

INT104 ARTIFICIAL INTELLIGENCE

L10- Unsupervised Learning II Gaussian mixture model (GMM)

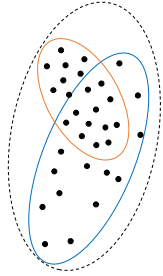
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CONTENT

- Mixture Gaussian Model and EM method
 - Gaussian distribution
 - Mixture of gaussians
 - EM (Expectation-Maximization) method

Motivation

K-means make *hard* assignments to data points: $x^{(i)}$ must belong to one of the clusters $1, 2, \dots, K$
Sometimes, one data point can belong to multiple clusters

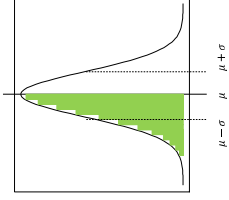


- Clusters may overlap
- Hard assignment may be simplistic
- Need a *soft* assignment: data points belong to clusters with different **probabilities**

Gaussian (Normal) distribution

1-D (univariate) Gaussian $\mathcal{N}(\mu, \sigma)$

Probability density function (PDF): $p(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$ μ : mean σ : standard deviation



$$P(x < \mu) = \int_{-\infty}^{\mu} p(x) dx = 0.5 = P(x > \mu)$$

$$P(x < \mu - \sigma) = \int_{-\infty}^{\mu - \sigma} p(x) dx \approx 0.157 = P(x > \mu + \sigma)$$

Gaussian is ubiquitous

- In biology, the *logarithm* of various variables
- Measures of size: length, height, weight, ...
 - Blood pressure of adult humans

- In finance, the logarithm of change rates
- Price indices
 - Stock market indices

- In linguistics, the logarithm of
- Word frequency
 - Sentence length

- Many scores
- Z-scores, t-scores
 - Bell curve grading

Tend to have a Gaussian distribution

Gaussian model

μ and σ fully define a gaussian distribution

Use them as parameter $\theta = (\mu, \sigma)$ to define the model:
suppose each data point is randomly *drawn* from the distribution

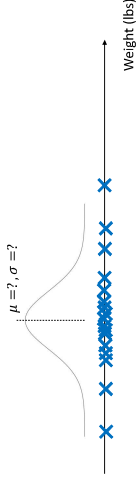
μ, σ are **unknown**, but they can be learned (estimated) from **data**
Job: find the parameters that best fit the data

What is "best fit"? → **Maximum Likelihood Estimation (MLE)**

Gaussian model example

Data: weight of Salmon fish. Assumption: The weight is from a Gaussian distribution

Task: to estimate the μ , σ of Salman



Maximum Likelihood Estimation (MLE)

Given m data points $X = \{x^{(1)}, \dots, x^{(m)}\}$

Fit

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PDF at $x^{(i)}$: $p(x^{(i)}|\theta) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x^{(i)}-\mu)^2}{2\sigma^2}}$ How likely it is to observe $x^{(i)}$ given θ

Assuming all data points are independent, then the likelihood of observing the whole dataset:

$$p(X|\theta) = \prod_{i=1}^m p(x^{(i)}|\theta) = \prod_{i=1}^m \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x^{(i)}-\mu)^2}{2\sigma^2}}$$

A good estimation of θ needs to maximize $p(X|\theta)$, the **likelihood** of data given the parameters

Maximum Likelihood Estimation (MLE) (cont.)

Likelihood function:

$$\mathcal{L}(\theta) = p(X|\theta) = \prod_{i=1}^m \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x^{(i)} - \mu)^2}{2\sigma^2}}$$

It is easier to work with log-likelihood:

$$\mathcal{LL}(\theta) = \log(\mathcal{L}(\theta)) = -\frac{m \log(2\pi)}{2} - m \log(\sigma) - \sum_{i=1}^m \frac{(x^{(i)} - \mu)^2}{2\sigma^2}$$

Goal: find the $\theta = (\mu, \sigma)$ that maximizes $\mathcal{LL}(\theta)$

Mixture of Gaussians

Previous example has the assumption that data are drawn from **one** Gaussian distribution $\mathcal{N}(\mu, \sigma)$

What if there are **multiple** Gaussian distributions: $\mathcal{N}(\mu_1, \sigma_1), \mathcal{N}(\mu_2, \sigma_2), \dots, \mathcal{N}(\mu_k, \sigma_k)$

How do we generate the data?

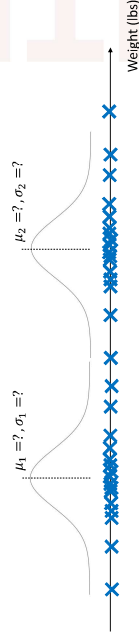
Step 1: Draw from k distributions with probabilities Q_1, Q_2, \dots, Q_k

Step 2: Suppose distribution j is chosen, draw a data point from $\mathcal{N}(\mu_j, \sigma_j)$

$$p(x^{(i)}|\mu_j, \sigma_j) = \frac{1}{\sqrt{2\pi}\sigma_j} e^{-\frac{(x^{(i)} - \mu_j)^2}{2\sigma_j^2}}$$

Example of 2 Gaussians

Weights of two kinds of fish: Salmon & Tuna fish



Maximum Likelihood Estimation (MLE) (cont.)

Take the derivative of $\mathcal{LL}(\theta)$ w.r.t μ and σ

$$\left[\frac{\partial \mathcal{L}(\theta)}{\partial \mu} = -\frac{1}{\sigma^2} \sum_{i=1}^m (x^{(i)} - \mu), \quad \frac{\partial \mathcal{L}(\theta)}{\partial \sigma} = -\frac{m}{\sigma} + \frac{1}{\sigma^3} \sum_{i=1}^m (x^{(i)} - \mu)^2 \right]$$

$\mathcal{L}(\theta)$ has extreme values when $\frac{\partial \eta}{\partial \mathcal{J}(\theta)} = 0$ and $\frac{\partial \sigma}{\partial \mathcal{J}(\theta)} = 0$

$$\mu = \frac{1}{m} \sum_{i=1}^m x^{(i)} = \bar{X} \quad \Rightarrow \quad \sigma = \sqrt{\frac{1}{m} \sum_{i=1}^m (x^{(i)} - \mu)^2}$$

Mean of data
(sample mean)Variance of data
(sample variance)

When μ is estimated by \bar{X} ,

$$\sigma = \sqrt{\frac{1}{m-1} \sum_{i=1}^m (x^{(i)} - \bar{X})^2}$$
in order to get an unbiased

These are the reasonable estimates of μ and σ from the data

$$p(x^{(i)}|\mu_j, \sigma_j) = \frac{1}{\sqrt{2\pi}\sigma_j} e^{-\frac{(x^{(i)} - \mu_j)^2}{2\sigma_j^2}}$$

How a data point is generated

A data point $x^{(i)}$ is generated according to the following process:

- First, select the fish *kind* with
 - Probability ϕ_S of being Salmon
 - Probability ϕ_T of being Tuna
- $\phi_S + \phi_T = 1$

Given the fish *kind*, generate the data point from the corresponding Gaussian distribution

- $p(x^{(i)}|S) \sim \mathcal{N}(\mu_S, \sigma_S^2)$ for Salmon
- $p(x^{(i)}|T) \sim \mathcal{N}(\mu_T, \sigma_T^2)$ for Tuna



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Introduce latent (unobserved) variable

Model parameters: $\theta = (\phi_S, \phi_T, \mu_S, \mu_T, \sigma_S, \sigma_T)$

Parameters for mixture probabilities

Parameters for each Gaussian distribution

For each data point $x^{(i)}$, we don't know if it is a Salmon or Tuna

Let $z^{(i)}$ be the latent random variable indicating which Gaussian distribution $x^{(i)}$ is from

$z^{(i)} = 1$ for Salmon, $z^{(i)} = 2$ for Tuna

Then the likelihood of $x^{(i)}$ is:

$$p(x^{(i)}|\theta) = \sum_{z^{(i)}} p(x^{(i)}, z^{(i)}|\theta)$$

$$\begin{aligned} & \text{Rewrite the likelihood} \\ & p(x^{(i)}|\theta) = \sum_{z^{(i)}} Q_i(z^{(i)}) \frac{p(x^{(i)}|\theta)}{Q_i(z^{(i)})} \\ & \quad \text{Let } Q_i \text{ be the distribution of } z^{(i)} \\ & \quad \text{s.t. } \sum_{z^{(i)}} Q_i(z^{(i)}) = 1 \\ & \quad Q_i(z^{(i)} = j) \text{ is the probability of } z^{(i)} = j \end{aligned}$$



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Log likelihood of data

The likelihood of the whole data: $\mathcal{L}(\theta) = \prod_{i=1}^m p(x^{(i)}, z^{(i)}|\theta) = \prod_{i=1}^m \sum_{z^{(i)}} Q_i(z^{(i)}) \frac{p(x^{(i)}, z^{(i)}|\theta)}{Q_i(z^{(i)})}$

$$\text{Log likelihood: } \mathcal{LL}(\theta) = \sum_{i=1}^m \log \left(\sum_{z^{(i)}} Q_i(z^{(i)}) \frac{p(x^{(i)}, z^{(i)}|\theta)}{Q_i(z^{(i)})} \right) = \sum_{i=1}^m \log \left(Q_i(z^{(i)} = 1) \frac{p(x^{(i)}, z^{(i)}|\theta)}{Q_i(z^{(i)})} + Q_i(z^{(i)} = 2) \frac{p(x^{(i)}, z^{(i)}|\theta)}{Q_i(z^{(i)})} \right)$$

It is difficult to take the derivative of $\mathcal{LL}(\theta)$ w.r.t. $\phi_S, \phi_T, \mu_S, \mu_T, \sigma_S, \sigma_T$, and solve them analytically

Solution: Instead of maximizing $\mathcal{LL}(\theta)$, we can maximize the lower bound of $\mathcal{LL}(\theta)$

Idea: Find some expression E , s.t. $\mathcal{LL}(\theta) \geq E$. When we maximize E , $\mathcal{LL}(\theta)$ is also maximized.

E should have a form that is easier to calculate derivatives



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Find the lower bound of $\mathcal{LL}(\theta)$ (optional)

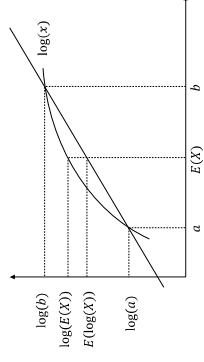
$$\mathcal{LL}(\theta) = \sum_{i=1}^m \log \left(\underbrace{Q_i(z^{(i)} = 1)}_{\text{Probability}} \underbrace{+ Q_i(z^{(i)} = 2)}_{\text{Probability}} \right)$$

Let a, b be two values of a random variable X
Then $Q_i(z^{(i)} = 1)a + Q_i(z^{(i)} = 2)b$ is the expectation of $E(X)$

Because $\log(x)$ is convex $\log(E(X)) \geq E(\log(X))$

$$\begin{aligned} \mathcal{LL}(\theta) & \geq \sum_{i=1}^m Q_i(z^{(i)} = 1) \log(a) + Q_i(z^{(i)} = 2) \log(b) \\ & = \sum_{i=1}^m Q_i(z^{(i)}) \log \left(\frac{p(x^{(i)}, z^{(i)}|\theta)}{Q_i(z^{(i)})} \right) \end{aligned}$$

We need to replace $Q_i(z^{(i)})$ with something we know



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Jensen's inequality: $f(E(X)) \geq E(f(X))$, when f is convex

How to estimate Q_i (optional)

$$\mathcal{LL}(\theta) \geq \sum_{i=1}^m \underbrace{Q_i(z^{(i)})}_{\text{guess}} \log \left(\frac{p(x^{(i)}, z^{(i)}|\theta)}{Q_i(z^{(i)})} \right) \quad Q_i(z^{(i)}) \text{ is unknown, but we can guess it after observing } x^{(i)}$$

I.e., after observing a data point $x^{(i)}$, we can "guess" which distribution it is from

A **reasonable** way to guess:

$$\frac{1}{\sqrt{2\pi}\sigma_S} e^{-\frac{(x^{(i)} - \mu_S)^2}{2\sigma_S^2}}$$

If $x^{(i)}$ is drawn from Salmon, then the likelihood of $x^{(i)}$ is $p(x^{(i)}|S)p(S) = \underbrace{p(x^{(i)}|\mu_S, \sigma_S)}_{\text{guess}} \phi_S$

If $x^{(i)}$ is drawn from Tuna, then the likelihood of $x^{(i)}$ is $p(x^{(i)}|T)p(T) = p(x^{(i)}|\mu_T, \sigma_T)\phi_T$

Then the chance of $x^{(i)}$ being Salmon is:

$$p(S|x^{(i)}) = \frac{p(x^{(i)}|S)p(S)}{p(x^{(i)}|S)p(S) + p(x^{(i)}|T)p(T)} = \underbrace{\frac{p(x^{(i)}|T)p(T)}{p(x^{(i)}|S)p(S) + p(x^{(i)}|T)p(T)}}_{\text{Posterior, } w_T^{(i)}}$$



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New form of Log-likelihood function (optional)

$$\begin{aligned} \mathcal{LL}(\theta) & \geq \sum_{i=1}^m \sum_{z^{(i)}} Q_i(z^{(i)}) \log \left(\frac{p(x^{(i)}, z^{(i)}|\theta)}{Q_i(z^{(i)})} \right) = \sum_{i=1}^m w_S^{(i)} \log \left(\frac{p(x^{(i)}, z^{(i)} = 1|\theta)}{w_S^{(i)}} \right) + w_T^{(i)} \log \left(\frac{p(x^{(i)}, z^{(i)} = 2|\theta)}{w_T^{(i)}} \right) = \mathcal{LL}'(\theta) \\ & p(x^{(i)}, z^{(i)} = 1|\theta) = p(x^{(i)}|\mu_S, \sigma_S)\phi_S = \frac{\phi_S}{\sqrt{2\pi}\sigma_S} e^{-\frac{(x^{(i)} - \mu_S)^2}{2\sigma_S^2}} \quad p(x^{(i)}, z^{(i)} = 2|\theta) = p(x^{(i)}|\mu_T, \sigma_T)\phi_T = \frac{\phi_T}{\sqrt{2\pi}\sigma_T} e^{-\frac{(x^{(i)} - \mu_T)^2}{2\sigma_T^2}} \end{aligned}$$

Treating w_S and w_T as known, the derivatives of $\mathcal{LL}'(\theta)$ is much easier to calculate

$$[\mathcal{LL}'(\theta)] = \mathcal{LL}'(\theta) = \sum_{i=1}^m w_S^{(i)} \log \left(\frac{\phi_S}{w_S^{(i)} \sqrt{2\pi}\sigma_S} e^{-\frac{(x^{(i)} - \mu_S)^2}{2\sigma_S^2}} \right) + w_T^{(i)} \log \left(\frac{\phi_T}{w_T^{(i)} \sqrt{2\pi}\sigma_T} e^{-\frac{(x^{(i)} - \mu_T)^2}{2\sigma_T^2}} \right)$$



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Maximizing $\mathcal{LL}'(\theta)$ (optional)

$$\left[\mathcal{LL}(\theta) \right] = \mathcal{LL}'(\theta) = \sum_{i=1}^m w_S^{(i)} \log \left(\frac{\phi_S}{w_S^{(i)} \sqrt{2\pi\sigma_S^2}} e^{-\frac{(x^{(i)} - \mu_S)^2}{2\sigma_S^2}} \right) + w_T^{(i)} \log \left(\frac{\phi_T}{w_T^{(i)} \sqrt{2\pi\sigma_T^2}} e^{-\frac{(x^{(i)} - \mu_T)^2}{2\sigma_T^2}} \right)$$

$$\frac{\partial \mathcal{LL}'(\theta)}{\partial \mu_S} = \sum_{i=1}^m \frac{\partial}{\partial \mu_S} \left[w_S^{(i)} \log \left(\frac{\phi_S}{w_S^{(i)} \sqrt{2\pi\sigma_S^2}} e^{-\frac{(x^{(i)} - \mu_S)^2}{2\sigma_S^2}} \right) \right] = \sum_{i=1}^m w_S^{(i)} (x^{(i)} - \mu_S) = 0 \quad \Rightarrow \quad \mu_S = \frac{\sum_{i=1}^m w_S^{(i)} x^{(i)}}{\sum_{i=1}^m w_S^{(i)}}$$

$$\frac{\partial \mathcal{LL}'(\theta)}{\partial \sigma_S^2} = \sum_{i=1}^m \frac{\partial}{\partial \sigma_S^2} \left[w_S^{(i)} \log \left(\frac{\phi_S}{w_S^{(i)} \sqrt{2\pi\sigma_S^2}} e^{-\frac{(x^{(i)} - \mu_S)^2}{2\sigma_S^2}} \right) \right] = \sum_{i=1}^m w_S^{(i)} \left(\frac{x^{(i)} - \mu_S}{\sigma_S^2} \right) = 0 \quad \Rightarrow \quad \sigma_S^2 = \frac{\sum_{i=1}^m w_S^{(i)} (x^{(i)} - \mu_S)^2}{\sum_{i=1}^m w_S^{(i)}}$$

Find the terms that only depends on ϕ_S and $\phi_T \longrightarrow \phi_S$ and ϕ_T cannot take any value Under constraint: $\phi_S + \phi_T = 1$

$$\mathcal{LL}'(\theta) = \sum_{i=1}^m w_S^{(i)} \log(\phi_S) + w_T^{(i)} \log(\phi_T) \longrightarrow \text{Construct a Lagrangian: } \mathcal{L}(\phi_S) = \left(\sum_{i=1}^m w_S^{(i)} \log(\phi_S) + w_T^{(i)} \log(\phi_T) \right) + \beta (\phi_S + \phi_T - 1)$$

$$\frac{\partial \mathcal{L}(\phi_S)}{\partial \phi_S} = \frac{\sum_{i=1}^m w_S^{(i)} - \beta}{\phi_S} + \beta = 0 \quad \Rightarrow \quad \phi_S = \frac{\sum_{i=1}^m w_S^{(i)}}{-\beta} \quad \phi_T = \frac{\sum_{i=1}^m w_T^{(i)}}{-\beta} \quad \Rightarrow \quad -\beta = \sum_{i=1}^m (w_S^{(i)} + w_T^{(i)}) = m$$



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Solutions of maximizing $\mathcal{LL}'(\theta)$ (optional)

$$\left\{ \begin{array}{l} \mu_S = \frac{\sum_{i=1}^m w_S^{(i)} x^{(i)}}{\sum_{i=1}^m w_S^{(i)}} \\ \sigma_S^2 = \frac{\sum_{i=1}^m w_S^{(i)} (x^{(i)} - \mu_S)^2}{\sum_{i=1}^m w_S^{(i)}} \\ \phi_S = \frac{\sum_{i=1}^m w_S^{(i)}}{m} \end{array} \right\} \quad \left\{ \begin{array}{l} \mu_T = \frac{\sum_{i=1}^m w_T^{(i)} x^{(i)}}{\sum_{i=1}^m w_T^{(i)}} \\ \sigma_T^2 = \frac{\sum_{i=1}^m w_T^{(i)} (x^{(i)} - \mu_T)^2}{\sum_{i=1}^m w_T^{(i)}} \\ \phi_T = \frac{\sum_{i=1}^m w_T^{(i)}}{m} \end{array} \right.$$

Repeatedly update all parameters,
 $\phi_S, \phi_T, \mu_S, \mu_T, \sigma_S, \sigma_T$ until convergence

$$\text{In which, } w_S^{(i)} = p(\mathbf{x}^{(i)}) = \frac{p(x^{(i)}) \phi_S}{p(x^{(i)}) \phi_S + p(x^{(i)}) \phi_T}$$

$$w_T^{(i)} = p(\mathbf{x}^{(i)}) = \frac{p(x^{(i)}) \phi_S}{p(x^{(i)}) \phi_S + p(x^{(i)}) \phi_T}$$



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E-M (Expectation-Maximization) Algorithm (1-D Gaussian)

Assume the data $\{x^{(i)}\}$ are drawn from k Gaussian distributions with probabilities $\phi_1, \phi_2, \dots, \phi_k$
Each distribution has parameters μ_j, σ_j^2 ($j = 1, 2, \dots, k$)

Randomly initialize all parameters $\phi_1, \phi_2, \dots, \phi_k$ and μ_j, σ_j^2 ($j = 1, 2, \dots, k$)

Repeat until convergence {

E-step: For each $x^{(i)}$, compute the expectation of which distribution it is from

$$w_j^{(i)} := p(x^{(i)} = j | x^{(i)}) = \frac{p(x^{(i)} | \mu_j, \sigma_j^2) \phi_j}{\sum_{j=1}^k p(x^{(i)} | \mu_j, \sigma_j^2) \phi_j} \quad \text{For } j = 1, 2, \dots, k$$

M-step: Update the parameters (as if $w_j^{(i)}$ is correct) by maximizing the likelihood:

$$\mu_j := \frac{\sum_{i=1}^m w_j^{(i)} x^{(i)}}{\sum_{i=1}^m w_j^{(i)}} \quad \sigma_j^2 := \frac{\sum_{i=1}^m w_j^{(i)} (x^{(i)} - \mu_j)^2}{\sum_{i=1}^m w_j^{(i)}} \quad \phi_j := \frac{\sum_{i=1}^m w_j^{(i)}}{m} \quad \text{For } j = 1, 2, \dots, k$$

Weighted average



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Compare with K-means

Randomly initialize all k centroids $\mu_1, \mu_2, \dots, \mu_k$

Repeat until convergence {

E-step: For each $x^{(i)}$, assign it to the closest centroid

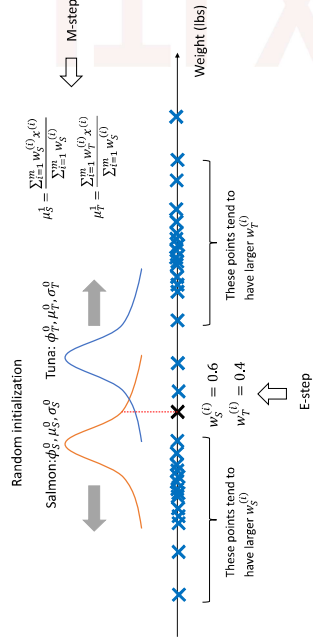
$$c^{(i)} := \arg \min_j \|x^{(i)} - \mu_j\|^2$$

M-step: Update the positions of centroids

$$\mu_j := \frac{\sum_{i=1}^m 1\{c^{(i)} = j\} x^{(i)}}{\sum_{i=1}^m 1\{c^{(i)} = j\}}$$

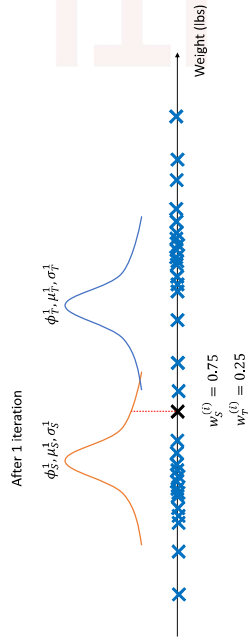
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Demonstration with $k = 2$, 1-D Gaussian



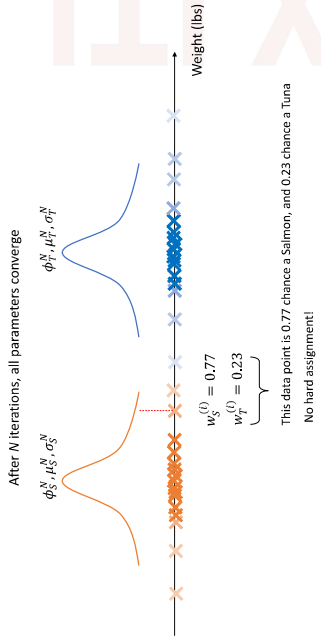
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Demonstration with $k = 2$, 1-D Gaussian



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Demonstration with $k = 2$, 1-D Gaussian



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What about multivariate Gaussians?

A random vector $X = \begin{pmatrix} X_1 \\ \vdots \\ X_n \end{pmatrix}$ is said to have a multivariate Gaussian distribution

If its probability density function is: $p(x) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp \left(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right)$

Mean: $\mu \in \mathbb{R}^n$ Covariance matrix: Σ

Property: $\frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} \exp \left(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right) dx_1 dx_2 \dots dx_n = 1.$

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Covariance matrix

If X_i, Y_j are a pair of 1-D random variables

Then the covariance is defined as: $\text{Cov}[X_i, Y_j] = E[(X - E(X_i))(Y - E(Y_j))] = E[X_i Y_j] - E(X_i)E(Y_j)$

If $X = \begin{pmatrix} X_1 \\ \vdots \\ X_n \end{pmatrix}, Y = \begin{pmatrix} Y_1 \\ \vdots \\ Y_n \end{pmatrix}$ are a pair of n -D random variables

Then the covariance matrix Σ is a $n \times n$ symmetric matrix whose (i, j) th entry is $\text{Cov}[X_i, Y_j]$

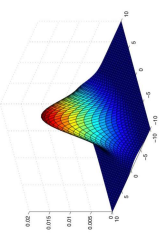
$$\Sigma = \begin{bmatrix} \text{Cov}[X_1, Y_1] & \text{Cov}[X_1, Y_2] & \dots & \text{Cov}[X_1, Y_n] \\ \text{Cov}[X_2, Y_1] & \text{Cov}[X_2, Y_2] & \dots & \text{Cov}[X_2, Y_n] \\ \vdots & \vdots & \ddots & \vdots \\ \text{Cov}[X_n, Y_1] & \text{Cov}[X_n, Y_2] & \dots & \text{Cov}[X_n, Y_n] \end{bmatrix}$$

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When $n=2$, 2-D Gaussian distribution

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \quad \mu = \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix} \quad \Sigma = \begin{bmatrix} \sigma_1^2 & \sigma_1 \sigma_2 \\ \sigma_1 \sigma_2 & \sigma_2^2 \end{bmatrix}$$

$$p(x) = \frac{1}{2\pi \sqrt{\sigma_1^2 \sigma_2^2 - \sigma_1^2 \sigma_2^2}} \exp \left(-\frac{1}{2} \begin{pmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{pmatrix}^T \begin{bmatrix} \sigma_1^2 & \sigma_1 \sigma_2 \\ \sigma_1 \sigma_2 & \sigma_2^2 \end{bmatrix}^{-1} \begin{pmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{pmatrix} \right)$$



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Special case: covariance matrix is diagonal

$$\begin{aligned} p(x) &= \frac{1}{2\pi \sqrt{\sigma_1^2 \sigma_2^2}} \exp \left(-\frac{1}{2} \begin{pmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{pmatrix}^T \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}^{-1} \begin{pmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{pmatrix} \right) \\ &= \frac{1}{2\pi \sqrt{\sigma_1^2 \sigma_2^2}} \exp \left(-\frac{1}{2} \begin{pmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{pmatrix}^T \begin{bmatrix} 1/\sigma_1^2 & 0 \\ 0 & 1/\sigma_2^2 \end{bmatrix}^{-1} \begin{pmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{pmatrix} \right) \\ &= \frac{1}{2\pi \sigma_1 \sigma_2} \exp \left(-\frac{1}{2\sigma_1^2} (x_1 - \mu_1)^2 - \frac{1}{2\sigma_2^2} (x_2 - \mu_2)^2 \right) \\ &= \underbrace{\frac{1}{2\pi \sigma_1} \exp \left(-\frac{1}{2\sigma_1^2} (x_1 - \mu_1)^2 \right)}_{\text{PDF for } x_1} \underbrace{\frac{1}{2\pi \sigma_2} \exp \left(-\frac{1}{2\sigma_2^2} (x_2 - \mu_2)^2 \right)}_{\text{PDF for } x_2} \end{aligned}$$

Product of two independent 1-D Gaussian distribution

PDF for x_2

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Contours of 2-D Gaussians

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$p(x) = \frac{1}{2\pi \sigma_1 \sigma_2} \exp \left(-\frac{1}{2\sigma_1^2} (x_1 - \mu_1)^2 - \frac{1}{2\sigma_2^2} (x_2 - \mu_2)^2 \right)$$

To draw contours, let $p(x)$ be a constant

$$\Sigma = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}$$

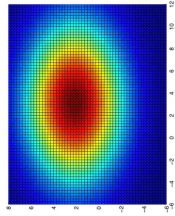
$$p(x) = c \quad \Leftrightarrow \quad 1 = \frac{(x_1 - \mu_1)^2}{2\sigma_1^2 \log \left(\frac{1}{2\pi c \sigma_1 \sigma_2} \right)} + \frac{(x_2 - \mu_2)^2}{2\sigma_2^2 \log \left(\frac{1}{2\pi c \sigma_1 \sigma_2} \right)}$$

$$1 = \frac{(x_1 - \mu_1)^2}{r^2} + \frac{(x_2 - \mu_2)^2}{r^2} \quad \text{An ellipse!}$$

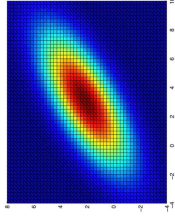


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Covariance matrix decides the shape of ellipse



$$\mu = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \quad \Sigma = \begin{bmatrix} 25 & 0 \\ 0 & 9 \end{bmatrix}$$



$$\mu = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \quad \Sigma = \begin{bmatrix} 10 & 5 \\ 5 & 5 \end{bmatrix}$$



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E-M algorithm for mixture of multivariate gaussians

Assume the data $\{x^{(i)}\}$ are drawn from k n -D Gaussian distributions with probabilities $\phi_1, \phi_2, \dots, \phi_k$
Each distribution has parameters μ_j, Σ_j ($j = 1, 2, \dots, k$)

Randomly initialize all parameters $\phi_1, \phi_2, \dots, \phi_k$ and μ_j, Σ_j ($j = 1, 2, \dots, k$)
Repeat until convergence {

E-step: For each $x^{(i)}$, compute the expectation of which distribution it is from

$$w_j^{(i)} := p(z^{(i)} = j | x^{(i)}) = \frac{p(x^{(i)} | \mu_j, \Sigma_j) \phi_j}{\sum_{l=1}^k p(x^{(i)} | \mu_l, \Sigma_l) \phi_l} \quad \text{For } j = 1, 2, \dots, k$$

M-step: Update the parameters (as if $w_j^{(i)}$ is correct) by maximizing the likelihood:

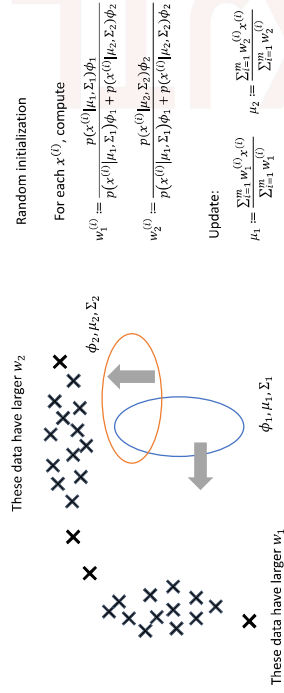
$$\mu_j := \frac{\sum_{i=1}^m w_j^{(i)} x^{(i)}}{\sum_{i=1}^m w_j^{(i)}} \quad \Sigma_j := \frac{\sum_{i=1}^m w_j^{(i)} (x^{(i)} - \mu_j)(x^{(i)} - \mu_j)^T}{\sum_{i=1}^m w_j^{(i)}} \quad \phi_j := \frac{\sum_{i=1}^m w_j^{(i)}}{m} \quad \text{For } j = 1, 2, \dots, k$$

}



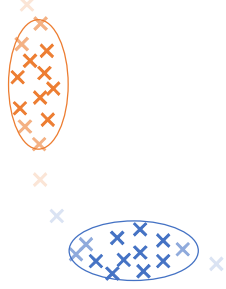
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Demo of learning a mixture of 2-D Gaussians



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Demo of learning a mixture of 2-D Gaussians (cont.)



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