

# Generic IDL: Parametric Polymorphism for Software Component Architectures

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# Motivation:

- ➊ Multilanguage Architectures

- components are developed independently, and then combined to construct applications
  - have lagged behind in exposing new language ideas

- ➋ Our Goals

- extend Software Component Architectures, making them competitive for multi-language programming using modern language constructs efficiently
  - assisted interface generation for generic libraries
  - explore optimizations in multi-language environments
  - optimizations of deeply composed generics

# Parametric Polymorphism

- one mechanism to support generic programming
- increases the flexibility, reusability, expressive power, avoids the need for down-casting, and ensures type inference termination in some higher order lang.
- various semantics in different prog. lang.  
(C++, Modula, GJ, Ada, ML, Aldor)
- a general mechanism should accommodate both:  
compile and run time type instantiation  
qualified/free type variables

# Multilanguage Environments

- Extern C
- Java Native Interface
- CORBA
- DCOM
- .NET
- Parametric Polymorphism has become a common feature of mainstream programming languages, but SCAs have not as yet exposed it

# Early Experiment: FRISCO project (1997)

- Objective: allow Aldor programs to make use of the PoSSo library (heavy use of C++ templates)
- Aldor: strongly typed functional language, with a higher order type system:
  - each value belongs to some unique type: its domain;
  - domains can be created at run time by user defined functions
  - domains belong to type categories (can be statically determined)
  - explicit p.p. through dependent types

vs.

# Early Experiment (conclusions)

- ➊ Through clever use of virtual functions, we were able to:
  - produce proper binding time semantics by prototypic instantiation of templates
  - produce lightweight proxies to make hierarchies available on either side of the language interface

- ➋ Conclusions:
  - the C++/Aldor semantics gap can be overcome  
(objects vs. type-categories and compile vs. run time bindings for generics)
  - a general, well defined semantics for p.p. can be constructed  
(for which C++/Aldor mappings are particular solutions)
  - need a systematic solution that encompasses more languages  
***GIDL***

# Introduction to GIDL

- mappings to C++, GJ, Aldor

- type variables may be qualified:

  - extend based qualification      T : B

  - export based qualification      T :- B

```
interface Foo { void foo(); };  
interface Foo_extend : Foo {};  
interface Foo_impl { void foo(); }; // not in an isA relation with Foo
```

```
interface Test<T1 : Foo, T2 :- Foo> { void print(T a); };  
interface Main {  
    Test< Foo_extend, Foo_extend > op1(); //OK  
    Test< Foo_extend, Foo_impl > op2(); //OK  
    Test< Foo_impl,   Foo_impl  > op3(); //Error  
};
```

# GIDL' s model for generics

- allows generic type qualifications
  - generic type has a well defined meaning (context independent)
  - precise, easily extensible GIDL specifications
- natural mappings to common prog. langs. within a small overhead cost
- homogeneous implementation approach, based on a type-erasure technique
  - preserves backward compatibility
  - works on top of any CORBA vendor implementation

# Type Checking

- generic types are attached to GIDL interfaces
- the visibility scope is throughout the defining interface
- sub-typing is defined to be invariant with respect to the type variables
  - $\text{List}\langle S \rangle \not\subset \text{List}\langle T \rangle$ , even if  $S \subset T$  guarantees type checking termination for mutual recursive generic type bounds
- the extend qualification is stronger than the export one:

```
interface Test0<C:Type1> {..};  
interface Test1<A:-Type1>  
  : Test0<A>{..}; //Error
```

# Type Checking Example

```
interface Comp<A> {  
    boolean compare(in A a);  
};
```

```
interface Double : Comp<Float> {...};  
interface Float : Comp<Double> {...};
```

```
interface Comparator<A: Comp<B>, B : Comp<A>> {  
    Comparator<Comp<B>, Comp<A>> op3(); /** Error  
    Comparator<Double, Float> op4(); /* OK  
}
```

**//\*\* Comp<B> should extend Comp<Comp<A>>**  
**// (False since then B==Comp<A>)**  
**/\* Double extends Comp<Float> by def., so true**

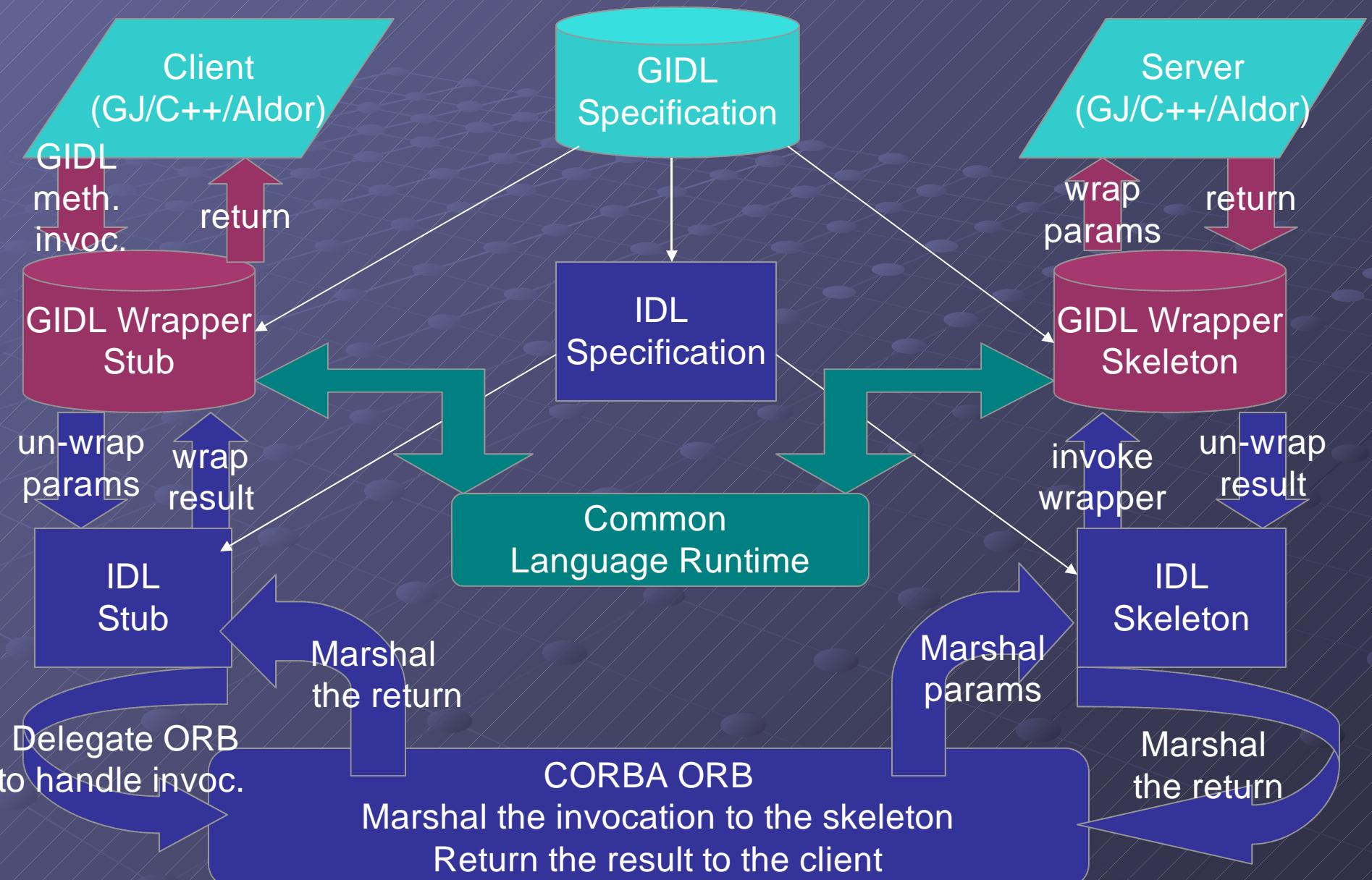
# GIDL translator output

- erasure technique: GIDL => IDL
  - preserves the backward compatibility
  - translator works on top of any CORBA implementation
  - can generate proxies (extern C/JNI/..) and link them in a single process environment
  - opportunities for cross file, inter-language optimizations
- recover the lost generic type information at the mapped language skeleton/stub wrapper level

```
//GIDL
interface Test<T,
P:ExtQual, Q:-ExpQual> {
    T op1();
    P op2();
    Q op3(Test<T,P,Q> a);
};
```

```
//IDL
interface Test {
    any op1();
    ExtQual op2();
    Object op3(Test a);
};
```

# GIDL Base Application Architecture



# Using the Architecture

- Server side: inherits and implements the GIDL skeleton wrappers
- Most of the implementation details are hidden
- Now client/server may use generic programming as desired

```
// GIDL Specification
interface GPriorElem<A:-GPriorElem<A>>
{
    short getPriority();
    short compareTo(in A r);
    A createNewA(in short s);
};

interface PriorElem :
    GPriorElem<PriorElem>{};

interface PriorQueue<A:-GPriorElem<A>>
{
    void enqueue(in A a); A dequeue();
    boolean empty();      short size();
    A createPriorElem(in short s);
};
```

```
// code excerpt from a C++ CLIENT
1. CORBA::Object_var obj = orb->string_to_object
   (s);
2. GIDL::PriorQueue<GIDL::PriorElem> gpq
   (pq_orig);
3. GIDL::PriorElem gPEobj = gpq.createPriorElem
   (GIDL::Short_GIDL(1));
4. gpq.enqueue(gPEobj);
//Obtain a reference to a CORBA::Object – obj
5. gpq.enqueue(obj); //ERROR
6. gPEobj = gpq.dequeue();
7. GIDL::Short_GIDL sh = gPEobj.getPriority();
8. cout<<sh<<endl; //prints “ 1”
```

# GIDL to C++ Mapping

- follows closely CORBA-C++ mapping ideas: scopes  
scopes, modules namespaces, interfaces (generic)  
classes
- C++ wrappers (erased) CORBA reference  
+ associated generic type inf. + two way casting +  
functionality
- export/extend base qualification mapping introduce no  
run-time overhead  
their implementation relies on C++' s static binding time

# GIDL to C++ Mapping Example

```
// GIDL specification!!!
interface Foo { /*...*/ };
interface Test<T1:Foo, T2:-Foo, T3>
{ Foo op(in T1 t1, in T2 t2, in T3 t3, in Foo f); };
```

```
template<class T1, class T2, class T3> class
Test : virtual public ::GIDL::GIDL_Object {
protected: ::Test_var* obj;
private:
virtual void implTestFunction() {
if(1) return;
T2 a_T2; T1 a_T1; Foo f = (Foo)a_T1;
GIDL::String_GIDL t=a_T2.tostring();
}
public: Test(::Test_var ob) {
obj = new ::Test_var(ob); implTestFunction();
}
static ::Test_var _narrow(Test<T1, T2, T3> o) {...}
static Test<T1, T2, T3> _lift(CORBA::Object_var o) { ...}
static Test<T1, T2, T3> _any_lift(CORBA::Any_var a) { ...}
static CORBA::Any_var _any_narrow(Test<T1,T2,T3> w){...}
```

```
virtual GIDL::Foo op(T1 a1, T2 a2,
T3 a3, GIDL::Foo a4) {
::Foo_var a = a1._narrow(a1);
CORBA::Object_var b=
a2._narrow(a2);
CORBA::Any_var c=
a3._any_narrow(a3);
::Foo_var d = a4._narrow(a4);
::Foo_var a0=(*obj)->op(a, b, c, d)
GIDL::Foo ret; return ret._lift(a0);
}
}
```

# GIDL to GJ Mapping

- same main ideas as the C++ mapping
- user's help is required, as GJ does not support:
  - generic type object instantiation,
  - reflective features for the generic types
- new scopes GJ packages
- GIDL's implicit parametric structures generic classes

```
// GIDL specification
interface Base<C:Object, D, E> {
    typedef struct BaseStruct {
        C field_C;
        E field_E;
    };
}
```

```
package GIDL.Base; import GIDL.*;
public final class BaseStruct
<C extends GIDL_Object, E extends GIDL_Value>
implements GIDL_Value {
    private C c; private E e;
    private org.omg.CORBA.Object obj;
    public BaseStruct(C c, E e,
        org.omg.CORBA.Object ob){
        this.c=c; this.e=e; this.obj=ob;
    } /* ... */};
```

# Export Qualification Mapping

## Most General Generic Unifier (MGGU)

- <A:-Type> compute the MGGU for A,  
w.r.t. all the types in the specification
  - use unification algo. to minimize the # of generic types  
and the # of MGGUs
  - preserve the inheritance hierarchy among MGGUs

```
IDL interface Tp1<A:-Tp1<A>> {..}; // A MGGU1  
interface Tp2<B:-Tp2<B>>:Tp1<B> {..}; // B MGGU2
```

```
interface MGGU2<T> extends MGGU1<T> {...};
```

# MGGU (continuation)

{ GIDL

```
interface Element { tp0 op(in tp1 a, in tp2 b); };
interface GenEl1<T,P> { P op(in T a, in tp2 b); };
interface GenEl2<T,P> { tp0 op(in P a, in T b); };
interface Test<A:-Element> { /* use A */ };
```



{ GJ

```
interface MGGU<T,P,Q> { T op(in P a, in Q b); }

interface Element extends MGGU<tp0, tp1, tp2>{...}
interface GenEl1<T,P> extends MGGU<P, T, tp2>{...}
interface GenEl2<T,P> extends MGGU<tp0, P, T >{...}

interface Test<A implements MGGU<tp0, tp1, tp2>> {...}
```

# Semi-Automatic STL Translation

- Library interface   GIDL specification   stub/  
skeleton + implementation  
(STL == black box    $TAT^{-1}$  scheme is applied).
- STL:
  - 6 components: containers, generic algorithms, iterators, function objects, adaptors, allocators
  - orthogonal components   by using iterators (abstract data accessing methods)
    - each container/algorithm provides/requires certain iterator' s categories – specified in English; we can do better with GIDL

# Translation design

- enforces component orthogonality at the lang. level
- iterators/containers design is non-intrusive (do not assume any inheritance relation)

```
interface InputIterator<T, It:-Iterators::InputIterator<T, It>> {..};
```

```
interface STLvector<T, Ite:-Iterators::RandAccessIterator<T,  
Ite>,  
II:-Iterators::InputIterator<T,II> >{..};
```

```
interface InPIterator<T> : InputIterator<T, InPIterator<T>> {..};
```

# Difficulties in Translating STL

- STL call by value; GIDL-STL application level call by reference

Provide *clone()* and *destroy()* methods for GIDL-STL objects (create/destroy CORBA objects).

Big overhead when using iterators (since they are just supposed to be pointers)

- Optimization is needed!!!

```
//STL internal implementation
interface FindAlg<T, It:-InputIterator<T,It>>
{ It find(in It first, in It last, in T val); }
```

```
//C++ STL implementation for find:
while(first<last) {
    //.....
    first++;
}
```

# Multi-Language Environment Optimizations

- We have covered the declarative aspect:  
way of having software typed in one program
- Ultimate goal: optimization of modules with p.p. in a  
multi-language environment
  - Inter-procedural, inter-file optimizations between programs in  
different languages (inlining, ..., etc.)
  - Macroscopic optimization: speculative(optimistic) / semantic driven  
optimizations (eg: library translation)

# Conclusions:

- Exposed parametric polymorphism to software component architectures
- Qualification of type parameters can be enforced in various target languages, and come with small overhead penalty
- Semi-automatic generic library translation
- Opportunity for inter-language optimizations