RESUMÉ

Chien-Chen(Calvin) Weng

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Summary

My research field is about Robotics Navigation.

▶ particularly, it is moving object tracking introducing neighboring interaction model.

Familiar with Machine Learning.

- ► know how to extract key information from data.
- ► know how to get the optimal estimation of the model.

With Computer Vision background knowledge.

► Able to deal with vision-based perception.

Work Experience

Product Developer, ACTi Corp., Aug. 2012 - current

- ▶ Design vision-based algorithms for surveillance and business service. I am mainly incharge of pedestrian and car detection.
- ► Support developments of moving object tracking and license plate recognition.
- ► Complete other applications such as tripwire, forbidden area, customer heatmap and crowd analysis.
- ▶ Port and maintain algorithm packages under ACTi IVS(Intelligent Video System) framework.

Education

National Taiwan University, Taipei, Taiwan,

► M.S., Computer Science and Information Engineering, Sep 2008 - Jan 2012

National Chung Cheng University, Chiayi, Taiwan

► B.S., Computer Science and Information Engineering, Sep 2000 - Jul 2005

Skills

System Programming : C/C++(Solid). **Data Analysis :** Matlab/Octave(Solid)

Concepts: Machine Learning, Computer Vision

Language: English

Publication

Chien-Chen Weng, Chieh-Chih Wang, Jennifer Healey, A Segmentation and Data Association Annotation System for Laser-based Multi-Target Tracking Evaluation, in Proceedings of the IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM 2012), July 2012. PDF Kuo-Huei Lin, **Chung-Han Weng**¹ and Chieh-Chih Wang, LIDAR-based Multitarget Tracking using Neighboring Interaction Force Models, in Proceedings of the 24th IPPR Conference on Computer Vision, Graphics and Image Processing (CVGIP), August, 2011.

Interests and Continued learning

Robotics, Machine Learning @Coursera, Computer Vision @CRCV, Android Application

 $^{^{1}}$ my former name