Technical Report: A Stratification Approach to Partial Dependence for Codependent Variables

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Abstract

1 Introduction

Partial dependence, the isolated effect of a specific variable or variables on the response variable, y, is important to researchers and practitioners in many disparate fields such as medicine, business, and the social sciences. For example, in medicine, physicians are interested in the relationship between an individual's demographics or clinical features and their susceptibility to illness. Business analysts at a car manufacturer might need to know how changes in their supply chain are affecting defect rates. Climate scientists are interested in how different atmospheric carbon levels affect temperature.

For an explanatory matrix, \mathbf{X} , with a single variable, x_1 , a plot of the y against x_1 visualizes the marginal effect of feature x_1 on y exactly. Given two or more features, one can similarly plot the marginal effects of each feature separately, however, the analysis is complicated by the interactions of the variables. Variable interactions, codependencies between features, result in marginal plots that do not isolate the specific contribution of a feature of interest to the target. For example, a marginal plot of sex (male/female) against body weight would likely show that, on average, men are heavier than women. While true, men are also taller than women on average, which likely accounts for most of the difference in average weight. It is unlikely that two "identical" people, differing only in sex, would be appreciably different in weight.

Rather than looking directly at the data, there are several partial dependence techniques that interrogate fitted models provided by the user: Friedman's original partial dependence (which we will denote FPD) Friedman [2000], Individual Conditional Expectations (ICE) Goldstein et al. [2015], Accumulated Local Effects (ALE) Apley [2016], and most recently SHAP Lundberg and Lee [2017]. Model-based techniques dominate the partial dependence research literature because interpreting the output of a fitted model has several advantages. Models have a tendency to smooth over noise. Models act like analysis preprocessing steps, potentially reducing the computational burden on model-based partial dependence techniques; e.g., ALE is O(n) for the n records of \mathbf{X} . Model-based techniques are typically model-agnostic, though for efficiency, some provide model-specific optimizations, as SHAP does. Partial dependence techniques that interrogate models also provide insight into the models themselves; i.e., how variables affect model behavior. It is also true that, in some cases, a predictive model is the primary goal so creating a suitable model is not an extra burden.

Model-based techniques do have some disadvantages, however. As we demonstrate in Section 4 using synthetic and real data sets, model-based techniques vary in their ability to

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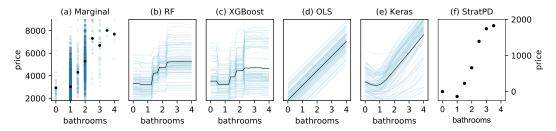


Figure 1: Plots of bathrooms versus rent price using New York City apartment rent data. (a) marginal plot, (b) PD/ICE plot derived from random forest, (c) PD/ICE plot derived from gradient boosted machine, and (d) PD/ICE plot derived from ordinary least squares regression; sample size is 10,000 observations of ~50k. The PD/ICE plots are different for the same data set, depending on the chosen user model. X['bathrooms'].unique() shows (array([0., 1., 1.5, 2., 2.5, 3., 3.5, 4.]), array([54, 8151, 140, 1539, 39, 67, 3, 7])). StratPD has missing last value, not enough data. what are R^2 values. how tuned

tease apart the effect of codependent features on the response. Also, recall that there are vast armies of business analysts and scientists at work that need to analyze data, in a manner akin to exploratory data analysis (EDA), that have no intention of creating a predictive model. Either they have no need, perhaps needing only partial dependence plots, or they do not have the expertise to choose, tune, and assess models (or write software at all).

Even in the case where a machine learning practitioner is available to create a fitted model for the analyst, hazards exist. First, if a fitted model is unable to capture the relationship between features and y accurately, for whatever reason, then partial dependence does not provide any useful information to the user. To make interpretation more challenging, there is no definition of "accurate enough." Second, given an accurate fitted model, business analysts and scientists are still peering at the data through the lens of the model, which can distort partial dependence curves. Separating visual artifacts of the model from real effects present in the data requires expertise in model behavior (and usually the implementation of model fitting algorithms).

Consider the combined FPD/ICE plots shown in Figure 1 derived from several models (random forest, gradient boosting, linear regression, deep learning) fitted to the same New York City rent data set Kaggle [2017]. The subplots in Figure 1(b)-(e) present starkly different partial dependence relationships and it is unclear which, if any, is correct. The marginal plot, (a), drawn directly from the data shows a roughly linear growth in price for a rise in the number of bathrooms, but this relationship is biased because of the dependence of bathrooms on other variables, such as the number of bedrooms. (Five bathroom, one bedroom apartments are unlikely.) For real data sets with codependent features, the true relationship is unknown so it is hard to evaluate the correctness of the plots. (Humans are unreliable estimators, which is why we need data analysis algorithms in the first place.) Nonetheless, having the same algorithm, operating on the same data, give meaningfully different partial dependences is undesirable and makes one question their validity.

Experts are often able to quickly recognize model artifacts, such as the stairstep phenomenon inherent to the decision tree-based methods in Figure 1(b) and (c). In this case, though, the stairstep is more accurate than the linear relationship in (d) and (e) because the number of bathrooms is discrete (except for "half baths"). The point is that techniques for partial dependence that interrogate models can be misleading, even for experts.

In this paper, we propose a strategy, called STRATified Partial Dependence (STRATPD), that computes partial dependences directly from training data (\mathbf{X}, \mathbf{y}) , rather than through the predictions of a fitted model. Figure 1(f) shows the partial dependence plot computed by STRATPD. We first define the idealized partial dependence as the integration over the partial derivative of y with respect to the variable of interest for the smooth function that generated (\mathbf{X}, \mathbf{y}) . As that function is unknown, we estimate the partial derivatives from the data non-parametrically. Colloquially, the approach examines changes in y across x_j while holding $\mathbf{X}_{\backslash i}$ constant $(\mathbf{X}_{\backslash i})$ indicates all variables except x_j .

To estimate partial derivatives, StratPD stratifies $\mathbf{X}_{\backslash j}$ feature space into disjoint regions of observations where all $\mathbf{X}_{\backslash j}$ variables are approximately matched across the observations in that region. Within each $\mathbf{X}_{\backslash j}$ region, any fluctuations in the response variable are likely due to the variable of interest, x_j . Estimates of the partial derivative within a region are computed discretely via the changes in y values between unique x_j positions. The overall partial derivative at $x_j = z$ is the average of all slopes, found in any region, whose x_j range spans z. Stratification occurs through the use of a decision tree but only for the purpose of partitioning feature space; StratPD never uses predictions from any model.

The technique seems to isolate variables well and has linear behavior for numeric variables and mildly quadratic behavior for categorical variables in practice. The theoretical complexity is $O(n^2)$ like FPD.

Model selection is never obvious and a nonparametric technique that could provide insight into the relationship between variables and the response would be a welcome aid to choosing an appropriate model.

in the end, increasing the range of available techniques allows users to choose according to their specific needs, what could even mundane characteristics that include availability of libraries in a particular language or deployment environment.

cold start, counting execution time and number of hyper parameters. particularly deep learning

what are our disadvantages: * we can't do bivariate predictors * no interaction effects * we need diff techniques for regr and classifiers

The techniques differ in algorithm simplicity, performance, and ability to isolate codependent variables. a nonparametric technique could also inform which machine learning model to use if a model is desired.

The goal of this work is to characterize partial dependence in a way that (a) does not rely on, nor make predictions from, a user's model, and (b) does not presume mutually-independent features.

SHAP is mean centered FPD for independent variables, proof in supplemental material.

state up front it only gets pure partial dependence, no interaction and has quadratic theoretical complexity, but it has the advantage that it doesn't require a fitted model. Sometimes there is an advantage to a model, smoothing etc. But, in many cases lack of model increases the accessibility of the tool to analysts and could prevent nonexpert machine learning practitioners from interpretation errors from poorly fit or tuned models.

2 Partial dependence without model predictions

Definition 1 The *idealized partial dependence* of y on feature x_j for smooth generator function $f: \mathbb{R}^p \to \mathbb{R}$ evaluated at $x_j = z$ is the cumulative sum up to z:

$$PD_{j}(z) = \int_{\min(x_{j})}^{z} \frac{\partial y}{\partial x_{j}} dx_{j}$$
 (1)

 $PD_j(z)$ is the value contributed to y by x_j at $x_j = z$ and $PD_j(min(x_j)) = 0$. The advantages of this partial dependence definition are that it does not depend on predictions from a fitted model and is insensitive to collinear or otherwise codependent features, unlike the Friedman's original definition that he points out is less accurate for codependent data sets. We will denote Friedman's as FPD_j to distinguish it from this ideal, PD_j .

For example, consider quadratic equation $y=x_1^2+x_2+100$ as a generator of data in [0,3]. The partial derivatives are $\frac{\partial y}{\partial x_1}=2x_1$ and $\frac{\partial y}{\partial x_2}=1$, giving $PD_1=x_1^2$ and $PD_2=x_2$.

The obvious disadvantage of this feature impact definition is that function f, from which PD_j is derived, is unknown in practice, so symbolically computing the partial derivatives is

not possible. But, if we could compute accurate partial dependence curves by some other method, then this definition would still represent a viable means to obtain feature impacts.

STRATPD stratifies a data set into groups of observations that are similar, except in the variable of interest, x_j , through the use of a single decision tree. Any fluctuation of the response variable within a group (decision tree leaf) is likely due to x_j . The β_1 coefficient of a simple local linear regression fit to the (x_j,y) values within a group provides an estimate of $\frac{\partial y}{\partial x_j}$ in that group's x_j range. Averaging the partial derivative estimates across all such groups yields the overall $\frac{\partial y}{\partial x_j}$ partial derivative approximation. The cumulative sum of the estimated partial derivative yields the partial dependence curve.

3 Existing work

FPD

ICE

ALE

SHAP

4 Experimental results

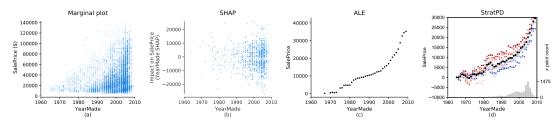


Figure 2: (a) Marginal plot of bulldozer YearMade versus SalePrice using subsample of 20k observations, (b) partial dependence drawn by SHAP interrogating an RF with 40 trees and explaining 1000 values with 100 observations as background data, (c) StratPD partial dependence.

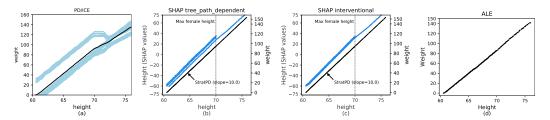


Figure 3: SHAP partial dependence plots of response body weight on feature height using 2000 synthetic observations from Equation (??). SHAP interrogated an RF with 40 trees and explained all 2000 samples; the interventional case used 100 observations as background data.

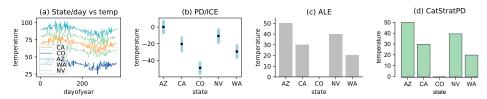


Figure 4: foo.

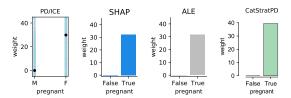


Figure 5: foo.

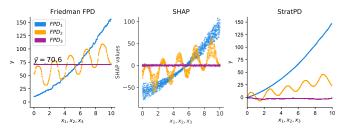


Figure 6: $y = x_1^2 + x_1x_2 + 5x_1sin(3x_2) + 10$ where $x_1, x_2, x_3 \sim U(0, 10)$ and x_3 does not affect y. No noise added.

5 Algorithms

StratPD

```
Fit tree regressor to all but x_c with hyper parameter min_slopes_per_x
For each leaf:
    y bar = Group leaf samples by x_c, computing average y per unique x_c
    dx = discrete difference between adjacent unique x_c
    dy = discrete difference between adjacent average y bar
    add (x[i], x[i+1], dy[i]/dx[i]) for each unique x_c to list D

for each x in unique x_c from X:
    slopes = [slope for (a, b, slope) in D if x >= a and x < b]
    count[x] = |slopes|
    dydx[x] = mean(slopes)

Drop slope estimates computed using fewer than min_slopes_per_x values
pdx = discrete difference between adjacent unique x_c
pdy = cumulative sum of dydx * pdx
return pdx, [0]+pdy // insert 0 for pdx[0] since sum contributed from beyond left is 0</pre>
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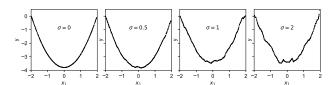


Figure 7: $y = x_1^2 + x_1 + 10 + N(0, \sigma)$ where $x_1, x_2 \sim U(-2, 2)$ and $\sigma \in [0, 0.5, 1, 2]$.

```
Algorithm: StratPD
 Input: X, y, c, min_samples_leaf, min_slopes_per_x
 Output: pdx, pdy: Unique x_c, partial dependence values across x_c
 T := \text{Decision tree regressor fit to } (\mathbf{X}_{\overline{c}}, \mathbf{y}) \text{ with hyper-parameter: } min\_samples\_leaf
 for each leaf l \in T do
       (\mathbf{x}_l, \mathbf{y}_l) = \{(x_c^{(i)}, y^{(i)})\}_{i \in l}
                                                                                                                                 // Get leaf samples
       \mathbf{u}\mathbf{x} := unique(\mathbf{x}_l)
       \bar{\mathbf{y}} := \text{Group leaf records } (\mathbf{x}_l, \mathbf{y}_l) \text{ by value of } \mathbf{x}_l, \text{ computing } \bar{y} \text{ per unique value}
       \mathbf{d}\mathbf{x} := \mathbf{u}\mathbf{x}^{(i+1)} - \mathbf{u}\mathbf{x}^{(i)}_{i=1..|\mathbf{u}\mathbf{x}|-1}
                                                                                                                             // Discrete difference
       \begin{aligned} \mathbf{d}\mathbf{y} &:= \bar{\mathbf{y}}^{(i+1)} - \bar{\mathbf{y}}^{(i)}_{i=1..|\mathbf{u}\mathbf{x}|-1} \\ \text{Add tuples } (\mathbf{u}\mathbf{x}^{(i)}, \mathbf{u}\mathbf{x}^{(i+1)}, \ \mathbf{d}\mathbf{y}^{(i)}/\mathbf{d}\mathbf{x}^{(i)})_{i=1..|\mathbf{u}\mathbf{x}|-1} \text{ to list } \mathbf{d} \end{aligned}
 end
 \mathbf{ux} := unique(\{x_c^{(i)}\}_{i=1..n})
 for each x \in \mathbf{ux}
                                                             // Counts slopes, compute average slope per unique x_c value
 do
        slopes := [slope \text{ for } (a, b, slope) \in \mathbf{d} \text{ if } x \ge a \text{ and } x < b]
       \mathbf{c}_x := |slopes|
        \mathbf{dydx}_x := \overline{slopes}
 end
 \mathbf{dydx} := \mathbf{dydx}[\mathbf{c} \geq min\_slopes\_per\_x] \qquad \textit{// Drop slope estimates computed from too few}
 \mathbf{ux} := \mathbf{ux}[\mathbf{c} \geq min\_slopes\_per\_x]
 \mathbf{pdx} := \mathbf{ux}^{(i+1)} - \mathbf{ux}_{i=1..|\mathbf{ux}|-1}^{(i)}
 \mathbf{pdy} := [0] + \text{cumulative\_sum}(\mathbf{dydx} * \mathbf{pdx}) // integrate, inserting 0 for leftmost x_c
 return pdx, pdy
CatStratPD
```

```
Fit tree regressor to all but x_c with hyper parameter min_slopes_per_x
For each leaf:
    y bar = Group leaf samples by categories of x_c, computing average y per unique category x_c
    Compute unique categories and counts per category
    refcat is randomly chosen category from x_c
    For each unique category x in leaf:
        delta[cat,leaf] = Subtract y for refcat from all y bar (refcat delta will be 0)
end
Let Avg[cat] be vector with running sum mapping category to count
work = set of leaf indexes
while more work and something changed and less than max iterations:
    for each leaf in leaves:
        if cat in delta[:,leaf] intersects with Avg:
            j = random category in intersection
           adjust delta[:,leaf] to be relative to j so delta[j,leaf] == 0 then add Avg[j] so comparable
           merge into Avg
    work -= all j merged this iteration
```

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Daniel W Apley. Visualizing the effects of predictor variables in black box supervised learning models. arXiv preprint arXiv:1612.08468, 2016.

```
Algorithm: CatStratPD
\begin{array}{ll} \textbf{Input: X,y,} c, min\_samples\_leaf \\ \textbf{Output: } \Delta^{(k)} = \text{category } k\text{'s effect on } y \text{ where } mean(\Delta^{(k)}) = 0 \end{array}
               n^{(k)} = number of supported observations per category k
T:= Decision tree regressor fit to (\mathbf{X}_{\overline{c}},\mathbf{y}) with hyper-parameter: min\_samples\_leaf
// Get average y delta relative to random ref category for each sample in each leaf
Let \Delta_{x,l} be dictionary mapping (category, leaf) to delta from ref category
Let Count_{x,l} be dictionary mapping (category, leaf) to count
for each leaf l \in T do
    (\mathbf{x}_l, \mathbf{y}_l) = \{(x_c^{(i)}, y^{(i)})\}_{i \in l}
                                                                                                    // Get leaf samples
     \mathbf{u}\mathbf{x}, \mathbf{c}\mathbf{x} := unique(\mathbf{x}_l)
                                                           // Get unique categories, counts from leaf samples
     \bar{\mathbf{y}} := \text{Group leaf records } (\mathbf{x}_l, \mathbf{y}_l) \text{ by categories of } \mathbf{x}_l, \text{ computing } \bar{y} \text{ per unique category}
    refcat_l := random category from y
    for each x \in \mathbf{ux} do
         Count_{x,l} := \mathbf{c}\mathbf{x}_x
          \Delta_{x,l} := \bar{\mathbf{y}} - y[refcat_l]
end
work := 1 .. |uniq\_refcats|
Let Avg_x be vector with running sum mapping category to count
while len(work) > 0 and len(completed) > 0 and iteration <= max\_iter do
end
```

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