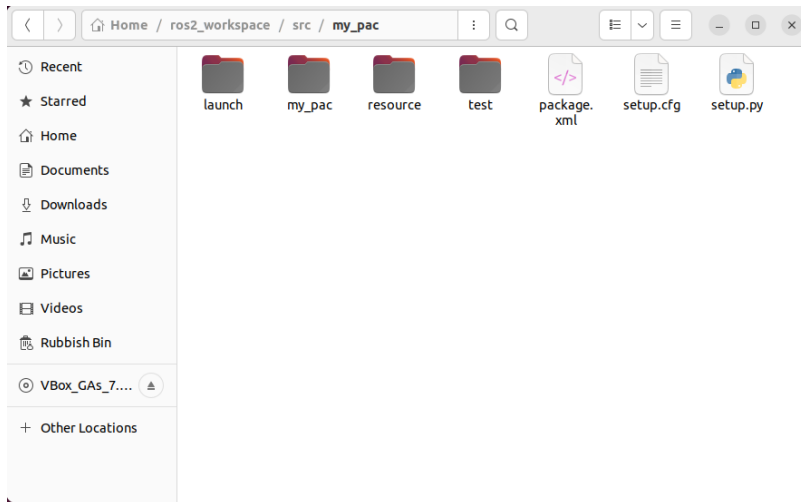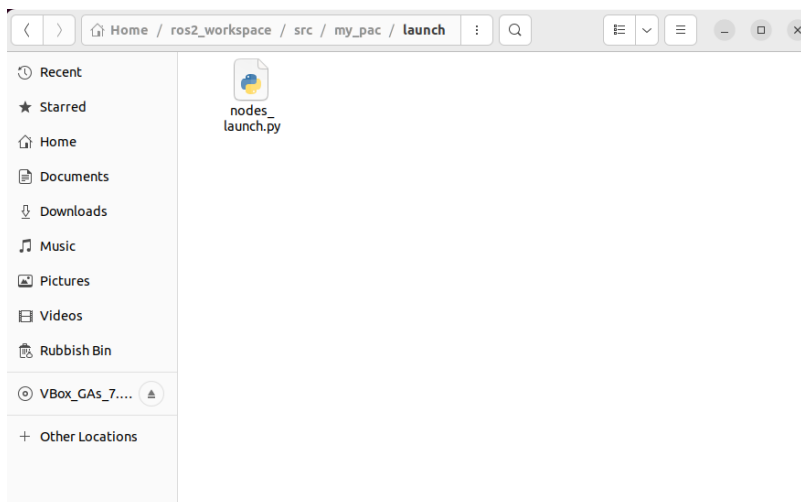# Automation Script

We provide an automated script to run all nodes in one go.

Firstly, create a launch folder under the in /my_pac/.

Place the nodes_launch.py file in the folder.

Add settings in setup.py

('share/' + package_name + '/launch', ['launch/nodes_launch.py']),

```
 5 setup(
 6     name=package_name,
 7     version='0.0.0',
 8     packages=find_packages(exclude=['test']),
 9     data_files=[
10         ('share/ament_index/resource_index/packages',
11             ['resource/' + package_name]),
12         ('share/' + package_name, ['package.xml']),
13         ('share/' + package_name + '/launch', ['launch/nodes_launch.py']),
14     ],
```

Afterwards, run the script using the following command:

```
cd ros2_workspace
colcon build
source install/setup.bash
ros2 launch my_pac nodes_launch.py
```

After running, use the following command to view the results:

```
ros2 topic echo /translated_sentence
```