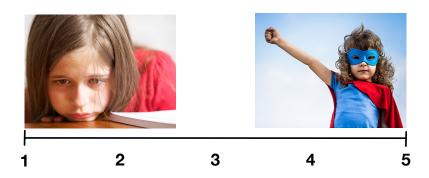
# Modeling Ordinal Categorical Variables Models for Socio-Environmental Data

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## How confident are you in your ability use Bayesian models?



We use *ordinal regression* to deal with data where the dependent variable is measured in ordered categories. Examples of such variables include:

- Psyschometric Likert scales
- Tumor grading
- General quantities (i.e. insurance level: none, adequate, full; index of environmental concern: none, low, moderate, high)
- Cover classes (i.e., Daubenmire classes)

#### Ordered categorical data can be

- unscaled (e.g. attitudes/opinions, etc.)
- scaled (e.g. cover/size classes, etc.)

#### Useful reference

## Doing Bayesian Data Analysis

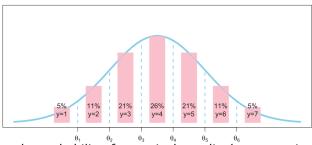
 $p(\theta|D) \quad p(D|\theta) \quad p(\theta) \quad p(D)$ 

A Tutorial with R, JAGS, and Stan

Kruschke, J. (2014). Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan. Academic Press.

#### "How do people generate a descrete ordered response?"

- Imagine that your true Bayesian abilities vary on a continuous scale, but you also have some sense of which categorical threshold you would report
- Central idea: there is a latent continuous metric that underlies the observed ordinal response
- Categories or thresholds partition regions of this continuous metric



**Crutial bit**: the probability of a particular ordinal outcome is the area under the normal curve between the thresholds of that outcome.

Therefore, the probability of outcome 2 is the area under the normal curve between thresholds  $\theta_1$  and  $\theta_2$ . How?

## A general, Bayesian model for ordinal data

$$[\boldsymbol{\theta}, \boldsymbol{\beta}, \sigma^{2} | \mathbf{y}] \propto \prod_{i=1}^{n} \left[ y_{i} \mid \underbrace{\int_{\theta_{k-1}}^{\theta_{k}} \underbrace{[z_{i} | g(\boldsymbol{\beta}, \mathbf{x}_{i}), \sigma^{2}]}_{Pr(\theta_{k-1} < z_{i} < \theta_{k})} dz_{i}} \right] [\boldsymbol{\beta}] [\boldsymbol{\theta}] [\boldsymbol{\sigma}^{2}]$$

- $y_i$  is *ith* observation in categories = k = 1,...K
- $oldsymbol{ heta}$  is an *ordered* vector of cutpoints
- $\theta_0 = -\infty$
- $\theta_K = +\infty$

Why is **z** missing from the posterior?

What is 
$$Pr(\theta_{k_{i-1}} < z_i < \theta_{k_i})$$
?

What is the quantity between the large brackets?

### An general algorithm for implementation

Let  $F(\theta_k, \mu, \sigma^2)$  be a properly moment matched, cummulative distribution function for the distribution of the latent quantity  $z_i$ . The function F() returns the proability that  $z_i < \theta_k$ . For notational convenience, we let  $\mu_i = g(\beta, \mathbf{x}_i)$ . Compute:

$$p[1,i] = F(\theta_1, \mu_i, \sigma^2) \tag{1}$$

$$p[2,i] = F(\theta_2, \mu_i, \sigma^2) - F(\theta_1, \mu, \sigma^2)$$
 (2)

$$p[K-1] = F(\theta_{K-1}, \mu, \sigma^2) - F(\theta_{K-2}, \mu, \sigma^2)$$
 (5)

$$p[K] = 1 - F(\theta_K, \mu, \sigma^2) \tag{6}$$

The likelihood of the data conditional on the parameters is then:

$$y_i \sim \text{categorical}(\mathbf{p}_i)$$

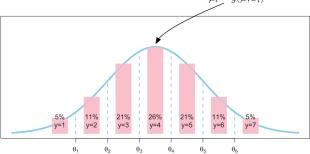
## The categorical distribution

$$y_i \sim \text{categorical}(\mathbf{p}_i)$$

Let  $y_i$  be an observation that can take on values k = 1,..,K. **p** is a vector of length K with elements  $p_i = \Pr(y_i = k_i)$ , which is the same as  $\Pr(y_i = i)$ .

You can use any continuous distribution appropriate to the support of the random variable,  $y_i$ .

Issues of identifiability and what to do about it

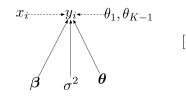


- The likelihood will not result in a unique solution.
- Both  $\beta$  and  $\theta$  are "location" parameters that calibrate the mapping from what is observed,  $y_i$  to the latent  $z_i$ .
- In other workds, there is no unique combination of  $\theta$  and  $\beta$  that produce equally informative posterior distributions.
- Put differently, for any given  $\beta$  there exists a  $\theta$  that produces a likelihood equal to that obtained from at least one other  $\beta$  and  $\theta$ .

## Potential Identification Contraints to Apply

Options	eta	σ	heta
1	unconstrained	fixed	fix one of $\theta_j$
2	drop intercept, $eta_0$	fixed	unconstrained
3	unconstrained	unconstrained	fix two of $ heta_j$

#### ample: Predicting A Unscaled Ordinal Quantity



$$\mu = \beta_1 + \beta_2 x_i$$

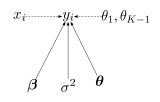
$$[\boldsymbol{\theta}, \boldsymbol{\beta}, \sigma^2 | \mathbf{y}] \propto \prod_{i=1}^n \left[ y_i \mid \int_{\theta_{k-1}}^{\theta_k} [z_i \mid g(\boldsymbol{\beta}, x_i), \sigma^2] dz_i \right]$$

$$\times [\beta_1] [\beta_2] \prod_{i=1}^{K-2} [\theta_i] [\sigma]$$

$$\begin{aligned} & \prod_{j=2} [\sigma_j][\sigma] \\ & y_i \sim \left[ y_i \mid \int_{\theta_{k-1}}^{\theta_k} [z_i \mid g(\boldsymbol{\beta}, x_i), \sigma^2] dz_i \right] \\ & \boldsymbol{\beta} \sim \text{normal}(0, 0.001) \\ & \boldsymbol{\sigma} \sim \text{uniform}(0, 100) \end{aligned}$$

 $\theta_i \sim \text{uniform}(0, 10)$ 

#### **Example: Predicting A Scaled Ordinal Quantity**



$$\mu = \frac{e^{\beta_1 + \beta_2 x_i}}{1 + e^{\beta_1 + \beta_2 x_i}} = g(\boldsymbol{\beta}, x_i)$$
$$[\boldsymbol{\theta}, \boldsymbol{\beta}, \sigma^2 | \mathbf{y}] \propto \prod_{i=1}^n \left[ y_i \mid \int_{\theta_{k-1}}^{\theta_k} [z_i \mid m(g(\boldsymbol{\beta}, x_i), \sigma^2)] dz_i \right]$$
$$\times [\beta_1][\beta_2] \prod_{i=2}^{K-2} [\theta_j][\sigma]$$

$$y_i \sim \left[ y_i \mid \int_{\theta_{k-1}}^{\theta_k} [z_i \mid m(g(\boldsymbol{\beta}, x_i), \sigma^2)] dz_i \right]$$
  
$$\boldsymbol{\beta} \sim \text{normal}(0, 0.0001)$$
  
$$\boldsymbol{\sigma} \sim \text{uniform}(0.01, .5)$$
  
$$\theta_i \sim \text{uniform}(0, 1)$$

#### Other notables

- Referred to as ordinal regression or ordered probit regression.
- Cut points are often specified using  $\tau$ .
- The latent quantity that we are calling  $z_i$  is also specified as  $y_i^*$
- Often in the unscaled case, the standard normal is used ( $\beta_0=0$  and  $\sigma=1$ ) with the probabily of outcome  $\theta_k$  being:

$$p(\tau = k \mid \mu, \sigma, \theta_j) = \Phi((\theta_k - \mu)/\sigma) - \Phi((\theta_{k-1} - \mu)/\sigma)$$

Table 15.2: For the generalized linear model: typical noise distributions and inverse-link functions for describing various scale types of the predicted variable y. The value  $\mu$  is a central tendency of the predicted data (not necessarily the mean). The predictor variable is x, and lin(x) is a linear function of x, such as those shown in Table 15.1. Copyright © Kruschke, J. K. (2014). *Doing Bayesian Data Analysis: A Tutorial with R, JAGS, and Stan. 2nd Edition.* Academic Press / Elsevier.

Scale Type of Predicted y	Typical Noise Distribution $y \sim \text{pdf}(\mu, [\text{parameters}])$	Typical Inverse-Link Function $\mu = f(\ln(x), [parameters])$
Metric	$y \sim \text{normal}(\mu, \sigma)$	$\mu = \lim(x)$
Dichotomous	$y \sim \text{bernoulli}(\mu)$	$\mu = \text{logistic} (\text{lin}(x))$
Nominal	$y \sim \text{categorical}(\ldots, \mu_k, \ldots)$	$\mu_k = \frac{\exp(\lim_{k(x)})}{\sum_c \exp(\lim_{c(x)})}$
Ordinal	$y \sim \text{categorical}(\ldots, \mu_k, \ldots)$	$\mu_k = \begin{array}{c} \Phi\left(\left(\theta_k - \ln(x)\right)/\sigma\right) \\ -\Phi\left(\left(\theta_{k-1} - \ln(x)\right)/\sigma\right) \end{array}$
Count	$y \sim \text{poisson}(\mu)$	$\mu = \exp\left(\ln(x)\right)$