7–2 Flip-Flops

Flip-flops are synchronous bistable devices, also known as *bistable multivibrators*. In this case, the term *synchronous* means that the output changes state only at a specified point (leading or trailing edge) on the triggering input called the **clock** (CLK), which is designated as a control input, *C*; that is, changes in the output occur in synchronization with the clock. Flip-flops are edge-triggered or edge-sensitive whereas gated latches are level-sensitive.

After completing this section, you should be able to

- Define clock
- Define edge-triggered flip-flop
- Explain the difference between a flip-flop and a latch
- Identify an edge-triggered flip-flop by its logic symbol
- Discuss the difference between a positive and a negative edge-triggered flip-flop
- Discuss and compare the operation of D and J-K edge-triggered flip-flops and explain the differences in their truth tables
- Discuss the asynchronous inputs of a flip-flop

An **edge-triggered flip-flop** changes state either at the positive edge (rising edge) or at the negative edge (falling edge) of the clock pulse and is sensitive to its inputs only at this transition of the clock. Two types of edge-triggered flip-flops are covered in this section: D and J-K. The logic symbols for these flip-flops are shown in Figure 7–13. Notice that each type can be either positive edge-triggered (no bubble at C input) or negative edge-triggered (bubble at C input). The key to identifying an edge-triggered flip-flop by its logic symbol is the small triangle inside the block at the clock (C) input. This triangle is called the *dynamic input indicator*.

The dynamic input indicator ▷ means the flip-flop changes state only on the edge of a clock pulse.

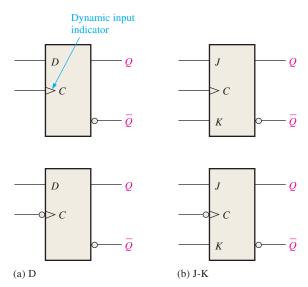


FIGURE 7-13 Edge-triggered flip-flop logic symbols (top: positive edge-triggered; bottom: negative edge-triggered).

The D Flip-Flop

The D input of the **D** flip-flop is a **synchronous** input because data on the input are transferred to the flip-flop's output only on the triggering edge of the clock pulse. When D is HIGH, the Q output goes HIGH on the triggering edge of the clock pulse, and the flip-flop

D flip-flop but *D* as variable.

InfoNote

Semiconductor memories consist of large numbers of individual cells. Each storage cell holds a 1 or a 0. One type of memory is the Static Random Access Memory or SRAM, which uses flip-flops for the storage cells because a flip-flop will retain either of its two states indefinitely as long as dc power is applied, thus the term *static*. This type of memory is classified as a volatile memory because all the stored data are lost when power is turned off. Another type of memory, the Dynamic Random Access Memory or DRAM, uses capacitance rather than flip-flops as the basic storage element and must be periodically refreshed in order to maintain the stored data.

is SET. When D is LOW, the Q output goes LOW on the triggering edge of the clock pulse, and the flip-flop is RESET.

This basic operation of a positive edge-triggered D flip-flop is illustrated in Figure 7–14, and Table 7–2 is the truth table for this type of flip-flop. Remember, the flip-flop cannot change state except on the triggering edge of a clock pulse. The D input can be changed at any time when the clock input is LOW or HIGH (except for a very short interval around the triggering transition of the clock) without affecting the output. Just remember, Q follows D at the triggering edge of the clock.

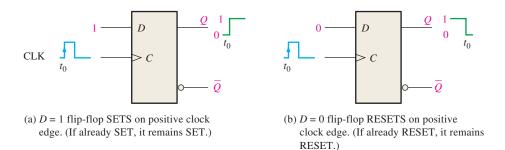


FIGURE 7-14 Operation of a positive edge-triggered D flip-flop.

TABLE 7-2					
Truth table for a positive edge-triggered D flip-flop.					
T 4	0.4.4				

Inputs		Outputs		
D	CLK	ϱ	$\overline{\mathcal{Q}}$	Comments
0	↑	0	1	RESET SET
		•		521

^{↑ =} clock transition LOW to HIGH

The operation and truth table for a negative edge-triggered D flip-flop are the same as those for a positive edge-triggered device except that the falling edge of the clock pulse is the triggering edge.

EXAMPLE 7-4

Determine the Q and \overline{Q} output waveforms of the flip-flop in Figure 7–15 for the D and CLK inputs in Figure 7–16(a). Assume that the positive edge-triggered flip-flop is initially RESET.

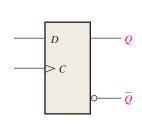


FIGURE 7-15

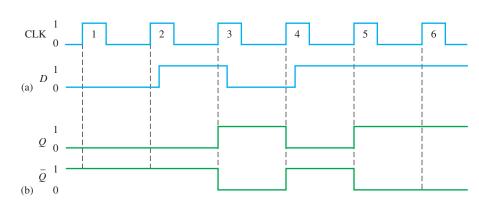


FIGURE 7-16

Solution

- 1. At clock pulse 1, D is LOW, so Q remains LOW (RESET).
- **2.** At clock pulse 2, *D* is LOW, so *Q* remains LOW (RESET).
- **3.** At clock pulse 3, *D* is HIGH, so *Q* goes HIGH (SET).
- **4.** At clock pulse 4, *D* is LOW, so *Q* goes LOW (RESET).
- **5.** At clock pulse 5, *D* is HIGH, so *Q* goes HIGH (SET).
- **6.** At clock pulse 6, *D* is HIGH, so *Q* remains HIGH (SET).

Once Q is determined, \overline{Q} is easily found since it is simply the complement of Q. The resulting waveforms for Q and \overline{Q} are shown in Figure 7–16(b) for the input waveforms in part (a).

Related Problem

Determine Q and \overline{Q} for the D input in Figure 7–16(a) if the flip-flop is a negative edge-triggered device.

The J-K Flip-Flop

The J and K inputs of the J-K flip-flop are synchronous inputs because data on these inputs are transferred to the flip-flop's output only on the triggering edge of the clock pulse. When J is HIGH and K is LOW, the Q output goes HIGH on the triggering edge of the clock pulse, and the flip-flop is SET. When J is LOW and K is HIGH, the Q output goes LOW on the triggering edge of the clock pulse, and the flip-flop is RESET. When both J and K are LOW, the output does not change from its prior state. When J and K are both HIGH, the flip-flop changes state. This called the **toggle** mode.

This basic operation of a positive edge-triggered flip-flop is illustrated in Figure 7–17, and Table 7–3 is the truth table for this type of flip-flop. Remember, the flip-flop cannot change state except on the triggering edge of a clock pulse. The J and K inputs can be changed at any time when the clock input is LOW or HIGH (except for a very short interval around the triggering transition of the clock) without affecting the output.

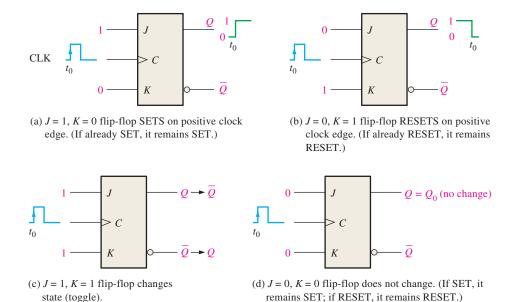


FIGURE 7–17 Operation of a positive edge-triggered J-K flip-flop.

TABLE 7-3

Truth table for a positive edge-triggered J-K flip-flop.

Inputs		Outputs			
J	K	CLK	Q	$\overline{\mathcal{Q}}$	Comments
0	0	<u> </u>	Q_0	\overline{Q}_0	No change
0	1	<u> </u>	0	1	RESET
1	0	<u> </u>	1	0	SET
1	1	1	\overline{Q}_0	Q_0	Toggle

 $[\]uparrow$ = clock transition LOW to HIGH

EXAMPLE 7-5

The waveforms in Figure 7–18(a) are applied to the J, K, and clock inputs as indicated. Determine the Q output, assuming that the flip-flop is initially RESET.

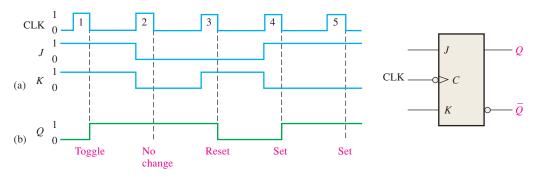


FIGURE 7-18

Solution

Since this is a negative edge-triggered flip-flop, as indicated by the "bubble" at the clock input, the Q output will change only on the negative-going edge of the clock pulse.

- 1. At the first clock pulse, both J and K are HIGH; and because this is a toggle condition, Q goes HIGH.
- **2.** At clock pulse 2, a no-change condition exists on the inputs, keeping Q at a HIGH level.
- **3.** When clock pulse 3 occurs, *J* is LOW and *K* is HIGH, resulting in a RESET condition; *Q* goes LOW.
- **4.** At clock pulse 4, *J* is HIGH and *K* is LOW, resulting in a SET condition; *Q* goes HIGH.
- **5.** A SET condition still exists on *J* and *K* when clock pulse 5 occurs, so *Q* will remain HIGH.

The resulting Q waveform is indicated in Figure 7–18(b).

Related Problem

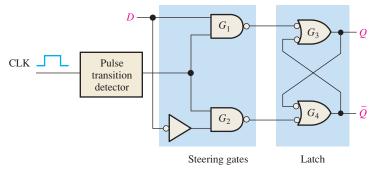
Determine the Q output of the J-K flip-flop if the J and K inputs in Figure 7–18(a) are inverted.

Edge-Triggered Operation

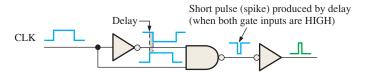
D Flip-Flop

A simplified implementation of an edge-triggered D flip-flop is illustrated in Figure 7–19(a) and is used to demonstrate the concept of edge-triggering. Notice that the basic D flip-flop differs from the gated D latch only in that it has a pulse transition detector.

 Q_0 = output level prior to clock transition



(a) A simplified logic diagram for a positive edge-triggered D flip-flop



(b) A type of pulse transition detector

FIGURE 7-19 Edge triggering.

One basic type of pulse transition detector is shown in Figure 7–19(b). As you can see, there is a small delay through the inverter on one input to the NAND gate so that the inverted clock pulse arrives at the gate input a few nanoseconds after the true clock pulse. This circuit produces a very short-duration spike on the positive-going transition of the clock pulse. In a negative edge-triggered flip-flop the clock pulse is inverted first, thus producing a narrow spike on the negative-going edge.

The circuit in Figure 7–19(a) is partitioned into two sections, one labeled Steering gates and the other labeled Latch. The steering gates direct, or steer, the clock spike either to the input to gate G_3 or to the input to gate G_4 , depending on the state of the D input. To understand the operation of this flip-flop, begin with the assumptions that it is in the RESET state (Q=0) and that the D and CLK inputs are LOW. For this condition, the outputs of gate G_1 and gate G_2 are both HIGH. The LOW on the Q output is coupled back into one input of gate G_4 , making the \overline{Q} output HIGH. Because \overline{Q} is HIGH, both inputs to gate G_3 are HIGH (remember, the output of gate G_1 is HIGH), holding the Q output LOW. If a pulse is applied to the CLK input, the outputs of gates G_1 and G_2 remain HIGH because they are disabled by the LOW on the D input; therefore, there is no change in the state of the flip-flop—it remains in the RESET state.

Let's now make D HIGH and apply a clock pulse. Because the D input to gate G_1 is now HIGH, the output of gate G_1 goes LOW for a very short time (spike) when CLK goes HIGH, causing the Q output to go HIGH. Both inputs to gate G_4 are now HIGH (remember, gate G_2 output is HIGH because D is HIGH), forcing the \overline{Q} output LOW. This LOW on \overline{Q} is coupled back into one input of gate G_3 , ensuring that the Q output will remain HIGH. The flip-flop is now in the SET state. Figure 7–20 illustrates the logic level transitions that take place within the flip-flop for this condition.

Next, let's make D LOW and apply a clock pulse. The positive-going edge of the clock produces a negative-going spike on the output of gate G_2 , causing the \overline{Q} output to go HIGH. Because of this HIGH on \overline{Q} , both inputs to gate G_3 are now HIGH (remember, the output of gate G_1 is HIGH because of the LOW on D), forcing the Q output to go LOW. This LOW on Q is coupled back into one input of gate G_4 , ensuring that \overline{Q} will remain HIGH. The flip-flop is now in the RESET state. Figure 7–21 illustrates the logic level transitions that occur within the flip-flop for this condition.

InfoNote

All logic operations that are performed with hardware can also be implemented in software. For example, the operation of a J-K flip-flop can be performed with specific computer instructions. If two bits were used to represent the J and K inputs, the computer would do nothing for 00, a data bit representing the Q output would be set (1) for 10, the Q data bit would be cleared (0) for 01, and the Q data bit would be complemented for 11. Although it may be unusual to use a computer to simulate a flip-flop, the point is that all hardware operations can be simulated using software.

The *Q* output of a D flip-flop assumes the state of the *D* input on the triggering edge of the clock.

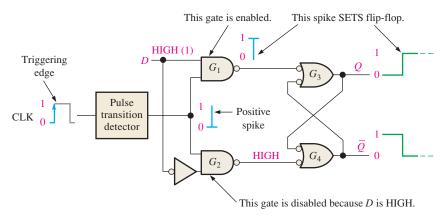


FIGURE 7-20 Flip-flop making a transition from the RESET state to the SET state on the positive-going edge of the clock pulse.

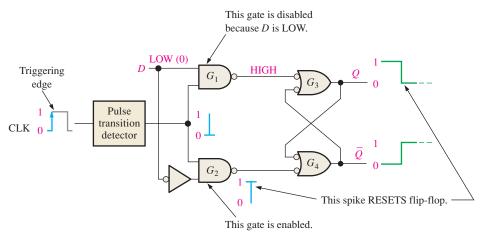


FIGURE 7–21 Flip-flop making a transition from the SET state to the RESET state on the positive-going edge of the clock pulse.

EXAMPLE 7–6

Given the waveforms in Figure 7–22(a) for the D input and the clock, determine the Q output waveform if the flip-flop starts out RESET.

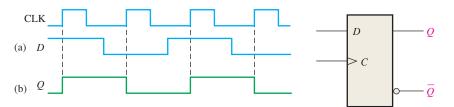


FIGURE 7-22

Solution

The Q output goes to the state of the D input at the time of the positive-going clock edge. The resulting output is shown in Figure 7–22(b).

Related Problem

Determine the Q output for the D flip-flop if the D input in Figure 7–22(a) is inverted.

J-K Flip-Flop

Figure 7–23 shows the basic internal logic for a positive edge-triggered J-K flip-flop. The Q output is connected back to the input of gate G_2 , and the \overline{Q} output is connected back to the input of gate G_1 . The two control inputs are labeled J and K in honor of Jack Kilby, who invented the integrated circuit. A J-K flip-flop can also be of the negative edge-triggered type, in which case the clock input is inverted.

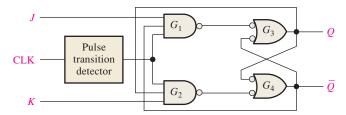


FIGURE 7-23 A simplified logic diagram for a positive edge-triggered J-K flip-flop.

Let's assume that the flip-flop in Figure 7–24 is RESET and that the J input is HIGH and the K input is LOW rather than as shown. When a clock pulse occurs, a leading-edge spike indicated by ① is passed through gate G_1 because \overline{Q} is HIGH and J is HIGH. This will cause the latch portion of the flip-flop to change to the SET state. The flip-flop is now SET.

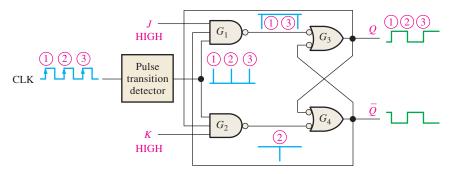


FIGURE 7-24 Transitions illustrating flip-flop operation.

If you make J LOW and K HIGH, the next clock spike indicated by ② will pass through gate G_2 because Q is HIGH and K is HIGH. This will cause the latch portion of the flip-flop to change to the RESET state.

If you apply a LOW to both the J and K inputs, the flip-flop will stay in its present state when a clock pulse occurs. A LOW on both J and K results in a *no-change* condition.

When both the J and K inputs are HIGH and the flip-flop is RESET, the HIGH on the \overline{Q} enables gate G_1 ; so the clock spike indicated by ③ passes through to set the flip-flop. Now there is a HIGH on Q, which allows the next clock spike to pass through gate G_2 and reset the flip-flop.

As you can see, on each successive clock spike, the flip-flop toggles to the opposite state. Figure 7–24 illustrates the transitions when the flip-flop is in the toggle mode. A J-K flip-flop connected for toggle operation is sometimes called a *T flip-flop*.

Asynchronous Preset and Clear Inputs

For the flip-flops just discussed, the *D* and *J-K* inputs are called *synchronous inputs* because data on these inputs are transferred to the flip-flop's output only on the triggering edge of the clock pulse; that is, the data are transferred synchronously with the clock.

In the toggle mode, a J-K flip-flop changes state on every clock pulse.

An active preset input makes the *Q* output HIGH (SET).

An active clear input makes the *Q* output LOW (RESET).

 $\begin{array}{c|c}
\hline
PRE} \\
D \\
\hline
C \\
\hline
CLR
\end{array}$

FIGURE 7-25 Logic symbol for a D flip-flop with active-LOW preset and clear inputs.

Most integrated circuit flip-flops also have **asynchronous** inputs. These are inputs that affect the state of the flip-flop *independent of the clock*. They are normally labeled **preset** (PRE) and **clear** (CLR), or *direct set* (S_D) and *direct reset* (R_D) by some manufacturers. An active level on the preset input will set the flip-flop, and an active level on the clear input will reset it. A logic symbol for a D flip-flop with preset and clear inputs is shown in Figure 7–25. These inputs are active-LOW, as indicated by the bubbles. These preset and clear inputs must both be kept HIGH for synchronous operation. In normal operation, preset and clear would not be LOW at the same time.

Figure 7–26 shows the logic diagram for an edge-triggered D flip-flop with active-LOW preset (\overline{PRE}) and clear (\overline{CLR}) inputs. This figure illustrates basically how these inputs work. As you can see, they are connected so that they override the effect of the synchronous input, D and the clock.

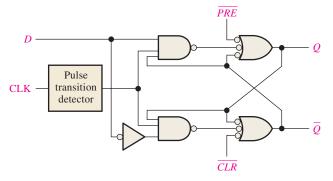
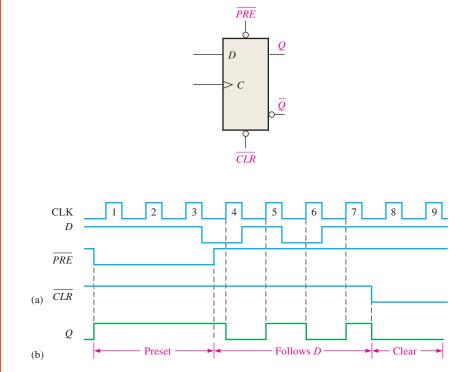


FIGURE 7-26 Logic diagram for a basic D flip-flop with active-LOW preset and clear inputs.

EXAMPLE 7-7

For the positive edge-triggered D flip-flop with preset and clear inputs in Figure 7–27, determine the Q output for the inputs shown in the timing diagram in part (a) if Q is initially LOW.







Solution

- **1.** During clock pulses 1, 2, and 3, the preset (\overline{PRE}) is LOW, keeping the flip-flop SET regardless of the synchronous *D* input.
- 2. For clock pulses 4, 5, 6, and 7, the output follows the input on the clock pulse because both \overline{PRE} and \overline{CLR} are HIGH.
- **3.** For clock pulses 8 and 9, the clear (\overline{CLR}) input is LOW, keeping the flip-flop RESET regardless of the synchronous inputs.

The resulting Q output is shown in Figure 7–27(b).

Related Problem

If you interchange the \overline{PRE} and \overline{CLR} waveforms in Figure 7–27(a), what will the Q output look like?

Let's look at two specific edge-triggered flip-flops. They are representative of the various types of flip-flops available in fixed-function IC form and, like most other devices, are available in CMOS and in bipolar (TTL) logic families.

Also, you will learn how VHDL is used to describe the types of flip-flops.

IMPLEMENTATION: D FLIP-FLOP



Fixed-Function Device The 74HC74 dual D flip-flop contains two identical D flip-flops that are independent of each other except for sharing $V_{\rm CC}$ and ground. The flip-flops are positive edge-triggered and have active-LOW asynchronous preset and clear inputs. The logic symbols for the individual flip-flops within the package are shown in Figure 7–28(a), and an ANSI/IEEE standard single block symbol that represents the entire device is shown in part (b). The pin numbers are shown in parentheses.

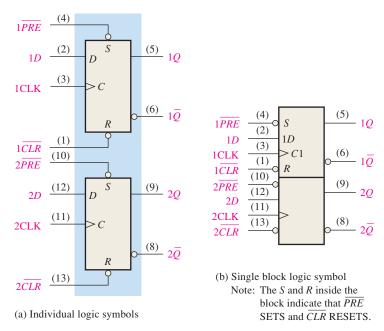


FIGURE 7-28 The 74HC74 dual positive edge-triggered D flip-flop.

Programmable Logic Device (PLD) The positive edge-triggered D flip-flop can be described using VHDL and implemented as hardware in a PLD. In this program, the behavioral approach will be used for the first time because it lends itself to describing sequential operations. A new VHDL statement, **wait until rising_edge**, is introduced. This statement allows the program to wait for the rising edge of a clock pulse to process the *D* input to create the desired results. Also the **if then else** statement is introduced. The keyword **process** is a block of code placed between the **begin** and **end** statements of the architecture to allow statements to be sequentially processed. The program code for a single D flip-flop is as follows:



```
library ieee;
use ieee.std_logic_1164.all;
                                                                D: Flip-flop input
entity dffl is
                                                                Clock: System clock
  port (D, Clock, Pre, Clr: in std_logic; Q: inout std_logic);
                                                                Pre: Preset input
end entity dffl;
                                                                Clr: Clear input
                                                                Q: Flip-flop output
architecture LogicOperation of dffl is
begin
process
  begin
     wait until rising_edge (Clock);
       if Clr = '1' then
                              Check for Preset and Clear conditions
          if Pre = '1' then
            if D = '1' then
                            Q input follows D input when Clr and Pre inputs
              Q \le '1';
                            are HIGH.
            else
               Q \le 0';
            end if:
          else
            Q <= '1'; Q is set HIGH when Pre input is LOW.
          end if:
       else
          Q \le 0; Q is set LOW when Clr input is LOW.
     end if:
  end process;
end architecture LogicOperation;
```

IMPLEMENTATION: J-K FLIP-FLOP



Fixed-Function Device The 74HC112 dual J-K flip-flop has two identical flip-flops that are negative edge-triggered and have active-LOW asynchronous preset and clear inputs. The logic symbols are shown in Figure 7–29.

Programmable Logic Device (PLD) The negative edge-triggered J-K flip-flop can be described using VHDL and implemented as hardware in a PLD. In this program, the behavioral approach will be used. A new VHDL statement, **if falling edge then,** is introduced. This statement allows the program to wait for the falling edge of a clock pulse

Flip-Flops

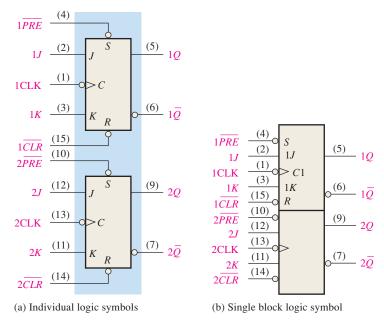


FIGURE 7-29 The 74HC112 dual negative edge-triggered J-K flip-flop.

to process the J and K inputs to create the desired results. The following program code describes a single J-K flip-flop with no preset or clear inputs.

```
library ieee;
use ieee.std_logic_1164.all;
entity JKFlipFlop is
                                                                Inputs and outputs
  port (J, K, Clock: in std_logic; Q, QNot: inout std_logic);
                                                                declared
end entity JKFlipFlop;
architecture LogicOperation of JKFlipFlop is
signal J1, K1: std_logic;
begin
process (J, K, Clock, J1, K1, Q, QNot)
  begin
    if falling_edge(Clock) and Clock = '0' then
                                                  Identifies with Boolean expressions
       J1 <= not (J and not Clock and QNot);
                                                  the inputs (J1 and K1) to the latch
       K1 \le not (K and not Clock and Q);
                                                  portion of the flip-flop
    end if:
       Q <= J1 nand QNot;
                               Defines the outputs in terms of J1 and
     QNot \le K1 \text{ nand } Q;
                              K1 with Boolean expressions
end process:
```

EXAMPLE 7-8

The 1*J*, 1*K*, 1CLK, 1 \overline{PRE} , and 1 \overline{CLR} waveforms in Figure 7–30(a) are applied to one of the negative edge-triggered flip-flops in a 74HC112 package. Determine the 1*Q* output waveform.

end architecture LogicOperation;

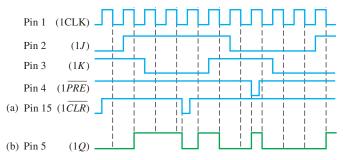


FIGURE 7-30

Solution

The resulting 1Q waveform is shown in Figure 7–30(b). Notice that each time a LOW is applied to the $1\overline{PRE}$ or $1\overline{CLR}$, the flip-flop is set or reset regardless of the states of the other inputs.

Related Problem

Determine the 1Q output waveform if the waveforms for $1\overline{PRE}$ and $1\overline{CLR}$ are interchanged.

SECTION 7-2 CHECKUP

- **1.** Describe the main difference between a gated D latch and an edge-triggered D flip-flop.
- 2. How does a J-K flip-flop differ from a D flip-flop in its basic operation?
- **3.** Assume that the flip-flop in Figure 7–22 is negative edge-triggered. Describe the output waveform for the same CLK and *D* waveforms.

7–3 Flip-Flop Operating Characteristics

The performance, operating requirements, and limitations of flip-flops are specified by several operating characteristics or parameters found on the data sheet for the device. Generally, the specifications are applicable to all CMOS and bipolar (TTL) flip-flops.

After completing this section, you should be able to

- Define propagation delay time
- Explain the various propagation delay time specifications
- Define set-up time and discuss how it limits flip-flop operation
- Define hold time and discuss how it limits flip-flop operation
- Discuss the significance of maximum clock frequency
- Discuss the various pulse width specifications
- Define *power dissipation* and calculate its value for a specific device
- Compare various series of flip-flops in terms of their operating parameters

Propagation Delay Times

A **propagation delay time** is the interval of time required after an input signal has been applied for the resulting output change to occur. Four categories of propagation delay times are important in the operation of a flip-flop:

- 1. Propagation delay t_{PLH} as measured from the triggering edge of the clock pulse to the LOW-to-HIGH transition of the output. This delay is illustrated in Figure 7–31(a).
- 2. Propagation delay t_{PHL} as measured from the triggering edge of the clock pulse to the HIGH-to-LOW transition of the output. This delay is illustrated in Figure 7–31(b).

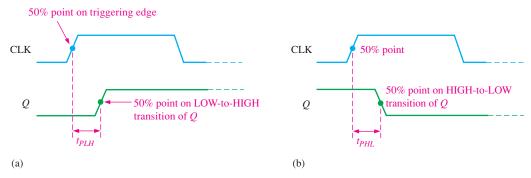


FIGURE 7-31 Propagation delays, clock to output.

- **3.** Propagation delay t_{PLH} as measured from the leading edge of the preset input to the LOW-to-HIGH transition of the output. This delay is illustrated in Figure 7–32(a) for an active-LOW preset input.
- **4.** Propagation delay t_{PHL} as measured from the leading edge of the clear input to the HIGH-to-LOW transition of the output. This delay is illustrated in Figure 7–32(b) for an active-LOW clear input.

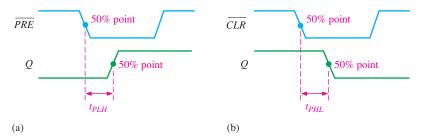


FIGURE 7-32 Propagation delays, preset input to output and clear input to output.

Set-up Time

The **set-up time** (t_s) is the minimum interval required for the logic levels to be maintained constantly on the inputs (J and K, or D) prior to the triggering edge of the clock pulse in order for the levels to be reliably clocked into the flip-flop. This interval is illustrated in Figure 7–33 for a D flip-flop.

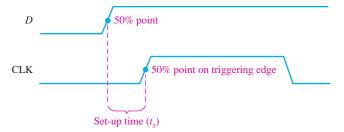


FIGURE 7–33 Set-up time (t_s). The logic level must be present on the D input for a time equal to or greater than t_s before the triggering edge of the clock pulse for reliable data entry.

Hold Time

The **hold time** (t_h) is the minimum interval required for the logic levels to remain on the inputs after the triggering edge of the clock pulse in order for the levels to be reliably clocked into the flip-flop. This is illustrated in Figure 7–34 for a D flip-flop.

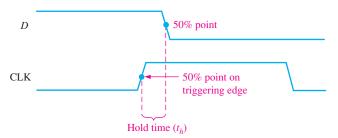


FIGURE 7–34 Hold time (t_h) . The logic level must remain on the D input for a time equal to or greater than t_h after the triggering edge of the clock pulse for reliable data entry.

Maximum Clock Frequency

The maximum clock frequency (f_{max}) is the highest rate at which a flip-flop can be reliably triggered. At clock frequencies above the maximum, the flip-flop would be unable to respond quickly enough, and its operation would be impaired.

Pulse Widths

Minimum pulse widths (t_W) for reliable operation are usually specified by the manufacturer for the clock, preset, and clear inputs. Typically, the clock is specified by its minimum HIGH time and its minimum LOW time.

Power Dissipation

The **power dissipation** of any digital circuit is the total power consumption of the device. For example, if the flip-flop operates on a +5 V dc source and draws 5 mA of current, the power dissipation is

$$P = V_{CC} \times I_{CC} = 5 \text{ V} \times 5 \text{ mA} = 25 \text{ mW}$$

The power dissipation is very important in most applications in which the capacity of the dc supply is a concern. As an example, let's assume that you have a digital system that requires a total of ten flip-flops, and each flip-flop dissipates 25 mW of power. The total power requirement is

$$P_{\rm T} = 10 \times 25 \,\text{mW} = 250 \,\text{mW} = 0.25 \,\text{W}$$



An advantage of CMOS is that it can operate over a wider range of dc supply voltages (typically 2 V to 6 V) than bipolar and, therefore, less expensive power supplies that do not have precise regulation can be used. Also, batteries can be used as secondary or primary sources for CMOS circuits. In addition, lower voltages mean that the IC dissipates less power. The drawback is that the performance of CMOS is degraded with lower supply voltages. For example, the guaranteed maximum clock frequency of a CMOS flip-flop is much less at $V_{\rm CC}=2$ V than at $V_{\rm CC}=6$ V.

This tells you the output capacity required of the dc supply. If the flip-flops operate on +5 V dc, then the amount of current that the supply must provide is

$$I = \frac{250 \text{ mW}}{5 \text{ V}} = 50 \text{ mA}$$

You must use a +5 V dc supply that is capable of providing at least 50 mA of current.

Comparison of Specific Flip-Flops

Table 7–4 provides a comparison, in terms of the operating parameters discussed in this section, of four CMOS and bipolar (TTL) flip-flops of the same type but with different IC families (HC, AHC, LS, and F).

TABLE 7-4

Comparison of operating parameters for four IC families of flip-flops of the same type at 25°C.

	CMOS		Bipolar (TTL)	
Parameter	74HC74A	74AHC74	74LS74A	74F74
t_{PHL} (CLK to Q)	17 ns	4.6 ns	40 ns	6.8 ns
t_{PLH} (CLK to Q)	17 ns	4.6 ns	25 ns	8.0 ns
$t_{PHL}(\overline{CLR} \text{ to } Q)$	18 ns	4.8 ns	40 ns	9.0 ns
$t_{PLH}(\overline{PRE} \text{ to } Q)$	18 ns	4.8 ns	25 ns	6.1 ns
t_s (set-up time)	14 ns	5.0 ns	20 ns	2.0 ns
t_h (hold time)	3.0 ns	0.5 ns	5 ns	1.0 ns
t_W (CLK HIGH)	10 ns	5.0 ns	25 ns	4.0 ns
t_W (CLK LOW)	10 ns	5.0 ns	25 ns	5.0 ns
$t_W(\overline{CLR}/\overline{PRE})$	10 ns	5.0 ns	25 ns	4.0 ns
f_{\max}	35 MHz	170 MHz	25 MHz	100 MHz
Power, quiescent	0.012 mW	1.1 mW		
Power, 50% duty cycle			44 mW	88 mW

SECTION 7-3 CHECKUP

- 1. Define the following:
 - (a) set-up time
- (b) hold time
- 2. Which specific flip-flop in Table 7–4 can be operated at the highest frequency?

7–4 Flip-Flop Applications

In this section, three general applications of flip-flops are discussed to give you an idea of how they can be used. In Chapters 8 and 9, flip-flop applications in registers and counters are covered in detail.

After completing this section, you should be able to

- Discuss the application of flip-flops in data storage
- Describe how flip-flops are used for frequency division
- Explain how flip-flops are used in basic counter applications

Parallel Data Storage

A common requirement in digital systems is to store several bits of data from parallel lines simultaneously in a group of flip-flops. This operation is illustrated in Figure 7–35(a) using four flip-flops. Each of the four parallel data lines is connected to the D input of a flip-flop. The clock inputs of the flip-flops are connected together, so that each flip-flop is triggered by the same clock pulse. In this example, positive edge-triggered flip-flops are used, so the data on the D inputs are stored simultaneously by the flip-flops on the positive edge of the clock, as indicated in the timing diagram in Figure 7–35(b). Also, the asynchronous reset (R) inputs are connected to a common \overline{CLR} line, which initially resets all the flip-flops.

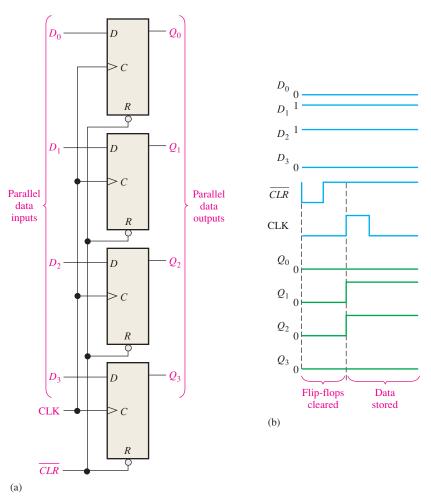


FIGURE 7-35 Example of flip-flops used in a basic register for parallel data storage.

This group of four flip-flops is an example of a basic register used for data storage. In digital systems, data are normally stored in groups of bits (usually eight or multiples thereof) that represent numbers, codes, or other information. Registers are covered in Chapter 8.

Frequency Division

Another application of a flip-flop is dividing (reducing) the frequency of a periodic waveform. When a pulse waveform is applied to the clock input of a D or J-K flip-flop that is connected to toggle ($D = \overline{Q}$ or J = K = 1), the Q output is a square wave with one-half the frequency of the clock input. Thus, a single flip-flop can be applied as a divide-by-2 device, as is illustrated in Figure 7–36 for both a D and a J-K flip-flop. As you can see in part (c), the flip-flop changes state on each triggering clock edge (positive edge-triggered in this case). This results in an output that changes at half the frequency of the clock waveform.

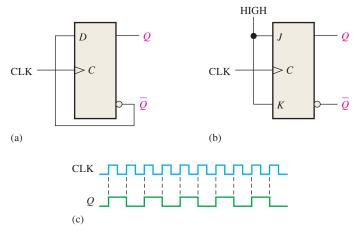


FIGURE 7–36 The D flip-flop and J-K flip-flop as a divide-by-2 device. *Q* is one-half the frequency of CLK. Open file F07-36 and verify the operation.



Further division of a clock frequency can be achieved by using the output of one flip-flop as the clock input to a second flip-flop, as shown in Figure 7–37. The frequency of the Q_A output is divided by 2 by flip-flop B. The Q_B output is, therefore, one-fourth the frequency of the original clock input. Propagation delay times are not shown on the timing diagrams.

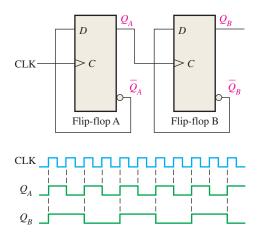


FIGURE 7-37 Example of two D flip-flops used to divide the clock frequency by 4. Q_A is one-half and Q_B is one-fourth the frequency of CLK. Open file F07-37 and verify the operation.



By connecting flip-flops in this way, a frequency division of 2^n is achieved, where n is the number of flip-flops. For example, three flip-flops divide the clock frequency by $2^3 = 8$; four flip-flops divide the clock frequency by $2^4 = 16$; and so on.

EXAMPLE 7-9

Develop the f_{out} waveform for the circuit in Figure 7–38 when an 8 kHz square wave input is applied to the clock input of flip-flop A.

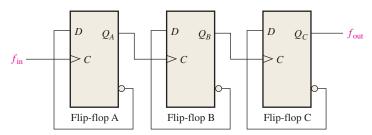


FIGURE 7-38

Solution

The three flip-flops are connected to divide the input frequency by eight $(2^3 = 8)$ and the $Q_C(f_{out})$ waveform is shown in Figure 7–39. Since these are positive edge-triggered flip-flops, the outputs change on the positive-going clock edge. There is one output pulse for every eight input pulses, so the output frequency is 1 kHz. Waveforms of Q_A and Q_B are also shown.

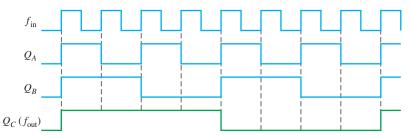


FIGURE 7-39

Related Problem

How many flip-flops are required to divide a frequency by thirty-two?

Counting

Another important application of flip-flops is in digital counters, which are covered in detail in Chapter 9. The concept is illustrated in Figure 7–40. Negative edge-triggered J-K flip-flops are used for illustration. Both flip-flops are initially RESET. Flip-flop A toggles on the negative-going transition of each clock pulse. The Q output of flip-flop A clocks flip-flop B, so each time Q_A makes a HIGH-to-LOW transition, flip-flop B toggles. The resulting Q_A and Q_B waveforms are shown in the figure.

Observe the sequence of Q_A and Q_B in Figure 7–40. Prior to clock pulse 1, $Q_A = 0$ and $Q_B = 0$; after clock pulse 1, $Q_A = 1$ and $Q_B = 0$; after clock pulse 2, $Q_A = 0$ and $Q_B = 1$; and after clock pulse 3, $Q_A = 1$ and $Q_B = 1$. If we take Q_A as the least significant bit, a 2-bit sequence is produced as the flip-flops are clocked. This binary sequence repeats every four clock pulses, as shown in the timing diagram of Figure 7–40. Thus, the flip-flops are counting in sequence from 0 to 3 (00, 01, 10, 11) and then recycling back to 0 to begin the sequence again.

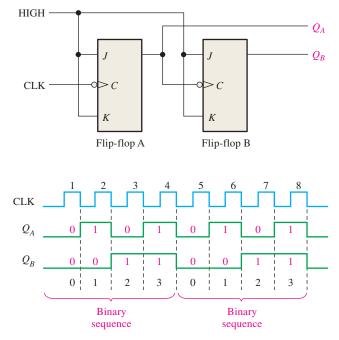
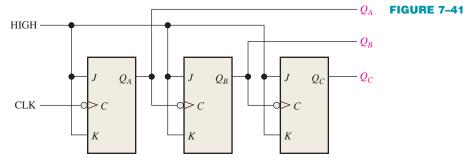


FIGURE 7-40 J-K flip-flops used to generate a binary count sequence (00, 01, 10, 11). Two repetitions are shown.

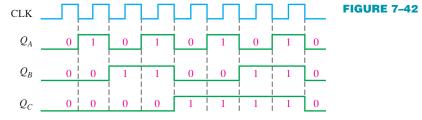
EXAMPLE 7-10

Determine the output waveforms in relation to the clock for Q_A , Q_B , and Q_C in the circuit of Figure 7–41 and show the binary sequence represented by these waveforms.



Solution

The output timing diagram is shown in Figure 7–42. Notice that the outputs change on the negative-going edge of the clock pulses. The outputs go through the binary sequence 000, 001, 010, 011, 100, 101, 110, and 111 as indicated.



Related Problem

How many flip-flops are required to produce a binary sequence representing decimal numbers 0 through 15?

SECTION 7-4 CHECKUP

- 1. What is a group of flip-flops used for data storage called?
- 2. How must a D flip-flop be connected to function as a divide-by-2 device?
- 3. How many flip-flops are required to produce a divide-by-64 device?

7–5 One-Shots

The **one-shot**, also known as a **monostable** multivibrator, is a device with only one stable state. A one-shot is normally in its stable state and will change to its unstable state only when triggered. Once it is triggered, the one-shot remains in its unstable state for a predetermined length of time and then automatically returns to its stable state. The time that the device stays in its unstable state determines the pulse width of its output.

After completing this section, you should be able to

- Describe the basic operation of a one-shot
- Explain how a nonretriggerable one-shot works
- Explain how a retriggerable one-shot works
- Set up the 74121 and the 74LS122 one-shots to obtain a specified output pulse width
- Recognize a Schmitt trigger symbol and explain basically what it means
- Describe the basic elements of a 555 timer
- Set up a 555 timer as a one-shot

A one-shot produces a single pulse each time it is triggered.

Figure 7–43 shows a basic one-shot (monostable multivibrator) that is composed of a logic gate and an inverter. When a pulse is applied to the **trigger** input, the output of gate G_1 goes LOW. This HIGH-to-LOW transition is coupled through the capacitor to the input of inverter G_2 . The apparent LOW on G_2 makes its output go HIGH. This HIGH is connected back into G_1 , keeping its output LOW. Up to this point the trigger pulse has caused the output of the one-shot, Q, to go HIGH.

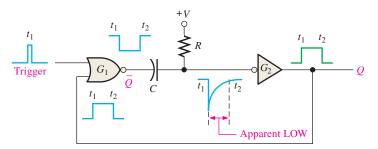


FIGURE 7-43 A simple one-shot circuit.

The capacitor immediately begins to charge through R toward the high voltage level. The rate at which it charges is determined by the RC time constant. When the capacitor charges to a certain level, which appears as a HIGH to G_2 , the output goes back LOW.

To summarize, the output of inverter G_2 goes HIGH in response to the trigger input. It remains HIGH for a time set by the RC time constant. At the end of this time, it goes LOW. A single narrow trigger pulse produces a single output pulse whose time duration is controlled by the RC time constant. This operation is illustrated in Figure 7–43.