# Small post processor

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## 2. Clear complete workspace

For new Matlab projects best practise is to clear the complete workspace and the command window. It is also a good habit to close all remaining figures since Matlab does not automatically open a new window each time a plot call is invoked.

```
path('./functions',path) % add functions directory the Matlab path
[datadir,flag]=ClearWs();
```

The above mentioned clears are performed in the function ClearWs. In addition some basic parameters like the name of the data directory or the dimensionality of the problem are also defined.

```
function [datadir,flag]=ClearWs()
close all
clear all
clc

datadir='data'; % specify the directory containg the data
flag='3D'; % specify the subdirectory of data
end
```

### 3. Read data files

During the evaluation of the function ReadData all data files neseccary for the calculation of the spectrum and the correlation coefficients are read, namely the velocity components. In addition the import operations are enclosed in a tic;... ; toc block measuring the time needed for reading the ASCII data. What you should get from the tic/toc block is that most of the time is spend during data I/O (Input/Output operations), nearly 220 s. The actual computation needs only about 8 s. What you can easily calculate from this is that the computation of the spectrum is nearly 27 times faster then the data import. Why the computation of Fourier transforms is that fast we will come to that later. Although the ASCII data format ist not the prefered choice in terms of speed and size, we will use it since other methodologies require additional knowledge of data processing. Just for your information a very famous and highly protable data format is hdf5. It is a software library that runs on a range of computational platforms, from laptops to massively parallel systems and implements a high-level API (Application programming interface) with C, C++, Fortran 90, and Java interfaces. Besides its hierarchical structure it is highly optimized for parallel I/O operations and can be read by nearly all data processing tools.

```
property is a send of the content of the conte
```

# 4. Set neccessary parameters

For further computations it is important to define some parmeters of the DNS simulation such as

- Number of grid points in on direction  $n_p$ ,
- Physical length of one direction  $L_x$ ,
- Physical grid spacing  $\triangle x$ ,
- Kinematic viscosity  $\nu$ .

```
1 [u,v,w,dim,Lx,dx,nu]=Params(uvel,vvel,wvel);
```

```
function [u, v, w, dim, Lx, dx, nu] = Params (uvel, vvel, wvel)
       dim=256; % number of points in one dimension
       Lx=5e-3; % domain size
3
       Lv=Lx;
       Lz=Lx:
       dx=Lx/dim; % grid spacing
       dy=dx;
       dz=dx:
        nu=1.7e-5; % viscosity
        u=reshape (uvel, dim, dim, dim); % reshape arrays to have them in 3D
10
11
        v=reshape (vvel, dim, dim, dim);
12
        w=reshape (wvel, dim, dim, dim);
        clear uvel vvel wvel
13
```

### 5. Compute 3D spectrum

The core of the provided code is contained in the function **PowerSpec**. It computes the three dimensional energy spectrum from the given velocity fields, obtained from a direct numerical simulation. Although the theoretical analysis is relatively demanding compared to one dimensional spectra its worth investing the effort. The theory of one dimensional spectra relies on the assumption that the propagation of spectral waves  $(\kappa_1)$  is in the direction of the observed velocity fields or to say it differently one dimensional spectra and correlation functions are Fourier transform pairs. The theory of correlation functions will be discussed in a later section. A key drawback of this theory is that the calculated spectrum has contributions from all wavenumbers  $\kappa$ , so that the magnitude of  $\kappa$  can be appreciably larger than  $\kappa_1$ . This phenomenon is called aliasing.

In order to avoid aliasing effects usually connected with a one dimensional spectrum it is also possible to produce correlations that involve all possible directions. The three dimensional Fourier transformation of such a correlation produces a spectrum that not only depends on a single wavenumber but on the wavenumber vector  $\kappa_i$ . Though the directional information contained in  $\kappa_i$  eliminates the aliasing problem the complexity makes a physical reasoning impossible. For homogeneous isotropic turbulence the situation can be simplified by integrating the three dimensional spectrum over spherical shells. The idea of this integration is illustrated in Fig. 1

$$E(\kappa) = \iint E(\kappa) dS(\kappa) = \iint \frac{1}{2} Phi_{ii}(\kappa) dS(\kappa)$$
 (1)

Since the surface of a sphere is completely determined by its radius the surface integral can be solved analytically.

$$\oint ()dS(\kappa) = 4\pi\kappa^2 \cdot ()$$
(2)

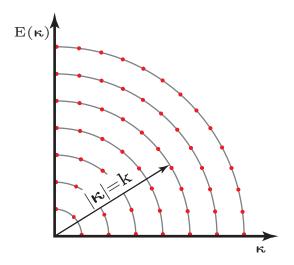


Fig. 1: Illustration of two dimensional shell integration

This leads to

$$E(|\kappa|) = \frac{1}{2} \Phi_{ii}(|\kappa|) \tag{3}$$

1 [spectrum,k,mu,mv,mw,time\_spec] = PowerSpec(u,v,w,Lx);

The content of PowerSpec reads

```
function [spectrum, k, mu, mv, mw, time] = power_spec(u, v, w, L)
   % nx = size(u,1);
   % ny = size(u, 2);
5 tic;
  NFFT = 2.^nextpow2(size(u)); % next power of 2 fitting the length of u
  u_fft=fftn(u,NFFT);
  v_fft=fftn(v,NFFT);
9
   w_fft=fftn(w,NFFT);
10
11
   NumUniquePts = ceil((NFFT(1)+1)/2);
^{12}
13
   % FFT is symmetric, throw away second half
14
  u_fft = u_fft(1:NumUniquePts,1:NumUniquePts,1:NumUniquePts);
15
   v_fft = v_fft(1:NumUniquePts,1:NumUniquePts,1:NumUniquePts);
   w_fft = w_fft(1:NumUniquePts,1:NumUniquePts);
17
mu = abs(u_fft)/length(u)^3;
  mv = abs(v_fft)/length(v)^3;
20
  mw = abs(w_fft)/length(w)^3;
```

```
22
24 mu = mu.^2;
25 \text{ mv} = \text{mv.}^2;
26 \text{ mw} = \text{mw.}^2;
27
   \$ The Nyquist component, if it exists, is unique and should not be multiplied by 2.
29
31
   if rem(NFFT, 2) % odd nfft excludes Nyquist point
      mu(2:end, 2:end, 2:end) = mu(2:end, 2:end, 2:end) *2;
32
      mv(2:end, 2:end, 2:end) = mv(2:end, 2:end, 2:end) *2;
33
     mw(2:end, 2:end, 2:end) = mw(2:end, 2:end, 2:end) *2;
34
35
   else
      mu(2:end -1, 2:end -1, 2:end -1) = mu(2:end -1, 2:end -1, 2:end -1) *2;
36
      mv(2:end -1, 2:end -1, 2:end -1) = mv(2:end -1, 2:end -1, 2:end -1) *2;
37
     mw(2:end -1, 2:end -1, 2:end -1) = mw(2:end -1, 2:end -1, 2:end -1) *2;
38
   end
39
   \ensuremath{\text{%}} Compute the radius vector along which the energies are sumed
   mx=NumUniquePts;
41
42
   my=NumUniquePts;
   mz=NumUniquePts;
43
44
45 dx=pi/L;
   dy=pi/L;
46
47
   dz=pi/L;
   for I=1:mx
48
           XO(I) = (I) * dx;
49
50
   end
51
52
   for J=1:my
           Y0(J) = (J) * dy;
53
54
55
   for K=1:mz
56
57
            ZO(K) = (K) * dz;
   end
58
59
   for I=1:mx
60
61
        for J=1:my
62
             for K=1:mz
                 R(I,J,K) = \mathbf{sqrt}(X0(I) * X0(I) + Y0(J) * Y0(J) + Z0(K) * Z0(K));
63
64
             end
        end
65
   end
66
67
   % P=mod(nx,2);
68
69
   % if (P < 1)
70
71
        Nmax=mx;
72
73
74 spectrum=zeros(Nmax,1);
   for N=1:Nmax
75
76
        Radius1=sqrt(3) * (N-1) *dx; %lower radius bound
        Radius2=sqrt(3) *N*dx; %upper radius bound
77
78
```

```
1 logical = (Radius1 <= R(:,:,:)) & (R(:,:,:) < Radius2);
8 build summation over shell components
1    T_EVP1=sum(mu(logical))+sum(mv(logical))+sum(mw(logical));
8 put them at position N in the spectrum
8 spectrum(N)=T_EVP1./2;
8 end
8 k=[1:Nmax].*dx;
8 spectrum = 1./(2*pi)^3.*spectrum;
8 time=toc;
8 end</pre>
```

## 6. Compute dissipation and turbulent kinetic energy

```
1 [Dissipation,kin_E_Sp,kin_E_Ph,up] = SpecProp(spectrum,k,nu,u,v,w);
  The content of SpecProp reads
  function [Dissipation, kin_E_Sp, kin_E_Ph, up] = SpecProp(E, k, nu, u, v, w)
      kin_E_Sp = trapz(k, E);
2
      Dissipation = trapz(k,2*nu.*k.^2.*E');
      up = sqrt(1/3*(u.^2+v.^2+w.^2));
4
      kin_E_Ph = sum(sum(3/2*up.^2)))/size(up,1)^3;
  end
  7. Kolmogrov properties
1 [eta,u_eta,tau]=KolmoScale(nu,Dissipation);
  The content of KolmoScale reads
  function [eta,u_eta,tau]=KolmoScale(nu,Dissipation)
      eta = (nu^3/Dissipation)^(1/4);
2
      u_eta = (nu*Dissipation)^(1/4);
3
      tau = (nu/Dissipation)^(1/2);
  end
  8. Compute model spectra
```

1 PlotModelSpec(k, spectrum, Dissipation, up, Lx, eta, nu);

The content of PlotModelSpec reads

```
kd = k (end);
4
       ke = pi/Lx/2;
       A = 1.5:
6
       up = mean2(up);
       VKP1 = A*up^5/Dissipation.*(k./ke).^4./(1+(k./ke).^2).^(17/6).*exp(-3/2*A.*(k./kd).^(4/3));
9
10
       kd = 1./eta;
11
       VKP2 = 1.5*(k./kd).^{(-5/3)}./(Dissipation*nu^{5})^{(-1/4)}.*exp(-1.5*1.5.*(k./kd).^{(4/3)});
12
13
14
       Kolmo=1.5*Dissipation^(2/3)*(k.^(-5/3));
15
16
17
       h=loglog(k, Kolmo, k, VKP1, k, VKP2, k, spectrum);
18
        set(h,'LineWidth',2);
19
20
       h=legend('Kolmogorov','VKP1','VKP2','Computed');
21
22
        set(h, 'Location', 'SouthWest')
   end
23
```

### 9. Compute correlations

Computing a correlation can be a tedious work (requireing tremendeous effort) especially if you have large data sets. From theory it is well known that the multiplication of the transform of a data set and its complex conjugate are an accurate representation of the correlation function. Using the FFT approach this gives an enormeous speed advantage. Since we already computed the veloity correlation tensor we may use this result in order to compute the correlation tensor.

$$R_{ij} = \frac{cov(U_i, U_j)}{\sqrt{\sigma_i^2 \, \sigma_j^2}} = \frac{(u_i' - \mu_i) \, (u_j - \mu_j)}{\sqrt{\sigma_i^2 \, \sigma_j^2}} \tag{4}$$

1 [R11,R22,r,R1,R2,R3]=Correlation(u,v,w,Lx);

The content of Correlation reads

```
function [R11,R22,r,R1,R2,R3]=correlation(u,v,w,Lx)
scaling = 1;
NFFT = 2.^nextpow2(size(u)); % next power of 2 fitting the length of u
u.fft=fftn(u,NFFT)./scaling; %2 pi -> definition of FFT

NFFT = 2.^nextpow2(size(v));
v.fft=fftn(v,NFFT)./scaling;

NFFT = 2.^nextpow2(size(w));
u.fft=fftn(w,NFFT)./scaling;
```

```
Rij_x=(u_fft.*conj(u_fft)); % compute velo. correlation tensor
12
13
       Rij_y=(v_fft.*conj(v_fft));
       Rij_z=(w_fft.*conj(w_fft));
14
15
16
       NFFT = 2.^nextpow2(size(u_fft));
17
       R1=ifftn(Rij_x,NFFT)/std2(u)^2./prod(NFFT);
19
       NFFT = 2.^nextpow2(size(v_fft));
       R2=ifftn(Rij_y,NFFT)/std2(v)^2./prod(NFFT);
21
22
       NFFT = 2.nextpow2(size(w_fft));
23
       R3=ifftn(Rij_z,NFFT)/std2(w)^2./prod(NFFT);
24
25
       R11 = (reshape(R3(1,1,:),NFFT(1),1)+R2(1,:,1)'+R1(:,1,1))/3;
26
27
       R11 = R11(1:size(u_fft)/2+1);
28
       R1_22 = (R1(1,:,1)+R3(1,:,1))/2;
29
30
       R2_22 = (R2(:,1,1)+R3(:,1,1))/2;
        {\tt R3.22 = (reshape(R1(1,1,:),size(u.fft,1),1)+reshape(R2(1,1,:),size(u.fft,1),1))/2; } \\ 
31
32
       R22 = (R1_22'+R2_22+R3_22)/3;
33
       R22 = R22(1:size(u_fft)/2+1);
34
35
       r = linspace(0, Lx/2, size(u_fft, 1)/2+1)/(Lx/2);
36
37 end
```