Modeling Ordinal Categorical Variables

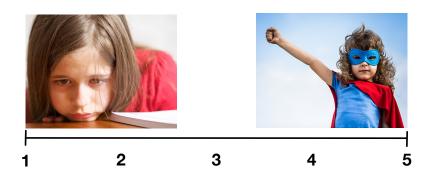
Models for Socio-Environmental Data

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How confident are you in your ability use Bayesian models?



We use *ordinal regression* to deal with data where the dependent variable is measured in ordered categories. Examples of such variables include:

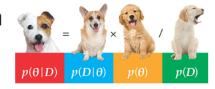
- Psyschometric Likert scales
- Tumor grading
- General quantities (i.e. insurance level: none, adequate, full; index of environmental concern: none, low, moderate, high)
- Cover classes (i.e., Daubenmire classes)

Ordered categorical data can be

- unscaled (e.g. attitudes/opinions, etc.)
- scaled (e.g. cover/size classes, etc.)

Useful reference

Doing Bayesian Data Analysis

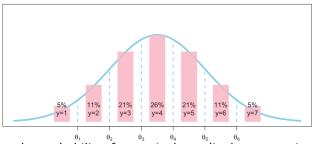


A Tutorial with R, JAGS, and Stan

Kruschke, J. (2014). Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan. Academic Press.

"How do people generate a descrete ordered response?"

- Imagine that your true Bayesian abilities vary on a continuous scale, but you also have some sense of which categorical threshold you would report
- **Central idea**: there is a latent continuous metric that underlies the observed ordinal response
- Categories or thresholds partition regions of this continuous metric



Crutial bit: the probability of a particular ordinal outcome is the area under the normal curve between the thresholds of that outcome.

Therefore, the probability of outcome 2 is the area under the normal curve between thresholds θ_1 and θ_2 . How?

A general, Bayesian model for ordinal data

$$\begin{split} [\theta,\beta,\sigma^2|\mathbf{y}] & \propto \prod_{i=1}^n [y_i \mid p_i] \beta_1] [\beta_2] \prod_{k=2}^{K-1} [\theta] [\sigma^2] \\ y_i & \sim \mathsf{categorical} \bigg(y_i \mid p_i = \bigg[\int_{-\infty}^{\theta_{k=1}} [z_i \mid g(\beta,x_i),\sigma^2] dz_i, \int_{\theta_{k=k+1}}^{\theta_{k=k+2}} [z_i \mid g(\beta,x_i),\sigma^2] dz_i \bigg) \\ \beta & \sim \mathsf{normal}(0,0.001) \\ \sigma^2 & \sim \mathsf{inversegamma}(0.001,0.001) \\ \theta_j & \sim \mathsf{uniform}(0,10) \end{split}$$

- y_i is *ith* observation in categories = k = 1,...K
- $oldsymbol{ heta}$ is an *ordered* vector of cutpoints
- $\theta_0 = -\infty$
- $\theta_K = +\infty$

Why is z missing from the posterior?

An general algorithm for implementation

Let $F(\theta_k, \mu, \sigma^2)$ be a properly moment matched, cummulative distribution function for the distribution of the latent quantity z_i . The function F() returns the proability that $z_i < \theta_k$. For notational convenience, we let $\mu_i = g(\beta, \mathbf{x}_i)$. Compute:

$$p[1,i] = F(\theta_1, \mu_i, \sigma^2) \tag{1}$$

$$p[2,i] = F(\theta_2, \mu_i, \sigma^2) - F(\theta_1, \mu, \sigma^2)$$
 (2)

$$p[K-1] = F(\theta_{K-1}, \mu, \sigma^2) - F(\theta_{K-2}, \mu, \sigma^2)$$
 (5)

$$p[K] = 1 - F(\theta_K, \mu, \sigma^2) \tag{6}$$

The likelihood of the data conditional on the parameters is then:

$$y_i \sim \text{categorical}(\mathbf{p}_i)$$

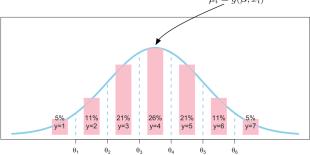
The categorical distribution

$$y_i \sim \text{categorical}(\mathbf{p}_i)$$

Let y_i be an observation that can take on values k = 1,..,K. **p** is a vector of length K with elements $p_i = \Pr(y_i = k_i)$, which is the same as $\Pr(y_i = i)$.

You can use any continuous distribution appropriate to the support of the random variable, y_i .

Issues of identifiability and what to do about it

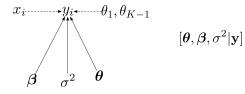


- The likelihood will not result in a unique solution.
- Both β and θ are "location" parameters that calibrate the mapping from what is observed, y_i to the latent z_i .
- In other workds, there is no unique combination of θ and β that produce equally informative posterior distributions.
- Put differently, for any given β there exists a θ that produces a likelihood equal to that obtained from at least one other β and θ .

Potential Identification Contraints to Apply

Options	β	σ	heta
1	unconstrained	fixed	fix one of θ_j
2	drop intercept, eta_0	fixed	unconstrained
3	unconstrained	unconstrained	fix two of $ heta_j$

ample: Predicting A Unscaled Ordinal Quantity



$$\mu = \beta_1 + \beta_2 x_i$$

$$[\boldsymbol{\theta}, \boldsymbol{\beta}, \sigma^2 | \mathbf{y}] \propto \prod_{i=1}^n \left[y_i \mid \int_{\theta_{k-1}}^{\theta_k} [z_i \mid g(\boldsymbol{\beta}, x_i), \sigma^2] dz_i \right]$$

$$\times [\beta_1] [\beta_2] \prod_{i=1}^{K-2} [\theta_i] [\sigma]$$

```
or (i in 1:length(y)) {
    m(i) = beto[2]**[i]
    y(i) ~ doat( pr[i,1:nrlevels))
    pr[i,i] ~ pnorm( thresh[i], mu[i] , tau)

for ( k in 2:(nrlevels-1) ) {
    pr[i,k] < max(_00001, pnorm( thresh[k] , mu[i] , tau) - pnorm( thresh[k-1] , mu[i] , tau ))
    }
    pr[i,nrlevels] < 1 - pnorm( thresh[nrlevels-1] , mu[i] , tau )
}
```

$$j=2$$

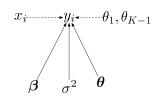
$$y_i \sim \left[y_i \mid \int_{\theta_{k-1}}^{\theta_k} [z_i \mid g(\boldsymbol{\beta}, x_i), \sigma^2] dz_i \right]$$

$$\boldsymbol{\beta} \sim \text{normal}(0, 0.001)$$

$$\boldsymbol{\sigma} \sim \text{uniform}(0, 100)$$

 $\theta_i \sim \text{uniform}(0, 10)$

Example: Predicting A Scaled Ordinal Quantity



$$\mu = \frac{e^{\beta_1 + \beta_2 x_i}}{1 + e^{\beta_1 + \beta_2 x_i}} = g(\boldsymbol{\beta}, x_i)$$
$$[\boldsymbol{\theta}, \boldsymbol{\beta}, \sigma^2 | \mathbf{y}] \propto \prod_{i=1}^n \left[y_i \mid \int_{\theta_{k-1}}^{\theta_k} [z_i \mid m(g(\boldsymbol{\beta}, x_i), \sigma^2)] dz_i \right]$$
$$\times [\beta_1][\beta_2] \prod_{i=2}^{K-2} [\theta_j][\sigma]$$

```
'( in .!length(y)) {
    mu[i] = ilogit(beta[i] + beta[2]*s[i])
    a[i] <=nox(.00001, [nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu[i]\times=nu
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$$y_i \sim \left[y_i \mid \int_{\theta_{k-1}}^{\theta_k} [z_i \mid m(g(\boldsymbol{\beta}, x_i), \sigma^2)] dz_i \right]$$

$$\boldsymbol{\beta} \sim \text{normal}(0, 0.0001)$$

$$\boldsymbol{\sigma} \sim \text{uniform}(0.01, .5)$$

$$\theta_i \sim \text{uniform}(0, 1)$$

Other notables

- Referred to as ordinal regression or ordered probit regression.
- Cut points are often specified using τ .
- The latent quantity that we are calling z_i is also specified as y_i^*
- Often in the unscaled case, the standard normal is used ($\beta_0=0$ and $\sigma=1$) with the probabily of outcome θ_k being:

$$p(\tau = k \mid \mu, \sigma, \theta_j) = \Phi((\theta_k - \mu)/\sigma) - \Phi((\theta_{k-1} - \mu)/\sigma)$$

Table 15.2: For the generalized linear model: typical noise distributions and inverse-link functions for describing various scale types of the predicted variable y. The value μ is a central tendency of the predicted data (not necessarily the mean). The predictor variable is x, and lin(x) is a linear function of x, such as those shown in Table 15.1. Copyright © Kruschke, J. K. (2014). *Doing Bayesian Data Analysis: A Tutorial with R, JAGS, and Stan. 2nd Edition.* Academic Press / Elsevier.

Scale Type of Predicted y	Typical Noise Distribution $y \sim \text{pdf}(\mu, [\text{parameters}])$	Typical Inverse-Link Function $\mu = f(\ln(x), [parameters])$
Metric	$y \sim \text{normal}(\mu, \sigma)$	$\mu = \lim(x)$
Dichotomous	$y \sim \text{bernoulli}(\mu)$	$\mu = \text{logistic} (\text{lin}(x))$
Nominal	$y \sim \text{categorical}(\ldots, \mu_k, \ldots)$	$\mu_k = \frac{\exp(\lim_{k(x)})}{\sum_c \exp(\lim_{c(x)})}$
Ordinal	$y \sim \text{categorical}(\ldots, \mu_k, \ldots)$	$\mu_k = \begin{array}{c} \Phi\left(\left(\theta_k - \ln(x)\right)/\sigma\right) \\ -\Phi\left(\left(\theta_{k-1} - \ln(x)\right)/\sigma\right) \end{array}$
Count	$y \sim \text{poisson}(\mu)$	$\mu = \exp\left(\ln(x)\right)$