<u>Materia:</u> Cinemática de robots <u>Profesor</u>: Morán Garabito Carlos Enrique

TAREA 3

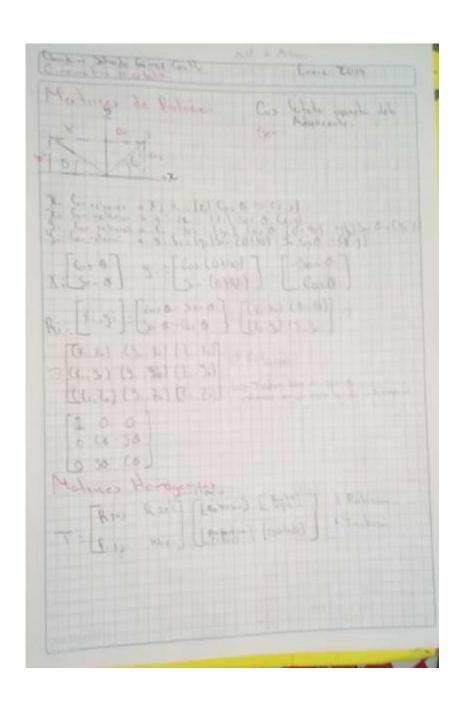
$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & T_x \\ 0 & 1 & T_y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

MATRICES DE ROTACION.

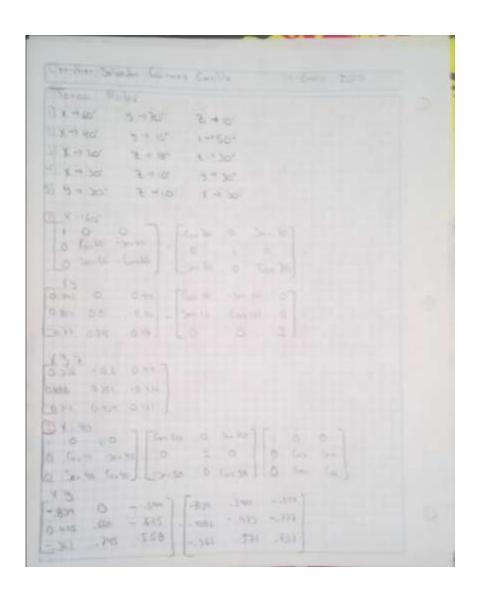
T/M 8'B UPZMG

Alumno: CHRISTIAN SALVADOR GOMEZ CARRILLO,





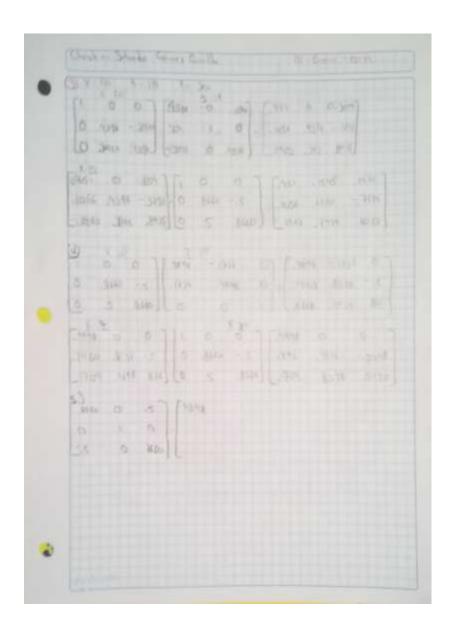




Alumno: CHRISTIAN SALVADOR GOMEZ CARRILLO,



<u>Materia:</u> Cinemática de robots <u>Profesor</u>: Morán Garabito Carlos Enrique



Alumno: CHRISTIAN SALVADOR GOMEZ CARRILLO,