



# Review of Some Elements of Linear Algebra

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ST445 Managing and Visualizing Data

# Norms

- A **norm** is any function  $f: \mathbf{R}^n \rightarrow \mathbf{R}_+$  that satisfies
  - $f(x) = 0 \Rightarrow x = 0$  (**definite** or **point separating**)
  - $f(x + y) \leq f(x) + f(y)$  (**subadditive** or satisfying **triangle inequality**)
  - $f(\alpha x) = |\alpha|f(x)$  for all  $\alpha \in \mathbf{R}$  (**absolutely homogeneous**)
- **$L_p$  norm**:  $\|x\|_p = (\sum_i |x_i|^p)^{1/p}$ ,  $p \in \mathbf{R}, p \geq 1$ 
  - $L_2$  is referred as **the Euclidean norm**
- **Max norm**:  $\|x\|_\infty = \max_i |x_i|$
- **Frobenius norm**:  $\|A\|_F = \sqrt{\sum_{i,j} a_{i,j}^2}$  for a matrix  $A$

# Some special matrices

- A matrix is **symmetric** if it is equal to its transpose:  $A = A^T$
- A **unit vector** is a vector with **unit norm**:  $\|x\|_2 = 1$
- A vector  $x$  and a vector  $y$  are **orthogonal** if  $x^T y = 0$ 
  - If, in addition, they are unit vectors, we say that they are **orthonormal**
- An **orthogonal matrix** is a square matrix whose rows (columns) are mutually orthonormal

$$A^T A = A A^T = I$$

- For any orthogonal matrix  $A$  the inverse matrix is equal to its transpose matrix:

$$A^{-1} = A^T$$

# Some special matrices (cont'd)

- A matrix whose **eigenvalues are all strictly positive** is said to be **positive definite**
- A matrix whose **eigenvalues are all positive** is said to be **positive semidefinite**
- Likewise, if all eigenvalues are negative or zero, the matrix is **negative definite**, and if all eigenvalues are negative, the matrix is **negative semidefinite**
- For any positive semidefinite matrix  $A$ :  $x^T A x \geq 0$  for all  $x$ 
  - In addition, if  $A$  is positive definite, then  $x^T A x = 0 \Rightarrow x = 0$

# Eigen-decomposition

- Suppose  $A$  is a  $n \times n$  matrix with mutually orthogonal eigenvectors  $v_1, v_2, \dots, v_n$  and the corresponding eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_n$
- The **eigen-decomposition** of  $A$  is defined as:

$$A = V\Lambda V^{-1}$$

where  $V = (v_1, v_2, \dots, v_n)$  and  $\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$

- Not every matrix has an eigen-decomposition
- Any real, symmetric matrix has an eigen-decomposition

# Singular Value Decomposition (SVD)

- For an  $m \times n$  matrix  $A$  the SVD is given by

$$A = U \Lambda V^T$$

where

$U$  is an  $m \times m$  matrix whose each column is a left-singular vector of  $A$

$\Sigma$  is an  $m \times n$  diagonal matrix whose each diagonal element is a singular value of  $A$

$V$  is an  $n \times n$  matrix whose each column is a right-singular vector of  $A$

# SVD (cont'd)

- The left-singular vectors of  $A$  correspond to the eigenvectors of  $AA^T$
- The right-singular vectors of  $A$  correspond to the eigenvectors of  $A^T A$
- The non-zero singular values of  $A$  are the square roots of the eigenvalues of  $A^T A$ 
  - Same is true for  $AA^T$

# The Moore-Penrose pseudoinverse

- The **pseudoinverse** of  $A$  is defined as a matrix

$$A^+ = \lim_{\alpha \downarrow 0} (A^T A + \alpha I)^{-1} A^T$$

- Suppose that  $A$  is a  $m \times n$  matrix and consider the linear equation  $Ax = b$  and let

$$x^* = A^+ b$$

- If  $m \leq n$ , then  $x^*$  has the smallest Euclidean norm  $\|x\|_2$  among all possible solutions
- If  $m > n$  then  $Ax = b$  may not have a solution; in this case  $x^*$  minimizes  $\|Ax - b\|_2$



# The trace of a matrix

- The **trace** operator is defined as the sum of all the diagonal elements of a matrix:

$$\mathbf{tr}(A) = \sum_i a_{i,i}$$

- The trace is related to the **Frobenius norm** of a matrix:

$$\|A\|_F = \sqrt{\mathbf{tr}(AA^T)}$$

# Low-rank matrix approximation

- Suppose given is a matrix  $M \in \mathbf{R}^{m \times n}$  and a positive integer  $r$
- Definition of the [matrix approximation problem](#):

$$\text{minimize} \quad \|M - \hat{M}\|_F$$

$$\text{subject to} \quad \mathbf{rank}(\hat{M}) \leq r$$

- Let  $M = U\Sigma V^T$  be the SVD
- Let  $\Sigma_1$  be a  $r \times r$  diagonal matrix,  $U_1$  be a  $m \times r$  matrix and  $V_1$  be a  $n \times r$  matrix

$$U = (U_1, U_2), \Sigma = \begin{pmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{pmatrix} \text{ and } V = (V_1, V_2)$$

# Matrix approximation lemma

- **Theorem:** The rank- $r$  matrix  $U_1 \Sigma_1 V_1^T$  is a solution to the matrix approximation problem.

Moreover, it holds:

$$\|M - U_1 \Sigma_1 V_1^T\|_F = \sqrt{\sigma_{r+1}^2 + \cdots + \sigma_n^2}$$

The solution is unique if  $\sigma_r \neq \sigma_{r+1}$

- **Comment:** if  $M$  is a square matrix, then all the above statements hold by using the eigen-decomposition