NCTU Pattern Recognition, Homework 5

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Coding (100%):

In this coding assignment, you need to implement the deep neural network by any deep learning framework, e.g. Pytorch, TensorFlow, or Keras, then train the DNN model by the Cifar-10 dataset and try to beat the baseline performance.

Download dataset HERE.

Please note that you should only train and evaluate your model on the provided dataset.
DO NOT download the data from other resources**.**

If you are a newbie in a deep learning framework, we recommend you learn **Keras** or **Pytorch**.

- Pytorch tutorial
- Keras tutorial
- TensorFlow tutorial

1. **(100%) Show your accuracy of your model on the provided test data by screenshot the results of your code and paste them on your report**

   Evaluation:

Accuracy	Your scores
acc >= 0.95	100 points
0.9 <= acc < 0.95	90 points
0.80 <= acc < 0.90	80 points
0.75 <= acc < 0.80	70 points
0.65 <= acc < 0.75	60 points
0.6 <= acc < 0.65	50 points
acc <0.6	No points

   Note**:** Keyword to boost your model performance
   1. Data augmentation
   2. Hyperparameter searching for model structure (number of filers, number of convolution/dense layer) and optimizer (learning rate)
   3. Regularization

   Note: If your result is bad, check this tutorial first to debug your model

2. My performance:

▾ DO NOT MODIFY CODE BELOW!

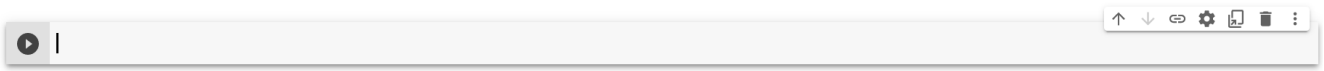
Please screen shot your results and post it on your report

```
[50] # Change the label to the number of class
     y_pred = model.predict(x_test)
     y_pred = np.argmax(y_pred, axis=1)

[51] assert y_pred.shape == (10000,)

[52] y_test = np.load("drive/Colab Notebooks/y_test.npy")
     print("Accuracy of my model on test set: ", accuracy_score(y_test, y_pred))

     Accuracy of my model on test set: 0.9012
```



This is the screen shot from google Colab, I trained my model on it.
Also I added " y_pred = np.argmax(y_pred, axis=1) " after "y_pred = model.predict(x_test)" cause I needed to transfer the 10-dimension probability I got after prediction to the number of the most likely class. I didn't modify the other codes so I guess my change is permitted?

3. Implementation details and hyperparameters in my model:

This table is my record of training with different parameters and in the last page I put the bigger version of this table.

filter layer	Max_pooling	Dense layer	optimizer	initial ln	decay	schedule_decay	patience	factor	epoch	batch_size	Test accuracy	BatchNormalization() + z-score	Dropout	Fractional Max-Pooling
3	1	3	Adam	0.0005	0	0	2	0.5	75	64	0.72			
4	1	3	Adam	0.0005	0	0	3	0.4	75	64	0.73			
4	1	3	Adam	0.0005	0	0	3	0.4	79	64	0.73			
4	1	3	Nadam	0.0005	0	0.004	2	0.4	75	64	0.73			
4	1	3	Nadam	0.0008	0	0.004	2	0.1	50	64	0.7257			
4	1	3	Adam	0.0008	0.004	0.004	2	0.35	50	64	0.5734			
4	1	3	Nadam	0.0006	0	0.004	2	0.2	50	64	0.7024			
4	1	4	Nadam	0.0008	0	0.004	2	0.5	50	64	0.7258			
6	2	2	Nadam	0.0008	0	0.004	2	0.4	50	64	0.78			
6	2	2	SGD	0.001	momentum=0.9	0.004	2	0.4	75	100	0.5883			
6	2	2	Nadam	0.0008	0	0.004	2	0.4	50	64	0.8037		3	
6	2	2	Nadam	0.0008	0	0.004	2	0.4	50	64	0.7906	yes	4	
8	2	2	Nadam	0.001	0	0.004	2	0.4	50	64	0.8152	yes	4	
8	4	2	rmsprop	0.001		0.004		0.35	50	64	0.8294	yes	4	
8	4	2	Nadam	0.0008		0.004	2	0.4	50	50	0.8391	yes	4	
8	4	2	Nadam	0.0008	0	0.004	2	0.4	150	200	0.858	yes	5	
8	4	2	Nadam	0.0008		0.004	2	0.1	50	200	0.8167	yes	5	
8	4	2	Nadam	0.0008		0.004	2	0.6	100	200	0.8432	yes	5	
8	4	2	Nadam	0.0008		0.004	2	0.6	100	200	0.8511	yes	5	
8	4	2	Nadam	0.0008		0.004	2	0.4	150	200	0.8637	yes	5	yes
8	4	2	Nadam	0.001	I set the learing rate reducing schedule by following reference.				125	64	0.9	yes	5	yes

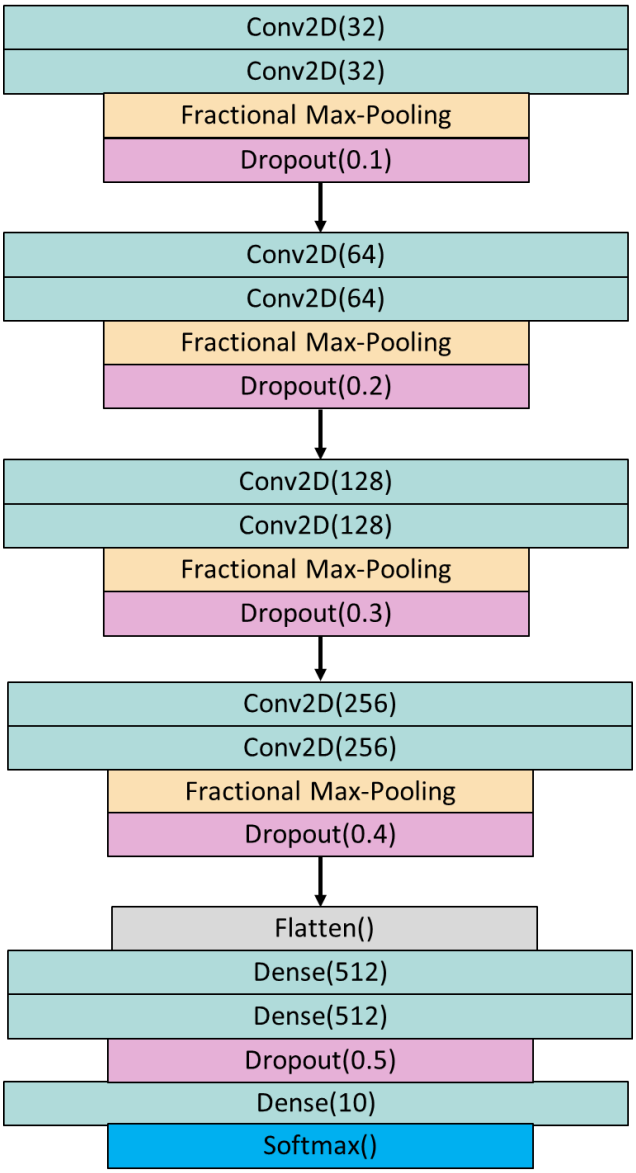
Data preprocess

Instead of directly dived the data by 255, I used z-score to normalize data.
(The last 11 rounds I used z-score and it improved my accuracy from around 0.78 to 0.7906~0.81.)
This picture shows my code of implementation of z-score.

```
#z-score
mean = np.mean(x_train,axis=(0,1,2,3))
std = np.std(x_train,axis=(0,1,2,3))
x_train = (x_train-mean)/(std+1e-7)
x_test = (x_test-mean)/(std+1e-7)
```

Model Structure (referred to the B website**)**

This is the simplified graph of my structure, I tried to use different number of the filter layer, Max_pooling and sense layer. I got better performance when I used more layers of filter, and more pooling layers, but when I increased the dense layers, the accuracy didn't improve as I thought. I think filters and pooling contribute more then dense layer, if the model has enough convolution times and pooling, it only needs one or two dense layer to classify these data.



I used BatchNormalization() to normalize the activation of the previous layer at each batch as a regularizer. (Referred to the A website)

I also used Fractional Max-Pooling to replace the usual Max-Pooling Model, and it slight improved my performance from 0.8511 to 0.8637 in previous training. (Showed in the attached table)

The settings of learning rate and optimizer

I implement different optimizers, learning rate, decay and factor by ReduceLROnPlateau from keras.callbacks, and I get over 0.8 accuracy by using Nadam optimizer with 0.0008 for learning rate, 0.004 for schedule_decay, 0.4 for factor and patience= 2, but I couldn't get over 0.9 although I tried different settings of other parameter like batch size, so in the end I try the setting in the reference A website and I got best performance (over 0.9), the code of decay schedule showed below:

```
def lr_schedule(epoch):
    lrate = 0.001
    if epoch > 75:
        lrate = 0.0005
    if epoch > 100:
        lrate = 0.0003
    return lrate
```

By using this schedule, I forced the model to train by larger learning rate till over 75 epochs. I think the previous round when I use ReduceLROnPlateau to reduce learning rate by patience = 2, my model got stuck in the local minima, I guess if I change patience to larger number (like 5 or 8) may improve the performance in previous settings.

The settings of learning epoch and batch_size

I tried 50, 75, 100, 125, 150 epochs and 64, 100, 200 batch_size, and I get best accuracy by using epoch = 125 and batch_size = 64.

Data augmentation

I used ImageDataGenerator to generate data for training. The parameters I used is: rotation_range=40, width_shift_range=0.2, height_shift_range=0.2, shear_range=0.2, zoom_range=0.2, horizontal_flip=True, fill_mode="nearest". I think to rotate image by 40 degree and shift it around 0.2 is a fine criteria cause I could recognize this image after the changes, and also flip the data horizontally. In our class we have the labels of " automobile" and "ship", I think these kind of image will be weird if I flip it vertically, so I only set horizontal_flip=True but not vertical.

I referred to this two websites for the structure and data normalization methods:

A. https://appliedmachinelearning.blog/2018/03/24/achieving-90-accuracy-in-object-recognition-task-on-cifar-10-dataset-with-keras-convolutional-neural-networks/?fbclid=IwAR3_p9HF8UTP4xKnPnzz_v6-OwkPoDZTdumLV_pmaBQWUW0g0EdUOIcv_1k
B. https://laplacetw.github.io/data-sci-vgg-cifar10/

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