores, which are present in the bulk of CCSN progenitors. The emitted GWs could be detected with advanced ground-based GW detectors (Advanced LIGO[3], Advanced Virgo[4] and KAGRA[5]) within 5 kpc [6, 7]. Such a galactic event has a rate of about 2–3 per century [8, 9]. For the case of fast rotating progenitor cores the result is likely a magneto-rotational explosion, with a more powerful GW signal that could be detected within 50 kpc and for some extreme models up to 5 – 30 Mpc [6, 7]. However, only about 1% of the electromagnetically observed events show signatures of fast rotation (broad-lined type Ic SNe [10] or events associated to long GRBs [11]), making this possibility

a subdominant channel of detection with an event rate of $\sim 10^{-4} \text{yr}^{-1}$ add ref?. Therefore, we focus this work only in neutrino-driven CCSNe. Despite the low rates, CCSN are of great scientific interest because they produce a complex GW signals which could provide significant clues about the physical processes that occur in the moments after the collapse.

In the last decade, significant progress has been made in the development of numerical codes, in particular in the treatment of multidimensional effects [12]. In the case of neutrino-driven explosions, the GW emission is primarily induced by instabilities developed at the newly formed proto-neutron star (PNS) and by the non-spherical accreting flow of hot matter over its surface [13]. This dynamics excite the different modes of oscillation of the PNS, which ultimately leads to the emission of GWs. The frequency and time evolution of these modes carry information about the properties of the GW emitter and could allow to perform PNS asteroseismology.

The main feature appearing systematically in the GW spectrum of multidimensional numerical simulations is a strong and relatively narrow oscillation in the post bounce evolution with raising frequency from about 100 Hz up to a few kHz (at most) and a typical duration of 0.5 – 1 s. This feature has been interpreted as a continuously excited gravity mode (g-mode, see [14, 15] for a definition in this context) of the PNS [16–21]. In

these models the monotonic raise of the frequency of the mode is related to the contraction of the PNS. The typical frequencies of these modes make them a promising source for ground-based interferometers.

The properties of g-modes in hot PNSs have been studied since the end of last century by means of linear perturbation analysis of background PNS models. The oscillation modes associated to the surface of hot PNSs was first considered by McDermott, van Horn & Scholl [22]. Additionally, the stratified structure of the PNS allows the presence of different types of g-modes related with the fluid core [23]. Many posterior works used simplified neutron star models assuming an equilibrium configuration as a background, to study the effect of rotation [24], general relativity [25], non-linearities [26], phase transition [27] and realistic equation of state [28]. Only recently, there has been an effort to incorporate realistic backgrounds based in numerical simulations in the computation of the mode structure and evolution [1, 29–36].

The eigenmode spectrum of the region within the shock (including the PNS and the post-shock region) using results from 2D CCSN numerical simulations as a background studied in [30, 32] show a good match of the mode frequencies computed and the features observed in the GW spectrum of the same simulation (specially when space-time perturbations are included [32]). This result reveals that it is possible to perform CCSN asteroseismology under realistic conditions and serves as a starting point to carry out inference of astrophysical parameters of PNSs. [1] went one step further showing that it was possible to derive simple relations between the instantaneous frequency of the g-mode and the mass and radius of the PNS at each time of the evolution. These relations are universal in the sense that they do not depend on the equation of state (EOS) used or the mass of the progenitor, and only weakly on the numerical code used (see discussion in section II). Similar relations have been found by [35, 36], which also found that the universal relations do not depend on the dimensionality (1D, 2D or 3D) of the numerical simulation used as a background.

In this work, we present a method to infer from the GW data alone, the time evolution of some properties of the PNS, namely a combination of its mass and radius. For this purpose we have developed an algorithm to extract the time-frequency evolution of the main feature in the spectrograms of the GW emission of 2D simulations of CCSN. This feature corresponds to the 2g_2 mode, according to the nomenclature used in [1] (different authors may have slightly different naming convention). Next, we use the universal relations obtained by [1], based on a set of 1D simulations, to infer the time evolution of the ratio $M_{\text{PNS}}/R_{\text{PNS}}^2$, being M_{PNS} and R_{PNS} the mass and radius of the PNS. Using 2D CCSN waveform corresponding to different progenitor masses we estimate the performance of the algorithm for current and future generation of ground-based GW detectors.

This paper is organised as follows. Section II describes the details of the CCSN simulations used in the paper.

Section III focuses on the algorithm that extracts the time evolution of a combination of the mass and radius of the PNS corresponding to a g-mode. Section IV shows the performance of the data analysis method with simulated GW detectors data. Finally, we discuss the results in section V.

II. CORE COLLAPSE SUPERNOVA SIMULATIONS

Unless other methods used GW astronomy, the algorithm proposed in this work does not require accurate waveforms in order to infer the properties of the PNS. Instead, it relies on the evolution of the frequency of oscillation of some particular modes, as seen in the GW spectrum. The frequency of these modes depends, in a universal way, on the surface gravity of the PNS ($r = M_{\text{PNS}}/R_{\text{PNS}}^2$), in the sense that if at a given time we observe GW emission at a certain frequency f we can determine univocally the value of the surface gravity, within a certain error, regardless of the details of the numerical simulation. In this work we use two sets of simulations: i) The *model set*, composed by 1D simulations, which is used to build the universal relation (model), $r(f)$, linking the ratio r with the observed frequency f , and ii) the *test set*, composed by 2D simulations, for which we know both the GW signal and the evolution of the ratio, $r(t)$, and that is used to test performance of the algorithm.

We have used two different numerical codes in our numerical simulations. CoCoNuT [37, 38] is a code for general relativistic hydrodynamics coupled to the Fast Multigroup Transport scheme [39] providing an approximate description of the emission and transport of neutrinos. AENUS-ALCAR [40] combines special relativistic (magneto-)hydrodynamics, a modified Newtonian gravitational potential approximating the effects of general relativity [41], and a spectral two-moment neutrino transport solver [40]. We included the relevant reactions between matter and neutrinos of all flavours, i.e., emission and absorption by nucleons and nuclei, electron-positron pair annihilation, nucleonic bremsstrahlung, and scattering off nucleons, nuclei, and electrons.

For the *model set*, we use the 25 spherically symmetric (1D) simulations of [32] including progenitors with zero-age main sequence (ZAMS) masses in the range $M_{\text{ZAMS}} = 11.2 - 75 M_{\odot}$. The set contains simulations using the two numerical codes and six different equations of state. Details can be found in [32]. The reason to use one dimensional simulations for the model set is that the computational cost of those is significantly smaller than the cost of multidimensional simulations, so is easier to accumulate the statistics necessary to build a good model for $r(f)$. **For each time of each simulation we compute the ratio r and the frequency of the 2g_2 mode by means of the linear analysis described in [1, 30, 32].**

For the *test set*, we use 8 axisymmetric (2D) simula-

Model name	M_{ZAMS} [M_{\odot}]	progenitor model	EOS	t_{f} [s]	$t_{\text{explosion}}$	$M_{\text{PNS,f}}$ [M_{\odot}]
s11	11.2	[42]	LS220	1.86	×	1.47
s15	15.0	[42]	LS220	1.66	×	2.00
s15S	15.0	[42]	SFHo	1.75	×	2.02
s15G	15.0	[42]	GShen	0.97	×	1.86
s20	20.0	[42]	LS220	1.53	×	1.75
s20S	20.0	[43]	SFHo	0.87	×	2.05
s25	25.0	[42]	LS220	1.60	0.91	2.33
s40	40.0	[42]	LS220	1.70	1.52	2.23

TABLE I. List of axisymmetric simulations used for the *test set*. The last three columns show, the post-bounce time at the end of the simulation, the one at the onset of the explosion (non exploding models marked with \times), and the PNS mass at the end of the simulation.

tions using the AENUS-ALCAR code (see Table I for a list of models). 7 of these simulations use a selection of progenitors with masses in the range $M_{\text{ZAMS}} = 11.2 - 40 M_{\odot}$ evolved through the hydrostatic phases by [42]. We performed one simulation of each stellar model using the equation of state of [44] with an incompressibility of $K = 220 \text{ MeV}$ (LS220) and added comparison simulations with the SFHo EOS [45] and the GShen EOS [46] for the progenitor with $M_{\text{ZAMS}} = 15 M_{\odot}$. To this set of simulations, we add the waveform of a two-dimensional model used in [32], denoted s20S. It corresponds to a star with the same initial mass, $M_{\text{ZAMS}} = 20 M_{\odot}$, as for one of the other 7 axisymmetric simulations, but was taken from a newer set of stellar-evolution models [43]. It was evolved with the SFHo EOS.

For all the simulations, we mapped the pre-collapse state of the stars to a spherical coordinate system with $n_r = 400$ zones in radial direction distributed logarithmically with a minimum grid width of $(\Delta r)_{\text{min}} = 400 \text{ m}$ and an outer radius of $r_{\text{max}} = 8.3 \times 10^9 \text{ cm}$ and $n_{\theta} = 128$ equidistant cells in angular direction. For the neutrino energies, we used a logarithmic grid with $n_e = 10$ bins up to 240 MeV . Unlike the model set, the simulations in the test set are not 1D because we need to extract the gravitational wave signal, which is a multi-dimensional effect. For each simulation we extract the gravitational wave signal, $h_+(t)$, by means of the quadrupole formula and compute the time evolution of the surface gravity, $r(t)$.

All spherical and most axisymmetric models fail to achieve shock revival during the time of our simulations. Only the two stars with the highest masses, s25 and s40, develop relatively late explosions in axisymmetry. Consequently, mass accretion onto the PNSs proceeds at high rates for a long time in all cases and causes them to oscillate with their characteristic frequencies. The final masses of the PNSs are in the range of $M_{\text{PNS}} = 1.47 - 2.33 M_{\odot}$, i.e., insufficient for producing a black hole.

III. METHODS DESCRIPTION

In this section, we outline a strategy for estimating the time evolution of the ratio $r = M_{\text{PNS}}/R_{\text{PNS}}^2$ of the mass of the PNS and its squared radius (in units of solar mass and km) from the observation of the 2g_2 oscillation mode in the gravitational wave detector data. An integral part of this strategy is the universal relations that relate the characteristic frequency of the PNS oscillation f , g and p modes with the mass and the radius of the PNS, the shock radius and the total mass inside the shock as demonstrated in [1].

To build the model of the ratio r as a function of the frequency f we use the spherically symmetric (1D) simulations of the *model set*. Figure 1 shows the data for the 25 numerical simulations. As identified by [1], the only systematic deviation from a single universal relation is the numerical code used in the simulations. To avoid any systematic effect, we only use the 18 simulations performed with the ALCAR-AENUS code, which is the same code that was used in our test set. The consequences of this choice are discussed in the conclusions. Using this data, we parametrize the ratio with a cubic polynomial regression with heteroscedastic errors

$$r_i = \beta_1 f_i + \beta_2 f_i^2 + \beta_3 f_i^3 + \epsilon_i \quad (1)$$

where ϵ_i are assumed to be independent zero-mean Gaussian errors with variances σ_i^2 that increase with frequency f_i . The model for frequency-dependent variances is

$$\log \sigma_i = \alpha_0 + \alpha_1 f_i + \alpha_2 f_i^2 + \delta_i \quad (2)$$

with independent and identically zero-mean Gaussian errors δ_i . The R-package `lmvar` [47] that implements a maximum likelihood approach was used to fit the model.

The best fitting model amongst polynomials of degree 1, 2, and 3 was chosen according to the Aikake information criterion with coefficients given in Table II, which is actually the model defined in (1). The data and fit of the model including 95% confidence bands are displayed in Figure 1.

Coefficient	Estimate	Standard error
β_1	1.00×10^{-06}	2.12×10^{-08}
β_2	-8.22×10^{-10}	5.00×10^{-11}
β_3	1.01×10^{-12}	2.70×10^{-14}
α_0	$-1.02 \times 10^{+01}$	6.80×10^{-02}
α_1	7.24×10^{-04}	1.56×10^{-04}
α_2	6.23×10^{-07}	8.15×10^{-08}

TABLE II. Estimate and standard error of the coefficients of the best fit model describing the ratio $r = M_{\text{PNS}}/R_{\text{PNS}}^2$ as function of the frequency of the 2g_2 mode.

We use this model to infer the properties of the simulations in the *test set* described in in Section II. To describe

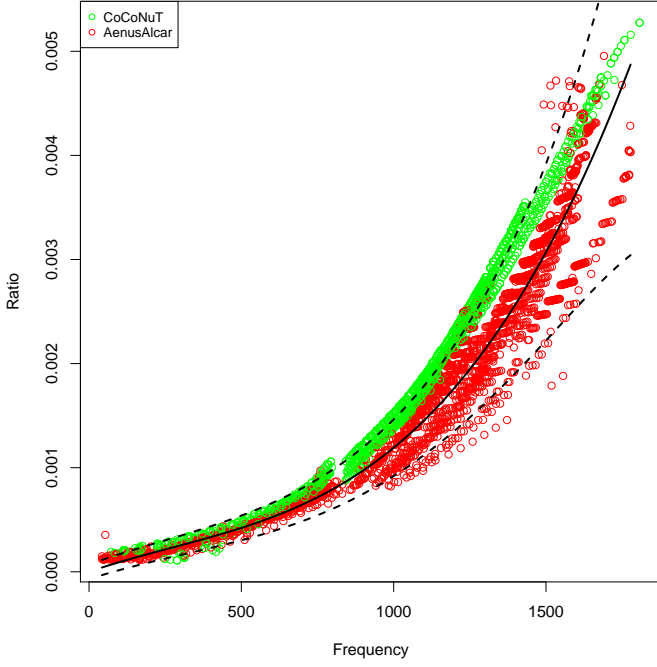


FIG. 1. Ratio $M_{\text{PNS}}/R_{\text{PNS}}^2$ from 25 1D simulations AENUS-ALCAR (red) and CoCoNuT (green) code. The solid line is the maximum likelihood estimate of heteroscedastic cubic model with 95% confidence bands (dashed lines) considering only the AENUS-ALCAR data points (18 simulations).

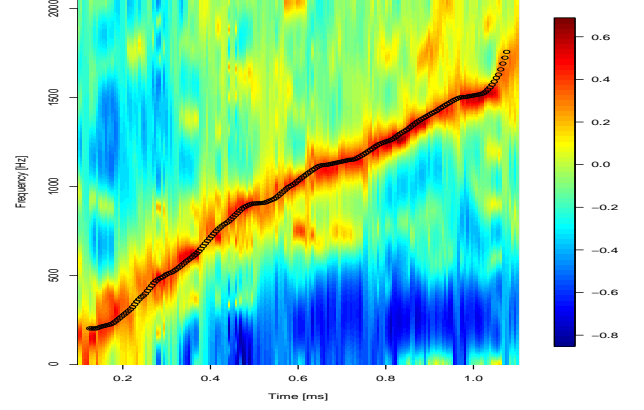


FIG. 2. Spectrogram of the gravitational wave signal **s20S** sampled at 4096 Hz. The spectrogram is obtained using data stretch of 200 samples overlapping at 90% with each other.

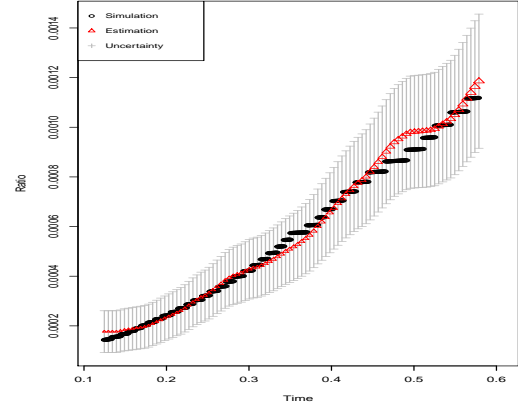


FIG. 3. Ratio $M_{\text{PNS}}/R_{\text{PNS}}^2$ as function of time extracted from the 2g_2 -mode of the **s20S** signal (red points and the 95% confidence belt in grey) compared to the ratio value derived from the PNS mass and radius given by the simulation code (black points) **To be redone in python.**

the method we focus on the gravitational wave signal of **s20S**, originally sampled at 16384 Hz but resampled at 4096 Hz. A spectrogram of this signal is shown in Figure 2 based on autoregressive estimates [CITATION?] of the local spectra for successive time intervals of length 200 with a 90% overlap. The dominant emission mode corresponds to the PNS oscillation 2g_2 -mode. We have developed a time-frequency method to track the ridge $m(t)$ in the spectrogram, taking into account that it is monotonically increasing as time goes. This is a property of the 2g_2 -mode, the frequency of which increases as the object becomes more massive and compact. Starting from either the left- or right-most column of the time-frequency matrix we identify and trace the sequence of amplitude peaks within a certain frequency band given the monotonicity constraint. Appendix A is providing more details on the reconstruction of the g mode ridge.

We collect the instantaneous frequency $f(t_i)$ corresponding to the ridge $m(t_i)$ for the midpoint t_i of each local time interval of the spectrogram and interpolating $f(t)$ for values in between the t_i . We then use our model given by Eq. (1) to obtain estimates of the time evolution of the ratio together with 95% confidence intervals. An exemple is given in Figure 3 where the red points are the point estimates and the grey bands represent 95% confidence bands. Ratio values computed using the mass and radius values obtained from the simulation code (true values) are shown in black.

In this case, for a GW signal without any noise, the coverage of our 95% confidence band is 100% of the true values. In the next section we investigate the performance of the reconstruction of $r(t)$ when the gravitational wave signal is embedded in noise.

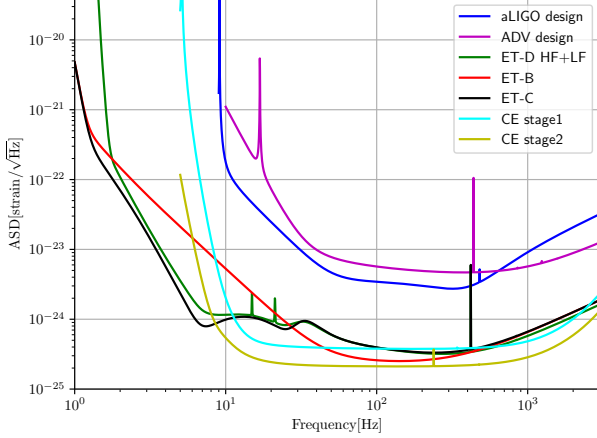


FIG. 4. Amplitude spectral density of the GW detectors ad-340
vanced LIGO (aLIGO) and Advanced Virgo (ADV) at de-341
sign sensitivity and of the proposed third generation detectors342
Cosmic Explorer and Einstein Telescope. Einstein Telescope343
sensitivity curve ET-B is obtained pushing second genera-344
tion detector technology at its limit. ET-C and ET-D sen-345
sitivity curves correspond to a detector configuration where a346
low-power cryogenic low-frequency interferometer and a high-347
power room temperature high-frequency interferometer are348
sharing the same infrastructure [49]. Cosmic Explorer design349
sensitivity will be achieved in two stages. Stage 1 (CE1) is ex-350
pected to use the technology developed for the “A+” upgrade351
to advanced LIGO but scaled up to a 40 km detector while352
stage 2 (CE2) will implement state-of-the-art technology to353
decrease quantum and thermal noises [50].354

IV. DETECTION SENSITIVITY WITH ADVANCED GRAVITATIONAL WAVE DETECTORS

To estimate how accurately we can infer the time evo-360
lution of $r = M_{\text{PNS}}/R_{\text{PNS}}^2$ in the gravitational wave de-361
tector data, we have added the GW signal from s20S to362
100 Gaussian noise realisations whose power spectral den-363
sity follows the advanced LIGO (aLIGO) spectrum [48]364
shown on Figure 4.365

We have varied the distance to the source, covering366
a large range of distances for which a detection in sec-367
ond generation of gravitational wave detectors is feasi-368
ble. The source is optimally oriented with respect to the369
gravitational wave detector. We are assuming a GW sig-370
nal from a core collapse phenomena has been identified371
in the data and that the beginning of the GW signal is372
known within $O(10 \text{ ms})$. The data (signal embedded in373
noise) are whitened using the function *prewhiten* of the374
R-package TSA. An auto-regressive model with maximal375
100 coefficients has been used.376

For each of the noise realisations, we reconstruct the377
ratio time series r_i of length N starting from the left side378
of the spectrogram and constraining the beginning of the379
track to be smaller than 200 Hz. The reconstructed ratio380

is then compare to the “true” ratio r_i^0 derived from the
PNS mass and radius computed from the s20S simula-
tion.

Figure 5 is showing the distribution of the fraction of
the ratio r_i^0 values that fall within the 95% confidence
interval of r_i . This quantity, *coverage*, is taking maximal
values when the source is located within few kpc and then
decreases with the distance.

To better quantify how well we reconstruct the ratio,
we have also considered Δ the mean over the track of the
relative error of r_i .

$$\Delta = \frac{1}{N} \sum_{i=1}^N \frac{|r_i - r_i^0|}{r_i^0} \quad (3)$$

Δ values of each of the 100 noise realisation are shown
as well as function of the distance on Figure 5. For a
source located up to $\sim 9 \text{ kpc}$ the relative error remains
smaller than 20%. At small distance, Δ is small but not
null. This reflects the approximation of the model used
for r . It is nevertheless remarkable that, on average, one
can reconstruct the ratio time series with a good preci-
sion at distance up to $\sim 9 \text{ kpc}$ for this particular wave-
form, with *coverage* value larger than 80%. There are
few noise realisations for a source located at $< 9 \text{ kpc}$
for which Δ takes large values, indicating that the method
start failing to reconstruct with accuracy the ratio.

We have tested that the method does not depend on
features of s20S using the 7 other waveforms of the *test*
set described in section II covering a large range of pro-
genitor masses.

Figure 6 shows that apart s11.2-LS220 and to a lesser
extent s20.0-SFHo, the ratio is well reconstructed for
all waveforms up to $\sim 15 \text{ kpc}$. In an effort to better deter-
mine the maximal distance of the source at which we can
reconstruct the ratio we have run 100 simulations with-
out injecting a signal and have measured *coverage* for
the reconstructed ratios. The median of *coverage* as well
as the 95 quartile are shown on Figure 6. The noise only
median value is null in this case, but it can be different
from zero because the g-mode reconstruction algorithm
is looking for a continuously frequency increasing track in
the spectrogram, starting between 0 and 200 Hz, where
we expect the GW signal to be. This is enhancing the
probability of overlap. This effects explains why outliers
can reach values as high as 80%. Figure 7 shows Δ as
function of the distance for the same signals as well as
the result when only noise is considered. In Table III we
are reporting the distance d_r at which *coverage* median is
lower than 95% of the noise only values. We have checked
that *coverage* and Δ provide similar values. These num-
bers are an estimate of the order of magnitude of the
source maximal distance at which a reconstruction of the
ratio could be possible with current GW detectors. They
are also upper limits as we are taking into account the
detector antenna response in our simulation but consider
the source is optimally oriented. Table III reports also

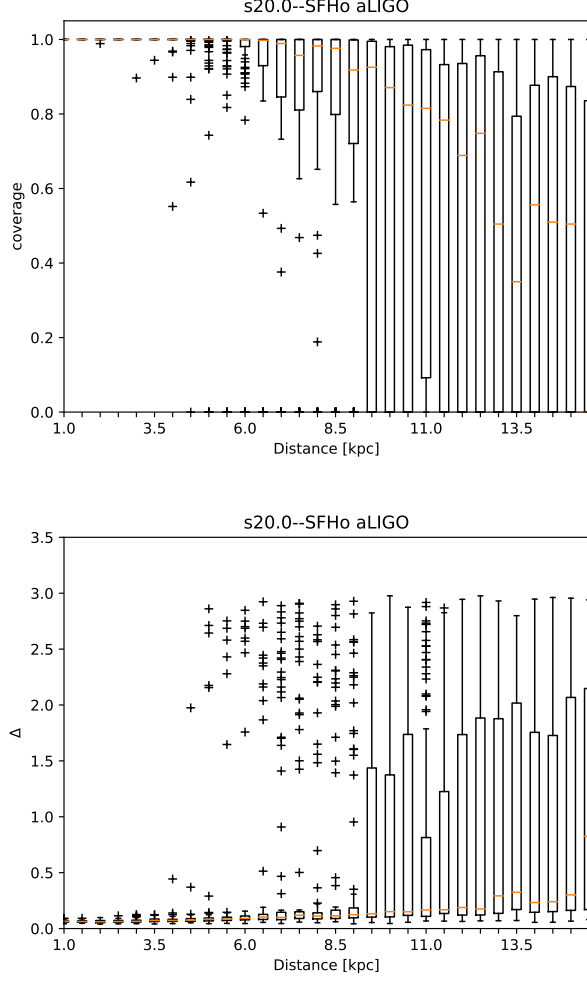


FIG. 5. Boxplots of *coverage* (upper panel) and Δ (lower panel) for *s20S* signal embedded in aLIGO noise at different distances from the Earth. 100 noise realisations is considered for each distance.

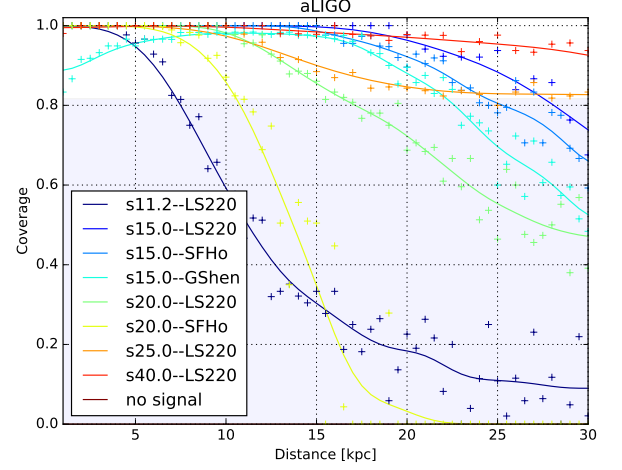


FIG. 6. Median of *coverage* for 8 CCSN waveforms embedded in aLIGO noise and located at different distance from the Earth. The “no signal” line and band show the median and first and third quartile of *coverage* in absence of any signal.

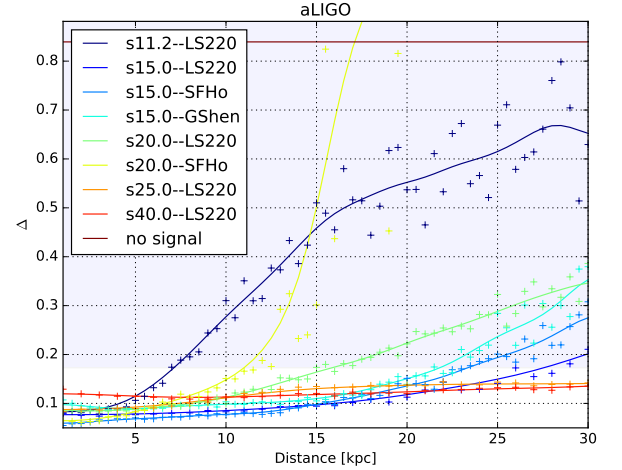


FIG. 7. Median of *Delta* for 8 CCSN waveforms embedded in aLIGO noise and located at different distance from the Earth. The “no signal” line and band show the median and first and third quartile of *Delta* in absence of any signal.

d_r for the advanced Virgo detector at design sensitivity. Results are very similar to aLIGO, despite the detector sensitivity differences. Note that Table III provides the distance at which one could detect a source optimally oriented with a matched filter signal-to-noise ratio of 13.

The same analysis has been performed using expected sensitivity curves for the third generation of gravitational wave detectors. In Europe the Einstein Telescope project proposes to host in a 10-km equilateral triangle configuration 3 low-power low-frequency cryogenic interferometers as well as 3 high-power high-frequency interferometers. Three sensitivity curves, ET-B, ET-C and ET-D corresponding to different options and stages of the project [49] are considered in this study. The US based project Cosmic Explorer [50] is proposing to reach its design sensitivity circa 2040 through two phases labeled CE1 and CE2 also shown in Figure 4.

Figure 8 shows Δ as function of the source distance

for *s20.0--SFHo* waveform for the 5 3G detectors configurations. Overall, the ratio is well reconstructed up to distances in the range 100–200[kpc] which represents an improved of at least a factor 10 with respect to advanced LIGO and advanced Virgo detectors. We can also note that the Einstein Telescope results lay in between the 2 Cosmic Explorer results. This is confirmed for all other waveforms, expect *s25.0--LS220* for which the maximal distance reach in CE2 is significantly lower than CE1. This is partly due to the small variation of the reconstruction quality to the distance of the source making the estimation of d_r rather uncertain for this waveform.

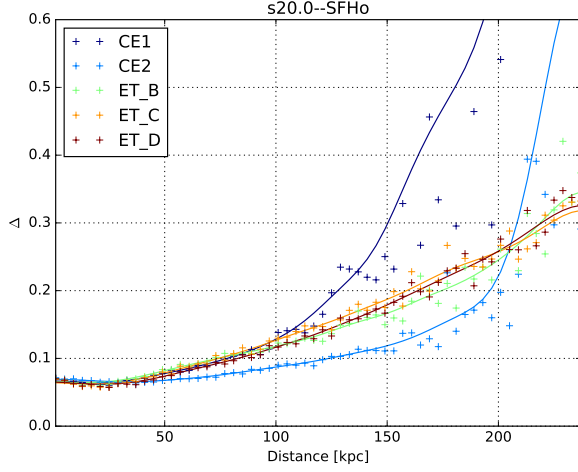


FIG. 8. Median of Δ for s20.0-SFHo CCSN waveform embedded in 3G detectors noise and located at different distance from the Earth.

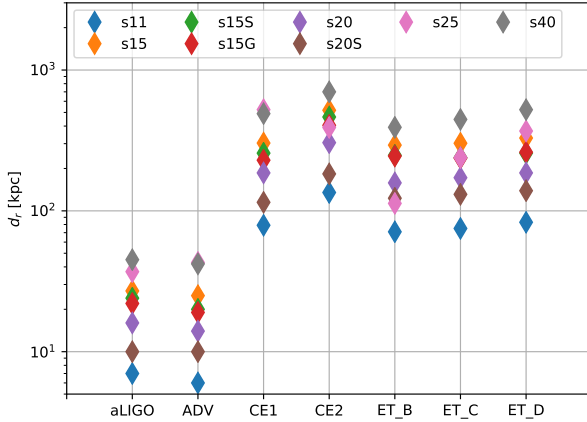


FIG. 9. Maximal distance d_r at which the ratio $r = M_{\text{PNS}}/R_{\text{PNS}}^2$ is reconstructed with good accuracy for a source optimally oriented with respect to the GW detectors for the 7 CCSN waveforms considered in this study.

All results are summarized in Table III and Figure 9. It is remarkable that with 3G detectors the ratio could be reconstructed for sources located up to several hundred of kpc. It is nevertheless important to note the rather wide range obtained for the different waveforms probing a large range of progenitor masses. We did not find any correlation between the mass of the progenitor and d_r , nor the equation of state. On the other hand, the quality of the ratio reconstruction depends on the signal-to-noise ratio, expressed in Table III by d_{det} .

		s11	s15	s15S	s15G	s20	s20S	s25	s40
aLIGO	d_r	7	28	24	22	16	11	38	46
	d_{det}	11	36	26	27	21	16	74	61
ADV	d_r	7	26	20	19	15	10	43	42
	d_{det}	10	32	22	23	18	13	64	52
CE1	d_r	79	304	258	229	187	115	524	490
	d_{det}	115	377	270	282	217	168	774	633
CE2	d_r	135	499	451	405	305	183	391	898
	d_{det}	197	649	468	489	375	294	1347	1100
ET_B	d_r	71	293	248	245	158	123	113	392
	d_{det}	106	364	274	391	216	200	805	665
ET_C	d_r	75	302	239	237	172	131	239	446
	d_{det}	97	332	246	260	194	164	727	603
ET_D	d_r	83	329	257	261	186	139	369	523
	d_{det}	107	368	271	285	213	174	796	661

TABLE III. Maximal distance d_r at which the ratio $r = M_{\text{PNS}}/R_{\text{PNS}}^2$ is reconstructed with good accuracy for a source optimally oriented with respect to the GW detectors considered in this study. d_{det} is the distance at which one could detect a source optimally oriented with a matched filter signal-to-noise ratio of 13 in the different GW detectors.

V. CONCLUSION

The algorithm presented in this paper is a first attempt to infer the time evolution of a combination of the mass of the PNS and its radius based on the universal relations found in PNS asteroseismology. More precisely, we have considered in this paper the ratio $r = M_{\text{PNS}}/R_{\text{PNS}}^2$ derived from the observation of the 2g_2 oscillation mode in the GW data. We have especially investigated the performance of the algorithm in the case of an optimally oriented source detected in a single GW detector. For Advanced LIGO or Advanced Virgo, the ratio can be reconstructed for a source in the Galaxy. We have shown that this is true for a wide range of progenitor mass and that the quality of the inference mainly depends on the signal-to-noise ratio of the signal. For third generation of GW detectors such as Einstein Telescope and Cosmic Explorer, the 2g_2 will be reconstructible for sources at distances of several kpc. Cosmic Explorer in its stage 2 configuration is obtaining the best performance for all waveforms considered here thanks to its excellent sensitivity in the 100-1000[Hz] range. Among the three configuration of Einstein Telescope, ET-D is providing the best performance, especially for the waveforms with the highest progenitor mass (25 M_{\odot} and 40 M_{\odot}). Comparing d_r for ET-B and the other third generations projects, it seems that having a good sensitivity below 200[Hz] is important for massive mass progenitor signals.

This study does not include the realistic case of operating within a network of detectors. We defer this for a forthcoming publication. The sources of GWs we have considered here are optimally oriented. The reported distance at which we can infer the time evolution

of $r = M_{\text{PNS}}/R_{\text{PNS}}^2$ are thus an upper limit that may be lower by a factor 2–3 on average for a source located anywhere on the sky.

Finally, this method can be adapted to other PNS cillation modes, changing few parameters such as the frequency range of the beginning of the mode and its monotonic raise or descent. Being able to reconstruct several modes in a same GW signal would allow to infer individually each of the PNS property.

Acknowledgments —

Appendix A G-MODE RECONSTRUCTION

Given the spectrogram and an specified time interval for the g-mode reconstruction, our proposal method works as follows. The starting point must be specified. It can be either at the beginning or at the end of the signal. Then, in one of these extremes, the maximum energy value is identified, registering its frequency. This is done independently for a number of consecutive time intervals. Then we calculate the median of these frequency values, providing a robust starting value for the g-mode reconstruction.

The starting frequency value is the first g-mode estimate for the first or the last time interval, depending on the specified starting location. If the reconstruction is set to start at the beginning of the signal, the reconstruction

will be done progressively over the time intervals, where each maximum frequency value will be calculated within a frequency range specified by the previous g-mode estimate. Given the non-decreasing behaviour of the true g-mode values, the g-mode estimates will be forced to be greater or equal than the one estimated for its previous time interval, and lower than a specified upper limit. As a result, the g-modes estimates will be a non-decreasing sequence of frequency values.

If the reconstruction is set to start at the end of the signal, the g-modes will be estimated backward in time. Each maximum frequency is calculated within a range determined by its successor (in time) g-mode estimate. These estimates are forced to be lower or equal than its successor (in time) estimate, but greater than a specified lower limit. Thus, a non-decreasing sequence of g-mode estimates is guaranteed.

This g-mode reconstruction method works if and only if the signal is strong enough to provide information about the g-mode, which is reflected in the spectrogram.

Given the sequence of g-mode estimates, the confidence band will be calculated by using the model defined in (1). The g-mode estimates are frequency values which we use as predictors in the model in order to generate confidence intervals for the ratios. Since the g-mode estimates are indexed by time, the confidence intervals for the ratios are too. Thus, we generate the confidence band by interpolating the lower and upper limits of the collection of consecutive confidence intervals, which will be valid for the time range of the g-mode estimates. This confidence band is used to estimate the coverage probabilities in our simulation studies presented below above.

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