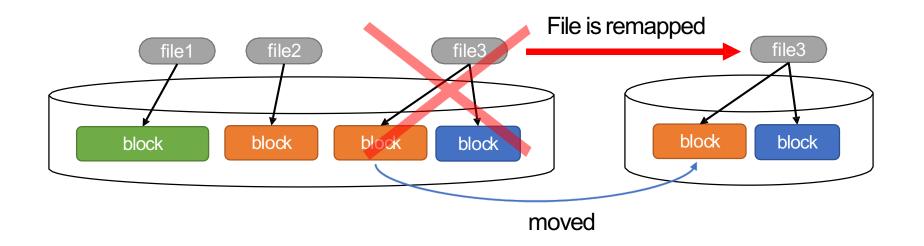
# GoSeed: Generating an Optimal Seeding Plan for Deduplicated Storage

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### Background

- **➤ Data Migration:**
- Moving data between volume
- Typically performed for load balancing and resizing
- >Seeding: Data migration with empty destination

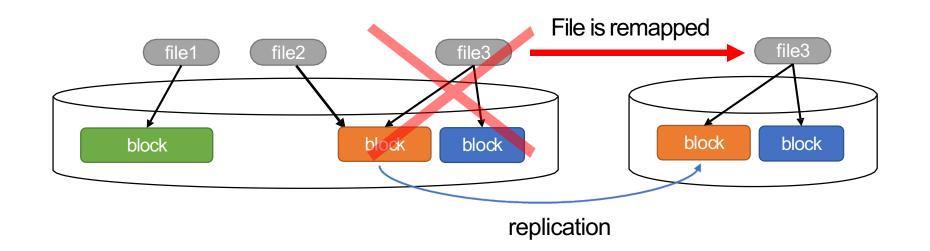


### Motivation

- > Deduplication complicates the migration:
- File remapped will cause replication.

#### **≻**Current status:

• Greedy algorithms for determining the set of migrated files, but the efficiency has never been systematically compared.



### Background: What is ILP

#### **≻**Satisfies

$$a_0x_0 + a_1x_1 + a_2x_3 + \dots + a_{n-1}x_{n-1} \le c$$
, where  $a_0, \dots, a_{n-1}, c \in \mathbb{Z}$ 

#### **≻**Maximizes

$$Tx = a_0x_0 + a_1x_1 + a_2x_3 + a_0x_0 + \dots + a_{n-1}x_{n-1}$$

### >How to combine data migration

c as the the migration amount, make  $a_0x_0 + a_1x_1 + a_2x_3 + a_0x_0 + \cdots + a_{n-1}x_{n-1}$  closest to c.

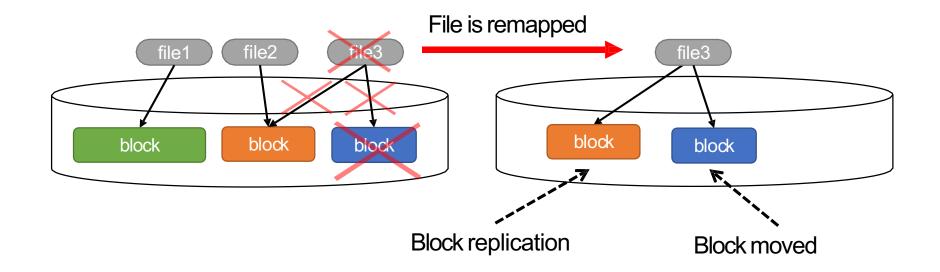
### Design: ILP combine data migration

- ➤ Migrate M% of physical occupancy
- $\triangleright$  Actually  $M \pm \epsilon$
- >R as the cost of the migration
- >m<sub>i</sub>: block i migrated (0/1)
- >r<sub>i</sub>: block i replicated (0/1)
- $> x_i$ : file i remmaped (0/1)
- >s : the size of the block
- $\succ$ M :  $\sum b_i \in B_{V_1} s(b_i) \cdot m_i = M$ , The total size of migrated blocks
- $\triangleright$ R :  $\sum b_i \in B_{V_1} s(b_i) \cdot r_i$

target: minimize R, closest M

### Constraint: blocks & file are always bound

- > Blocks are copied or moved with their files
- > Blocks cannot move without their files



### Design: ILP formulation

 $V_1$   $b_0$   $b_1$   $b_1$   $b_2$   $b_1$   $b_2$   $b_2$   $b_3$   $b_4$   $b_2$   $b_4$   $b_5$   $b_5$   $b_5$   $b_6$   $b_7$   $b_8$   $b_8$   $b_8$   $b_8$   $b_8$   $b_8$ 

- >m<sub>i</sub>: block i migrated (0/1)
- $> x_i$ : file i remmaped (0/1)
- >s : the size of the block
- $ightharpoonup M: \sum b_i \in B_{V_1} s(b_i) \cdot m_i = M,$ The total size of migrated blocks
- $\triangleright$ R :  $\sum b_i \in B_{V_1} s(b_i) \cdot r_i$

target: minimize R, closest M

- Block  $b_2$  is migrated:  $m_2 = 1$
- · File  $f_2$  is remapped:  $x_2 = 1$
- Block  $b_1$  is replicated:  $r_1 = 1$
- · The remaining files and blocks are untouched:

$$x_0 = x_1 = m_0 = m_1 = r_0 = r_2 = 0$$

• The total cost is  $R = 3 \cdot r_1 = 3$ 

# Theory vs. Practice

- ➤ Dedup: ~10 logical TB ⇒ ~billion variables and constraints
- > ILP Solvers: Solvers are efficient with several 100K

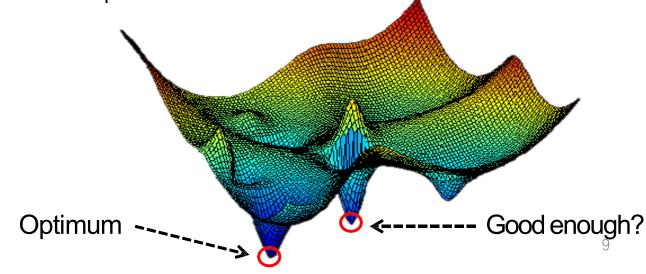
### Method I: Solver timeout

#### Limited the runtime of ILP solver

- Specifying a timeout value
- > Return the best feasible solution found thus far

#### Problem:

When the solver is timed out, we cannot necessarily tell how far the suboptimal solution is from the optimal one.



# Method II: fingerprint sampling

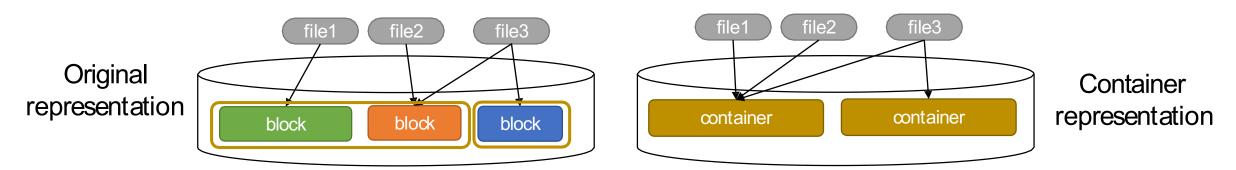
- > Sample a subset of the fingerprints [Harnik et al. FAST19]
- > Sample degree k: each sample  $\frac{1}{.2^k}$  of the blocks

#### Problem:

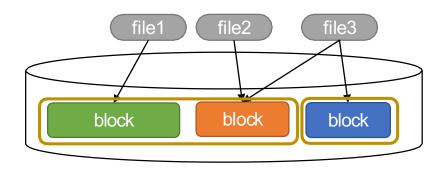
- > Smaller sample
- ⇒ a larger ILP instance
- ⇒ more accurately represents the sampled system
- ⇒ more likely to time out

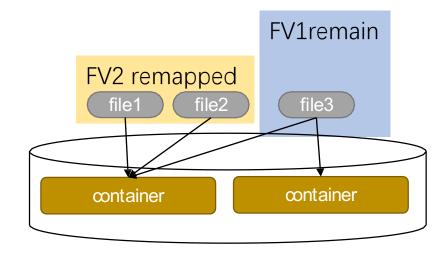
# Method III: container-based aggregation

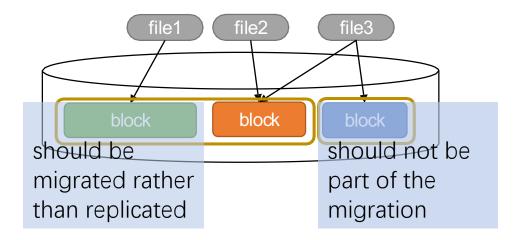
- Deduplication system stores blocks in containers
- We treat each container as a block
- use only the container IDs for generating the variables and constraints.
- +smaller ILP problem
- +no need to decompress/unpack containers
- -false positives

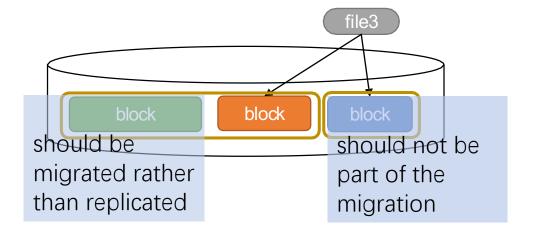


### -false positives









# Experimental setup

- We compare:
- GoSeed: our ILP-based approach
- Rangoli [Nagesh & Kathpal Systor'13]:
  - Sort & divide the blocks into bins
  - Migrate the "best" bin
- SGreedy [Harnik et al. FAST19]:
  - Iterative method
  - Each iteration remap the "best"
     file

	UBC 500	Homes	MacOS -day
Logical size	19.5TB	8.9TB	43TB
Dedup ratio	0.31	0.13	0.01

### Cost

- Rangoli **SGreedy**
- SGreedy (k=12)
- GoSeed (k=12)

MacOS-Day consists daily backups

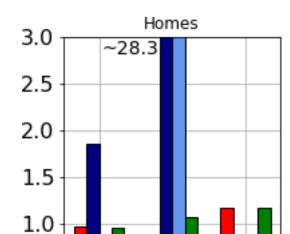
- UBC-500 is considered "easy"
- - Low dedup UBC-500 Cost (% replicated) 33 20

M (%)

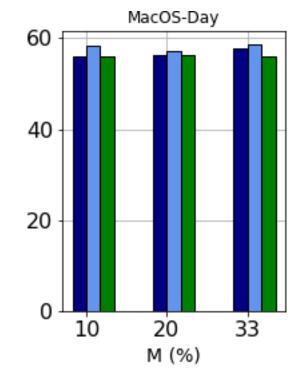
Homes is harder



High dedup







> GoSeed always finds a solution, it's often the best

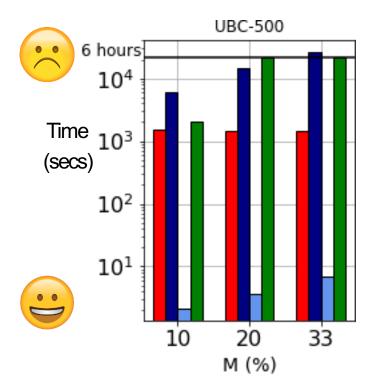
0.5

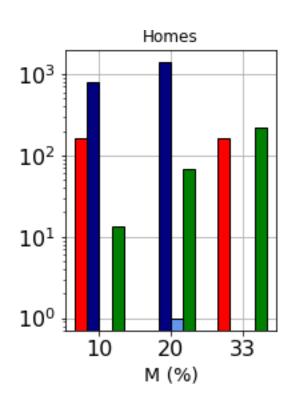
> Greedy algorithms sometimes fail to find a solution

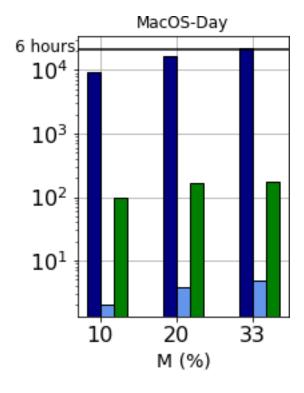
20

M (%)

# Rangoli SGreedy (k=12) SGreedy GoSeed (k=12)



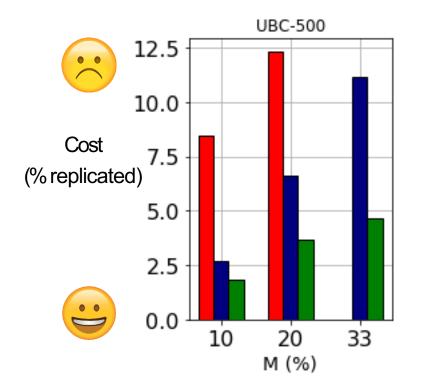


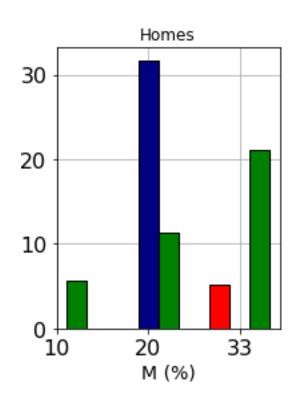


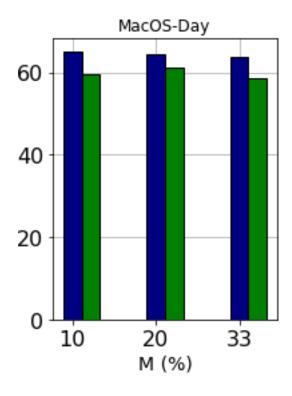
> Runtimes and resources are acceptable.

### Container cost



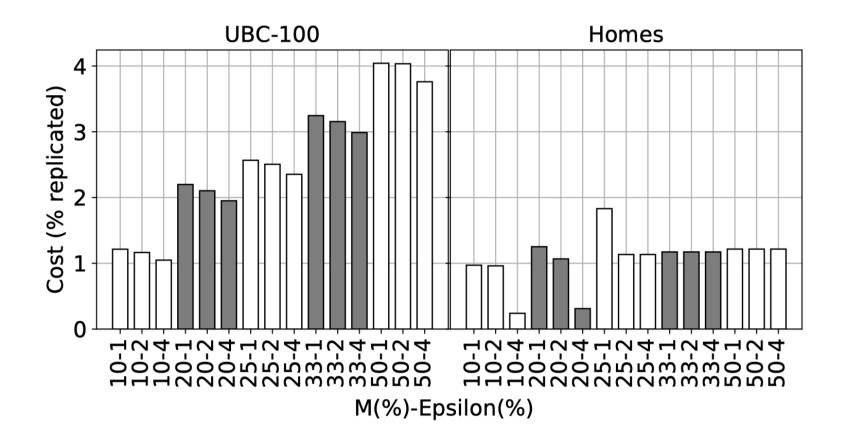






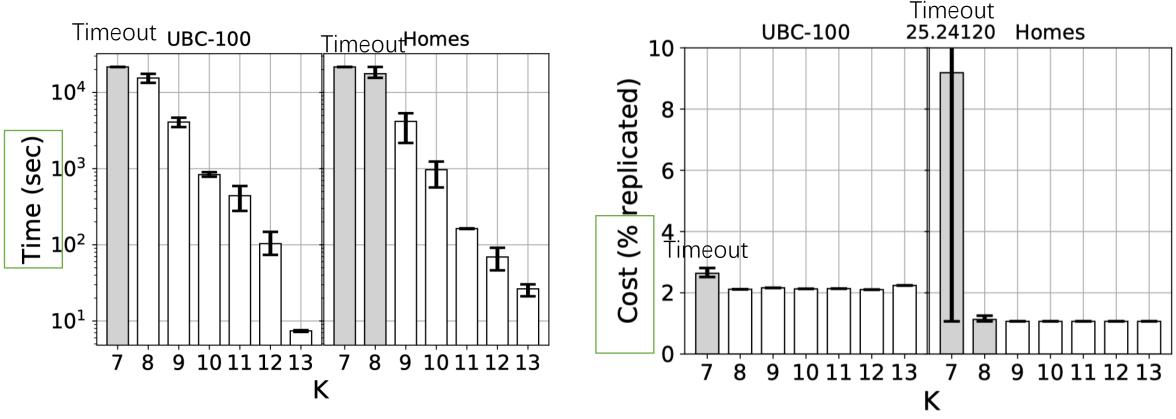
> GoSeed always gives a solution, almost always better

# ILP parameter M-Epsilon Evalution



 $\triangleright$  The increase of M leads to higher cost, and the increase of  $\epsilon$  leads to the decrease of cost

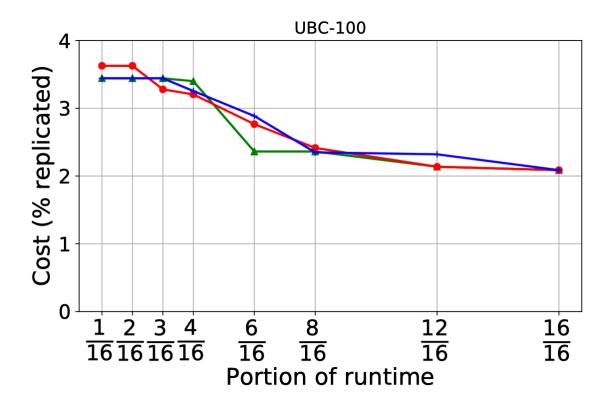
# Effect of fingerprint sampling



- ➤ Solving time increases exponentially with instance size
  - ➤ Cost is hardly affected by the sampling degree, unless the instance becomes too large. 18

## Suboptimal solution

-Solve Timeout



Migration cost decreases when timeout increases

### Conclusions

- Formulate of data migration as an ILP problem and solve it with ILP solvers
- Use three acceleration methods and they are essential and effective
- GoSeed often outperforms greedy approaches, and always find a feasible solution to the problem.
- The container-based approach is separate from the sample-based approach, applicable to different deduplication systems