

PARAMETERS TO ANALYZE THE EFFECTIVENESS OF FILTERS

To evaluate how well each filter removes noise while preserving image quality, use the following parameters in MATLAB:

1. Peak Signal-to-Noise Ratio (PSNR):

- **Formula:** $PSNR = 10 * \log_{10}((MAX_I^2) / MSE)$, where MAX_I is the maximum possible pixel value (255 for 8-bit images), and MSE is the Mean Squared Error.
- **MATLAB Function:** `psnr (denoised_image, original_image)`.
- **Interpretation:** Higher PSNR (e.g., >30 dB) indicates better denoising with less distortion. Compare PSNR between noisy and denoised images to assess improvement.
- **Use:** Measure how close the denoised image is to the original.

2. Mean Squared Error (MSE):

- **Formula:** $MSE = (1/m) * \sum [(original(i,j) - denoised(i,j))^2]$, where m is the number of pixels.
- **MATLAB Function:** `immse (denoised_image, original_image)`.
- **Interpretation:** Lower MSE values indicate less error and better denoising. A value close to 0 is ideal.
- **Use:** Quantify the average squared difference between original and denoised images.

3. Structural Similarity Index (SSIM):

- **Formula:** SSIM compares luminance, contrast, and structure between two images, ranging from -1 to 1 (1 being perfect similarity).

- **MATLAB Function:** Use the Image Processing Toolbox function `ssim(denoised_image, original_image)`.
- **Interpretation:** SSIM > 0.9 suggests good structural preservation; lower values indicate loss of detail or structure.
- **Use:** Assess how well the filter preserves the image's structural information.

4. Edge Preservation (Gradient Magnitude):

- **Method:** Compute the gradient magnitude of the original and denoised images using `imgradient` or `edge` functions.
- **Interpretation:** Higher correlation (close to 1) indicates better edge preservation.
- **Use:** Evaluate if the filter blurs edges excessively.

5. Noise Reduction Ratio (Optional):

- **Method:** Compare the variance of the noise (noisy - original) vs. residual noise (denoised - original).
- **MATLAB Approach:**

```
noise_variance = var(double(noisy_sp(:)) - double(original(:)));
```

```
residual_variance = var(double(denoised_sp(:)) - double(original(:)));
```

```
reduction_ratio = noise_variance / residual_variance;
```

```
fprintf('Noise Reduction Ratio (Salt & Pepper): %.2f\n', reduction_ratio);
```

- **Interpretation:** A higher ratio indicates better noise removal.
- **Use:** Quantify how much noise is reduced by the filter.