# **BST Application** Range Tree 邓俊辉 deng@tsinghua.edu.cn

顺藤摸瓜

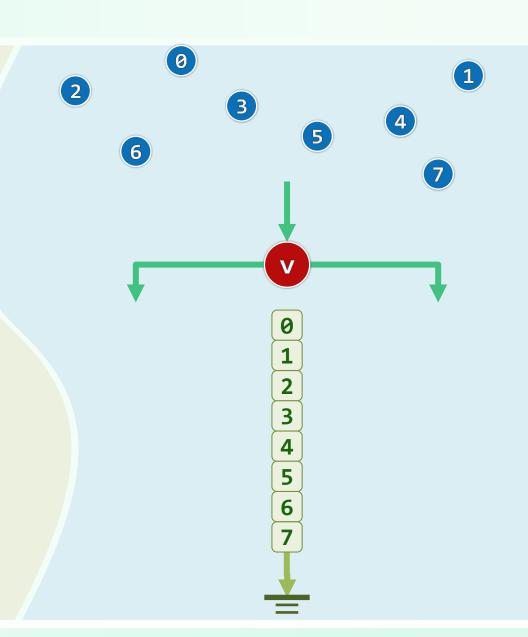
#### BBST<BBST<T>> --> BBST<List<T>>

- ❖ Each y-search is just
  - a 1D query without further recursions
- ❖ So it not necessary

to store each canonical subset

as a BBST

❖ Instead, a sorted y-list simply works



#### Coherence

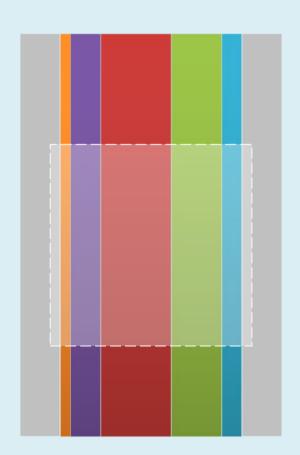
❖ For each query, we

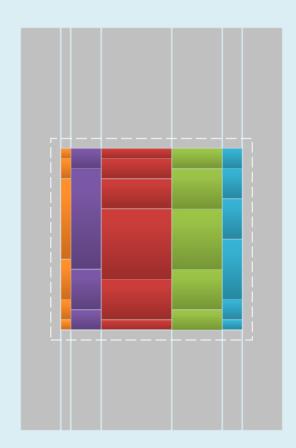
- need to repeatedly search

DIFFERENT y-lists,

- but always with

the SAME key





#### Links Between Lists

❖ We can CONNECT all the different lists

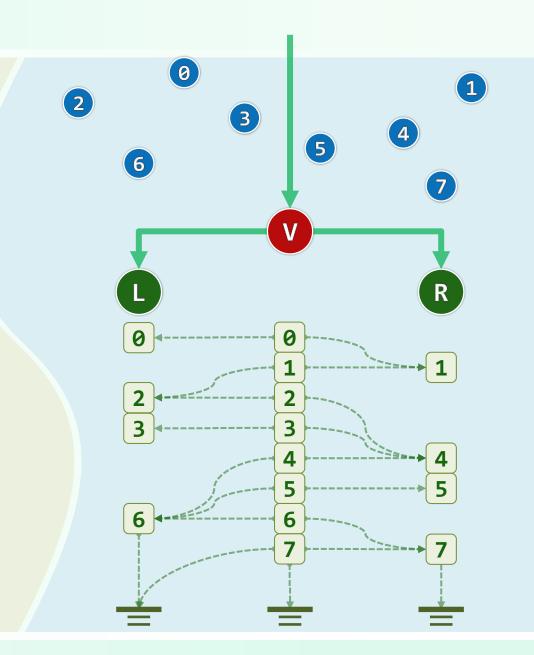
into a **SINGLE** massive list

❖ Thus, once a parent y-list is searched,

we can get, in O(1) time,

the entry for child y-list by

following the link between them



## **Using Coherence**

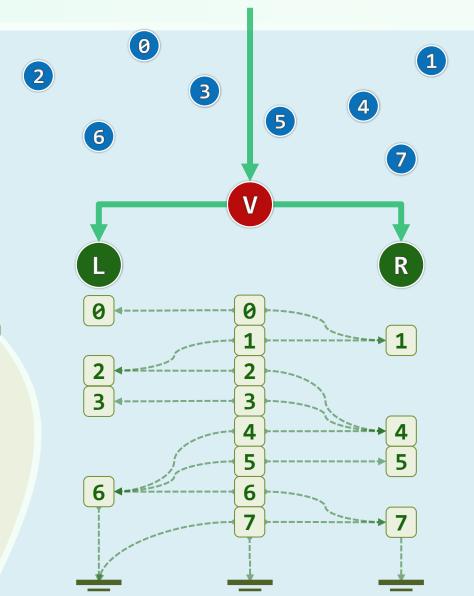
❖ To answer a 2D range query, we will
do an O(logn) search
on the y-list for the root

❖ Thereafter, while descending the x-tree, we can

keep track of the position of y-range

in each successive list in O(1) time

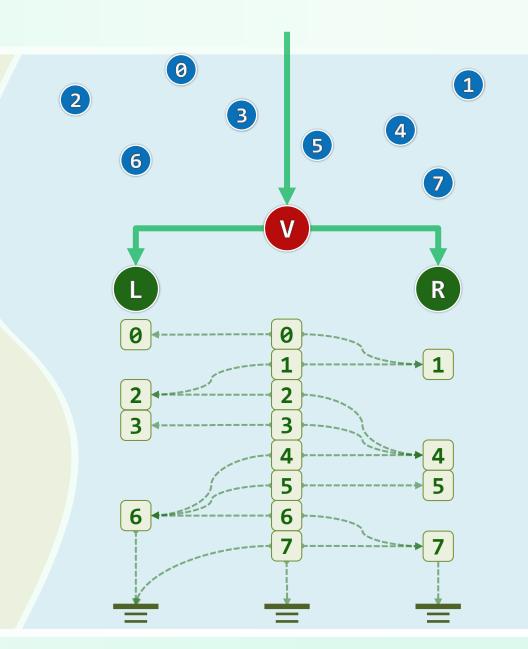
❖ This technique is called .....



## Fractional Cascading

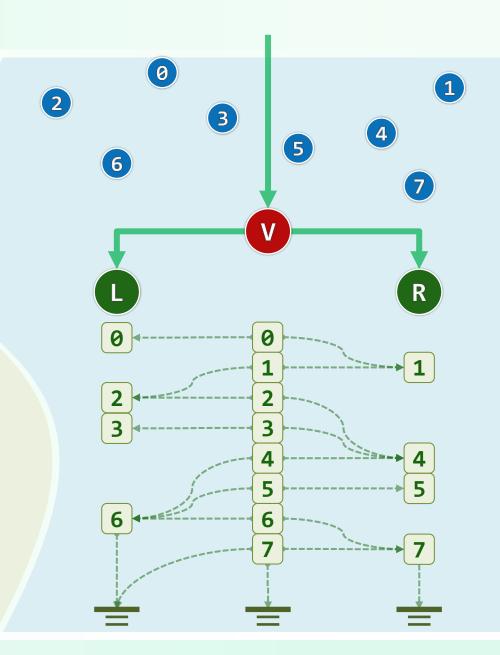
❖ For each item in A<sub>v</sub>, we store two pointers to the item of NLT value in  $A_L$  and  $A_R$  resp.  $\Leftrightarrow$  Hence for any y-query with  $q_v$ , once we know its entry in  $A_v$ , we can determine its entry in either  $A_L$  or  $A_R$ 

in O(1) additional time



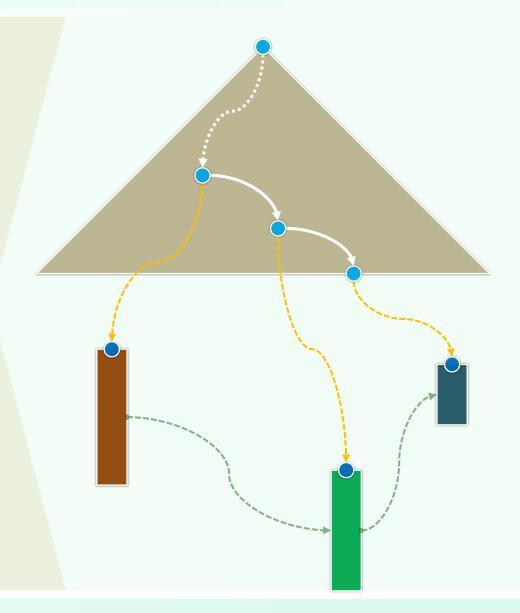
## Construction By 2-Way Merging

- ❖ Let V be an internal node in the x-tree
  with L/R its left/right child resp.
- **\diamondsuit** Let  $A_v$  be the y-list for v and  $A_L/A_R$  be the y-lists for its children
- ❖ Assuming no duplicate y-coordinates, we have
  - $A_{\nu}$  is the disjoint union of  $A_{L}$  and  $A_{R}$ , and hence
  - $A_v$  can be obtained by merging  $A_L$  and  $A_R$  (in linear time)



## Complexity

- ❖ An MLST with fractional cascading is called a range tree
- $\diamondsuit$  A y-search for root is done in  $O(\log n)$  time
- ❖ To drop down to each next level, we can get, in O(1) time, the current y-interval from that of the prior level
- ❖ Hence, each 2D orthogonal range query
  - can be answered in  $\mathcal{O}(r + \log n)$  time
  - from a data structure of size  $\mathcal{O}(n \cdot \log n)$  ,
  - which can be constructed in  $\mathcal{O}(n \cdot \log n)$  time



#### Beyond 2D

Unfortunately, the trick of fractional cascading
can ONLY be applied to

the LAST level the search structure

- $\clubsuit$  Given a set of n points in  $\mathcal{E}^d$ , an orthogonal range query
  - can be answered in  $\mathcal{O}(r + \log^{d-1} n)$  time
  - from a data structure of size  $\mathcal{O}(n \cdot \log^{d-1} n)$  ,
  - which can be constructed in  $\mathcal{O}(n \cdot \log^{d-1} n)$  time

