Supplementary Information: A data-driven semiparametric model of SARS-CoV-2 transmission dynamics in the United States

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Model diagram

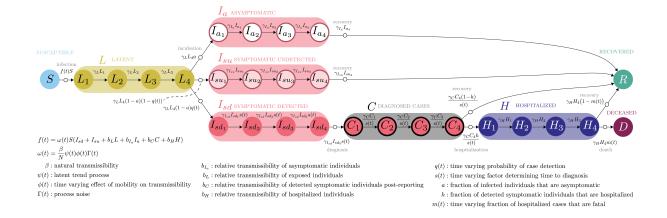


Figure S1: Model diagram.

Model parameters

Table S1: Fixed model parameters.

Parameter definition	Parameter symbol	Value	Source
Reproduction number	\mathcal{R}_0	7	Sanche et al. (2020)
Transmission rate of symptomatic individuals	β	$\mathcal{R}_0 \times 0.1 \times \frac{1}{N}$	Assumption
Fraction of infected individuals that are asymptomatic	a	0.18	Mizumoto et al. (2020);
Fraction of diagnosed cases that are hospitalized	h	0.12	Verity et al. (2020)
Relative transmissibility of L to $I_{su/sd}$	b_L	0.12	Li et al. (2020)

	Parameter		
Parameter definition	symbol	Value	Source
Relative transmissibility of I_a to $I_{su/sd}$	b_{I_a}	0.5	Li et
, 34/04			al. (2020)
Relative transmissibility of C to $I_{su/sd}$	b_{I_a}	0.27	Assumption
Relative transmissibility of H to $I_{su/sd}$	b_{I_a}	4.5×10^{-5}	Moghadas
·			et al. (2020)
Rate of movement through a single L stage	γ_L	$\frac{1}{1 \text{ days}}$	Li et
		-	al. (2020)
Rate of movement through a single I_a stage	γ_{I_a}	$\frac{1}{0.88 \text{ days}}$	Li et
			al. (2020)
Rate of movement through a single I_{su} stage	$\gamma_{I_{su}}$	$\frac{1}{1.5 \text{ days}}$	Li et
		aug	al. (2020)
Rate of movement through a single I_{sd} stage	$\gamma_{I_{su}}$	$\frac{1}{0.75 \text{ days}}$	Assumption
Rate of movement through a single C stage	γ_C	$\frac{1}{0.75 \text{ days}}$	Assumption
Rate of movement through a single H stage	γ_H	$\frac{1}{1.5 \text{ days}}$	Moghadas
			et al. (2020)
Minimum detection probability	q_{\min}	0.1	Assumption
Maximum detection probability	$q_{ m max}$	0.4	Assumption
Day at which detection probability is halfway	$q_{ m half}$	30	Assumption
between q_{\min} and q_{\max}			
Rate of increase from q_{\min} to q_{\max}	$q_{ m r}$	1.0	Assumption
Maximum factor by which diagnosis speed incrases	$s_{ m max}$	1.0	Assumption
Day at which diagnosis speed-up factor (s) is	$s_{ m half}$	30	Assumption
halfway between 0 and $s_{\rm max}$			
Rate of increase from 0 to s_{max}	s_r	1.0	Assumption
Initial size of susceptible pool	S(t=1)	$N_{ m state}$	Assumption

Table S2: Estimated parameters and starting ranges for MIF estimation procedure.

	Parameter	
Parameter definition	symbol	Start range
Baseline fraction of hospitalizations that result in death	$m_{ m base}$	[expit(-6), expit(6)]
Minimum fraction of hospitalizations that result in death	$m_{ m min}$	[expit(-6), expit(6)]
Day at which death fraction is halfway between $m_{\rm base}$ and $m_{\rm min}$	$m_{ m half}$	$[\exp(-5), \exp(5)]$
Extra-demographic process noise	σ	$[\exp(-5), \exp(5)]$
Case reporting dispersion	$ heta_c$	$[\exp(-5), \exp(5)]$
Death reporting dispersion	$ heta_d$	$[\exp(-5), \exp(5)]$
Initial size of latent compartment	L(t=0)	$[\exp(0), \exp(10)]$
Initial size of asymptomatic infectious compartment	$I_a(t=0)$	$[\exp(0), \exp(10)]$
Initial size of undetected infectious compartment	$I_{su}(t=0)$	$[\exp(0), \exp(10)]$
Initial size of detected infectious compartment	$I_{sd}(t=0)$	$[\exp(0), \exp(10)]$
B-spline coefficients	g_i	[-10, 10]

Mean absolute scaled errors (MASE)

The MASE is a ratio of mean absolute error (MAE) in the model to MAE of an in-sample naïve model (a random walk forecast from the last observation, adjusted for weekly seasonality). MASE values were calculated for each of the 500 particle filter replicates for each state using the **yardstick** package in R. Most

states had a mean MASE less than one for cases, while MASE was greater than one for deaths for most states. Thus, our model does not always outperform the benchmarking model, but it does offer mechanistic insight that the random walk model does not.

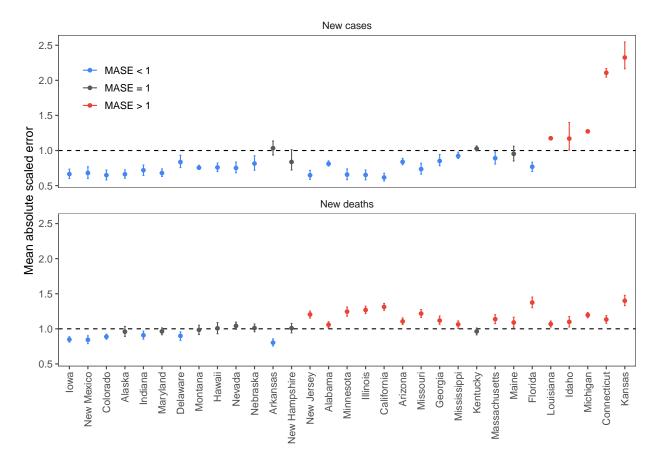
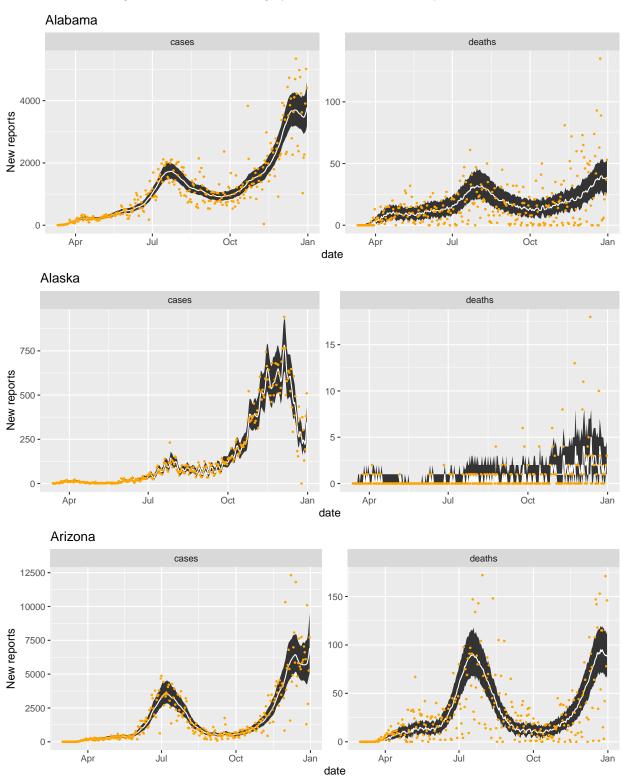


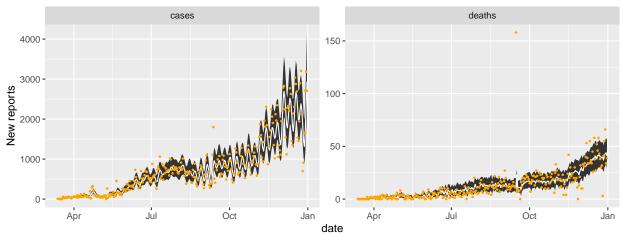
Figure S2: Mean and 95% intervals of mean absolute scaled errors (MASE) for each state. MASE was calculated for each of the 500 particle filter replicates for each state, yielding a distribution of MASE values. The point shows the mean of the MASE distribution and the errorbars show the 95% interval (lower 0.025 quantile to upper 0.975 quantile). States are ranked approximately from lowest MASE to highest MASE across both cases and deaths.

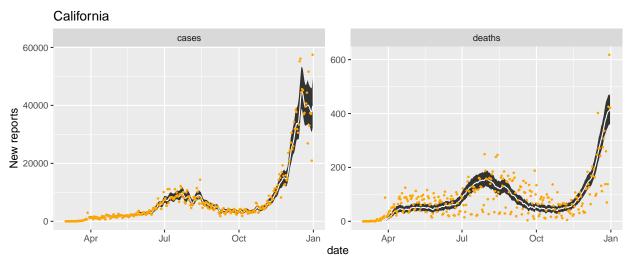
Time series of incident case and death reports

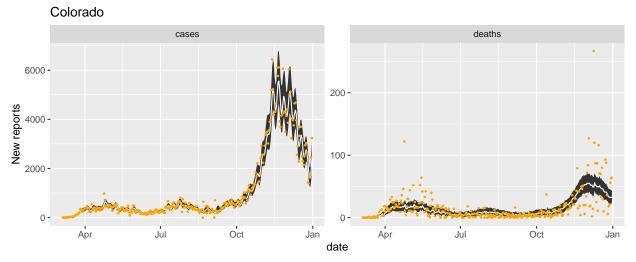
In the following plots, orange points are the reported daily cases or deaths, white line shows the median of the smoothed filtering distributions, and the grey ribbon bounds the 95% prediction interval.



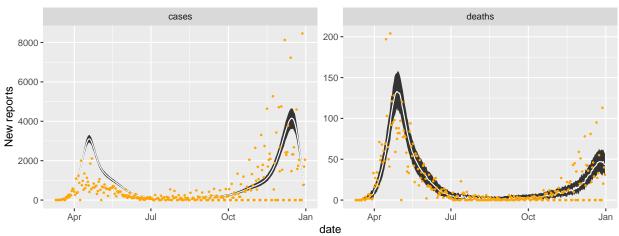




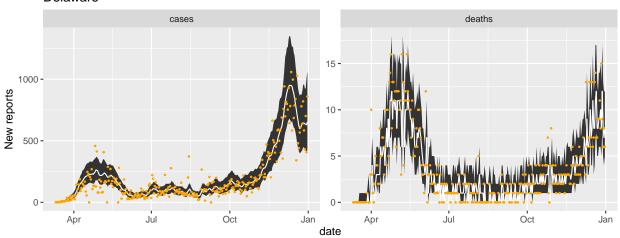




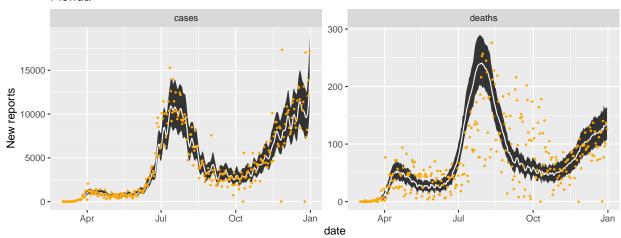


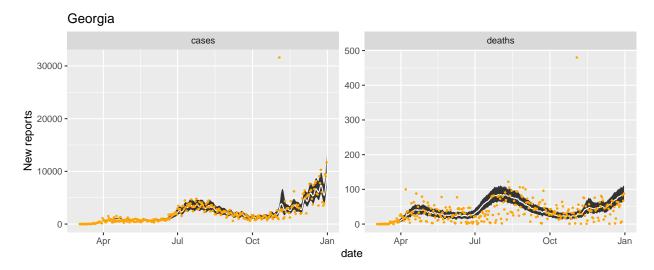


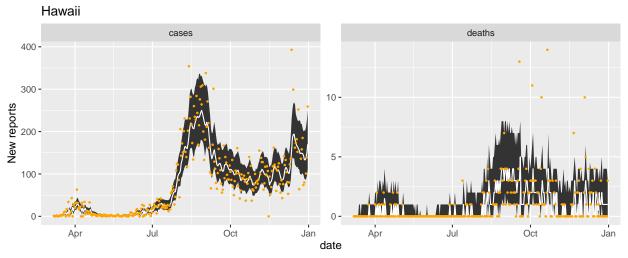
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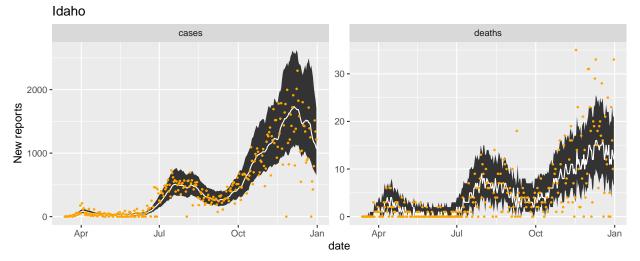


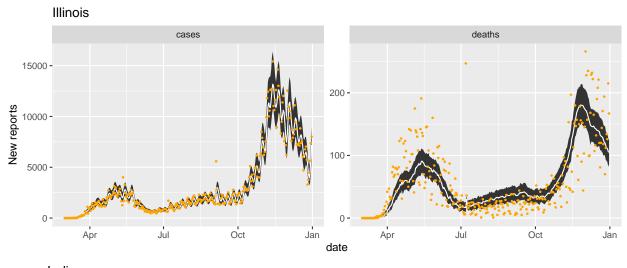
Florida

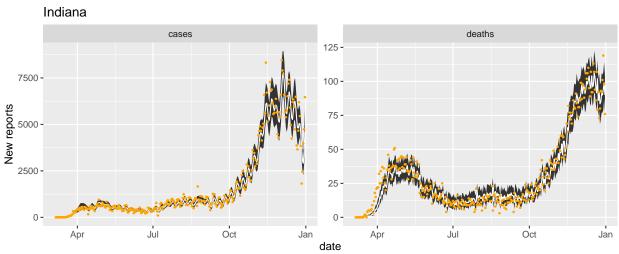


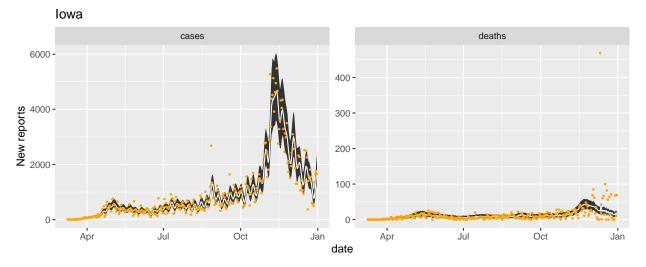




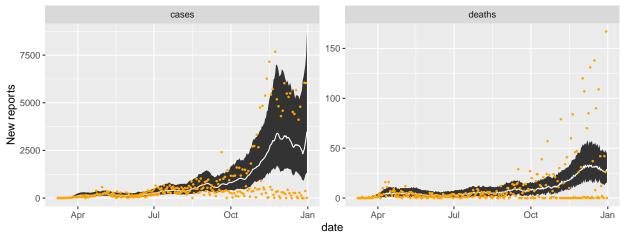




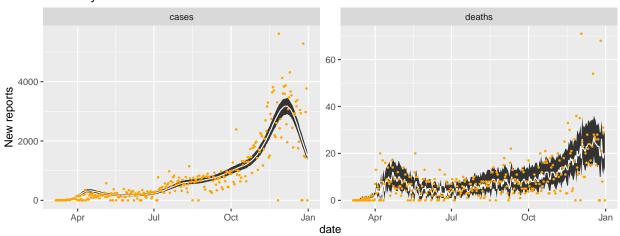




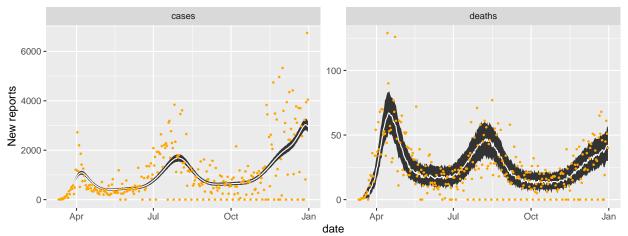


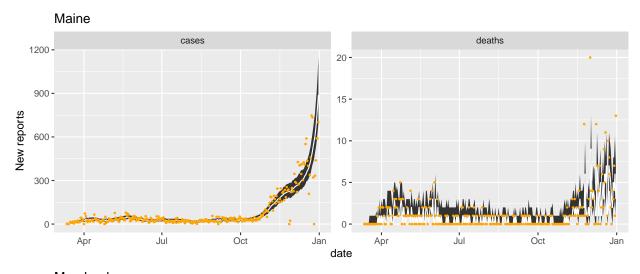


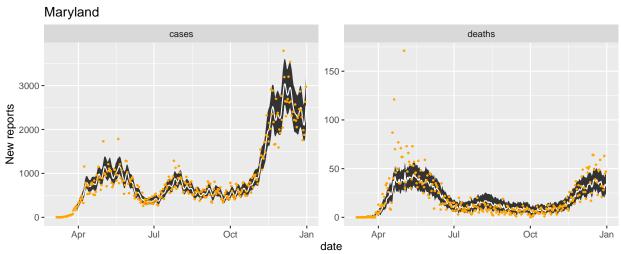
Kentucky

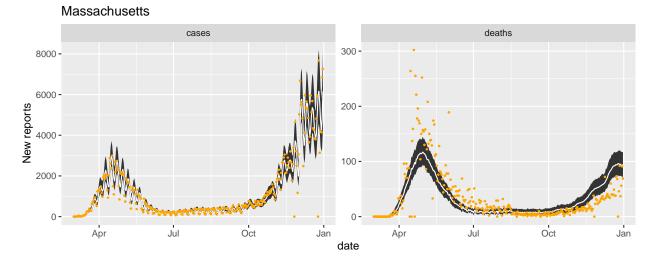


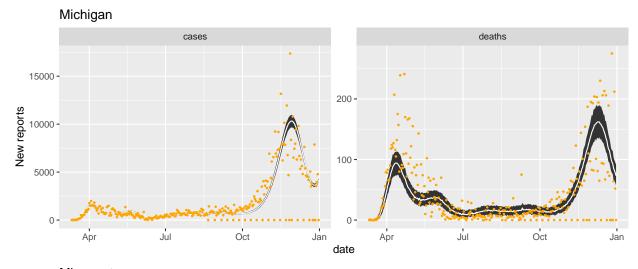
Louisiana

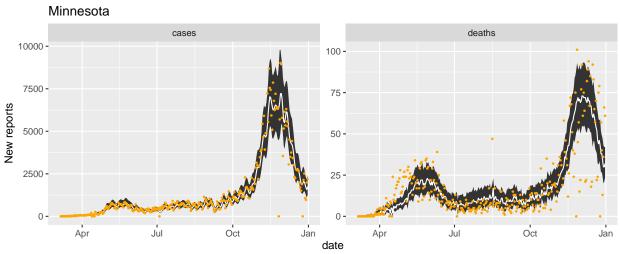


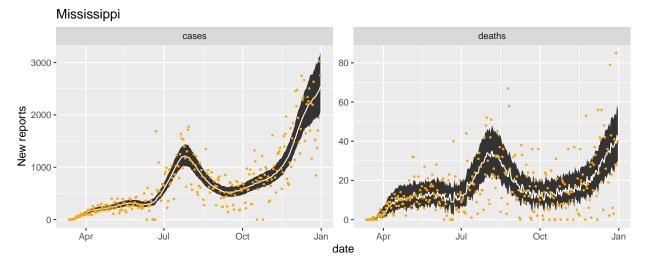


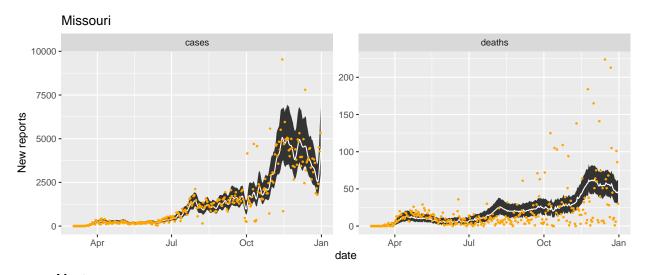


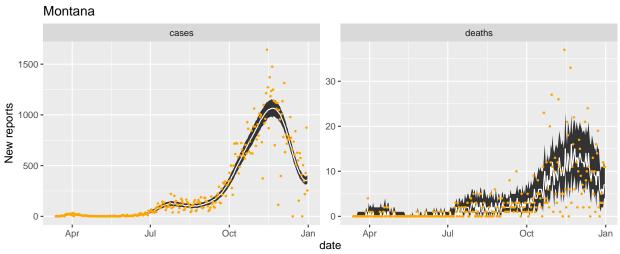


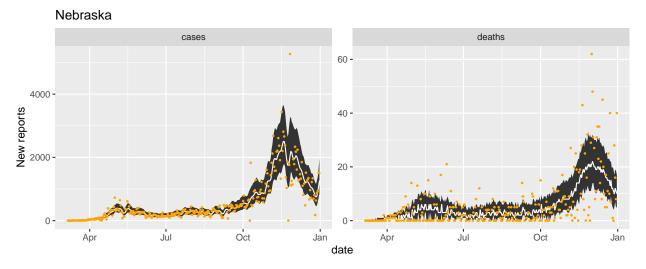


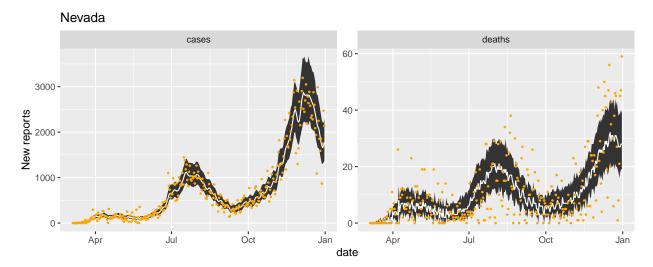


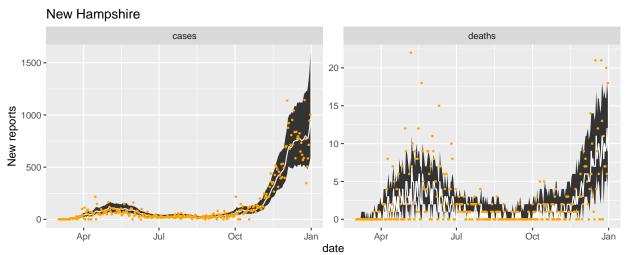


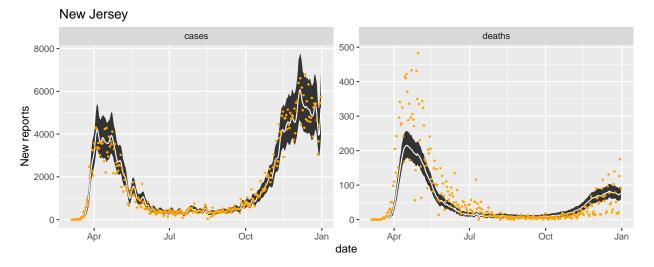


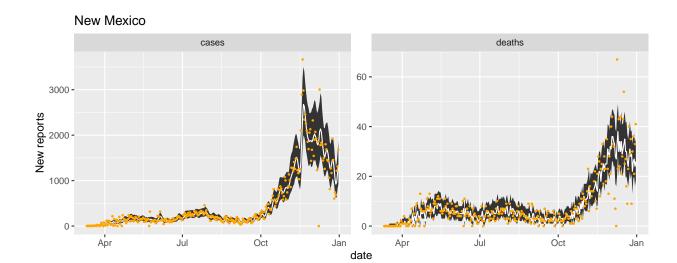






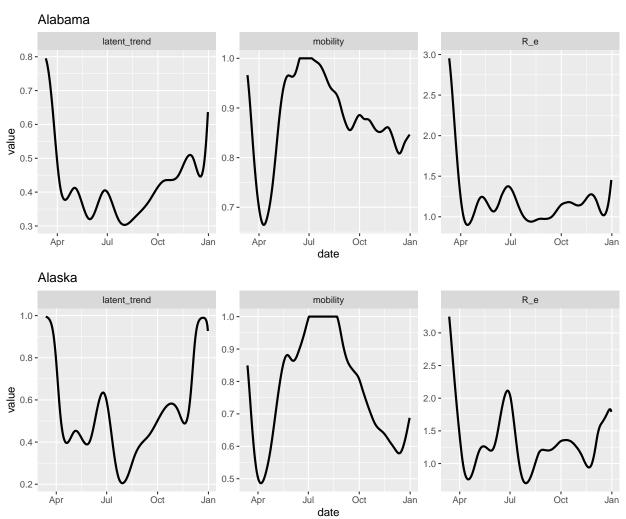


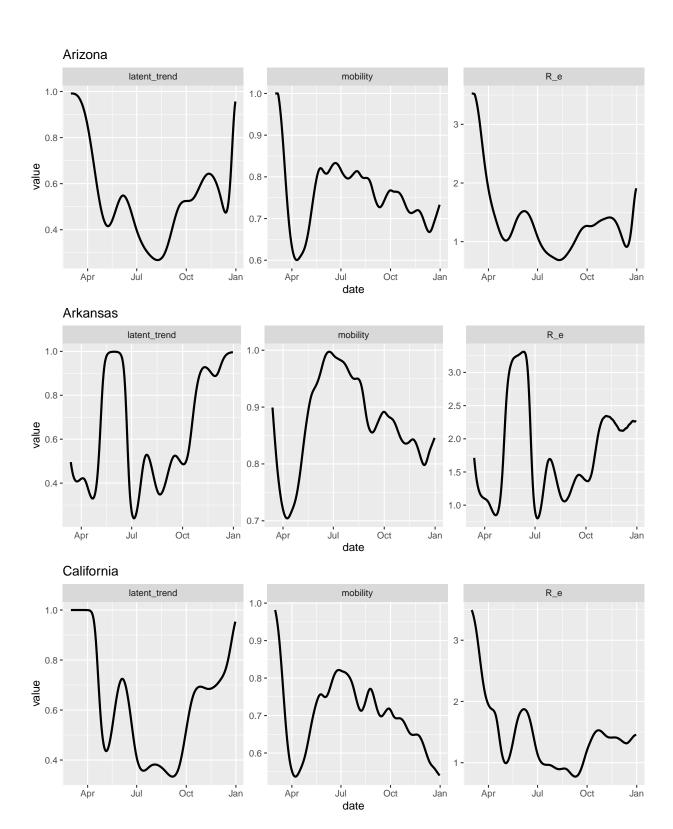


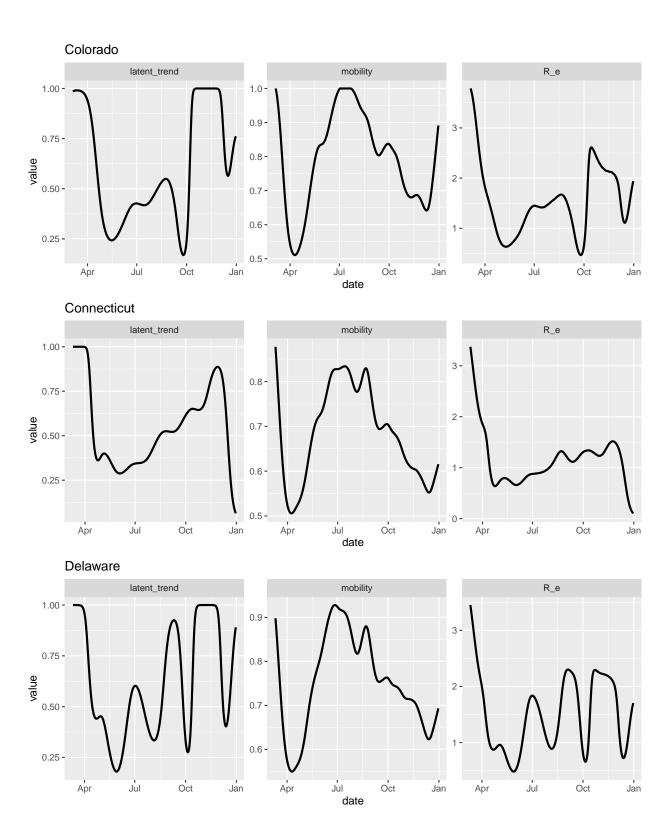


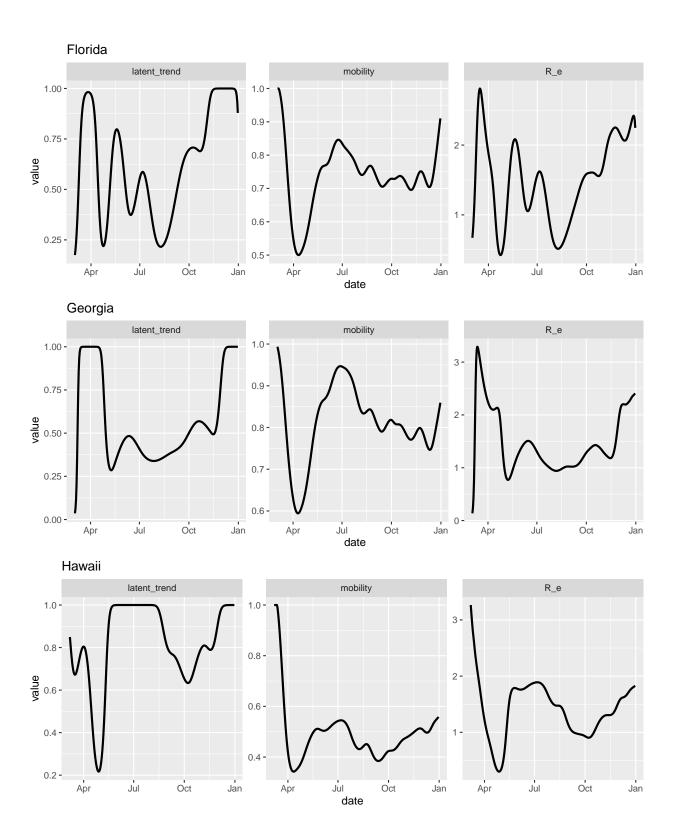
Time series of mobility, estimated latent trend, and \mathcal{R}_e

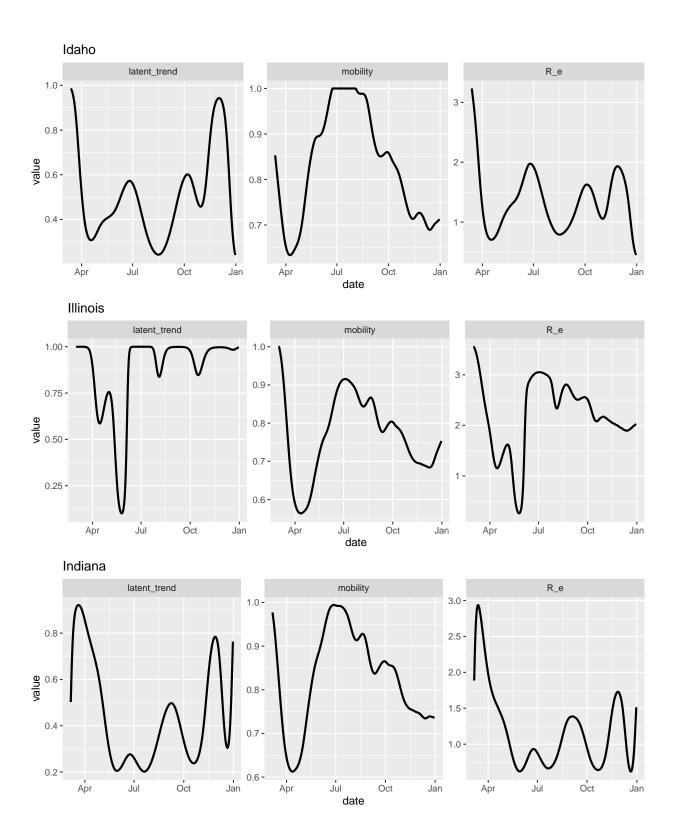
The following plots show the estimated latent trend, relative mobility, and estimated \mathcal{R}_e over time for each state. The latent trend is estimated using the maximum likelihood parameter estimates for the g_i coefficients of the B-spline (see Materials and Methods in main text).

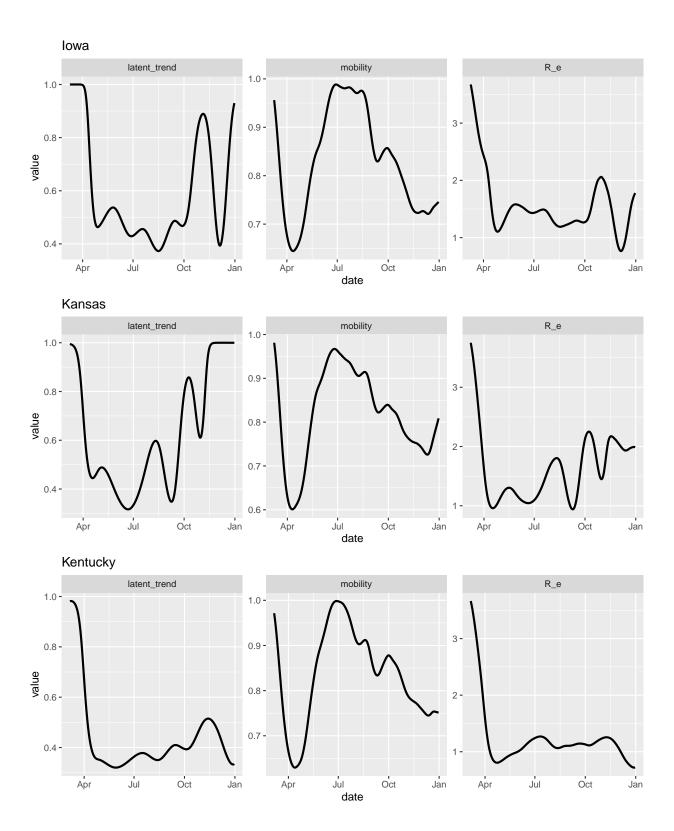


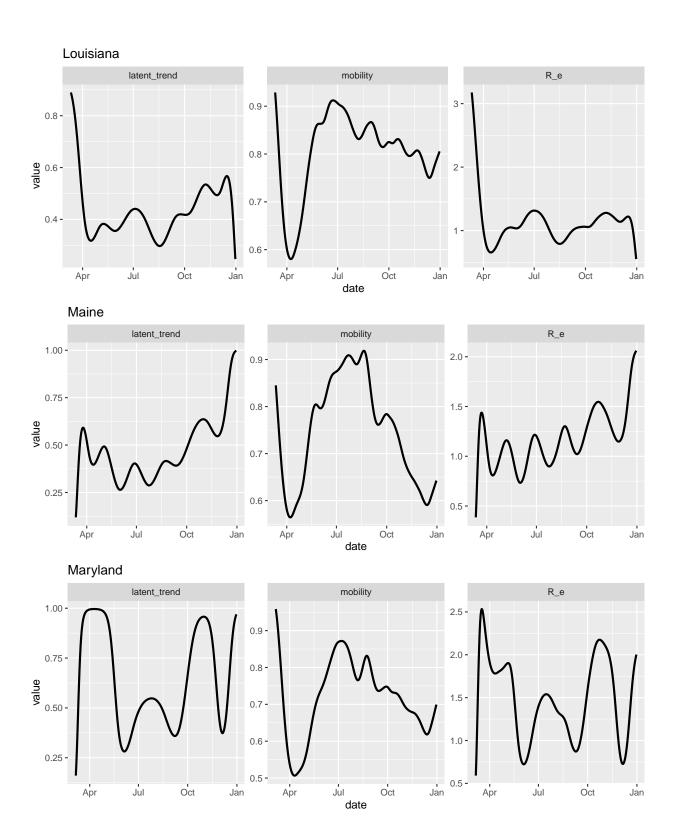




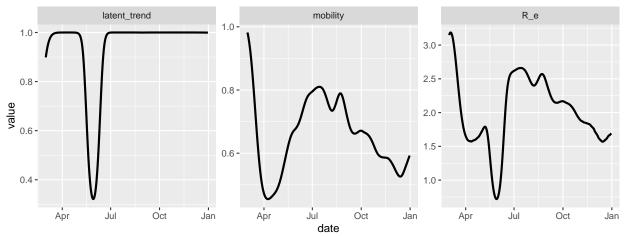




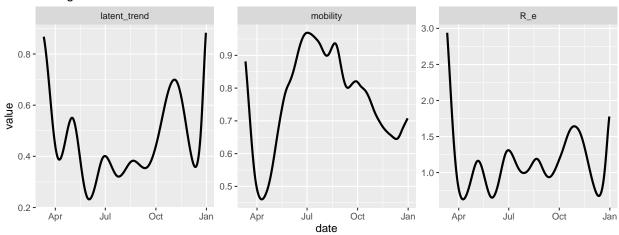




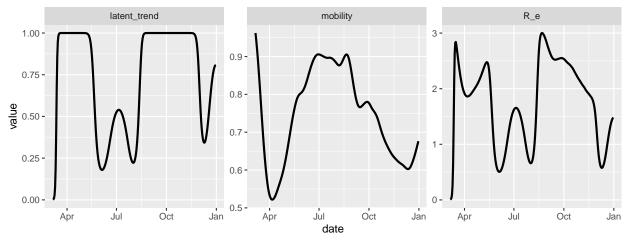


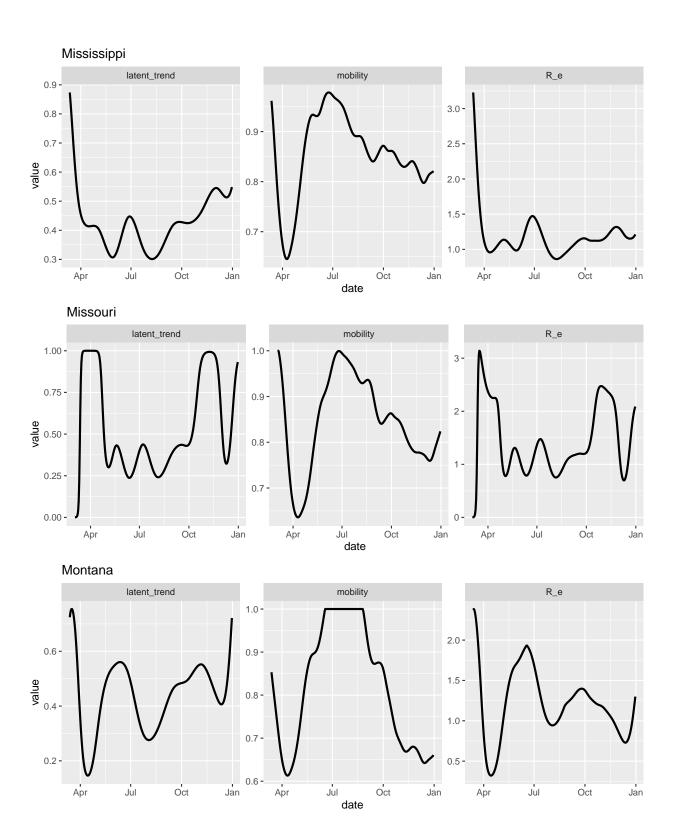


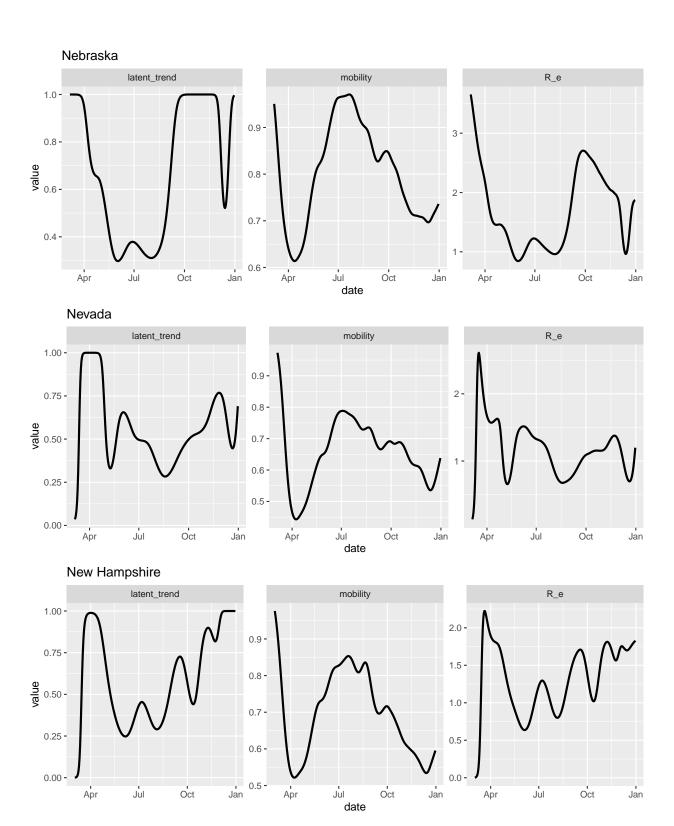
Michigan

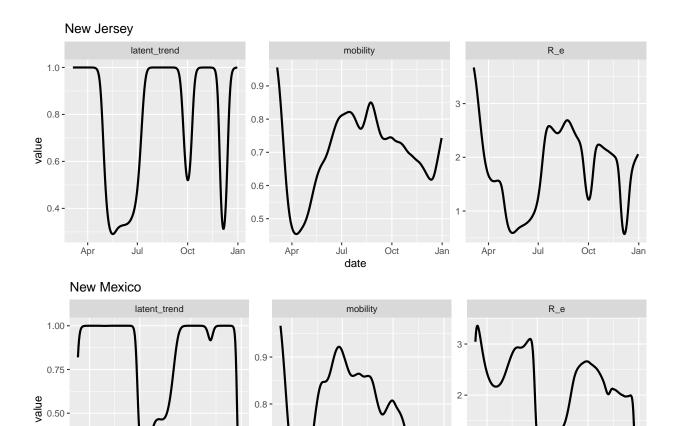


Minnesota









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