

3:39:49 PM: Compiled

```
-----  
try: 1  
start angle: 0.5  
ERROR! angle went backwards! previous: 0.5 current: 0.1  
end angle: 96.8  
-----  
try: 2  
start angle: 0.2  
ERROR! angle went backwards! previous: 0.2 current: 0.0  
end angle: 92.4  
-----  
try: 3  
start angle: 0.2  
ERROR! angle went backwards! previous: 0.2 current: 0.1  
end angle: 91.6  
-----  
try: 4  
start angle: 0.5  
end angle: 94.8  
-----  
try: 5  
start angle: 0.1  
ERROR! angle went backwards!  
previous: 0.1 current: 0.0end angle: 96.0  
-----  
try: 6  
start angle: 0.0  
end angle: 93.5  
-----  
try: 7  
start angle: 0.0  
ERROR! - gyro value -1  
ERROR! angle went backwards! previous: 0.0 current: -0.1  
end angle: 92.5  
-----  
try: 8  
start angle: 0.2  
ERROR! angle went backwards! previous: 0.3 current: 0.0  
end angle: 180.0  
-----  
Traceback (most recent call last):  
  File "gyro-turn-test-print", line 98, in <module>  
  File "gyro-turn-test-print", line 97, in main
```

SystemExit: 0

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try: 1

start angle: 0.5

ERROR! angle went backwards! previous: 0.5 current: 0.1

end angle: 96.8

try: 2

start angle: 0.2

ERROR! angle went backwards! previous: 0.2 current: 0.0

end angle: 92.4

try: 3

start angle: 0.2

ERROR! angle went backwards! previous: 0.2 current: 0.1

end angle: 91.6

try: 4

start angle: 0.5

end angle: 94.8

try: 5

start angle: 0.1

ERROR! angle went backwards!

previous: 0.1 current: 0.0end angle: 96.0

try: 6

start angle: 0.0

end angle: 93.5

try: 7

start angle: 0.0

ERROR! - gyro value -1

ERROR! angle went backwards! previous: 0.0 current: -0.1

end angle: 92.5

try: 8

start angle: 0.2

ERROR! angle went backwards! previous: 0.3 current: 0.0

end angle: 180.0

Traceback (most recent call last):

File "gyro-turn-test-print", line 98, in <module>

File "gyro-turn-test-print", line 97, in main

SystemExit: 0