Smart Waste Management System for Metropolitan Cities - ASSIGNMENT 4

Write code and connections in wokwi for ultrasonic sensors.Whenever distance is less than 100 cms send "alert" to ibm cloud anddisplay in device recent events.Upload document with wokwi share link and images of ibmcloud

CODE:

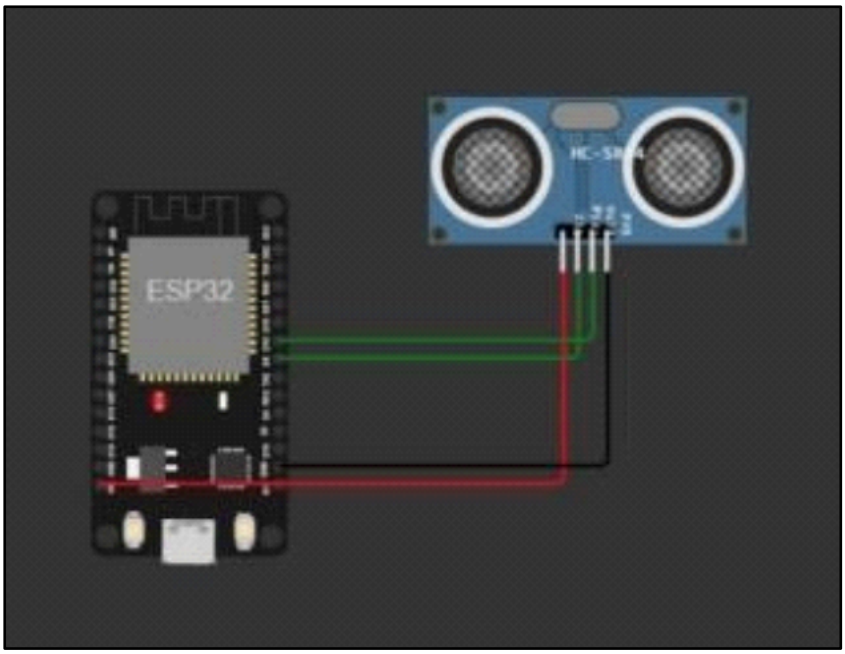
```
include #<WiFi.h>

#include <PubSubClient.h>

WiFiClient wifiClient;

#define ORG "jant3i"

#define DEVICE_TYPE "raspberrypi"

#define DEVICE_ID "USE YOUR ID"

#define TOKEN "USE YOUR TOKEN"

#define speed 0.034

char server[] = ORG

".messaging.internetofthings.ibmcloud.com"; char

publishTopic[] = "iot-2/evt/raspberrypi_1/fmt/json";

char topic[] = "iot-2/cmd/home/fmt/String";

char authMethod[] = "use-token-auth";

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;

PubSubClient client(server, 1883, wifi

char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
```

```
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
long duration;
float dist;
void setup()
{
Serial.begin(115200);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
}
void loop() {
publishData();
delay(500);
if (!client.loop()) {
mqttConnect();
}
}
void wifiConnect() {
Serial.print("Connecting to "); Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
```

```
}
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP()); }
void mqttConnect() {
if (!client.connected()) {
Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice() {
if (client.subscribe(topic)) {
// Serial.println(client.subscribe(topic));
Serial.println("subscribe to cmd OK");
}
else {
Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
{
digitalWrite(trigpin,LOW);
```

```
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
String payload = "{\"Alert distance\":";
payload +=
dist; payload
+= "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str()))
{ Serial.println("Publish OK");
} else {
Serial.println("Publish FAILED");
}
}
}
```

CONNECTIONS:



WOKWI LINK:

https://wokwi.com/projects/347022808948146772

OUTPUT: