

Autonomous Vehicle Challenge 2017 (AVC) Proposed Plan

5 May 2017

Group at Monday 4PM

Team Clap Trap

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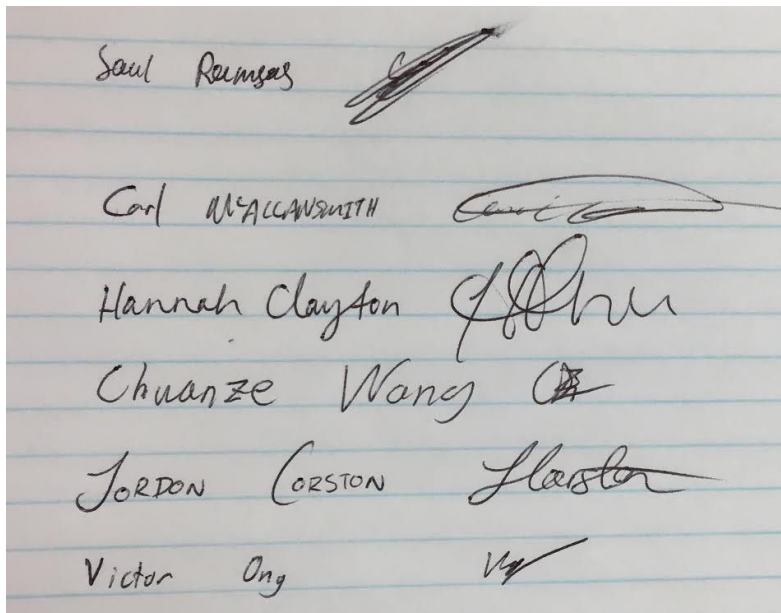
Chuanze(Charlie) Wang: andywcz@live.com 02102254815

Saul Ramsay: rainbowpotatoes@gmail.com 0221512350

Team Agreement

By signing below, all team members are acknowledging that they have read and committed to their part in the AVC. They acknowledge that they will attempt to complete the tasks agreed on by the group each week and document this on the team github account. They acknowledge that failure to meet these goals can result in the team recommending any member receives a lesser grade for their AVC report. In the event that a team member is unable to complete their task due to circumstances beyond their control (i.e. sickness, bereavement etc) that they will inform the team at the earliest possible time. Finally, the team acknowledges that a member going a week without contact with other team members (except when discussed with the team in advance) will constitute the member in question being considered AWOL. In this instance the team agrees to inform the ENGR101 course co-ordinator immediately. The penalty this for this can range from a reduction in the nal grade to immediate failure of the AVC (and thus the ENGR101 course). Should the team unanimously agree that a member (or members) have failed to contribute to the AVC sufficiently for other reasons, on the day of robot testing the team will be given the opportunity to anonymously vote for a team member to receive 0% for the robot part of the AVC. Should the team choose this option they MUST be able to show that the member in question had been assigned tasks that they failed to complete and that the team had a ordered them an opportunity to make up for past mistakes.

Signed by all team members: 01/05/17



Communication Tool: Email and Github

https://github.com/CGMcAllansmith/AVC_CLAP-TRAP_T12017/

https://ecs.victoria.ac.nz/foswiki/pub/Courses/ENGR101_2017T1/LectureSchedule/AVC.pdf

Overview

Weekly Meetings - Monday 4pm, Thursday 5pm.

RPi ip address

Member's Objectives

Hannah Clayton - Software and documentation (documenting performance against milestones)

Jordon Corston - Software Architect (writing core code and extending functionality)

Carl McAllansmith - Project lead and hardware support (organising team meetings, reporting regularly on progress)

Victor Ong - Software (software testing and documentation (debugging software and committing to git, writing test cases)

Charlie Wang - Assembly (building the chassis, testing components, connecting sensors)

Saul Ramsay - Hardware (CAD designing components and general electronics, debugging hardware)

Team Conflicts

Exams -

Name	Exams				
All	3 May 6pm - ENGR101				
Hannah	17-Jun-2017	Sat	09:30	NWEN241	
	26-Jun-2017	Mon	09:30	MATH151	
	03-Jul-2017	Mon	09:30	SWEN221	
Carl	26 May ENGR121 Test				
Jordon	21-Jun-2017		Wed	14:30	ENGR121
	24-Jun-2017		Sat	09:30	PHYS122
	30-Jun-2017		Fri	14:30	COMP102
Charlie	26 May ENGR121 Test				
	21-Jun-2017		Wed	14:30	ENGR121
	24-Jun-2017		Sat	09:30	PHYS122
	30-Jun-2017		Fri	14:30	COMP102
Victor	21-Jun-2017		Wed	14:30	ENGR121
	24-Jun-2017		Sat	09:30	PHYS122
	30-Jun-2017		Fri	14:30	COMP102
Saul	Date		Course	Name	
	21-Jun-2017	Wed	14:30	ENGR121	Eng Math Foundations
	29-Jun-2017	Thu	14:30	PHYS114	Physics 1A
	30-Jun-2017	Fri	14:30	COMP102	Intro to Comp Prog Design

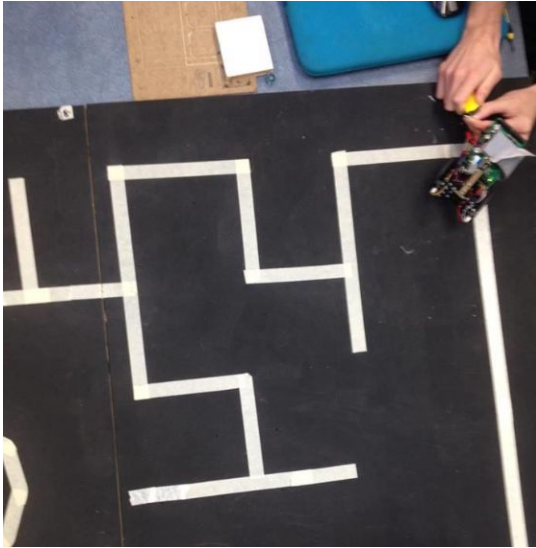
Work/home life -

Name	Conflict(s)
Hannah	Work all day Sunday
Carl	Work - weekdays between 12-5pm.
Jordon	Friday 3 onwards. Weekends.
Charlie	/
Victor	Work - Friday 3-7pm, Sunday 10am-7pm
Saul	/

Milestones

Week	Dates	Team Objectives	Items Due	Tasks	Notes
1	1 May	Intro	AVC plan due 5th May 12pm	Arrange team meetings, all sign agreement, set up git-hub	Team meetings: Thursdays start at 5pm Git-hub: https://github.com/CGMcAllansmith/AVC_CLAP-TRAP_T12017/invitations
2	8 May	Quadrant 1	Progress Report Due - 12 May	Final chassis design, implement sensor, straight line code done	
3	15 May	Quadrant 2			
4	22 May	Quadrant 3			
5	29 May	Quadrant 4			

A large white number 5 is drawn on a black background. Below the number is a small white square dot. To the right of the number, there is a vertical line and a horizontal line, suggesting a coordinate system or a grid.

**Problems Log:**

Problem	Ideas on how to solve