

Implementation of famous research paper (SIAMESE NETWORK) in pytorch [PAPER TO PROJECT]

1) Importing important libraries

```
import torch.nn as nn
import torch.nn.functional as F
from torch.utils.data import DataLoader, TensorDataset
from sklearn.model_selection import train_test_split

!pip install opencv-python

Requirement already satisfied: opencv-python in c:\users\chiranjee\anaconda3\lib\site-packages (4.9.0.80)
Requirement already satisfied: numpy>=1.21.2 in c:\users\chiranjee\anaconda3\lib\site-packages (from opencv-python) (1.24.3)

import numpy as np
import matplotlib.pyplot as plt
import random
import cv2
```

2) Creating Directories using "os"

```
POS_PATH=os.path.join('data', 'positives')
NEG_PATH=os.path.join('data', 'negatives')
ARCH_PATH=os.path.join('data', 'archs')

os.makedirs(POS_PATH, exist_ok=True)
os.makedirs(NEG_PATH, exist_ok=True)
os.makedirs(ARCH_PATH, exist_ok=True)

POS_PATH
'data\\positives'
```

3) Giving universal unique identifier(uuid) to each image in files basically to identify each image uniquely and importing them into specific folders at the same time using different trigger keys

```
import uuid

cap=cv2.VideoCapture(0)
while(True):
```

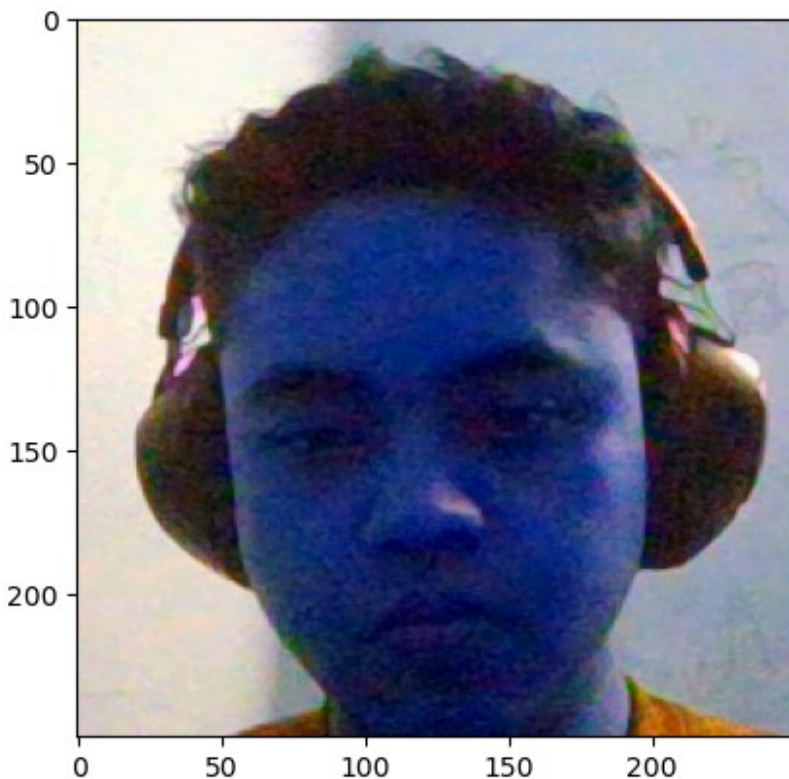
```

ret, frame=cap.read()
cv2.imshow('Image', frame[150:150+250, 220:220+250,:])
if cv2.waitKey(1)&0xFF==ord('p'):
    imagename=os.path.join(POS_PATH, '{}.jpg'.format(uuid.uuid1()))
    cv2.imwrite(imagename, frame)
if cv2.waitKey(1)&0xFF==ord('a'):

imagenam=os.path.join(ARCH_PATH, '{}.jpg'.format(uuid.uuid1()))
cv2.imwrite(imagenam, frame)
if cv2.waitKey(1)&0xFF==ord('q'):
    break
cap.release()
cv2.destroyAllWindows()

plt.imshow(frame[150:150+250, 220:220+250,:])
<matplotlib.image.AxesImage at 0x1cfffcdcf0d0>

```



4) Unzipping the negatives that we have downloaded and transferring to previously created files

```

!tar xf lfw.tgz

for directory in os.listdir('lfw'):
    directory_path=os.path.join('lfw',directory)

```

```

for file in os.listdir(directory_path):
    EX_PATH=os.path.join('lfw',directory,file)
    NEW_PATH=os.path.join(NEG_PATH,file)
    os.replace(EX_PATH,NEW_PATH)

```

5) Importing data from "RESEARCH" directory

```

import torch
from torch.utils.data import DataLoader
from torchvision import datasets,transforms

target_size=(250,250)
path=r'D:\RESEARCH\data'

data=datasets.ImageFolder(root=path,transform=transforms.Compose([tran
sforms.Resize(target_size),transforms.ToTensor(),]))

data

Dataset ImageFolder
  Number of datapoints: 900
  Root location: D:\RESEARCH\data
  StandardTransform
Transform: Compose(
  Resize(size=(250, 250), interpolation=bilinear,
max_size=None, antialias=warn)
  ToTensor()
)

class_labels = data.classes
class_names = [name.split("\\")[-1] for name in class_labels] #
Extract class names from paths

# Print the available classes
print("Available Classes:", class_names)

Available Classes: ['archs', 'negatives', 'positives']

```

6) Partitioning the data and batching it for training

```

info_anchor=[]
info_neg=[]
info_pos=[]
for x,y in data:
    if y==0:
        info_anchor.append(x[0])
    elif y==1:
        info_neg.append(x[0])

```

```

        else:
            info_pos.append(x[0])
    len(info_anchor)
    300

info_0_tensor = torch.zeros(300, 1, 250, 250)
info_1_tensor = torch.zeros(300, 1, 250, 250)
info_2_tensor = torch.zeros(300, 1, 250, 250)
label_0_tensor = torch.zeros(300)
label_1_tensor = torch.zeros(300)
label_2_tensor = torch.zeros(300)

for i in range(300):
    info_0_tensor[i, 0, :, :] = torch.tensor(info_anchor[i]).view(1,
250, 250)
    info_1_tensor[i, 0, :, :] = torch.tensor(info_neg[i]).view(1, 250,
250)
    info_2_tensor[i, 0, :, :] = torch.tensor(info_pos[i]).view(1, 250,
250)

    label_0_tensor[i] = torch.tensor([0])
    label_1_tensor[i] = torch.tensor([1])
    label_2_tensor[i] = torch.tensor([0])

train_data, test_data, train_label, test_label = train_test_split(info_0_te
nsor, label_0_tensor, train_size=0.9)
train_0_pytorch = TensorDataset(train_data, train_label)
test_0_pytorch = TensorDataset(test_data, test_label)
train_0_loader = DataLoader(train_0_pytorch, shuffle=True, batch_size=32, d
rop_last=True)
test_0_loader = DataLoader(train_0_pytorch, shuffle=True, batch_size=32, dr
op_last=True)

train_data, test_data, train_label, test_label = train_test_split(info_1_te
nsor, label_1_tensor, train_size=0.9)
train_1_pytorch = TensorDataset(train_data, train_label)
test_1_pytorch = TensorDataset(test_data, test_label)
train_1_loader = DataLoader(train_1_pytorch, shuffle=True, batch_size=32, d
rop_last=True)
test_1_loader = DataLoader(train_1_pytorch, shuffle=True, batch_size=32, dr
op_last=True)

train_data, test_data, train_label, test_label = train_test_split(info_2_te
nsor, label_2_tensor, train_size=0.9)
train_2_pytorch = TensorDataset(train_data, train_label)
test_2_pytorch = TensorDataset(test_data, test_label)

```

```
train_2_loader=DataLoader(train_2_pytorch,shuffle=True,batch_size=32,drop_last=True)
test_2_loader=DataLoader(train_2_pytorch,shuffle=True,batch_size=32,drop_last=True)
```

```
C:\Users\Chiranjeet\AppData\Local\Temp\ipykernel_22188\2254438236.py:9: UserWarning: To copy construct from a tensor, it is recommended to use sourceTensor.clone().detach() or sourceTensor.clone().detach().requires_grad_(True), rather than torch.tensor(sourceTensor).
```

```
info_0_tensor[i, 0, :, :] = torch.tensor(info_anchor[i]).view(1, 250, 250)
```

```
C:\Users\Chiranjeet\AppData\Local\Temp\ipykernel_22188\2254438236.py:10: UserWarning: To copy construct from a tensor, it is recommended to use sourceTensor.clone().detach() or sourceTensor.clone().detach().requires_grad_(True), rather than torch.tensor(sourceTensor).
```

```
info_1_tensor[i, 0, :, :] = torch.tensor(info_neg[i]).view(1, 250, 250)
```

```
C:\Users\Chiranjeet\AppData\Local\Temp\ipykernel_22188\2254438236.py:11: UserWarning: To copy construct from a tensor, it is recommended to use sourceTensor.clone().detach() or sourceTensor.clone().detach().requires_grad_(True), rather than torch.tensor(sourceTensor).
```

```
info_2_tensor[i, 0, :, :] = torch.tensor(info_pos[i]).view(1, 250, 250)
```

```
for x,y in train_0_loader:
    print(x.shape,y.shape)
```

```
torch.Size([32, 1, 250, 250]) torch.Size([32])
torch.Size([32, 1, 250, 250]) torch.Size([32])
torch.Size([32, 1, 250, 250]) torch.Size([32])
torch.Size([32, 1, 250, 250]) torch.Size([32])
torch.Size([32, 1, 250, 250]) torch.Size([32])
torch.Size([32, 1, 250, 250]) torch.Size([32])
torch.Size([32, 1, 250, 250]) torch.Size([32])
torch.Size([32, 1, 250, 250]) torch.Size([32])
torch.Size([32, 1, 250, 250]) torch.Size([32])
```

7) Creating user defined ContrastiveLoss mentioned in the paper

```
#loss fuction definition
class ContrastiveLoss(torch.nn.Module):
    def __init__(self,margin=2.0):
        super(ContrastiveLoss,self).__init__()
        #defining parameters
        self.margin =margin

    def forward(self,output1,output2,label):
        #calculate the euclidean distance and calculate the contastive
```

```

loss
    euclidean_distance =
F.pairwise_distance(output1,output2,keepdim = True)
    loss_contrastive =torch.mean((1-
label)*torch.pow(euclidean_distance,2)+
    (label)*torch.pow(torch.clamp(self.margin-
euclidean_distance,min=0.0),2))

    return loss_contrastive

```

8) Creating working SIAMESE network architecture by getting ideas from the paper

```

#Saemese Network

import torch
import torch.nn as nn

class Siamese(nn.Module):
    class arc(nn.Module):
        def __init__(self):
            super().__init__()
            ### Convolutional layers
            self.cnn1 = nn.Sequential(
                nn.Conv2d(1, 96, kernel_size=3, stride=4),
                nn.ReLU(),
                nn.MaxPool2d(3, stride=2),
                nn.Conv2d(96, 256, kernel_size=5, stride=1),
                nn.ReLU(),
                nn.MaxPool2d(2, stride=2),
                nn.Conv2d(256, 384, kernel_size=3, stride=1),
                nn.ReLU(inplace=True)
            )
            # Calculate the output size after convolutional layers
            self.conv_output_size = self._get_conv_output_size()

            # Setting up the fully connected layers
            self.fc1 = nn.Sequential(
                nn.Linear(self.conv_output_size, 1024), # Adjust
input features to match conv_output_size
                nn.ReLU(),
                nn.Linear(1024, 256),
                nn.ReLU(),
                nn.Linear(256, 2)
            )

        def _get_conv_output_size(self):
            # Compute the output size after convolutional layers
            with torch.no_grad():
                dummy_input = torch.zeros(1, 1, 250, 250) # Assuming

```

```

input size is 250x250
        conv_output = self.cnn1(dummy_input)
        conv_output_size =
conv_output.view(conv_output.size(0), -1).size(1)
        return conv_output_size

    def forward_once(self, x):
        output = self.cnn1(x)
        output = output.view(output.size(0), -1) # Flatten the
output tensor
        output = self.fc1(output)
        return output

    def forward(self, input1, input2):
        output1 = self.forward_once(input1)
        output2 = self.forward_once(input2)
        return output1, output2

    def __init__(self):
        super().__init__()
        self.siamese_network = self.arc()

    def forward(self, input1, input2):
        return self.siamese_network(input1, input2)

def network():
    net = Siamese()
    losfunc = ContrastiveLoss()
    optim = torch.optim.Adam(net.parameters(), lr=0.001)

    return net, losfunc, optim

net, losfunc, optim = network()

net

Siamese(
  (siamese_network): arc(
    (cnn1): Sequential(
      (0): Conv2d(1, 96, kernel_size=(3, 3), stride=(4, 4))
      (1): ReLU()
      (2): MaxPool2d(kernel_size=3, stride=2, padding=0, dilation=1,
ceil_mode=False)
      (3): Conv2d(96, 256, kernel_size=(5, 5), stride=(1, 1))
      (4): ReLU()
      (5): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
ceil_mode=False)

```

```

        (6): Conv2d(256, 384, kernel_size=(3, 3), stride=(1, 1))
        (7): ReLU(inplace=True)
    )
    (fc1): Sequential(
      (0): Linear(in_features=46464, out_features=1024, bias=True)
      (1): ReLU()
      (2): Linear(in_features=1024, out_features=256, bias=True)
      (3): ReLU()
      (4): Linear(in_features=256, out_features=2, bias=True)
    )
  )
)

```

9) Creating an instance of fake data for passing through the network to check if everything is working right or not

```

x = torch.randn(1, 1, 250, 250)
y = torch.randn(1, 1, 250, 250)
# Example input tensor
output = net(x, y)
print(output)

(tensor([[ -3.0215,  7.0274]], grad_fn=<AddmmBackward0>), tensor([[ -3.0176,  7.0446]], grad_fn=<AddmmBackward0>))

```

10) Creating a training function compatible to the multiple output architecture

```

# passing it through the values
def train(net, losfunc, optim, train_0_loader, train_2_loader,
test_0_loader, test_2_loader, epochs=100):
    loss_train = []
    loss_test = []

    for epoch in range(epochs):
        for (x_1, y_1), (x_2, y_2) in zip(train_0_loader,
train_2_loader):
            net.train()
            yhat_1, yhat_2 = net(x_1, x_2)
            loss = losfunc(yhat_1, yhat_2, y_1)

            # Backward pass
            optim.zero_grad()
            loss.backward()
            optim.step()

```



```

        loss_train.append(loss.item())

    for (x_1, y_1), (x_2, y_2) in zip(train_0_loader,
train_2_loader):
        net.eval()
        # Forward pass
        yhat_1, yhat_2 = net(x_1, x_2)
        loss = losfunc(yhat_1, yhat_2, y_1)

        loss_test.append(loss.item())

    return loss_train, loss_test, net

loss_train, loss_test, net = train(net, losfunc, optim, train_0_loader,
train_2_loader, test_0_loader, test_2_loader, epochs=100)

loss_train
[5.527718016651306e-08,
 5.8577686701255516e-08,
 1.1540588218394987e-07,
 3.4740015308898364e-08,
 4.565072586615315e-08,
 6.930076779099181e-08,
 2.8790307027293238e-08,
 1.0859655930062218e-07,
 4.779775863994473e-08,
 7.755588171676209e-08,
 4.309327650275918e-08,
 1.9930853412120086e-08,
 2.663107245837182e-08,
 2.8717890288021408e-08,
 4.472492776130821e-08,
 2.833900403231837e-08,
 4.237619677383009e-08,
 3.8595548090825105e-08,
 6.910395455861362e-08,
 3.021778738343528e-08,
 5.192356056227254e-08,
 7.841487104087719e-08,
 4.6666002617712365e-08,
 7.973847715447846e-08,
 5.06299464575477e-08,
 7.127390944106082e-08,
 8.760829928178282e-08,
 7.38949736955874e-08,
 1.3433653123229305e-07,
 6.940953767298197e-08,
 1.0363532254586971e-07,
 6.678499886447753e-08,

```

8.333668688464968e-08,
1.031192482514598e-07,
3.0887083113384506e-08,
7.036577898134055e-08,
1.5182713752892596e-07,
2.607956446354365e-07,
1.0007743611595288e-07,
8.813145768726827e-08,
2.4786552899058734e-07,
1.5405485953579046e-07,
3.3616558425819676e-07,
1.9873547785209666e-07,
7.661589052077034e-08,
2.3095752510471357e-07,
9.868477945929044e-08,
1.1179623271573291e-07,
6.797387896995133e-08,
6.944832620092711e-08,
5.566906935428051e-08,
8.909143645041695e-08,
3.3562955081833934e-08,
4.785095342185741e-08,
5.395123281459746e-08,
2.5179557994192692e-08,
8.95373375442432e-08,
4.679483467384671e-08,
7.293136405905898e-08,
6.227345039633292e-08,
4.6882540516435256e-08,
6.258510865109201e-08,
9.192182659489845e-08,
5.4047745834395755e-08,
6.346743219864948e-08,
5.249540180329859e-08,
3.713179452802251e-08,
8.704558496219761e-08,
9.956914226449953e-08,
4.1478241286085904e-08,
3.4812135396578014e-08,
4.609038128933207e-08,
3.308613472086108e-08,
8.288936470535191e-08,
5.3279563871910796e-08,
1.0985699816501437e-07,
7.789781619749192e-08,
1.5248521378907753e-07,
6.049507561556311e-08,
4.9804093293914775e-08,
8.160428421888355e-08,

7.740990781712753e-08,
4.265312014695155e-08,
1.8896616893471219e-07,
8.841390553016026e-08,
1.5540916820100392e-07,
1.0879840317556955e-07,
7.339326657529455e-08,
4.714341059752769e-07,
5.271263603390253e-08,
3.1122047516873863e-07,
2.3844219754209917e-07,
3.994386759131885e-07,
4.2587041093611333e-07,
1.5120252783162869e-07,
5.052248184256314e-07,
8.758820513321552e-08,
1.8878591845350456e-07,
2.1137432781870302e-07,
1.44396821610826e-07,
2.289128531174356e-07,
2.158232206284083e-07,
9.60567874130902e-08,
1.187769456123533e-07,
1.0939577776980514e-07,
6.389345230672916e-08,
1.1472421590497106e-07,
2.981215985187191e-08,
5.353174614697309e-08,
3.22638271654796e-08,
5.592596963310825e-08,
6.858386569774666e-08,
4.159684863225266e-08,
3.6059301322666215e-08,
3.3765783058470333e-08,
2.0061296623907765e-08,
3.631220479860531e-08,
6.557675646945427e-08,
2.7217355480502192e-08,
4.253669771969726e-08,
3.640792201053955e-08,
3.087039956994886e-08,
3.4140779092695084e-08,
3.738000131647823e-08,
3.712213469952985e-08,
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2.359948148011881e-08,
5.473334141470332e-08,
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2.39746640318117e-08,
3.8677409719412026e-08,
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4.596296321324189e-08,
2.6908184125318257e-08,
3.939966575217113e-08,
3.714683316502487e-08,
3.001268211733077e-08,
4.9371099208883606e-08,
3.8634610177723516e-08,
2.6274561193417867e-08,
2.8093181114741128e-08,
3.34901955056921e-08,
3.78203850459613e-08,
7.12508878564222e-08,
6.662239115939883e-08,
1.1136615540863204e-07,
1.0582510867607198e-07,
7.838014681738059e-08,
1.455335336686403e-07,
5.4415757233527984e-08,
1.6005344605218852e-07,
9.904858444542697e-08,
2.9025366643509187e-07,
8.654987482259457e-08,
1.1176756942177235e-07,
8.947994700747586e-08,
4.541849207839732e-08,
8.789640304485147e-08,
4.587982971315796e-08,
4.223634064715043e-08,
4.4239580887506236e-08,
3.7894121618364807e-08,
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6.006572306205271e-08,
1.7960631737423682e-07,
1.399309752514455e-07,
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1.7699301224638475e-07,

7.848137073551698e-08,
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1.0891280055602692e-07,
2.453716376749071e-07,
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7.554385206276493e-08,
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1.5760393523578387e-07,
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2.477144391832553e-07,
8.232390769080666e-07,
3.9591827771801036e-07,
3.482078057004401e-07,
1.1719143913069274e-06,
3.4859365882766724e-07,
1.1049615977754002e-06,
1.8615885437611723e-06,
1.880046283986303e-06,
8.923021255213825e-07,
8.070101671364682e-07,
5.66603887364181e-07,
2.958666982522118e-07,
3.9784029581824143e-07,
2.512424828182702e-07,
1.825495132834476e-07,
2.8891724923596485e-07,
3.324977342344937e-07,
2.3757658595968678e-07,
2.075390881373096e-07,
3.133599193461123e-07,
3.785305295878061e-07,

1.8038673488263157e-07,
2.448703071422642e-07,
9.222832630939592e-08,
4.62145237634104e-07,
2.9040322147011466e-07,
3.008188969033654e-07,
2.2048529046969634e-07,
2.7641866040539753e-07,
1.495109245297499e-07,
1.9519100646903098e-07,
2.518803796647262e-07,
1.8972163218222704e-07,
1.8967864434671355e-07,
3.257921150634502e-07,
1.9300044584724674e-07,
9.708855230883273e-08,
2.2338784333442163e-07,
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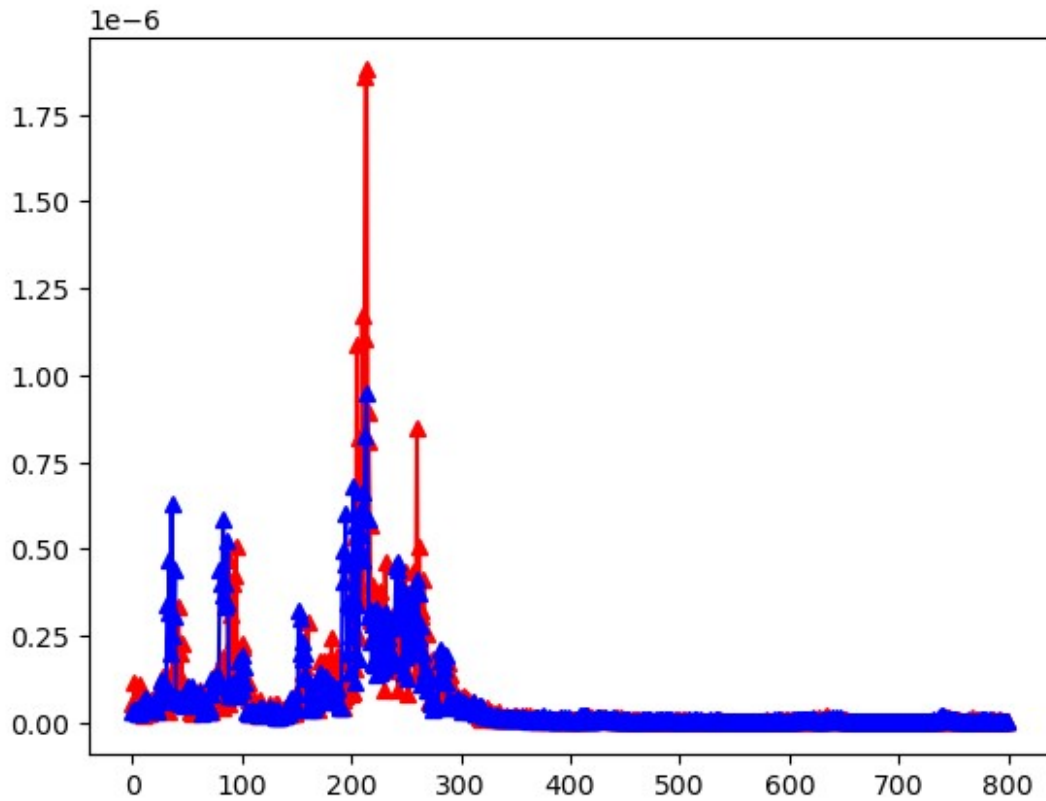
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plt.plot(loss_train, 'r^-')  
plt.plot(loss_test, 'b^-')
```

```
[<matplotlib.lines.Line2D at 0x1f2e3f7e610>]
```



11) Using Euclidean distance to differentiate positive and negatives

```
x,y=next(iter(train_0_loader))
x_1,y_1=next(iter(train_1_loader))
x_2,y_2=next(iter(train_2_loader))
output_1,output_2=net(x,x_1)
output_3,output_4=net(x,x_2)
similarity_1=F.pairwise_distance(output_3,output_4)
similarity=F.pairwise_distance(output_1,output_2)
print(similarity_1)
print(similarity)
```

```
tensor([1.6064e-04, 2.7940e-05, 3.1236e-05, 1.2562e-04, 1.6353e-06,
        1.0673e-04,
         1.0659e-04, 8.0889e-05, 6.7923e-05, 6.4562e-05, 9.0838e-05,
        8.0660e-05,
         4.7450e-05, 1.6541e-05, 1.5452e-05, 1.0662e-04, 7.7757e-05,
        5.3569e-05,
         2.4170e-05, 1.1588e-05, 7.5811e-05, 3.0322e-05, 7.3756e-05,
        5.0895e-05,
         1.2238e-04, 4.6117e-05, 6.2961e-05, 5.0414e-05, 5.1708e-05,
        4.7672e-05,
         3.9189e-05, 1.0763e-04], grad_fn=<NormBackward1>)
tensor([0.0002, 0.0003, 0.0008, 0.0013, 0.0011, 0.0003, 0.0018,
        0.0010, 0.0029,
```

```

        0.0011, 0.0010, 0.0008, 0.0008, 0.0020, 0.0012, 0.0002,
0.0004, 0.0011,
        0.0003, 0.0013, 0.0005, 0.0005, 0.0010, 0.0006, 0.0014,
0.0005, 0.0006,
        0.0001, 0.0011, 0.0002, 0.0013, 0.0004],
grad_fn=<NormBackward1>)
x_1,y_1=next(iter(train_0_loader))
x_3,y_3=next(iter(train_2_loader))

output_3,output_4=net(x_1,x_3)

x_plot_1 = np.transpose(x_1, (0, 2, 3, 1))
x_plot_3 = np.transpose(x_3, (0, 2, 3, 1))

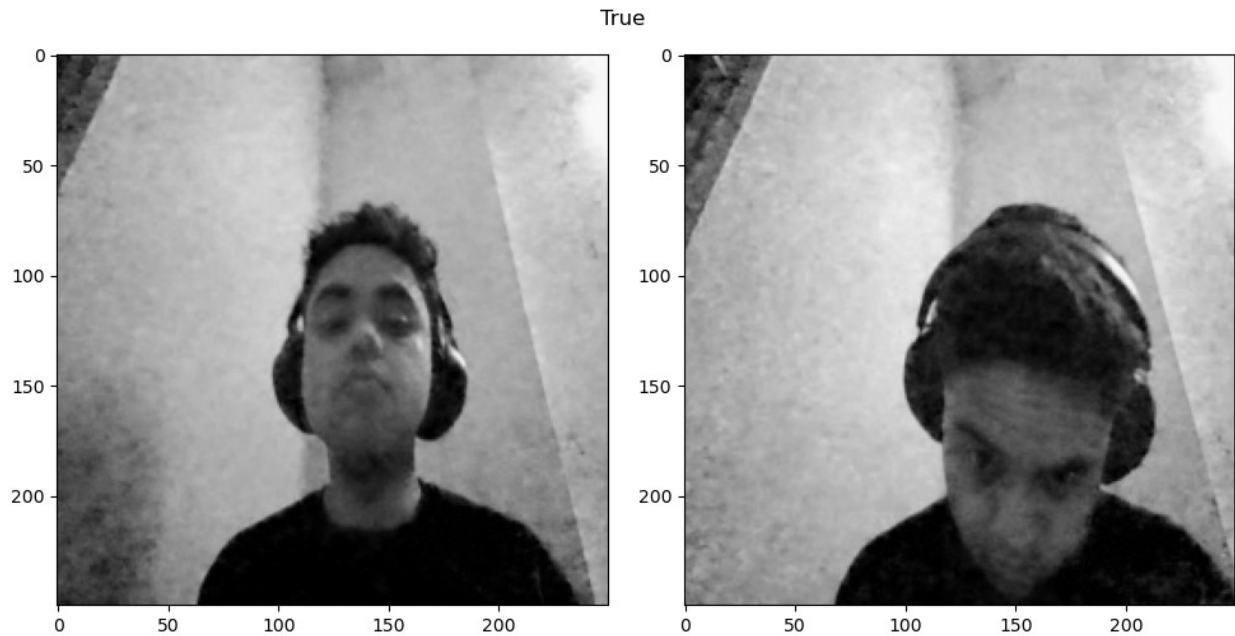
x_rgb_1 = np.repeat(x_plot_1, 3 ,axis=3)
x_rgb_3 = np.repeat(x_plot_3, 3 ,axis=3)
fig,ax=plt.subplots(1,2,figsize=(10,5))

ax[0].imshow(x_rgb_1[0])
ax[1].imshow(x_rgb_3[0])

plt.suptitle(f'{(F.pairwise_distance(output_3[0],output_4[0]))<1e-
04})}')

plt.tight_layout()
plt.show()

```

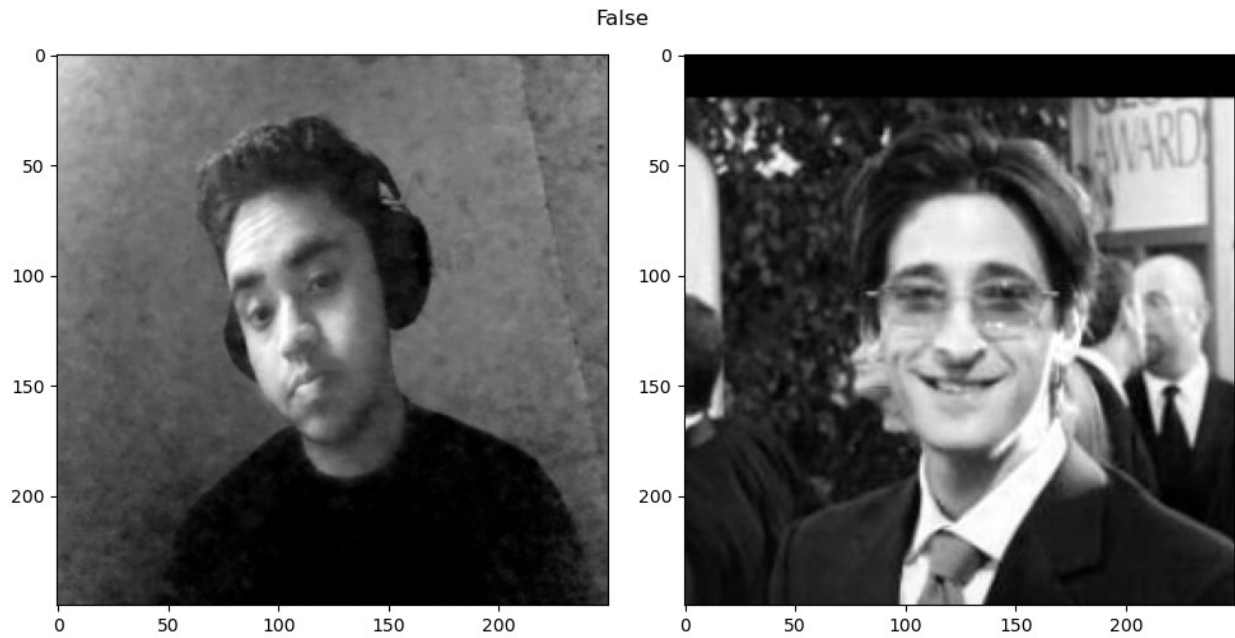


```
x_1,y_1=next(iter(train_0_loader))
x_2,y_2=next(iter(train_1_loader))
output_1,output_2=net(x_1,x_2)
x_plot_1 = np.transpose(x_1, (0, 2, 3, 1))
x_plot_2 = np.transpose(x_2, (0, 2, 3, 1))
x_rgb_1 = np.repeat(x_plot_1, 3 ,axis=3)
x_rgb_2 = np.repeat(x_plot_2, 3 ,axis=3)
fig,ax=plt.subplots(1,2,figsize=(10,5))

ax[0].imshow(x_rgb_1[0])
ax[1].imshow(x_rgb_2[0])

plt.suptitle(f'{{(F.pairwise_distance(output_1[0],output_2[0])<1e-
04)}}')

plt.tight_layout()
plt.show()
```



Hence, we have successfully converted paper research work into real time implementation project