# Data Structures Heaps

Andres Mendez-Vazquez

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#### Outline

- Heaps
  - Definitions
  - Finding Parents and Children
  - Max-Heapify
  - Build Max Heap: Using Max-Heapify

- 2 Applications of Heap Data Structure
  - Heap Sort
  - Priority Queues



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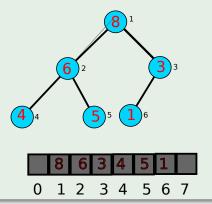
- 2 Applications of Heap Data Structure
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## Definition of a Heap

#### Definition

A heap is an array object that can be viewed as a nearly complete binary tree.



## Heap: Basic Attributes

## Given an array A, we have that length[A]

It is the size of the storing array.



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#### Thus, we have

$$0 \leq heap - size[A] \leq length[A]$$



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# Finding Parent and Children given a Node i in the heap

### Parent(i) - Parent Node

$$Parent(i) = \lfloor \frac{i}{2} \rfloor$$

Left(i) = 2i

Right Node Child:

Right(i) = 2i + 1



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## Right Node Child: Right(i)

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## Heap's Properties

#### Given that

A[i] returns the value of the key, we have that



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 $A[Parent(i)] \ge A[i]$ 



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#### Max heap property

 $A[Parent(i)] \ge A[i]$ 

#### Min heap property

 $A[Parent(i)] \le A[i]$ 

## The ADT Heap

```
Interface
public interface MaxHeapInterface<T extends Comparable<? super {
   public void add(T newEntry);
   public T removeMax();
   public T getMax();
   public boolean isEmpty();
   public int getSize();
   public void clear();
} // end MaxHeapInterface</pre>
```



## What is "?"?

#### This is coming from the idea of wildcards

For example if we have:

• void printCollection(Collection<Object> c) { for (Object e : c) { System.out.println(e); } }

We do not have a generic Collection!!!



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#### This is coming from the idea of wildcards

For example if we have:

• void printCollection(Collection<Object> c) { for (Object e : c) { System.out.println(e); } }

We do not have a generic Collection!!!

#### So we write Collection<?>

Collection of unknowns...



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#### What we want!!!

#### A function to keep the property of max or min heap

After all, remembering Kolmogorov, we are acting in a part of the array trying to keep certain properties

• Which ONE?



#### What we want!!!

#### A function to keep the property of max or min heap

After all, remembering Kolmogorov, we are acting in a part of the array trying to keep certain properties

Which ONE?

#### Important

Single nodes are always min heaps or max heaps



## Max-Heapify

Algorithm (preserving the heap property) when somebody violates the max/min property

#### Max-Heapify(A, i)

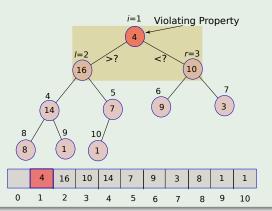
- r = Right(i)
- a largest = l
- $\bullet \ \, \text{If} \,\, r \leq heap-size\,[A] \,\, \text{and} \,\, A\,[r] > A\,[largest]$
- largest = r
- exchange A[i] with A[largest]
- $\bullet$  Max-Heapify(A, largest)

# Example keeping the heap property starting at i=1

#### Here, you could imagine that somebody inserted a node at i=1

- 3. If  $l \leq heap size[A]$  and A[l] > A[i]
- largest = l

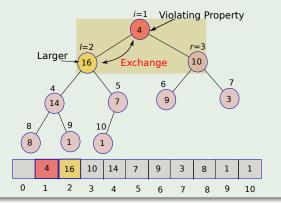
- largest = r

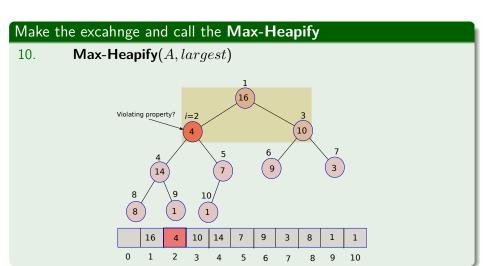


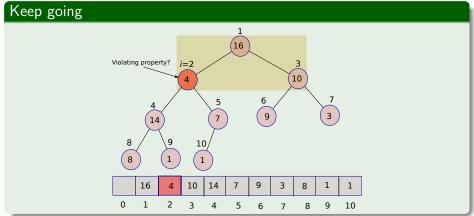
# Example keeping the heap property starting at i=1

## One of the children is chosen to be exchanged

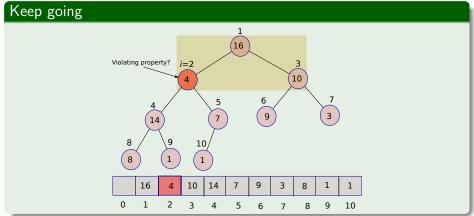
- 8. if  $largest \neq i$
- 9. exchange A[i] with A[largest]



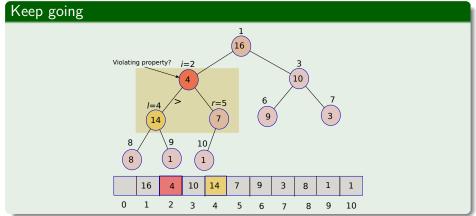




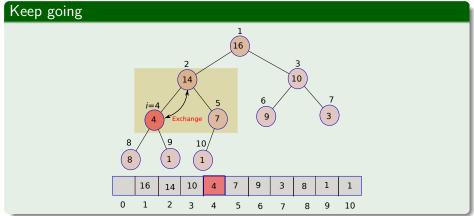




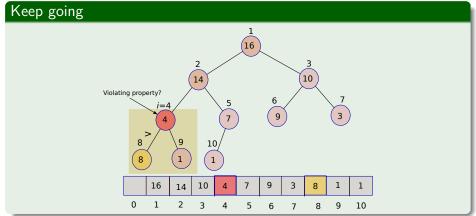




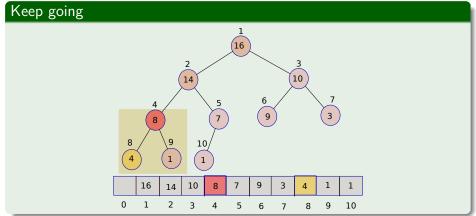














## Complexity of Max-Heapify

## Algorithm Complexity

 $O(\log n)$ .



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# Example: Using Max-Heapify

## Algorithm Build-Max-Heap

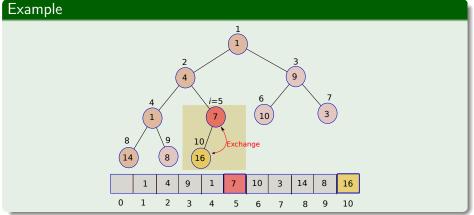
Build-Max-Heap(A, i)

- 2 for i = |length[A]/2| downto 1
- $\bullet$  Max-Heapify(A, i)

Figure: Building a Heap

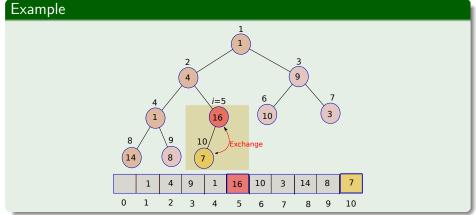


# Build Max Heap: Using Max-Heapify



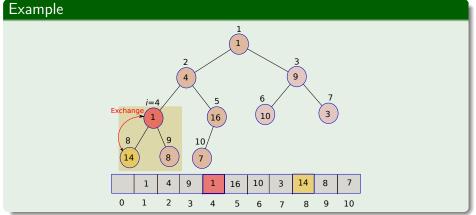


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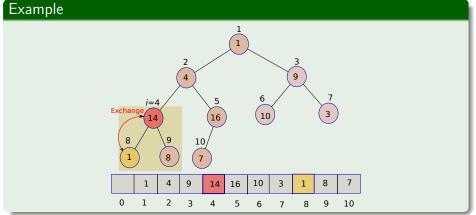




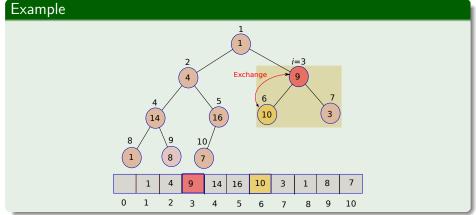
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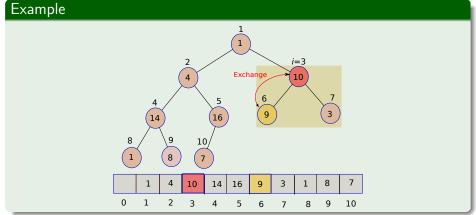




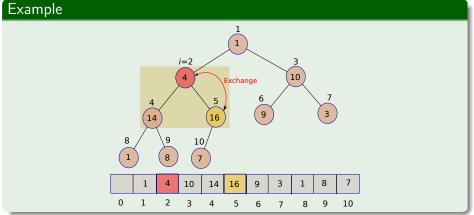




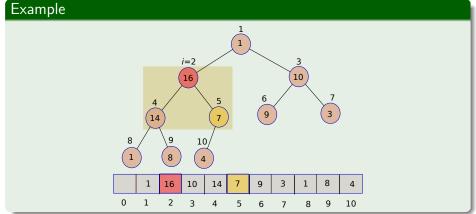




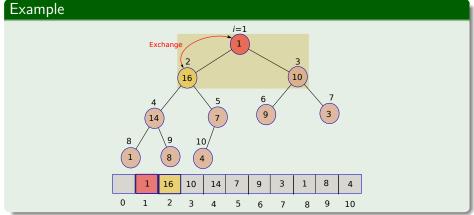




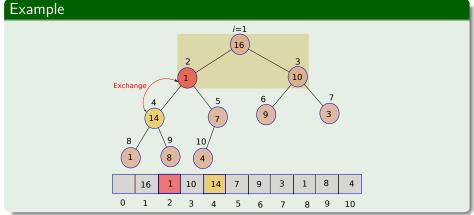




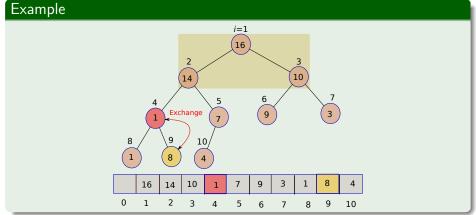




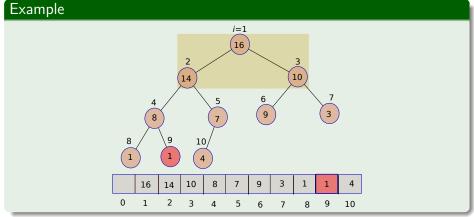










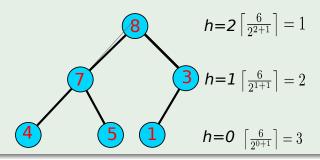




# Height h of the Heap for Complexity of Build-Max-Heap

#### We can use the height of a three to derive a tight bound

- ullet The height h is the number of edges on the longest simple downward path from the node to a leaf.
- You have at most  $\left\lceil \frac{n}{2^{h+1}} \right\rceil$  nodes at any height, where n is the total number of nodes.



# Cost of Building the Build-Max-Heap

### Cost

O(n)



## Applications of Heap Data Structure

### Heap Sort of Arrays

Clearly, if the list of numbers is stored in an array!!!

- Priority Queue
- Here, Heaps can be modified to support insert(), delete() and extractmax(),
- decreasekey() operations in O(logn) time

#### This has direct application

- Bandwidth management:
  - Many modern protocols for Local Area Networks include the concept of Priority Queues at the Media Access Control (MAC).
- Object Event Simulations
- Schedulers
- Muffman coding
- The Real-time Optimally Adapting Meshes (ROAM)
  - It computes a dynamically changing triangulation of a terrain using two priority queues

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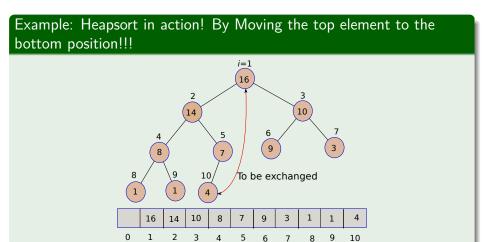
### Heapsort Algorithm

#### Heapsort(A)

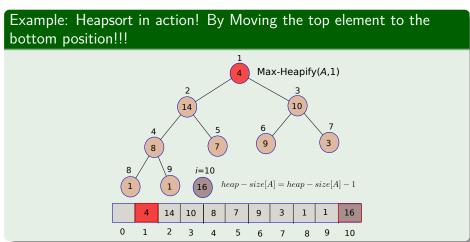
- $\bullet$  Build-Max-Heap(A)
- ② for i = length[A] downto 2
- $oldsymbol{3}$  exchange A[1] with A[i]
- $\bullet heap size[A] = heap size[A] 1$
- $\bullet$  Max-Heapify(A, 1)

Figure: Heapsort

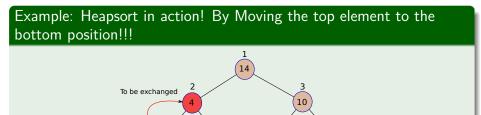


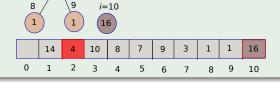




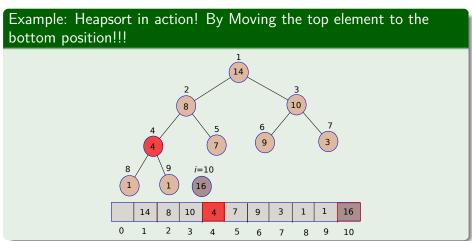




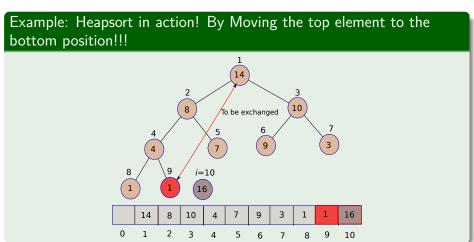




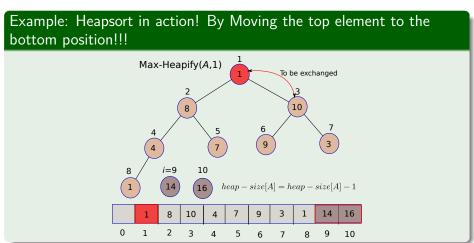




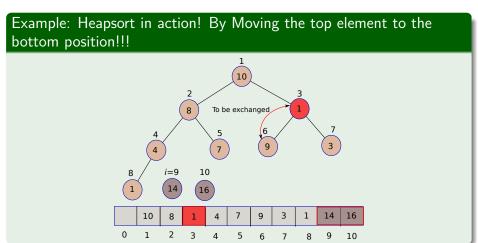




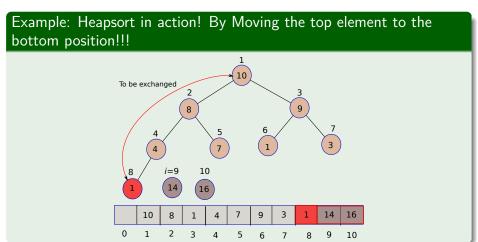




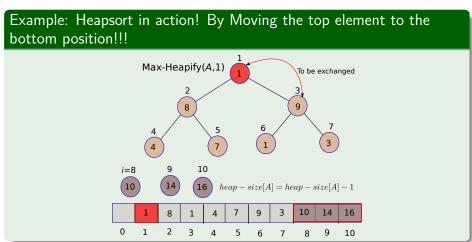




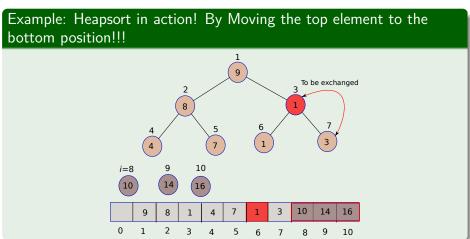




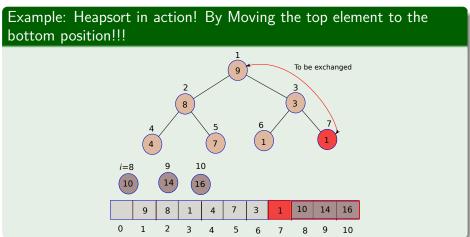




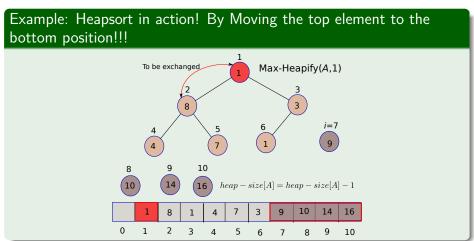




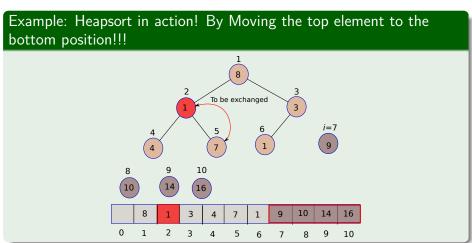




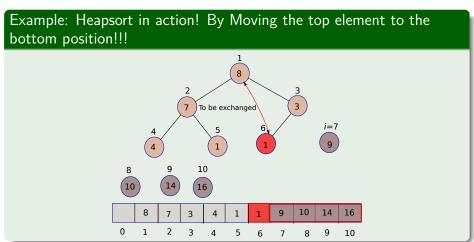




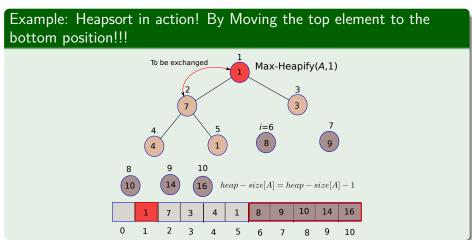




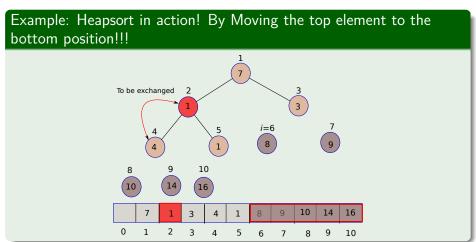




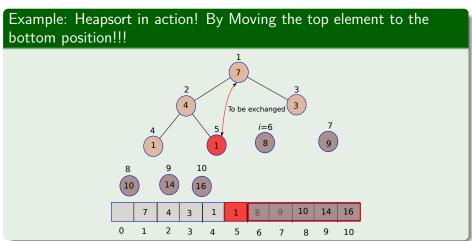




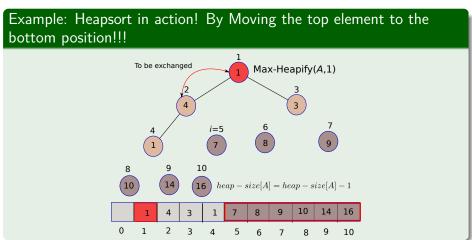




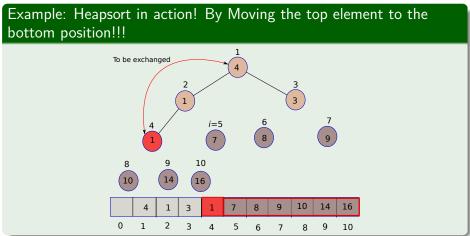




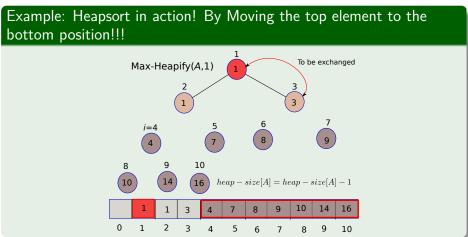




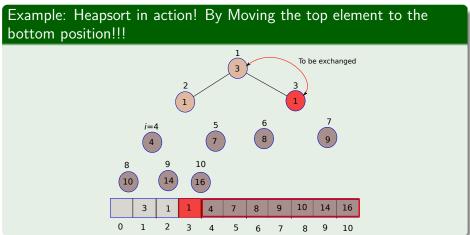




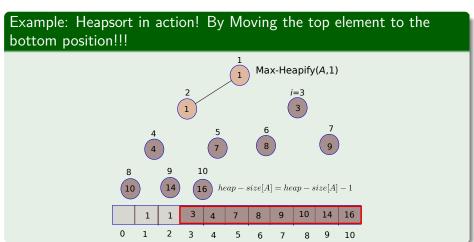




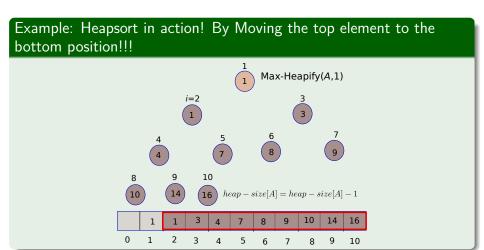




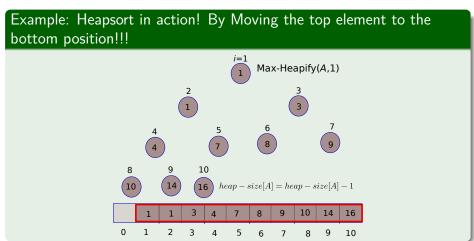














# Cost of the Heapsort

# Cost

 $O(n \log n)$ 



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## **Basic Concepts**

#### Definition

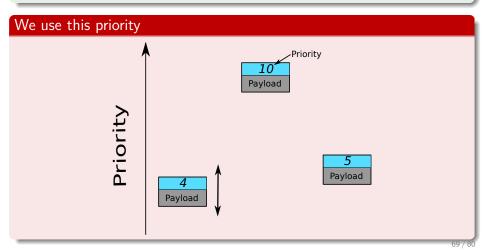
A priority queue is an abstract data type which is like a regular queue or stack data structure, but where additionally each element has a "priority" associated with it.



## **Basic Concepts**

#### Definition

A priority queue is an abstract data type which is like a regular queue or stack data structure, but where additionally each element has a "priority" associated with it.



# Clearly, you could sort the elements by priorities

# Cost of that $O\left(n\log n\right) \tag{2}$

After all that is what we do when designing data structures



# Clearly, you could sort the elements by priorities

#### Cost of that

 $O(n\log n)$ 

(2)

#### We want something better!!!

After all that is what we do when designing data structures



# First, the ADT of a Max Priority Queue

```
ADT of a Max Priority Queue
public interface MaxHeapInterface<T extends Comparable<? super 7
  public void Insert(T newEntry);
  public T Maximum();
  public T Extract-Max();
  public void Increase - Key(T, key)
  public boolean isEmpty();
  public int size();
```



# Thus, we need to look at the implementations

## First, insertion

public void Insert(T newEntry);

First, what do we do?

Where is the best place to put the new key?



# Thus, we need to look at the implementations

#### First, insertion

public void Insert(T newEntry);

#### First, What do we do?

See if you have enough space in the array!!!

Where is the best place to put the new key?



# Thus, we need to look at the implementations

#### First, insertion

public void Insert(T newEntry);

#### First, What do we do?

See if you have enough space in the array!!!

#### Second

Where is the best place to put the new key?



## What to do?



What about the following... when we draw the Heap!!!



## What to do?



#### Ideas?

What about the following... when we draw the Heap!!!



## Yes

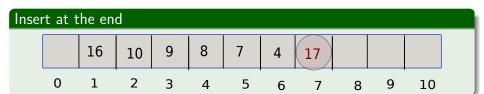


- Thus we need to move this up!
- lacksquare while i>1 and  $Heap\left[Parent\left(i
  ight)
  ight] < Heap\left[i
  ight]$
- exchange Heap[i] with Heap[Parent(i)]

Heap.heap - size = Heap.heap - size + 1



## Yes



## Thus we need to move this up!!!

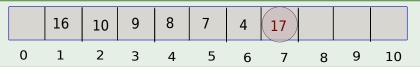
- $\textbf{ 0} \ \ \text{while} \ i > 1 \ \text{and} \ Heap\left[Parent\left(i\right)\right] < Heap\left[i\right]$
- $\textbf{exchange} \,\, Heap \left[ i \right] \, \text{with} \,\, Heap \left[ Parent \left( i \right) \right]$
- i = Parent(i)

Heap.heap - size = Heap.heap - size + 1



## Yes





## Thus we need to move this up!!!

- $\textbf{ 0} \ \ \text{while} \ i > 1 \ \text{and} \ Heap\left[Parent\left(i\right)\right] < Heap\left[i\right]$
- $\textbf{ exchange } Heap\left[i\right] \text{ with } Heap\left[Parent\left(i\right)\right]$
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#### In addition

Heap.heap - size = Heap.heap - size + 1

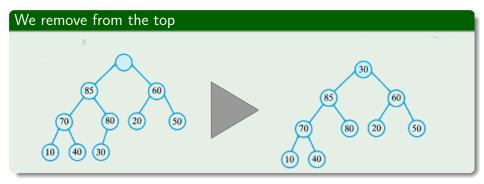


#### The Pseudo-Code

#### Insertion

```
Insertion_Max(newEntry){
 if (the array heap is full)
     Double the size of the array
 newIndex = Heap.heap-size + 1
 parentIndex = Parent(newIndex)
  while (parentIndex > 1 and newEntry > heap[parentIndex])
      heap[newIndex] = heap[parentIndex]
      newIndex = parentIndex
      parentIndex = Parent(newIndex)
  heap[newIndex] = newEntry
```

## What about Extract-Max





## Here, we can use Max-Heapify

To trickle down as the Max-Heap property is not working

Using the previous code...



### Pseudocode

# Extract-Max()

- if Heap.heap size < 1
- error "heap underflow"
- $\bullet$  max = Heap[1]
- $\bullet \ Heap[1] = Heap[Heap.heap size]$
- $\bullet Heap.heap size = Heap.heap size 1$
- Max-Heapify(1)
- return max



# What about Heap-Increase-Key?

#### Here, a design issue

- In a Max Priority Queue you can only increase keys
- In a Min Priority Queue you can only decrease keys



#### Then

#### Pseudo-Code

Increase-key(i, key)

- if key < Heap[i]
- error "new key is smaller than current key"
- $\bullet$  Heap [i] = key
- while i > 1 and Heap [Parent (i)] < Heap [i]
- ullet exchange  $Heap\left[i\right]$  with  $Heap\left[Parent\left(i\right)\right]$
- i = Parent(i)

