

# Do / Be / Feel List

Who	Do	Be	Feel
Operator	Give voice commands	Responsive	Being understood
	Get feedback when items cannot be found	Easy to understand	Reliable
	Get feedback when action cannot be found	Clear and intuitive	Satisfied
	Get feedback when commands are not completed correctly	Repetitive	Engaged
	Get feedback when the command is completed	Robust	Surprised
	Can see/hear the command content	Adaptive	Confident
	Place the required items in front of the robot lens	Transparent	Timely
	Input executable actions into the system	Rapid	
	Input the required item information into the system	Specific	
	Create new robot action		
	Detect and separate objects visually		
	Detect the position and distance of an object in relation to the robot		
	Track parts of the human anatomy (gaze, gesture, body, face) visually		
	Be able to monitor objects are being detected and separated on the GUI		
	Be able to monitor the position of an object calculated in relation to the robot on the GUI		
	Be able to monitor human anatomy (gaze, gesture, body, face) being correctly perceived on the GUI		
	Interrupt the executing command		
	Restore the robotic arm to its initial state after the command is completed		
	Switch the entire system		
	Notify when an error occurs in any subsystem		
	Complete voice input of commands within a certain period of time		
Tech Support	Monitor the results of real-time object detection		
	Spot irregular behaviours or bugs in the object detection module		
	Update the system to recognize new actions and new combinations of commands		
	Stop execution of commands when necessary		
	Can see specific logs for each operation		