

Chapter 7 Solution

5.

System is type 0. $K_p = 1.4881$.

$$\text{For } 20 u(t), e(\infty) = \frac{20}{1 + K_p} = 8.04$$

$$\text{For } 60 t u(t), e(\infty) = \infty$$

$$\text{For } 81 t^2 u(t), e(\infty) = \infty$$

8.

$$e(\infty) = \frac{15}{1 + K_p}; K_p = \frac{1020(13)(26)(33)}{(65)(75)(91)} = 25.65. \text{ Therefore, } e(\infty) = 0.563.$$

15.

Collapsing the inner loop and multiplying by $1000/s$ yields the equivalent forward-path transfer function as,

$$G_e(s) = \frac{10^5(s+2)}{s(s^2 + 1005s + 2000)}$$

Hence, the system is Type 1.

19.

$$e(\infty) = \frac{30}{K_v} = \frac{30}{Ka/30} = \frac{900}{Ka} = 0.005.$$

Hence, $Ka = 180000$.

25.

$$e(\infty) = \frac{1}{1 + K_p} = \frac{1}{1 + \frac{6K}{58}} = 0.08. \text{ Thus, } K = 111.$$

31.

System Type = 1. $T(s) = \frac{G(s)}{1+G(s)} = \frac{K}{s^2 + as + K}$. From $G(s)$, $K_v = \frac{K}{a} = 110$. For 12% overshoot, $\zeta =$

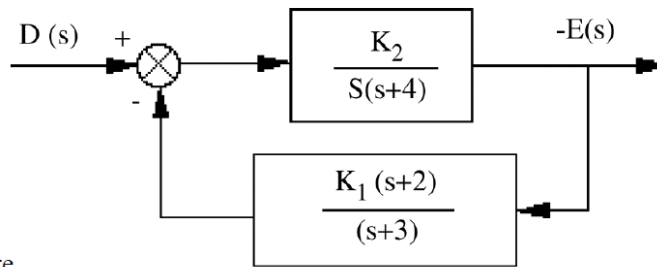
0.56. Therefore, $2\zeta\omega_n = a$, and $\omega_n^2 = K$. Hence, $a = 1.12 \sqrt{K}$.

Also, $a = \frac{K}{110}$. Solving simultaneously,

$K = 1.52 \times 10^4$, and $a = 1.38 \times 10^2$.

39.

Error due only to disturbance: Rearranging the block diagram to show $D(s)$ as the input,



Therefore,

$$-E(s) = D(s) \frac{\frac{K_2}{s(s+4)}}{1 + \frac{K_1 K_2 (s+2)}{s(s+3)(s+4)}} = D(s) \frac{K_2 (s+3)}{s(s+3)(s+4) + K_1 K_2 (s+2)}$$

For $D(s) = \frac{1}{s}$, $e_D(\infty) = \lim_{s \rightarrow 0} sE(s) = -\frac{3}{2K_1}$.

Error due only to input: $e_R(\infty) = \frac{1}{K_v} = \frac{1}{\frac{K_1 K_2}{6}} = \frac{6}{K_1 K_2}$.

Design:

$e_D(\infty) = -0.00001 = -\frac{3}{2K_1}$, or $K_1 = 150,000$.

$e_R(\infty) = 0.002 = \frac{6}{K_1 K_2}$, or $K_2 = 0.02$

53.

From Eq. (7.70),

$$e(\infty) = 1 - \lim_{s \rightarrow 0} \left(\frac{\frac{K_1 K_2}{(s+2)}}{1 + \frac{K_1 K_2 (s+1)}{(s+2)}} \right) - \lim_{s \rightarrow 0} \left(\frac{\frac{K_2}{(s+2)}}{1 + \frac{K_1 K_2 (s+1)}{(s+2)}} \right) = \frac{2 - K_2}{2 + K_1 K_2}$$

Sensitivity to K_1 :

$$S_{e:K_1} = \frac{K_1}{e} \frac{\delta e}{\delta K_1} = - \frac{K_1 K_2}{2 + K_1 K_2} = - \frac{(100)(0.1)}{2 + (100)(0.1)} = - 0.833$$

Sensitivity to K_2 :

$$S_{e:K_2} = \frac{K_2}{e} \frac{\delta e}{\delta K_2} = \frac{2K_2(1+K_1)}{(K_2-2)(2+K_1 K_2)} = \frac{2(0.1)(1+100)}{(0.1-2)(2+(100)(0.1))} = - 0.89$$

67.

a. When the speed controller is configured as a proportional controller, the forward-path transfer function of this system is:

$$G(s) = \frac{0.11 (s + 0.6) \times K_{p_{sc}}}{s (s + 0.5173) + 5 (s + 0.6) \times (s + 0.01908)} \quad (1)$$

For the steady-state error for a unit-step input, $r(t) = u(t)$, to be equal to 1%:

$$e_{step}(\infty) = \frac{1}{1 + \lim_{s \rightarrow 0} G(s)} = \frac{1}{1 + \lim_{s \rightarrow 0} \left(\frac{0.11 (s + 0.6) \times K_{p_{sc}}}{s (s + 0.5173) + 5 (s + 0.6) \times (s + 0.01908)} \right)} = 0.01 \quad (2)$$

From equation (2), we get: $\frac{1}{1 + \frac{0.11 \times 0.6 \times K_{p_{sc}}}{0 + 5 \times 0.6 \times 0.01908}} = 0.01$, which yields: $K_{p_{sc}} = 85.9$.

b. When the speed controller is configured as a proportional plus integral controller, the forward-path transfer function of the system becomes:

$$G(s) = \frac{0.11 (s + 0.6) \times (100s + K_{i_{sc}})}{s [s (s + 0.5173) + 5 (s + 0.6) \times (s + 0.01908)]} \quad (3)$$

For the steady-state error for a unit-ramp input, $r(t) = t u(t)$, to be equal to 2.5%:

$$e_{ramp}(\infty) = \frac{1}{\lim_{s \rightarrow 0} s G(s)} = \frac{1}{\lim_{s \rightarrow 0} \left(\frac{0.11 (s + 0.6) \times (100s + K_{i_{sc}})}{s [s (s + 0.5173) + 5 (s + 0.6) \times (s + 0.01908)]} \right)} = 0.025 \quad (4)$$

From equation (4), we get: $\frac{1}{\frac{0.11 \times 0.6 \times K_{i_{sc}}}{0 + 5 \times 0.6 \times 0.01908}} = 0.025$, which yields: $K_{i_{sc}} = 34.7$.

c. We'll start by finding $G_I(s)$, the equivalent transfer function of the parallel combination, representing the torque and speed controllers, shown in Figure P7.35:

$$G_I(s) = \frac{13.53 s}{(s + 0.5)} + \frac{3 (s + 0.6)}{(s + 0.5)} \left(\frac{100s + 40}{s} \right) = \frac{313.53s^2 + 300s + 72}{s(s + 0.5)} \quad (5)$$

Given that the equivalent transfer function of the car is: $G_2(s) = \frac{6.13 \times 10^{-3}}{s + 0.01908}$, we apply equation 7.62*

of the text taking into consideration that the disturbance here is a step with a magnitude equal to 83.7:

$$e(\infty) = -\frac{83.7}{\lim_{s \rightarrow 0} \frac{1}{G_2(s)} + \lim_{s \rightarrow 0} G_I(s)} = -\frac{83.7}{3.11 + \infty} = 0$$