## 共轭梯度法

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#### 共轭梯度法

共轭梯度法 (conjugate gradient method, CG) 是以共轭方向 (conjugate direction) 作为搜索方向的一类算法。

共轭梯度法是由Hesteness和Stiefel于1952年为求解线性方程组而提出的。后来用于求解无约束最优化问题,它是一种重要的数学优化方法。



Fig. 1. Wolfgang Wasow (left) and Magnus Hestenes (right).



Fig. 2. Eduard Stiefel [From Zeitschrift für angewandte Mathematik und Physik 30, 139 (1979); used with permission].

#### 线性方程组 Ax = b, 其中A为n阶对称正定矩阵

$$Ax = b \iff \min \phi(x) := \frac{1}{2} \left( x - x^* \right)^T A \left( x - x^* \right)$$

$$\iff \min \frac{1}{2} \left( Ax, x \right) - \left( b, x \right) + \frac{1}{2} \left( x^*, b \right)$$

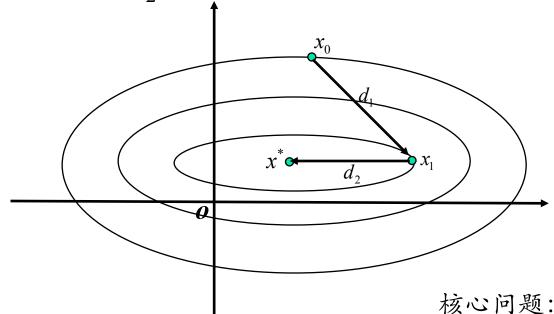
无约束最优化问题  $\min \varphi(x) := \frac{1}{2} (Ax, x) - (b, x)$ 

 $x^*$ 是线性方程组的解  $\longleftrightarrow$   $\varphi(x^*) = \min \varphi(x)$ 



$$\min \varphi(x) := \frac{1}{2} \left( Ax, x \right) - \left( b, x \right) \quad \longleftrightarrow \quad \min \phi(x) := \frac{1}{2} \left( x - x^* \right)^T A \left( x - x^* \right)$$

函数 $\phi(x)$ 的等值面 $\frac{1}{2}(x-x^*)^T A(x-x^*) = c$ 表示以 $x^*$ 为中心的椭球面



核心问题:确定方向、步长

#### 最速下降法

$$\min \varphi(x) := \frac{1}{2} (Ax, x) - (b, x)$$

下降方向: 负梯度方向

$$r = -\nabla \varphi(x) = -(Ax - b) = b - Ax$$

步长: 寻求步长 $\alpha$ , 使得  $\varphi(x+\alpha r) = \min$ 

$$\varphi(x+\alpha r) = \frac{1}{2} \Big( A(x+\alpha r), (x+\alpha r) \Big) - \Big( b, (x+\alpha r) \Big)$$

$$\frac{d\varphi(x+\alpha r)}{d\alpha} = \alpha (Ar,r) - (r,r) = 0$$

$$\alpha = \frac{(r,r)}{(Ar,r)}$$

#### 算法及收敛性分析

算法流程:对于给的初始向量x。

$$r_k = b - Ax_k$$

$$\alpha_k = (r_k, r_k)/(Ar_k, r_k)$$

$$k = 0, 1, 2, ...$$

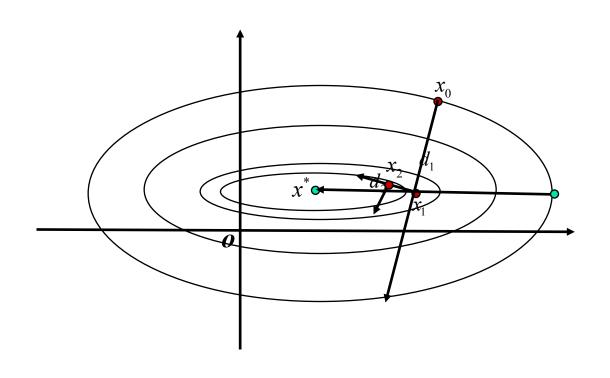
$$x_{k+1} = x_k + \alpha_k r_k$$

#### 收敛性定理:

$$\begin{split} & \left(r_{k+1}, r_{k}\right) = 0, \qquad k = 0, 1, 2, \dots \\ & \left\|x_{k} - x^{*}\right\|_{A} \leq \left(\frac{\lambda_{1} - \lambda_{n}}{\lambda_{1} + \lambda_{n}}\right)^{k} \left\|x_{0} - x^{*}\right\|_{A} \\ & + c \cdot \left(\frac{\lambda_{1} - \lambda_{n}}{\lambda_{1} + \lambda_{n}}\right)^{k} \left\|x_{0} - x^{*}\right\|_{A} \\ & + c \cdot \left(\frac{\lambda_{1} - \lambda_{n}}{\lambda_{1} + \lambda_{n}}\right)^{k} \left\|x_{0} - x^{*}\right\|_{A} \end{split}$$



## 最速下降法收敛速度



#### 共轭梯度法

$$\min \varphi(x) := \frac{1}{2} (Ax, x) - (b, x)$$

下降方向: 上步下降方向与当前残量的线性组合

$$p_k = r_k + \beta_{k-1} p_{k-1}$$

步长: 寻求步长 $\alpha$ , 使得 $\varphi(x+\alpha p) = \min$ 

$$\alpha = \frac{(r,p)}{(Ap,p)}$$

# 下降方向的计算

$$\min \varphi(x) := \frac{1}{2} (Ax, x) - (b, x)$$

对于
$$p_k = r_k + \beta_{k-1} p_{k-1}$$
,选择 $\beta_{k-1}$ ,使得

$$\varphi(x_k + \alpha_k (r_k + \beta_{k-1} p_{k-1})) = \min$$

$$\frac{d\varphi\left(x_{k}+\alpha_{k}\left(r_{k}+\beta p_{k-1}\right)\right)}{d\beta}=\left(\alpha_{k}^{2} p_{k-1}^{T} A p_{k-1}\right)\beta-\alpha_{k}\left(p_{k-1}^{T} r_{k}-\alpha_{k} p_{k-1}^{T} A r_{k}\right)=0$$

由于 
$$p_{k-1}^T r_k = 0$$
,

$$\beta_{k-1} = \frac{p_{k-1}^{T} A r_{k}}{p_{k-1}^{T} A p_{k-1}}$$

#### 共轭梯度法性质

$$(p_i, r_k) = 0, \quad i = 0, 1, ..., k-1$$
  
 $(r_i, r_k) = 0, \quad i = 0, 1, ..., k-1$   
 $(Ap_i, p_k) = 0, \quad i = 0, 1, ..., k-1$ 

共轭梯度法最多迭代n步即可求得问题的精确解

$$\alpha_{k} = \frac{(r_{k}, p_{k})}{(Ap_{k}, p_{k})} = \frac{(r_{k}, r_{k} + \beta_{k-1}p_{k-1})}{(Ap_{k}, p_{k})} = \frac{(r_{k}, r_{k})}{(Ap_{k}, p_{k})}$$

$$\beta_{k-1} = \frac{p_{k-1}^{T}Ar_{k}}{p_{k-1}^{T}Ap_{k-1}} = \frac{r_{k}^{T}(r_{k-1} - r_{k})}{p_{k-1}^{T}Ap_{k-1}} \frac{1}{\alpha_{k-1}} = \frac{(r_{k}, r_{k})}{(r_{k-1}, r_{k-1})}$$

#### 算法流程

对于给的初始向量
$$x_0$$
,  $r_0 = p_0 = b - Ax_0$ 

$$\alpha_k = (r_k, r_k) / (Ap_k, p_k)$$

$$x_{k+1} = x_k + \alpha_k p_k$$

$$r_{k+1} = r_k - \alpha_k A p_k$$

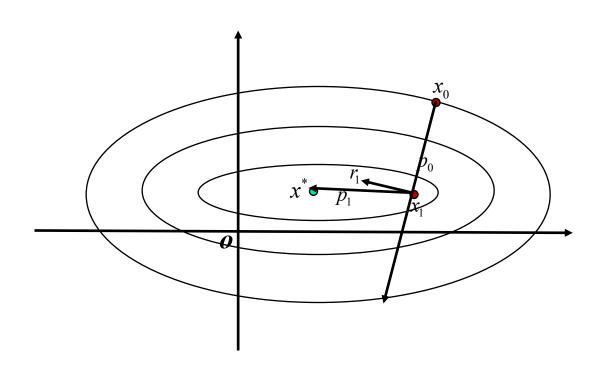
$$\beta_k = (r_{k+1}, r_{k+1})/(r_k, r_k)$$

$$p_{k+1} = r_{k+1} + \beta_k p_k$$

$$k = 0, 1, 2, \dots$$



## 共轭梯度法收敛速度



#### 例题

共轭梯度法求解线性方程组 
$$\begin{pmatrix} 2 & 0 & 1 \\ 0 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$
  $x_0 = \begin{pmatrix} 0 & 0 & 0 \end{pmatrix}^T$ 

$$\beta_0 = (r_1, r_1)/(r_0, r_0) = 1/50$$

$$r_0 = p_0 = b - Ax_0 = \begin{pmatrix} 1 & 1 & 1 \end{pmatrix}^T \qquad p_1 = r_1 + \beta_0 p_0 = \begin{pmatrix} 3/25 & 3/25 & -9/50 \end{pmatrix}^T$$

$$\alpha_0 = (r_0, r_0)/(p_0, Ap_0) = 3/10 \qquad \alpha_1 = (r_1, r_1)/(p_1, Ap_1) = 5/3$$

$$x_1 = x_0 + \alpha_0 p_0 = \begin{pmatrix} 3/10 & 3/10 & 3/10 \end{pmatrix}^T \qquad x_2 = x_1 + \alpha_1 p_1 = \begin{pmatrix} 1/2 & 1/2 & 0 \end{pmatrix}^T$$

$$r_1 = b - Ax_1 = \begin{pmatrix} 1/10 & 1/10 & -2/10 \end{pmatrix}^T \qquad r_2 = b - Ax_2 = \begin{pmatrix} 0 & 0 & 0 \end{pmatrix}^T$$