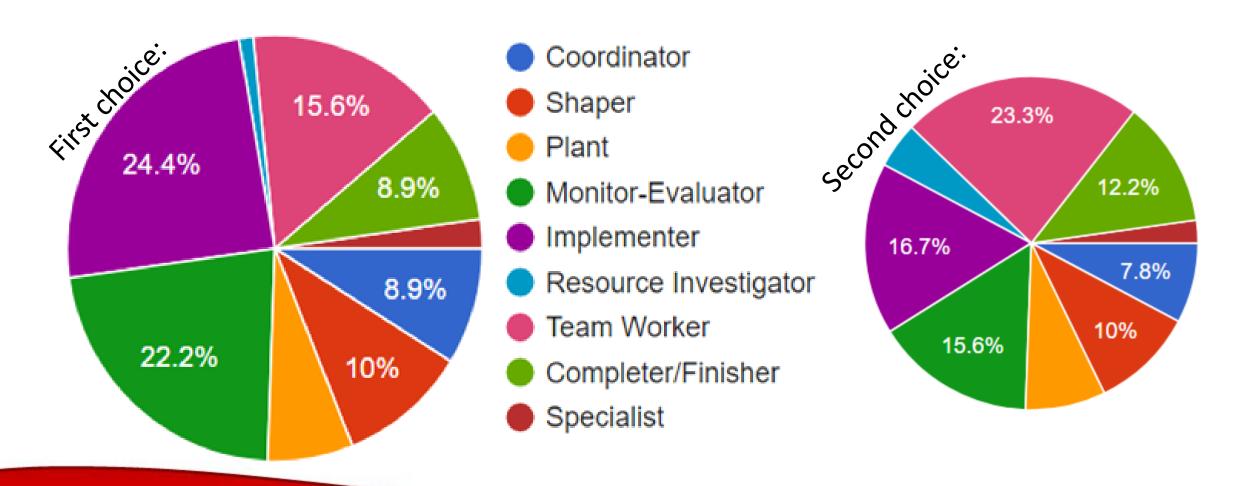
Join Piazza!

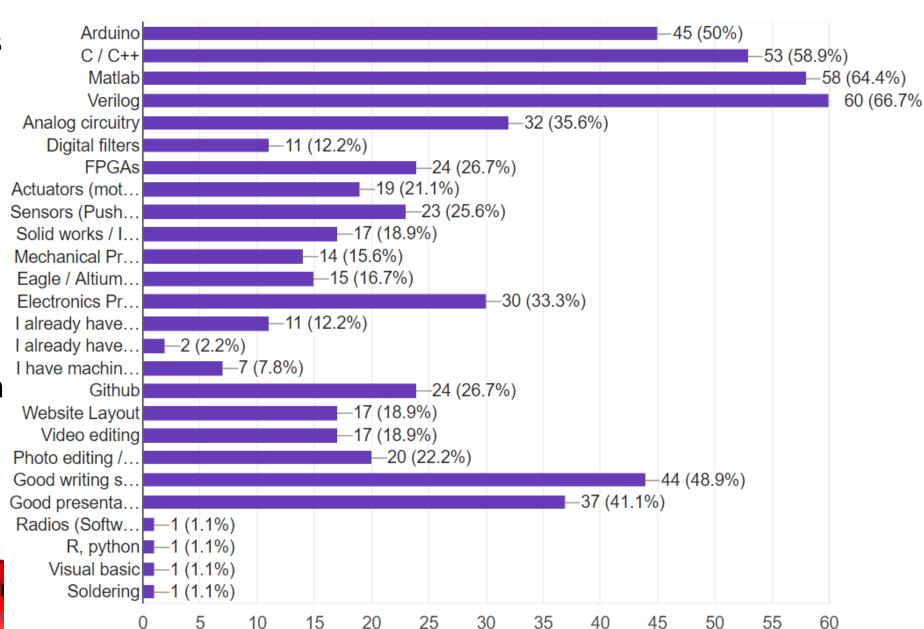
Find link on: https://cei-lab.github.io/ece3400/

Team compositions



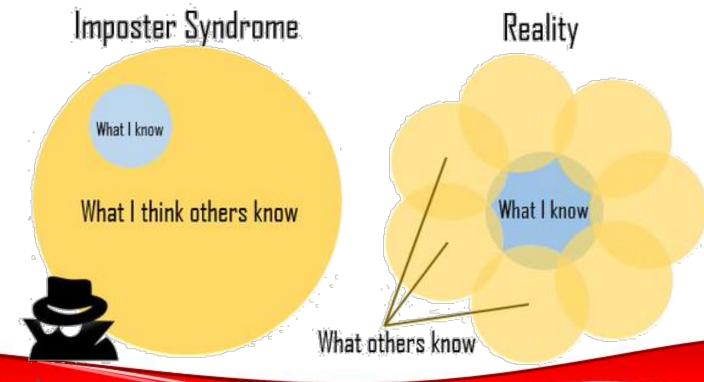
ECE3400 Cornell Engineering
Electrical and Computer Engineering

- Team compositions
- Biggest concerns
 - Technical skill
 - Electronics
 - Algorithms
 - Mechanics
 - Presentation



ECE3400 Cornel Eng

- Team compositions
- Biggest concerns
 - Technical skill (electronics, algorithms, mechanics, presentation)
 - Team
 - Dead weight
 - Not getting to do anything
 - Scheduling/finding time
 - Innovation/creativity
 - Disinterest / Laziness

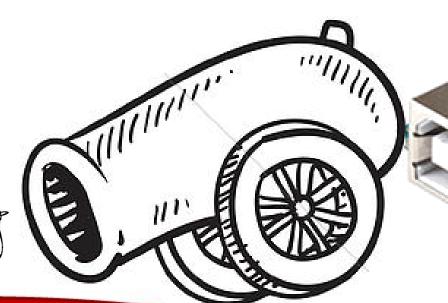


Introduction

Arduino Uno

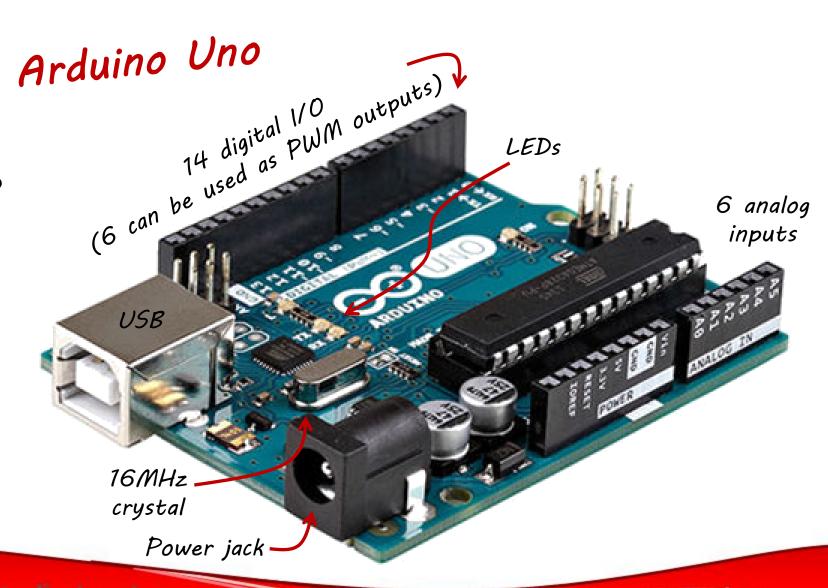
What under the hood?

How do you program it?

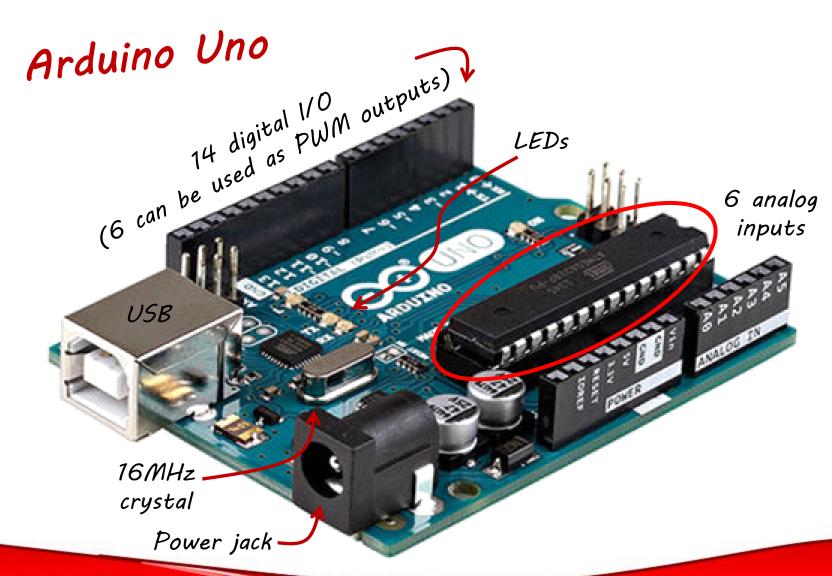




- Introduction
 - What under the hood?
 - How do you program it?



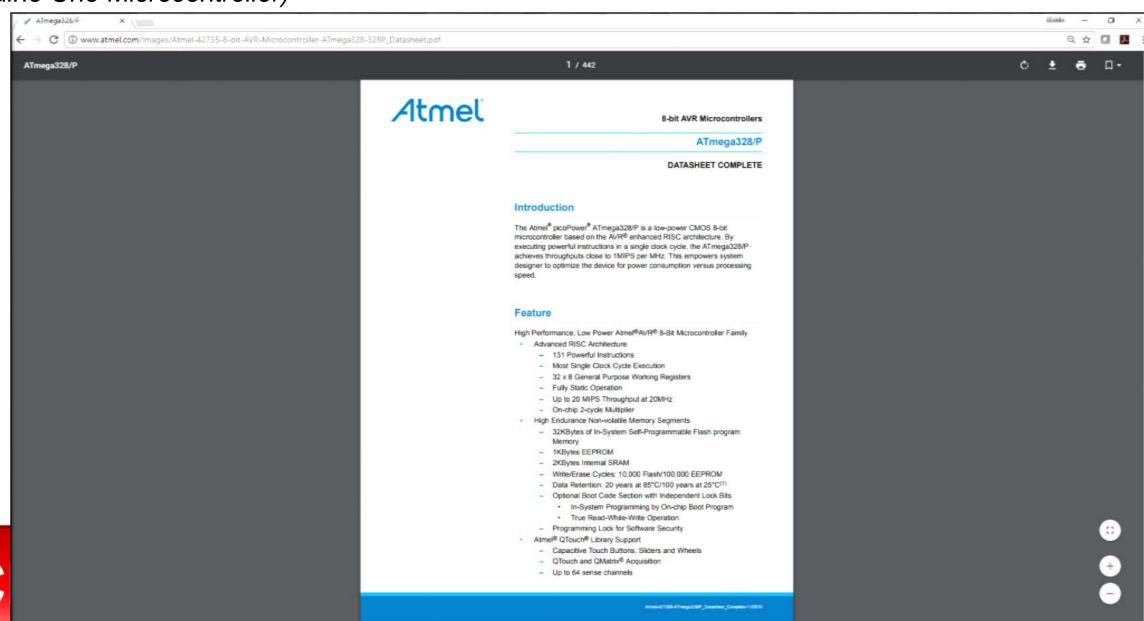
- Microcontroller (ATmega328)
- No operating system
- 32KB Flash
- 2KB SRAM
- 1KB EEPROM
- But it can do real-time control, sequential processing, timers, and interrupts!



ATmega328

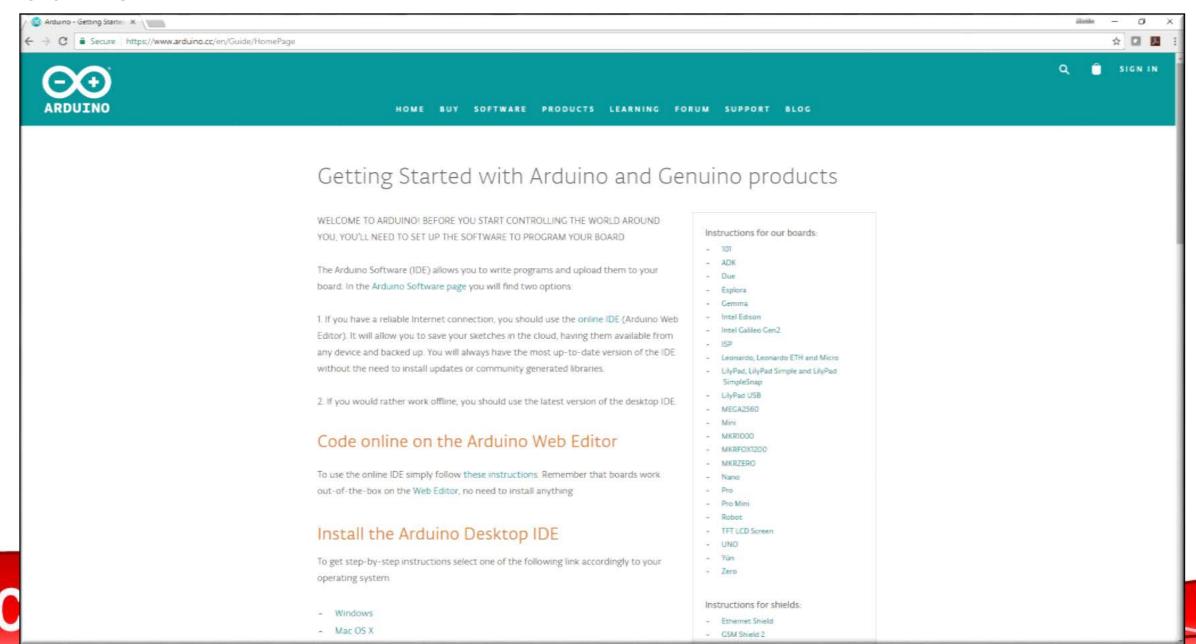
(Arduino Uno Microcontroller)

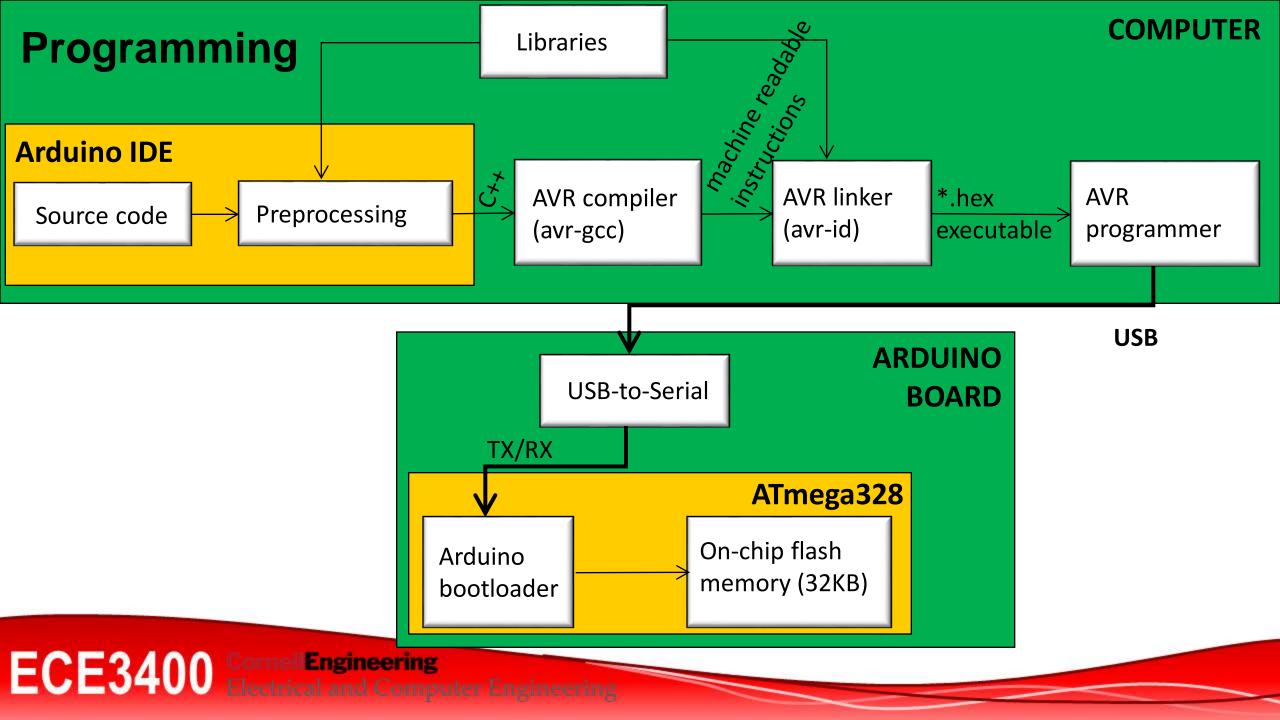
http://www.atmel.com/Images/Atmel-42735-8-bit-AVR-Microcontroller-ATmega328-328P_Datasheet.pdf



ATmega328 **SRAM** (Arduino Uno Microcontroller) debugWire CPU OCD Clock generation PB[7:0] XTAL1/ I/O PC[6:0] TOSC1 NVM 32.768kHz Calib RC PD[7:0] **PORTS** XOSC **FLASH** programming External clock XTAL2/ Power 16MHz LP TOSC2 GPIOR[2:0] 128kHz int XOSC management osc and clock **EEPROM** PD4 TC 0 control PD6 OC0A (8-bit) OC0B PD5 MISO0 PB4 VCC **EEPROMIF** MOSI0 PB3 SPI 0 **Power** SCK0 PB5 Watchdog SS0 Supervision PB2 RESET Timer POR/BOD & AIN0 PD6 AIN1 PD7 RESET AC GND Internal ADC6, ADC7 Reference PC[5:0] — ADC[7:0] **ADC** AREF PD[7:0], PC[6:0], PB[7:0] **EXTINT USART 0** TxD0 OC1A/B TC 1 (16-bit) TC 2 OC2A OC2B (8-bit async)

Arduino IDE





Input/Output Ports

DDxn	PORTxn	PINxn	Setup
1	0	X	Output low
1	1	X	Output high
1	X	1	Toggle output
0	1	X	Input
0	0/1	X	Tri-state

Input/Output Ports

Variable	Memory	Max (unsigned) value	Max signed value
Boolean	8 bits / 1 byte	-	-
Char	8 bits / 1 byte	28	2 ⁷
Int	16 bits / 2 bytes	2 ¹⁶	2 ¹⁵
Double	32 bits / 4 bytes	2 ³²	2 ³¹
Float	32 bits / 4 bytes	-	2 ³¹

Alternatives



















Alternatives

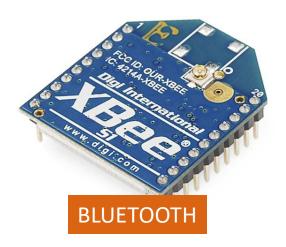
Raspberry Pi's and other mini computers



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Add-Ons



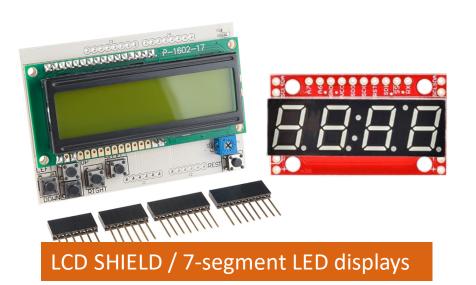












Commercial Vendors

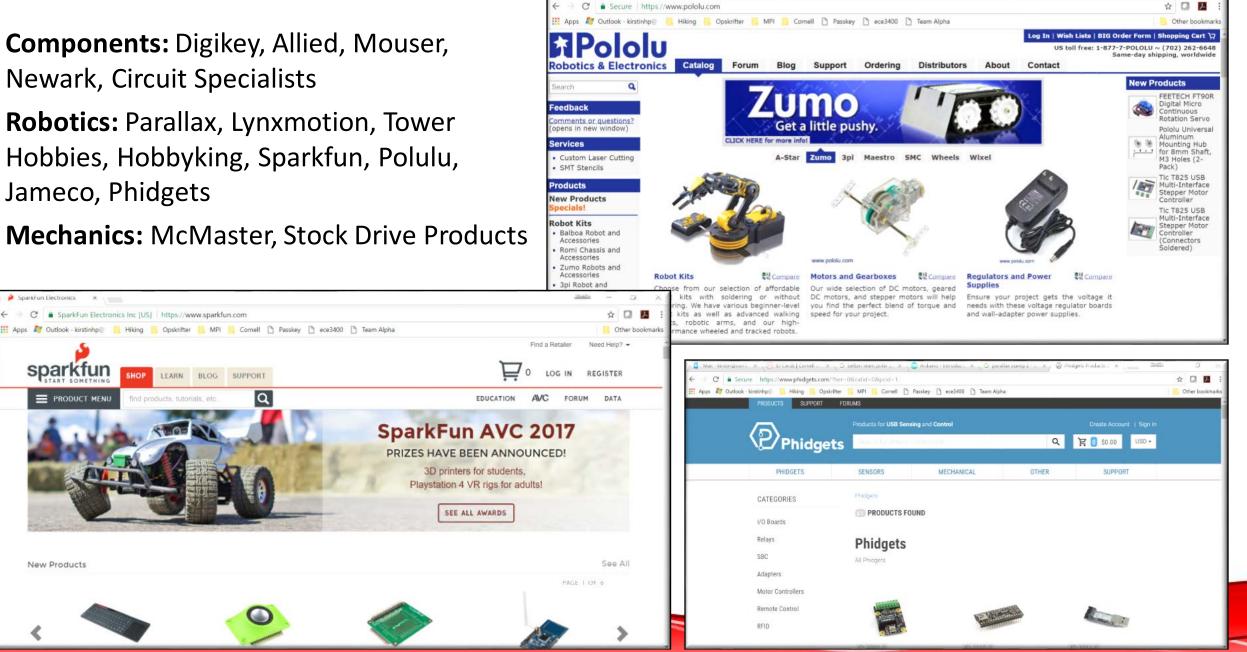
- **Components:** Digikey, Allied, Mouser, Newark, Circuit Specialists
- Robotics: Parallax, Lynxmotion, Tower Hobbies, Hobbyking, Sparkfun, Polulu, Jameco, Phidgets

Sparkfun Electronics ×

PRODUCT MENU

New Products

Mechanics: McMaster, Stock Drive Products



Pololu Robotics and Ele. X

Go Build Robots!



Class website: https://cei-lab.github.io/ece3400/

Piazza: https://piazza.com/cornell/fall2017/ece3400/home