

V1.0 20/07/2022 First Release


**Curtis**      **Controller: 1232SE5371 36/48V**  
**350A (máx) 175A (S2-60mn)**  
**115A máx → Imáx = 33% of 350A**  
**Motor Type 117**  
**EM Brake 48V**



*CLIC on 1232 picture to  
download Manual*

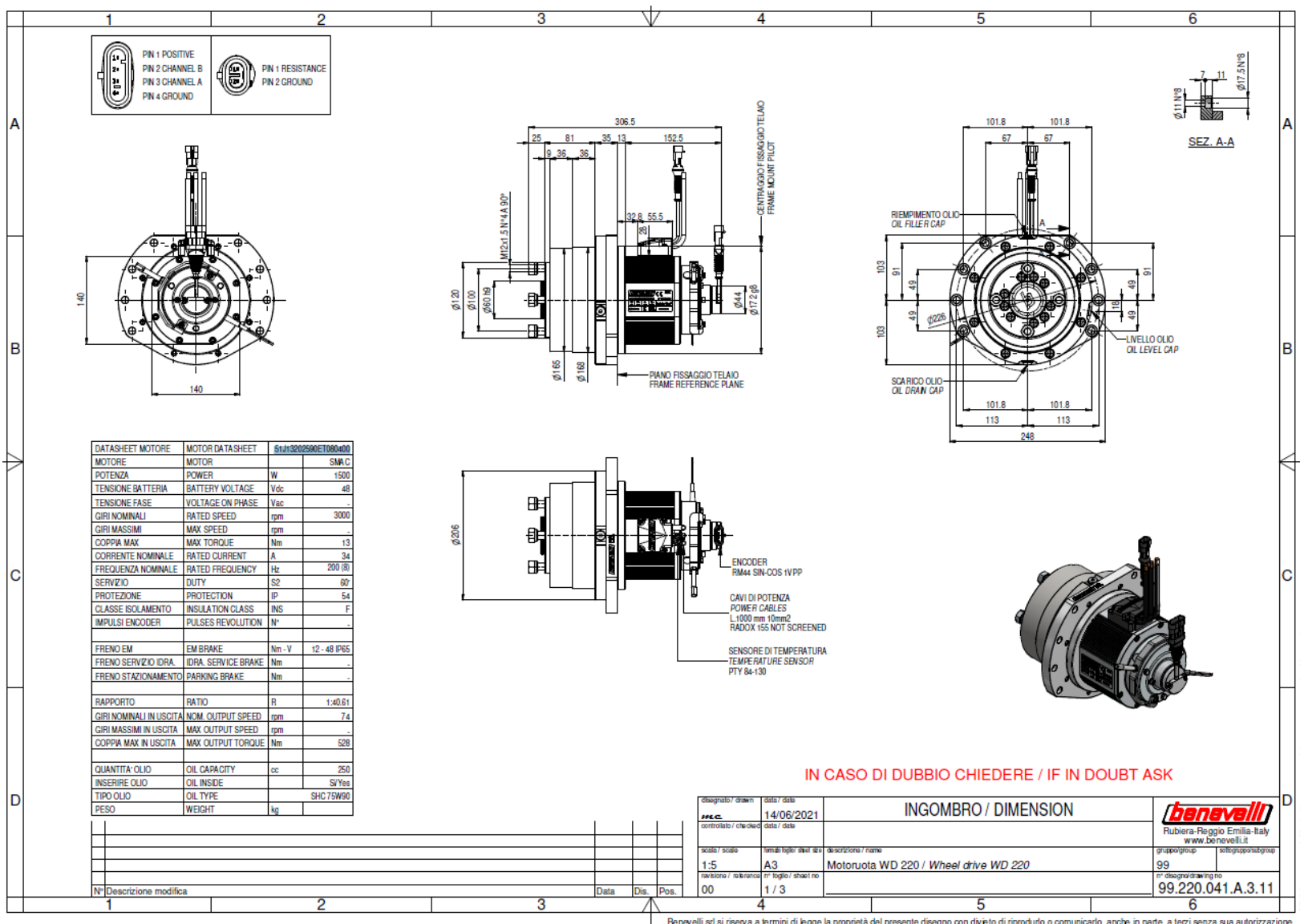
**Albright**      **Main contactor Ref. SU80-5242P 54V CO**


### SU80 Technical Information

Application	Rating ( $I_m$ )	
	Interrupted	Uninterrupted
Thermal Current Rating	150A	200A
Intermittent Current Rating:		
30% Duty	275A	365A
40% Duty	235A	315A
50% Duty	210A	285A
60% Duty	195A	260A
70% Duty	180A	240A
		
Rated Fault Current Breaking Capacity (Icn) 5ms Time Constant: <span>(In accordance with UL583*)</span>		
Blowouts	800A at 80V D.C.	
No Blowouts	800A at 48V D.C.	
Rated Fault Current Breaking Capacity (Icn) Resistive Load: <span>(In accordance with UL508*)</span>		
Blowouts	300A at 96V D.C.	
No Blowouts	300A at 60V D.C.	
Maximum Recommended Contact Voltages		
Blowouts	96V	96V
No Blowouts	48V	60V
Typical Voltage Drop per pole across New Contacts at 150A	40mV	
Mechanical Durability	> 3,000,000 Cycles	
Coil Voltage Available (Us) (Rectifier board required for A.C.)	6 - 240V	



SMAC132-025-90 48V 51J13202590ET080400 Type 1117 1500W 48V 34A S2 60' EM brake 12Nm 48V




	<b>SMAC SERIE</b> <b>TECHNICAL DATA SHEET</b> <b>3-PHASE SYNCHRONOUS MOTOR</b>			Code	51J13202590ET080400		
				Rev.	00		
				Date	17/03/2021		
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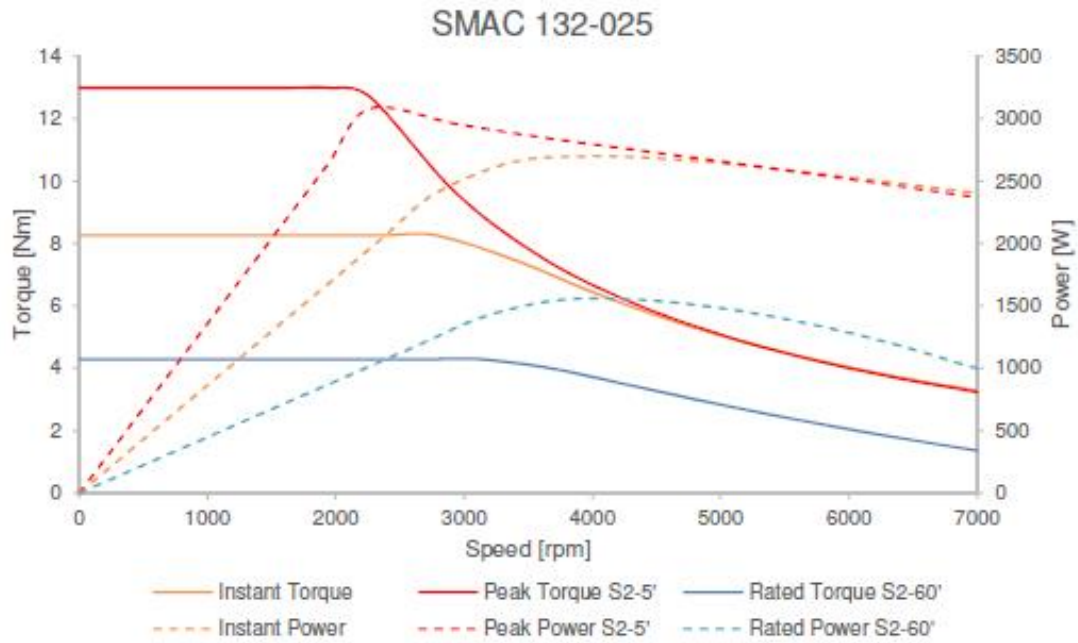
<b>Motor Rated Power</b>			<b>1500W</b>	
<b>Inverter Power Supply</b>			<b>48Vdc</b>	

Description		Symbol	Unit		
Duty		-	-	S2-60min	
Nominal Speed		$n_n$	rpm	3000	
Frequency (N° poles)		$f (2p)$	Hz	200.0 (8)	
Constant Voltage		$K_e$	Vrms/Krpm	8.5	
Constant Torque		$K_t$	Nm/Arms	0.14	
Instant Torque		$T_i$	Nm	13.0	
Instant Current		$I_i$	Arms	115.0	
Peak Torque		$T_p$	Nm	8.2	
Peak Current		$I_p$	Arms	68.0	
Rated Torque		$T_r$	Nm	4.3	
Rated Current		$I_r$	Arms	34.0	
Rotor Inertia		$J_r$	kg x m <sup>2</sup>	0.008	
Ambient Temperature		$\theta_a$	°C	-15 ÷ +40	
Protection Degree		IP		IP 54	up to IP67
Insulation Class		-	-	F	
Thermal protection		-	-	KTY 84-130	
Cooling system				Air	

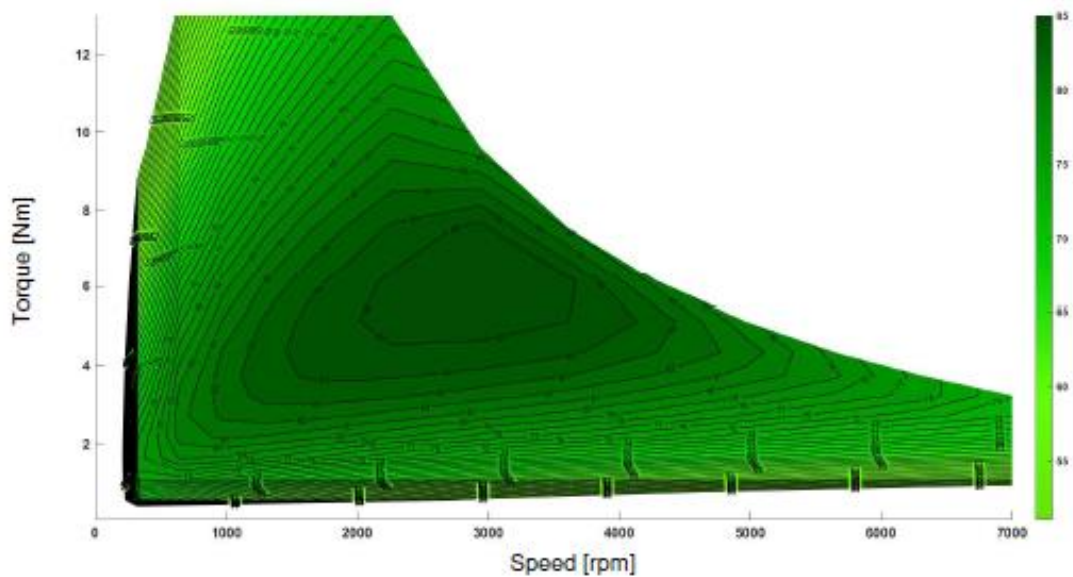
PRELIMINARY

	<b>SMAC SERIE</b>		Code	51J13202590ET080400
	<b>TECHNICAL DATA SHEET</b>		Rev.	00
	<b>3-PHASE SYNCHRONOUS MOTOR</b>		Date	17/03/2021
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Speed-Torque &amp; Speed Power Motor Curves (\*)




Efficiency Map % (\*)



\* MTPA Field Weakening strategy control & Optimized Advance Angle

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**0x200 + Node Id      CAN → Traction Controller**

	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7	Byte 8
	CAN_Motor_RPM_Request		CAN_Commands					
	L	H						
Format	Int 16							
Min/Max	-8000 / +8000 rpm							
	0xE0C0 / 0x1F40							

Speed Can be positive (Forward) or negative (Reverse).

**CAN\_Commands** Note:

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
						Reset	Interlock

**0x180 + Node Id      Traction Controller → CAN**

	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7	Byte 8
	Controller Temperature		Motor Temperature		Motor rpm		Motor Current RMS	
	L	H	L	H	L	H	L	H
Format	Int 16		Int 16		Int 16		Uint 16	
Min/Max	-100 / +300°C		-100 / +300°C		-12000 / +12000 rpm		0.0 / 1000.0 A	
	0xFC18 / 0xBB8		0xFC18 / 0xBB8		0xD120 / 0x2EE0		0 / 0x2710	

**0x280 + Node Id      Traction Controller → CAN**

Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7	Byte 8
Status 1	Status 2	Status 3	Status 4	Status 5	Status 6	Status 7	Status 8

If an error occurs in the Traction controller, we can identify it according to the following table:

<b>Status 1</b> Bit0 = Main Contactor Welded (Code 38) Bit1 = Main Contactor Did Not Close (Code 39) Bit2 = Pot Low OverCurrent (Code 45) Bit3 = Throttle Wiper Low (Code 42) Bit4 = Throttle Wiper High (Code 41) Bit5 = Pot2 Wiper Low (Code 44) Bit6 = Pot2 Wiper High (Code 43) Bit7 = EEPROM Failure (Code 46)	<b>Status 2</b> Bit0 = HPD/Sequencing Fault (Code 47) Bit1 = Severe B+ Undervoltage (Code 17) Bit2 = Severe B+ Overvoltage (Code 18) Bit3 = B+ Undervoltage Cutback (Code 23) Bit4 = B+ Overvoltage Cutback (Code 24) Bit5 = Sin/Cos Sensor Fault (Code 88) Bit6 = Controller Overtemp Cutback (Code 22) Bit7 = Controller Severe Undertemp (Code 15)
<b>Status 3</b> Bit0 = Controller Severe Overtemp (Code 16) Bit1 = Coill Driver Open/Short (Code 31) Bit2 = Coi12 Driver Open/Short (Code 32) Bit3 = Coil3 Driver Open/Short (Code 33) Bit4 = Coi14 Driver Open/Short (Code 34) Bit5 = PD Open/Short (Code 35) Bit6 = Main Open/Short (Code 31) Bit7 = EMBrake Open/Short (Code 32)	<b>Status 4</b> Bit0 = Precharge Failed (Code 14) Bit1 = Digital Out 6 Overcurrent (Code 26) Bit2 = Digital Out 7 Overcurrent (Code 27) Bit3 = Controller Overcurrent (Code 12) Bit4 = Current Sensor Fault (Code 13) Bit5 = Motor Temp Hot Cutback (Code 28) Bit6 = Parameter Change Fault (Code 49) Bit7 = Motor Open (Code 37)
<b>Status 5</b> Bit0 = External Supply Out of Range (Code 69) Bit1 = Motor Temp Sensor Fault (Code 29) Bit2 = VCL Run Time Error (Code 68) Bit3 = +5V Supply Failure (Code 25) Bit4 = OS General (Code 71) Bit5 = PDO Timeout (Code 72) Bit6 = Encoder Fault (Code 36) Bit7 = Stall Detected (Code 73)	<b>Status 6</b> Bit0 = Bad_Calibrations_Fault (Code 82) Bit1 = [Not Used] Bit2 = Emer Rev HPD (Code 47) Bit3 = [Not Used] Bit4 = Motor Type Fault (Code 89) Bit5 = Supervisor Fault (Code 77) Bit6 = Motor Characterization Fault (Code 87) Bit7 = [Not Used]
<b>Status 7</b> Bit0 = [Not Used] Bit1 = VCL/OS Mismatch (Code 91) Bit2 = EM Brake Failed to Set (Code 92) Bit3 = Encoder LOS (Limited Operating Strategy) (Code 93) Bit4 = Emer Rev Timeout (code 94) Bit5 = Dual Severe Fault (Code 75) Bit6 = Fault On Other Traction Controller (Code 74) Bit7 = Illegal Model Number (Code 98)	<b>Status 8</b> Bit0 = [Not Used] Bit1 = [Not Used] Bit2 = [Not Used] Bit3 = Parameter Mismatch (Code 99) Bit4 = Severe KSI Undervoltage (Code 17) Bit5 = [Not Used] Bit6 = [Not Used] Bit7 = Encoder Pulse Count Fault (Code 88)

Note: See also **User Fault 1 & Status 9** in next TxPDO (0x380 + Node Id).

**0x380 + Node Id      Traction Controller → CAN**

	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7	Byte 8
	Capacitor Voltage		Keyswitch Voltage		Status 9	User Fault 1		
	L	H	L	H	<div>See Note 1</div>	<div>See Note 2</div>		
Format	UInt 16		UInt 16					
Min/Max	0.0 / 200.0V		0.0 / 105.0V					
	0x0000 / 0x3200		0x0000 / 0x2904					

**Note1: Status 9**

Bit0 = Supervisor Incompatible (Code 78)

Bit1 = [Not Used]

Bit2 = [Not Used]

Bit3 = PMAC Commissioning Needed (Code 19)

Bit4 = [Not Used]

Bit5 = [Not Used]

Bit6 = Driver Supply (Code 83)

Bit7 = [Not Used]

**Note 2: User Fault 1:**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
							VCL Fault 1

VCL Fault 1 (code 51) PDO from ECU is Time out.

**0x700 + Node Id    NMT    Traction Controller****0x80 + Node Id    EMCY    Traction Controller**

Ver documento “NTJP20161130 EMCY en 123x.pdf” para la explotación de este Mensage.



