A white humanoid robot with a mobile base, standing and facing forward. It has a head with two small eyes, a torso with a small screen, and two arms. The base is white with orange accents and the text 'PAL ROBOTICS' is visible on it.

TIAGo Training Sessions

Voice synthesis

Introduction



Playing text-to-speech in terminal

- Tiago has an action server API to say written text. It is on the **/tts** action name of type pal_interaction_msgs/Tts

```
rostopic pub /tts/goal pal_interaction_msgs/TtsActionGoal "header:
  seq: 0
  stamp:
    secs: 0
    nsecs: 0
  frame_id: ''
  goal_id:
    stamp:
      secs: 0
      nsecs: 0
  id: ''
  goal:
    text: {}
  rawtext:
    text: 'Hello world'
    lang_id: 'en_GB'
  speakerName: ''
  wait_before_speaking: 0.0"
```

Playing text-to-speech with Python

```
#!/usr/bin/env python
import sys
import rospy
from actionlib import SimpleActionClient
from pal_interaction_msgs.msg import TtsAction, TtsGoal

if __name__ == '__main__':
    rospy.init_node('say_something')
    if len(sys.argv) > 1:
        text = ""
        for arg in sys.argv[1:]:
            text += arg + " "
    else:
        text = "I like talking to people"

    rospy.loginfo("I'll say: " + text)
    # Connect to the text-to-speech action server
    client = SimpleActionClient('/tts', TtsAction)
    client.wait_for_server()
    # Create a goal to say our sentence
    goal = TtsGoal()
    goal.rawtext.text = text
    goal.rawtext.lang_id = "en_GB"
    # Send the goal and wait
    client.send_goal_and_wait(goal)
```

Playing text-to-speech from web

- Access tiago's web interface <http://tiago-0c:8080>
- Go to the 5. Demos tab, type any text on the upper input box and press say.

0. Startup

1. Diagnostics

13. Control joints

2. Logs

3. General Info

4. Video

5. Demos

Hello world

english

Say

Copy Text

Paste Text

Switch to GRAVITY

Switch to WBC

Switch to POSITION

Follow by the hand START

Follow by the hand STOP

hi1

hi2

hi nice name

iam

iam nice place

thank you

its amazing

its amazing

Playing text-to-speech from web (II)

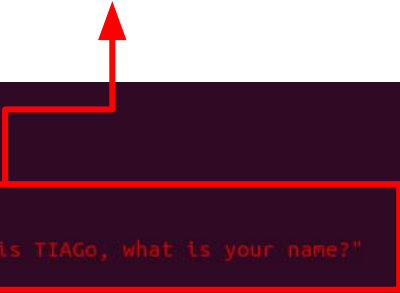
- Edit voice buttons

```
ssh pal@tiago-0c
```

```
cd .pal/wt
```

```
vi wt_tiago_section.yaml
```

You may add your own sentences or
edit/remove existing ones

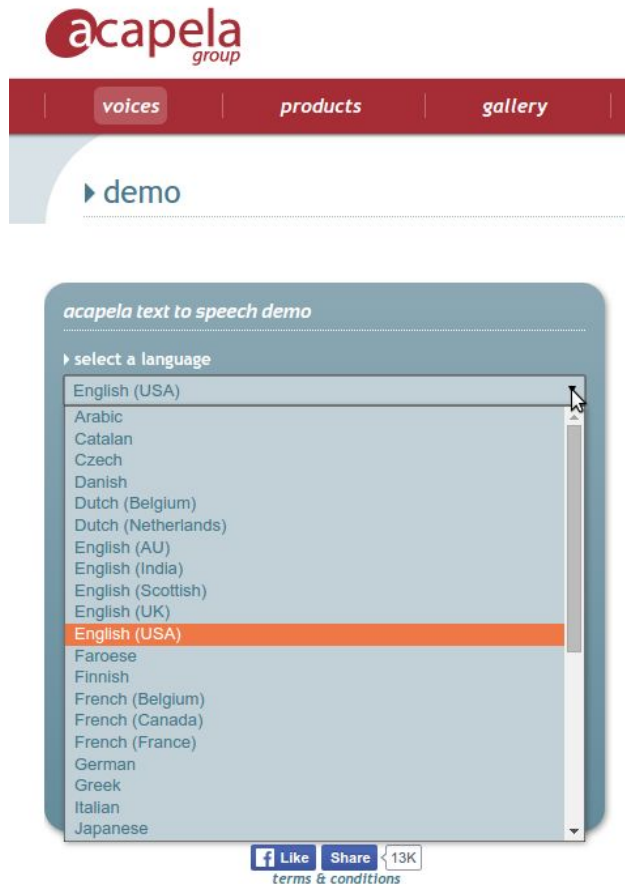


```
"5. Demos":  
  type: "Commands"  
  parameters:  
    buttons:  
      - name: "hi1"  
        say:  
          text: "Hello, my name is TIAGo, what is your name?"  
          lang: "en_GB"  
      - name: "hi2"  
        say:  
          text: "I am TIAGo, the robot that adapts to your research needs, not the other way around"  
          lang: "en_GB"  
      - name: "hi nice name"  
        say:  
          text: "Oh, what a wonderful name"  
          lang: "en_GB"  
      - name: "iam"  
        say:  
          text: "I am from Barcelona. Where are you from?"  
          lang: "en_GB"  
      - name: "iam nice place"  
        say:  
          text: "Oh, nice place"  
          lang: "en_GB"
```

Additional languages and voices

- TIAGo uses Acapela's voice synthesis software
- Additional languages and voices can be ordered and integrated into TIAGo:

<http://www.acapela-group.com/voices/demo/>



Questions?

