

Generative Model

PHYS591000 Spring 2021

The slide is based on:

- MIT 6.S191 [[slide](#)] [[video](#)]
- Lil'Log: [VAE](#), [GAN](#)

Supervised vs Unsupervised Learning

Supervised Learning

Goal: Learn function to map
x (data) to y (label)

Examples:

- Classification
- Regression
- Object Detection
- Semantic segmentation
- ...

Unsupervised Learning

Goal: Learn the hidden or underlying
structure of the data without labels.

Examples:

- Clustering
- Feature extraction
- Dimensionality reduction
- ...

Generative Models

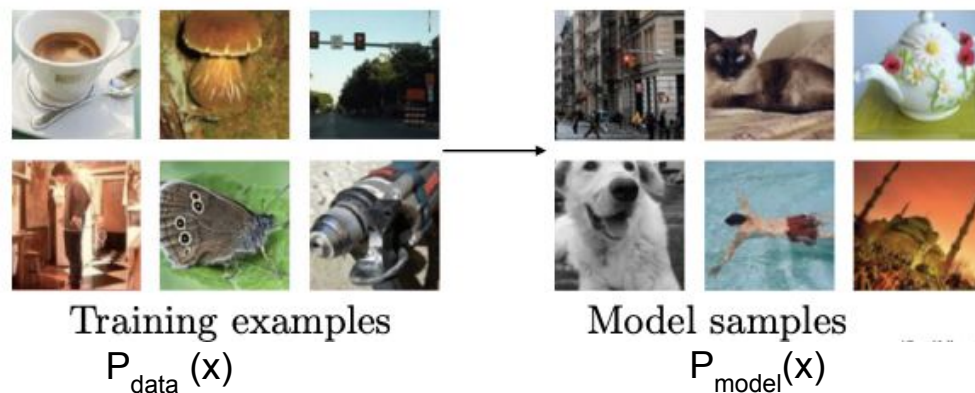
Goal: Take as input training samples from some distribution and learn a model that represent that distribution

Density Estimation



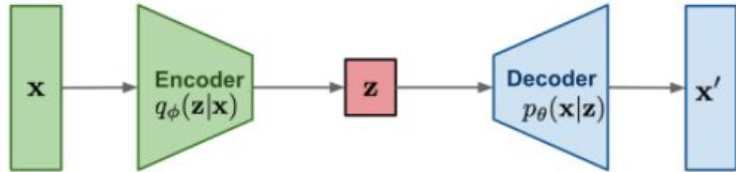
Sample Generation

How can we learn $P_{\text{model}}(x)$ similar to $P_{\text{data}}(x)$?

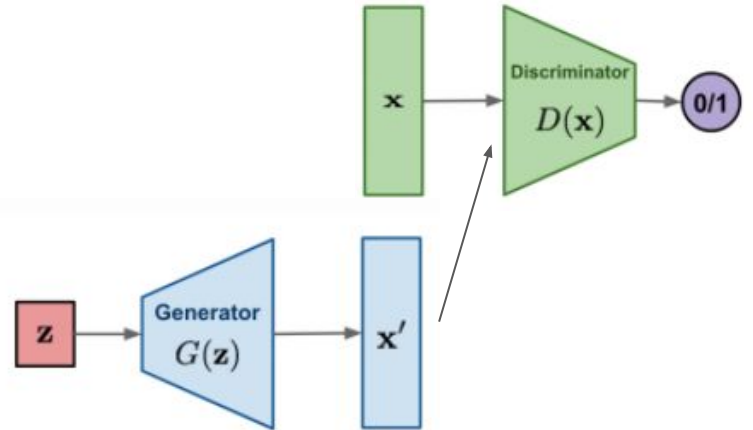


Generative Models

Autoencoders (AE) and
Variational Autoencoders (VAEs)



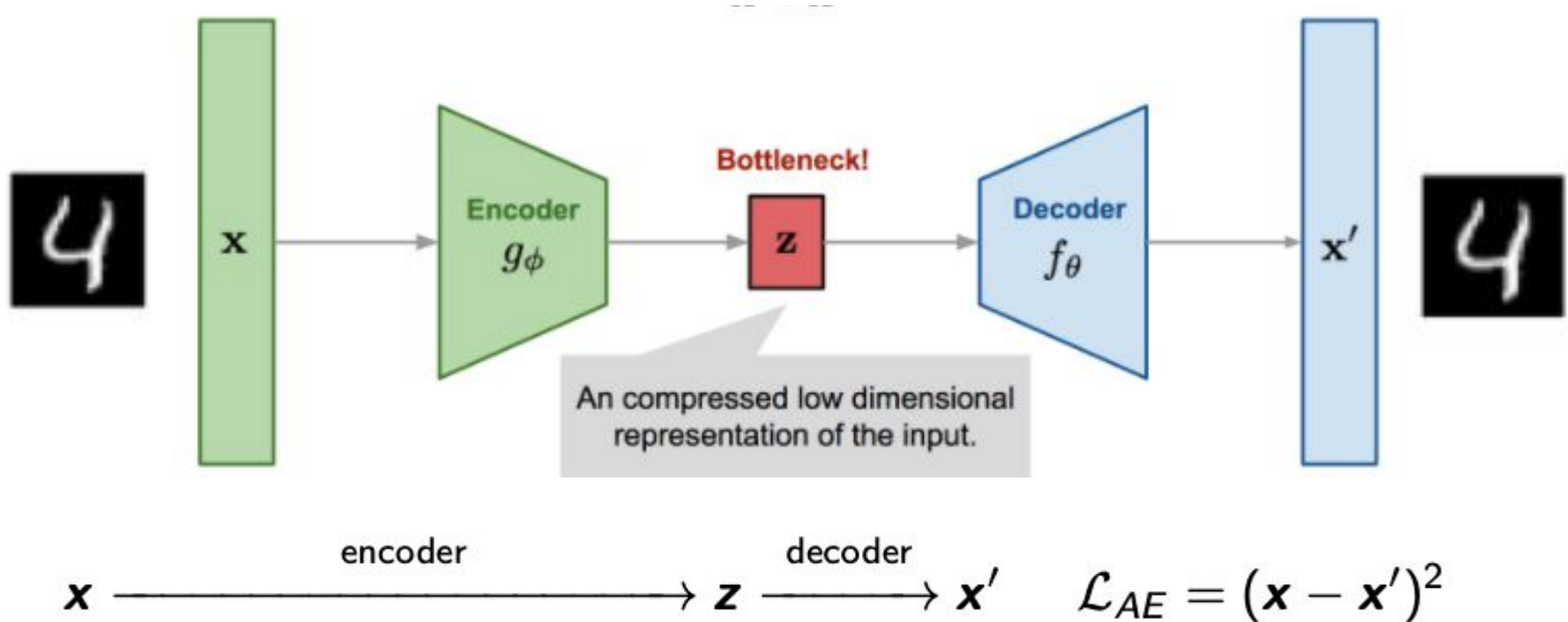
Generative Adversarial Network (GAN)



Autoencoders and Variational Autoencoders

Autoencoder

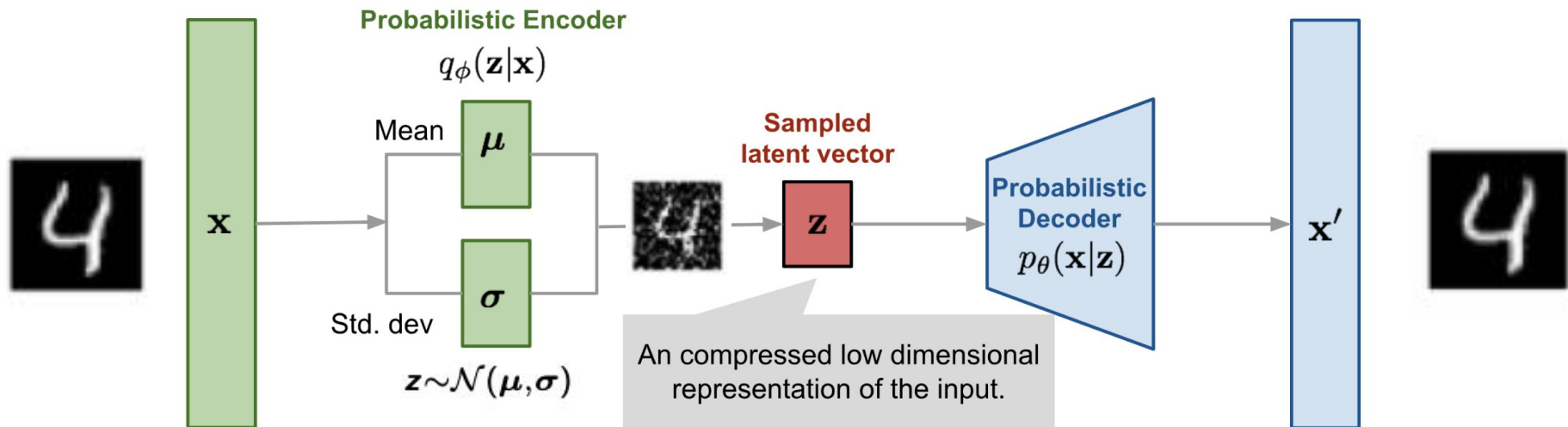
Bottleneck hidden layer: forces network to learn a compressed latent representation



Variational Autoencoders (VAEs)

VAEs are a probabilistic variation on autoencoders?

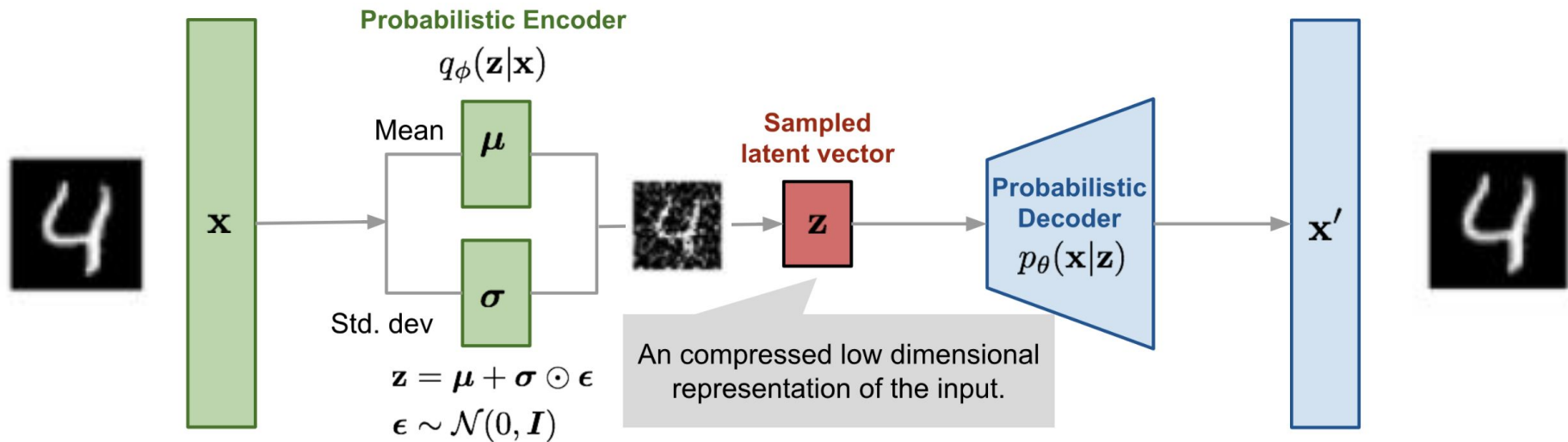
Sample from the mean and standard deviation to compute latent sample



$$\text{VAE: } \mathbf{x} \xrightarrow{\text{encoder}} \begin{pmatrix} \mu \\ \sigma \end{pmatrix} \xrightarrow[\mathbf{z} \sim \mathcal{N}(\mu, \sigma)]{\text{sample}} \mathbf{z} \xrightarrow{\text{decoder}} \mathbf{x}' \quad \mathcal{L}_{\text{VAE}} = \mathcal{L}_{\text{AE}} + \mathcal{L}_{\text{lat}}$$

β -Variational Autoencoders

Parametrization tricks: A fixed μ vector and a fixed σ vector scaled by random constants ϵ drawn from the prior distribution (usually Normal Gaussian)



$$\beta\text{-VAE: } \mathbf{x} \xrightarrow{\text{encoder}} \begin{pmatrix} \mu \\ \sigma \end{pmatrix} \xrightarrow[\mathbf{z} = \mu + \sigma \odot \epsilon]{\text{sample}} \mathbf{z} \xrightarrow{\text{decoder}} \mathbf{x}' \quad \mathcal{L}_{\text{VAE}} = \mathcal{L}_{\text{AE}} + \mathcal{L}_{\text{lat}}$$

β -VAE

Reconstruction Loss Regularization term

$$\beta\text{-VAE: } \mathbf{x} \xrightarrow{\text{encoder}} \begin{pmatrix} \mu \\ \sigma \end{pmatrix} \xrightarrow[\mathbf{z} = \mu + \sigma \odot \varepsilon]{\text{sample}} \mathbf{z} \xrightarrow{\text{decoder}} \mathbf{x}' \quad \mathcal{L}_{VAE} = \boxed{\mathcal{L}_{AE}} + \boxed{\mathcal{L}_{lat}}$$

Loss enforces Gaussian latent space

$$\begin{aligned} \mathcal{L}_{VAE} &= \mathcal{L}_{AE} + \beta \cdot \boxed{\text{KL}(q_{\mathbf{x}}(\mathbf{z}) || \mathcal{N}(0, 1))} \quad \leftarrow \text{similarity measure} \\ &= \mathcal{L}_{AE} + \frac{\beta}{2} \sum_j 1 + \log(\sigma_j^2) - \mu_j^2 - \sigma_j^2 \end{aligned}$$

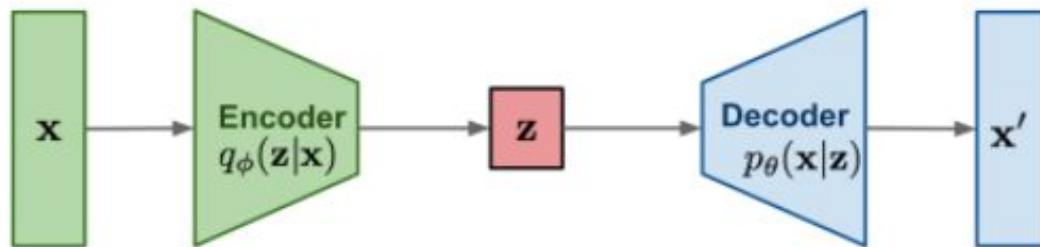
Kullback-Leibler (KL) divergence

- KL is a measure of how one probability distribution is different from a second
- Normal Gaussian encourages encodings to distribute encodings evenly around the center of the latent space

VAE summary

MIT 6.S191

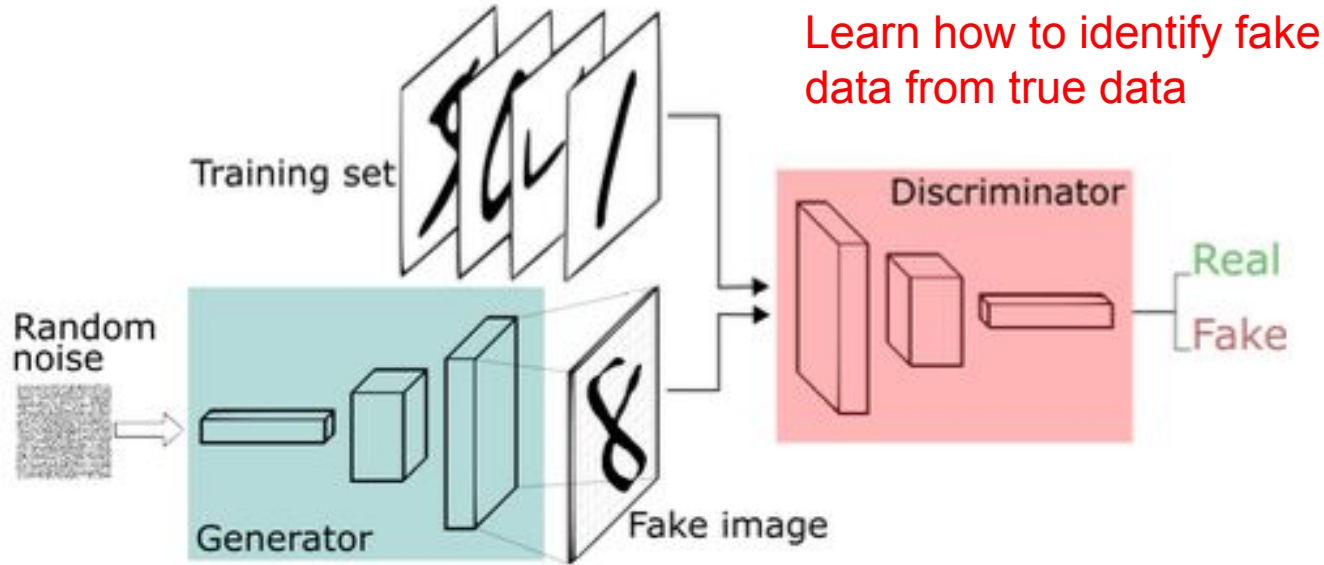
- Compress representation to something we can use to learn
- Reconstruction allows for unsupervised learning (no labels!)
- Reparameterization trick enables training
- Interpret hidden latent variables using perturbation
- Generating new examples



Generative Adversarial Network

Generative Adversarial Networks (GAN)

To make a generative model by having two neural networks compete with each other

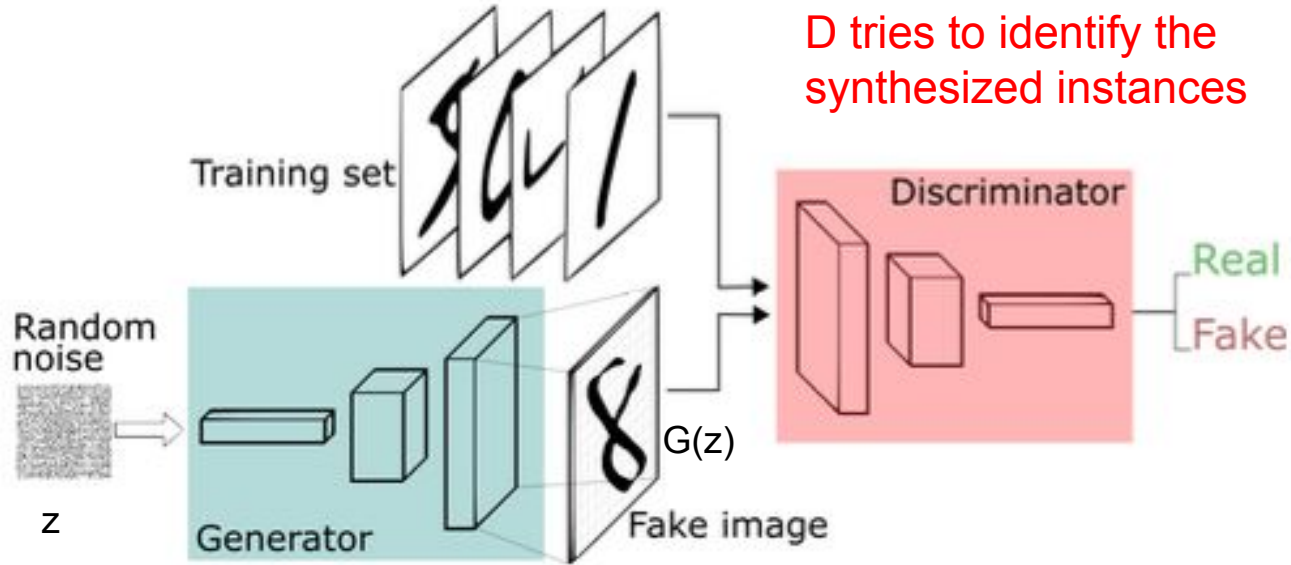


Learn data distribution

Generative Adversarial Networks

Training: adversarial objectives for D and G

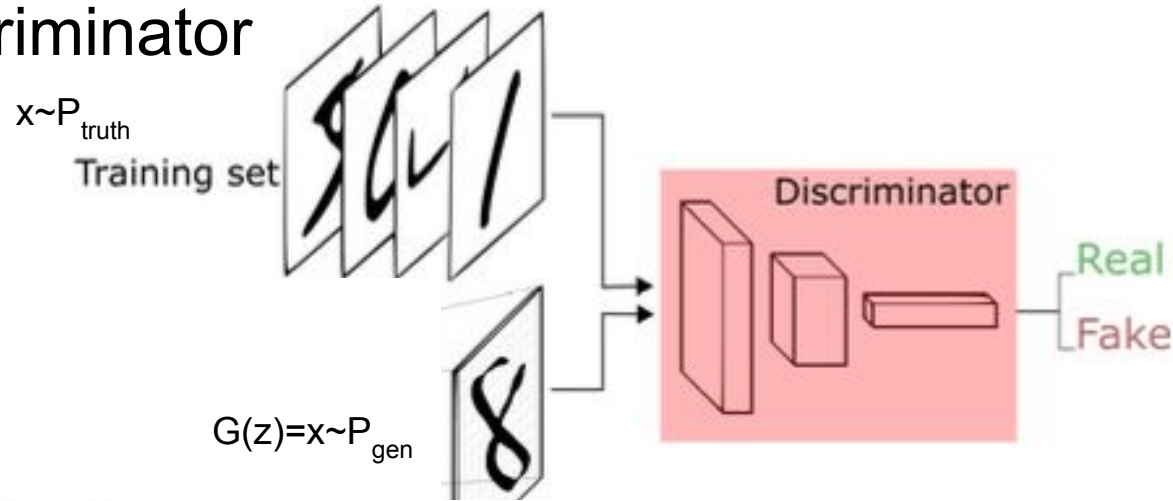
Goal: G reproduces the true data distribution



D tries to identify the synthesized instances

G tries to synthesize fake instances that fool D

Training Discriminator



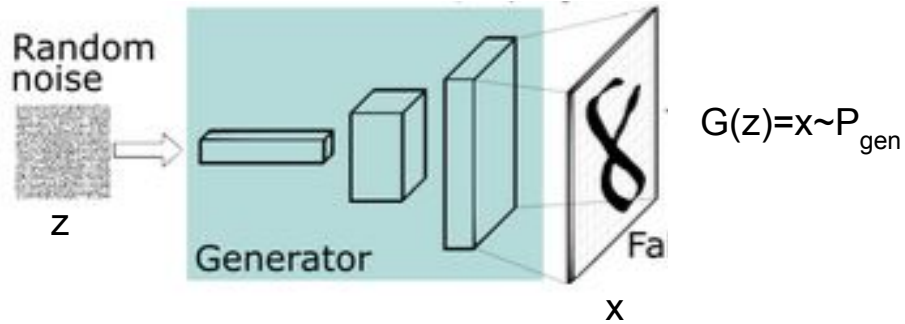
Discriminator

$$\arg \max_D L_D = \langle \log D(x) \rangle_{x \sim P_{\text{Truth}}} + \langle \log(1 - D(x)) \rangle_{x \sim P_{\text{Gen}}}$$

D's decisions over **real data** are accurate

D's output $\langle D(G(z)) \rangle = \langle D(x) \rangle_{x \sim P_{\text{gen}}}$ close to zero over **fake data**

Training Generator

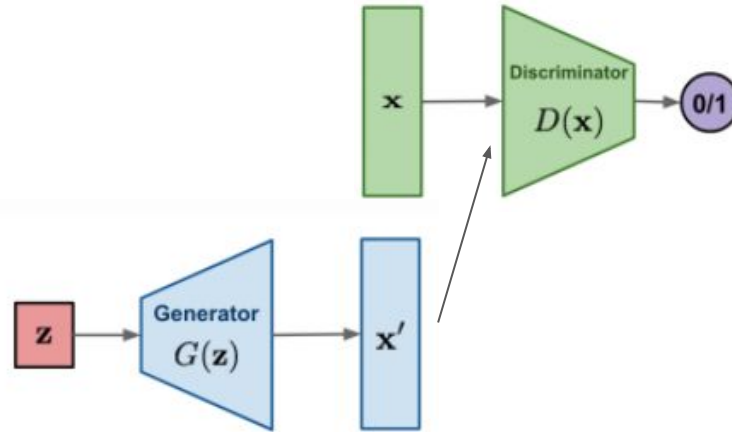


Generator

$$\arg \min_G L_G = \left\langle \log(1 - D(x)) \right\rangle_{x \sim P_{Gen}}$$

G is trained to increase the chance of D producing a high probability for a fake example.

Training: min-max game

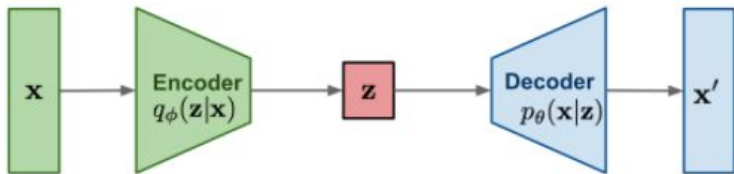


$$\arg \min_G \max_D L_D = \langle \log D(x) \rangle_{x \sim P_{\text{Truth}}} + \langle \log(1 - D(x)) \rangle_{x \sim P_{\text{Gen}}}$$

Generative Models

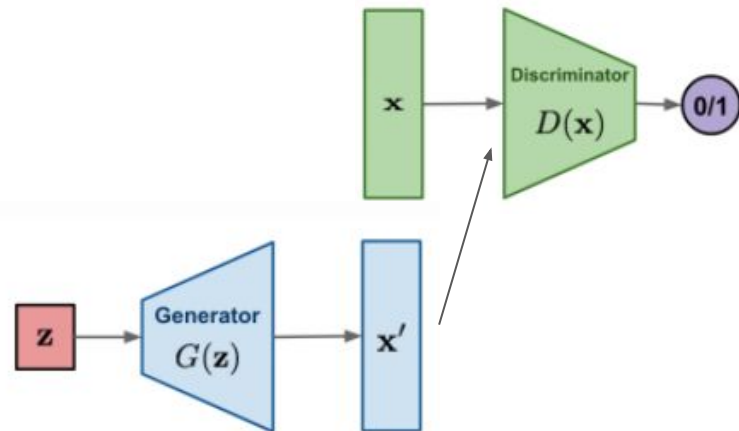
Autoencoders and Variational Autoencoders (VAEs)

Learn lower-dimensional **latent space** and **sample** to generate input reconstructions



Generative Adversarial Network (GAN)

Competing **generator** and **discriminator** networks



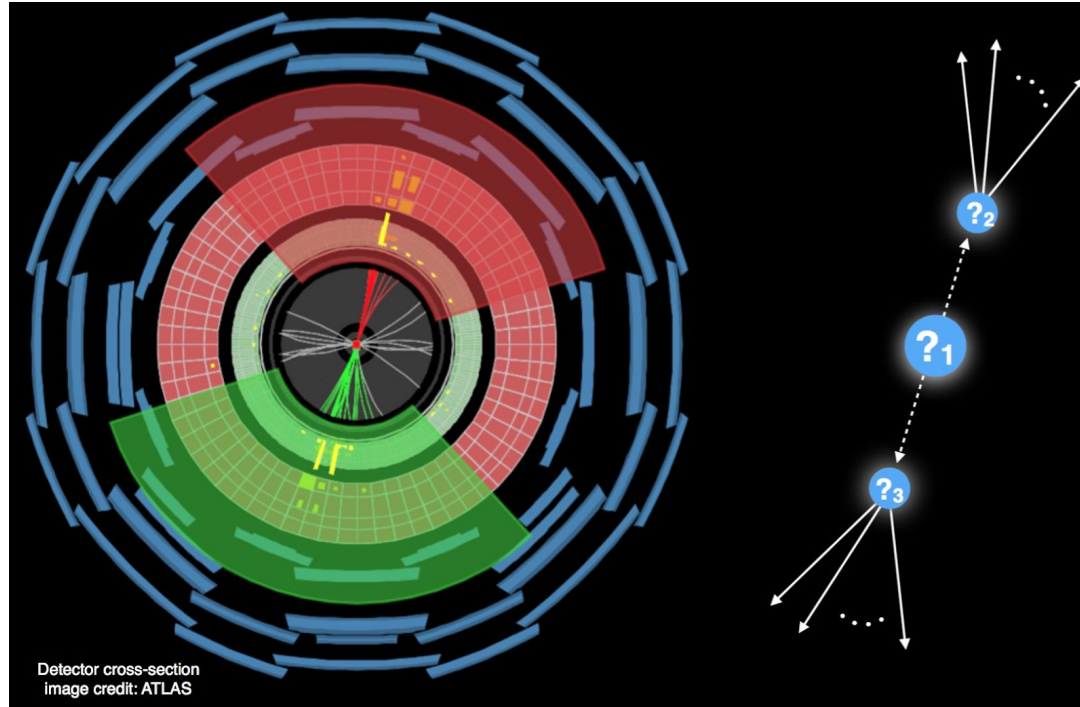
Which face is real?

<https://www.whichfaceisreal.com/methods.html>



Lab this week

Dijet Production



LHCO2020

$pp \rightarrow W' (3.5 \text{ TeV}) \rightarrow X + Y$

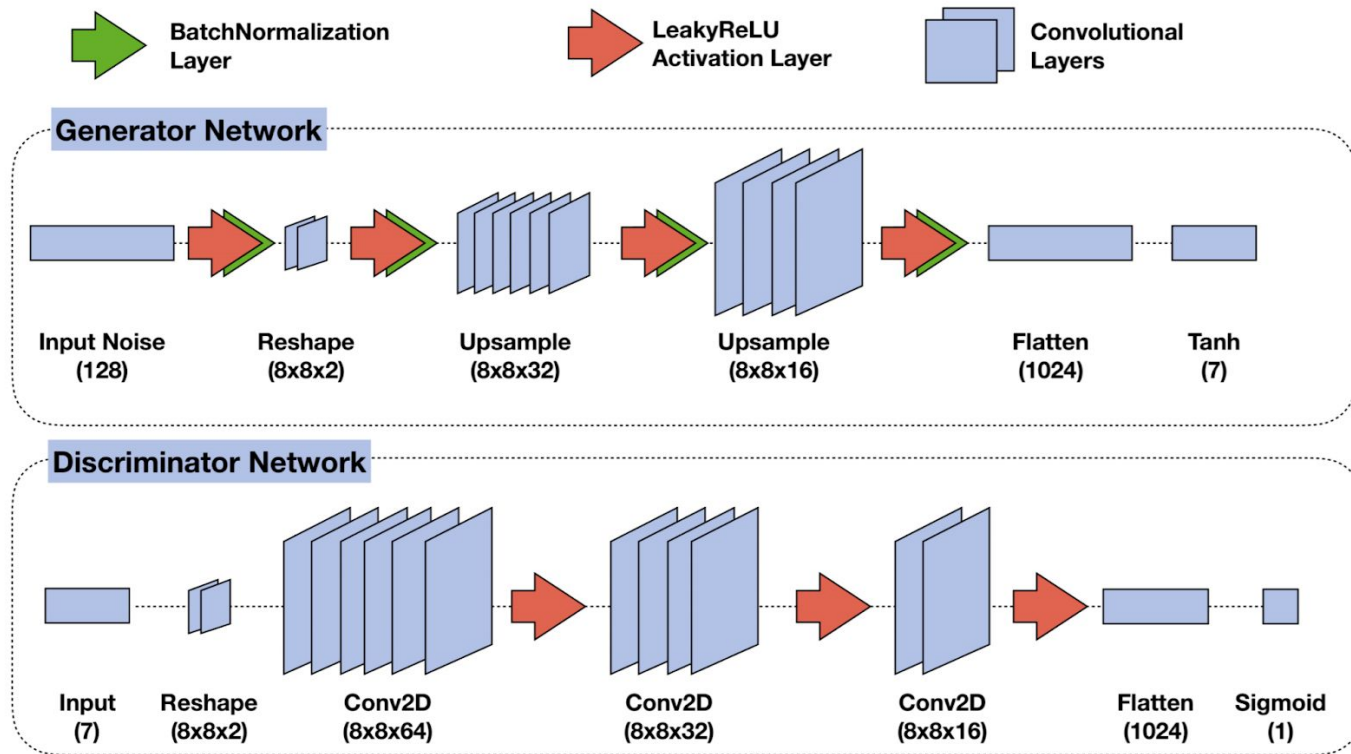
$X \rightarrow qq$ and $Y \rightarrow qq$

$m_X = 500 \text{ GeV}$

$m_Y = 100 \text{ GeV}$

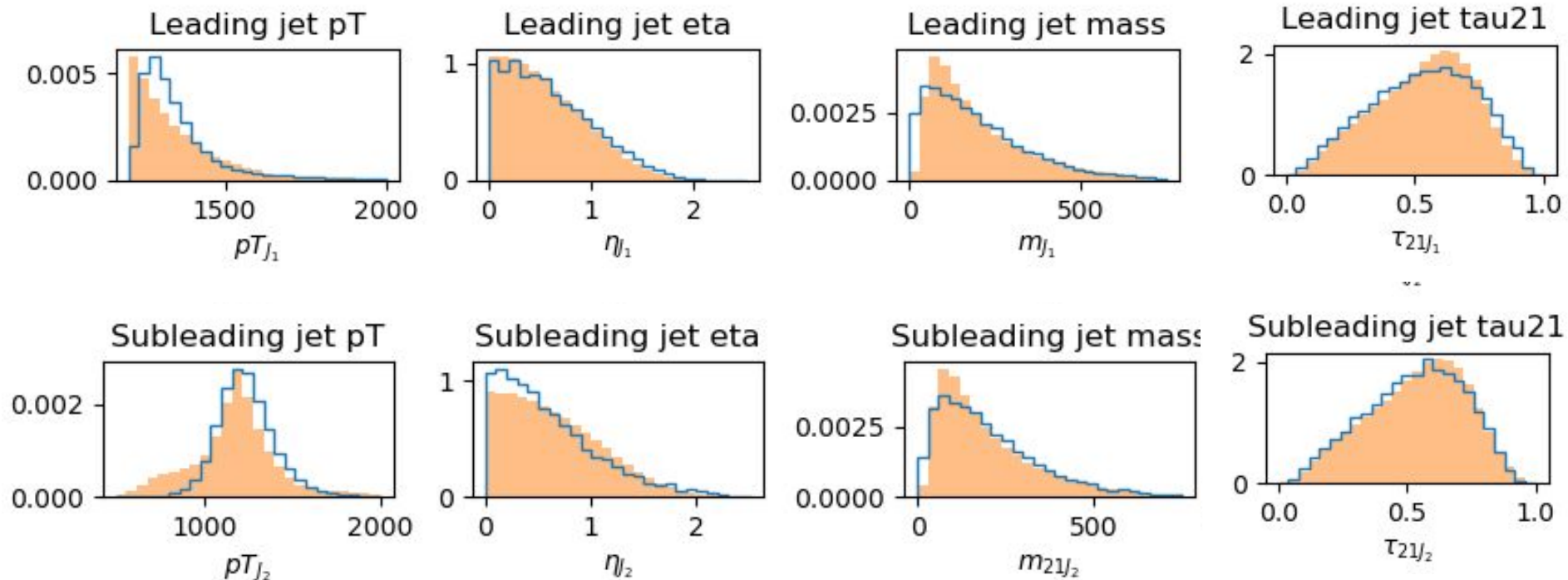
Anti-kT fat-jet $R = 1$, cuts of
 $p_T > 1.2 \text{ TeV}$ and $|\eta| < 2.5$

DijetGAN (code)



GAN results

Orange: input data Blue: Generated Data



References

- Lil'Log: [VAE](#), [GAN](#), [Flow-based](#)
- A. Butta, Machine learning for particle physicists, [Vietnam 2020](#)
- Deep Generative Model for Fundamental Physics, [BIDS March 2021](#)
- [CS 236 Fall 2019](#), Ermon & Grover, “Deep Generative Models”
- MIT 6.S191 A. Soleimany, “Introduction to Deep Learning” Lecture 4
[\[slide\]](#)[\[video\]](#)