

SPECTRA: Spectral Isotropy-Guided Training-Free Temporal Intervention for Long-Video VLMs

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Abstract. Long-video vision-language models often fail to use distant evidence because attention becomes highly concentrated on a few keys. We revisit this failure from a second-order viewpoint and show that temporal mRoPE anisotropy is controlled by two coupled conditions: block-wise isotropy within each rotary pair and cross-block decoupling across different frequencies. We further prove that, under finite discrete support, phase cancellation is incomplete for near-frequency pairs, leaving residual cross-subspace coupling that sharpens the covariance spectrum and compresses attention coverage. Motivated by this mechanism, we propose **SPECTRA**, a training-free temporal-only intervention. SPECTRA estimates per-head degradation through effective rank, allocates intervention strength with layer-head dual gating, and injects controlled Gaussian interpolation into temporal Q/K channels. The update preserves architecture, requires no retraining, and follows directly from the derived covariance dynamics.

Keywords: Long-Video VLM · mRoPE · Attention Anisotropy · Effective Rank · Training-Free Inference

1 Introduction

Long-video understanding requires integrating evidence across hundreds or thousands of frames. In mRoPE-based VLMs, a recurring failure mode is attention concentration: a few keys absorb most mass, and distant evidence receives little probability. This directly hurts temporal reasoning and multi-event integration.

Existing long-context fixes mostly adjust positional scaling or interpolation. They improve robustness, but they are mainly design heuristics and do not identify the structural source of collapse at layer/head level. Our goal is to derive a clear mechanism and translate it into a training-free intervention.

We show that long-video collapse is fundamentally a second-order problem in temporal channels. The key chain is

$$\begin{aligned} \text{incomplete phase cancellation} &\Rightarrow \text{cross-block covariance coupling} \\ &\Rightarrow \text{spectral peakedness} \\ &\Rightarrow \text{coverage compression.} \end{aligned} \tag{1}$$

The first implication comes from finite-support mRoPE phase analysis; the second and third come from covariance decomposition and logit-variance bounds.

Guided by this chain, we propose **SPECTRA**, a training-free temporal intervention. SPECTRA estimates degradation by effective rank, allocates strength with layer-head dual gating, and applies controlled Gaussian interpolation only to temporal Q/K channels on valid video tokens. The update is plug-and-play and architecture-preserving.

Contributions.

1. We provide a block-structured decomposition showing that global isotropy requires both intra-block isotropy and inter-block decoupling.
2. We analyze discrete phase cancellation and identify finite-support near-frequency coupling as a key source of residual anisotropy.
3. We prove a spectral-to-coverage link: spectral peakedness increases logit extremeness and compresses effective attention span.
4. We propose SPECTRA, a theory-aligned, training-free temporal intervention with explicit covariance-level effects and low overhead.

2 Related Work

2.1 RoPE and Long-Context Extrapolation

Long-context extrapolation for RoPE typically uses scaling, interpolation, or frequency remapping. These approaches improve stability for long sequences, but most analyses are frequency-local. Our perspective is complementary: we study the global second-order matrix after position aggregation and show that local smoothing is insufficient when cross-frequency blocks remain coupled.

2.2 Positional Encoding for Video-Language Models

Video-language models often apply multi-axis positional encoding across temporal and spatial axes. Prior studies indicate temporal encoding is the main bottleneck for long video. We provide a theoretical reason: temporal displacement grows with clip length, making temporal phase coverage increasingly sparse and error-prone under finite support.

2.3 Attention Anisotropy and Spectral Perspectives

Anisotropy in representations and attention has been widely studied via covariance spectra, condition numbers, and effective-rank metrics. Our work extends this line by connecting mRoPE phase dynamics to block-structured covariance coupling, and then connecting spectral peakedness to attention coverage compression.

3 Preliminaries and Problem Setup

3.1 Attention Setup and Notation

For layer l , head h , query index u , and key index v , attention is

$$s_{u,v}^{(l,h)} = \frac{\mathbf{q}_u^\top \mathbf{k}_v}{\sqrt{d_h}}, \quad \mathbf{a}_{u,:}^{(l,h)} = \text{softmax}(\mathbf{s}_{u,:}^{(l,h)}). \quad (2)$$

We focus on temporal mRoPE channels. Let $\mathbf{z}_{l,h,p} \in \mathbb{R}^{d_t}$ be the temporal feature at position p , where $d_t = 2m$ and each pair of dimensions forms one rotary block. Define centered covariance:

$$\mathbf{M}_{l,h} = \frac{1}{|\mathcal{P}|} \sum_{p \in \mathcal{P}} (\mathbf{z}_{l,h,p} - \bar{\mathbf{z}}_{l,h}) (\mathbf{z}_{l,h,p} - \bar{\mathbf{z}}_{l,h})^\top. \quad (3)$$

3.2 Coverage and Spectral Metrics

We track two behavior metrics and three spectral metrics.

Coverage metrics. For attention row $\mathbf{a}_{u,:}$,

$$\text{Span@}p(u) = \min \left\{ |I| : \sum_{v \in I} a_{u,v} \geq p \right\}, \quad (4)$$

and top- k entropy

$$\mathcal{H}_k(u) = - \sum_{v \in \text{TopK}(u)} \hat{a}_{u,v} \log(\hat{a}_{u,v} + \epsilon), \quad (5)$$

where $\hat{a}_{u,v}$ is renormalized over top- k keys. Small Span@p and low \mathcal{H}_k indicate coverage collapse.

Spectral metrics. For covariance \mathbf{M} ,

$$\Delta_{\text{iso}}(\mathbf{M}) = \|\mathbf{M} - \bar{\lambda} \mathbf{I}\|_F, \quad \bar{\lambda} = \frac{1}{2m} \text{tr}(\mathbf{M}), \quad (6)$$

$$\kappa(\mathbf{M}) = \frac{\lambda_{\max}(\mathbf{M})}{\lambda_{\min}(\mathbf{M}) + \epsilon}, \quad (7)$$

$$r_{\text{eff}}(\mathbf{M}) = \exp \left(- \sum_i \tilde{\lambda}_i \log(\tilde{\lambda}_i + \epsilon) \right), \quad \tilde{\lambda}_i = \frac{\lambda_i}{\sum_j \lambda_j}. \quad (8)$$

Lower Δ_{iso} , lower κ , and higher r_{eff} indicate flatter spectra.

3.3 mRoPE Temporal Structure

Each temporal rotary block uses frequency ω_i . For two blocks (i, j) , relative phase increment is $\Delta_{ij} = \omega_i - \omega_j$. The finite-support cancellation factor is

$$\mathcal{S}_{ij}(N) = \frac{1}{N} \sum_{p=0}^{N-1} e^{i\Delta_{ij}p}. \quad (9)$$

Its magnitude controls how strongly cross-block interactions survive after aggregation.

4 Theoretical Analysis

4.1 Global Isotropy as Block-Structured Second-Order Decoupling

Partition \mathbf{M} into $m \times m$ blocks with 2×2 entries $\mathbf{M}^{(i,j)}$. Then

Theorem 1 (Exact isotropy decomposition).

$$\Delta_{\text{iso}}(\mathbf{M})^2 = \sum_{i=1}^m \left\| \mathbf{M}^{(i,i)} - \bar{\lambda} \mathbf{I}_2 \right\|_F^2 + \sum_{i \neq j} \left\| \mathbf{M}^{(i,j)} \right\|_F^2. \quad (10)$$

Eq. (10) shows two independent requirements for global isotropy: (1) each block should be internally isotropic, and (2) different blocks should be weakly coupled. Therefore, fixing only diagonal terms cannot remove global anisotropy if off-diagonal energy remains. This directly motivates our method to target both effects: spectral flattening inside heads and selective suppression where coupling-induced degeneration is strongest.

4.2 Discrete Phase Cancellation and Cross-Subspace Coupling

Using the geometric-series form,

$$|\mathcal{S}_{ij}(N)| = \frac{1}{N} \left| \frac{\sin(N\Delta_{ij}/2)}{\sin(\Delta_{ij}/2)} \right|. \quad (11)$$

Assume pre-rotation cross-covariance decomposition $\mathbf{B}_p^{(i,j)} = \bar{\mathbf{B}}^{(i,j)} + \Delta\mathbf{B}_p^{(i,j)}$. Then

$$\left\| \mathbf{M}^{(i,j)} \right\|_F \leq \left\| \bar{\mathbf{B}}^{(i,j)} \right\|_F |\mathcal{S}_{ij}(N)| + \frac{1}{N} \sum_{p=0}^{N-1} \left\| \Delta\mathbf{B}_p^{(i,j)} \right\|_F. \quad (12)$$

This bound makes three points explicit: near-frequency pairs cancel slowly, finite N limits cancellation, and non-stationary content leaves residual terms. Hence cross-subspace coupling is expected in realistic long-video settings, not an edge case.

4.3 Spectral Peakedness Implies Attention Coverage Compression

Under a second-order approximation,

$$\text{Var}(s_{u,v}) = \frac{1}{d_h} \text{tr}(\Sigma_Q \Sigma_K) \leq \frac{1}{d_h} \lambda_{\max}(\Sigma_Q) \text{tr}(\Sigma_K). \quad (13)$$

When spectra are peaked, λ_{\max} dominates and logits become more extreme. The softmax then concentrates mass on fewer keys, causing smaller Span@p and lower top- k entropy. Therefore spectral flattening is directly tied to better attention coverage. This gives an operational objective for inference-time correction: reduce spectral dominance without retraining model weights.

4.4 Why Temporal-Only Intervention in mRoPE

For axis $a \in \{t, h, w\}$, phase excursion is $\Phi_{i,a} = \omega_i \Delta p_a$. In long-video inference, temporal displacement Δp_t grows with clip length, while spatial displacements are bounded by frame size. As a result, temporal channels dominate phase-mismatch risk and residual coupling. This motivates a temporal-only intervention: it targets the main source of degradation while minimizing side effects on spatial semantics.

5 Method

5.1 Overview

We propose **SPECTRA**, a training-free prefill-time module. Given Q/K states at layer l , SPECTRA performs four steps:

1. Estimate per-head spectral degradation on temporal channels.
2. Compute adaptive gates over layer and head dimensions.
3. Interpolate temporal Q/K with Gaussian anchors using gated strength.
4. Write back only to valid video tokens and temporal dimensions.

The design is strictly plug-and-play: no weight update, no architecture change.

Theory-to-design mapping.

- From Eq. (12): degradation is head-dependent and finite-support dependent, so we use per-head diagnostics instead of uniform perturbation.
- From Eq. (13): dominant eigenmodes drive coverage compression, so we monitor effective rank as a direct collapse signal.
- From Eq. (21): isotropic interpolation contracts dominant directions and lifts weak directions, yielding controlled spectral flattening.
- From temporal phase dominance (Sec. 4.4): intervention is temporal-only to maximize gain and limit semantic side effects.

5.2 Spectral-Rank-Aware Degradation Signal

For layer l , head h , collect temporal features $\mathbf{X}_{l,h} \in \mathbb{R}^{N_v \times d_t}$. Let top- r singular values be $\sigma_{l,h,1} \geq \dots \geq \sigma_{l,h,r}$. Define

$$\lambda_{l,h,i} = \frac{\sigma_{l,h,i}^2}{N_v + \epsilon}, \quad p_{l,h,i} = \frac{\lambda_{l,h,i}}{\sum_{j=1}^r \lambda_{l,h,j}}. \quad (14)$$

Head degradation is measured by effective rank:

$$r_{\text{eff}}(l, h) = \exp\left(-\sum_{i=1}^r p_{l,h,i} \log(p_{l,h,i} + \epsilon)\right). \quad (15)$$

A smaller $r_{\text{eff}}(l, h)$ means stronger concentration and stronger need for correction.

5.3 Dual Gating: Layer \times Head

Layer gate:

$$G_l = \text{clip}\left(1 - \frac{\min_h r_{\text{eff}}(l, h)}{\text{mean}_h r_{\text{eff}}(l, h) + \epsilon}, 0, 1\right). \quad (16)$$

Head gate:

$$G_{l,h} = \sqrt{\text{clip}\left(\frac{\text{median}_h r_{\text{eff}}(l, h) - r_{\text{eff}}(l, h)}{\text{median}_h r_{\text{eff}}(l, h) - \min_h r_{\text{eff}}(l, h) + \epsilon}, 0, 1\right)}. \quad (17)$$

Final strength:

$$\alpha_{l,h} = G_l G_{l,h}. \quad (18)$$

This gate design concentrates intervention on strongly degraded heads inside stressed layers.

5.4 Training-Free Injection and Complexity

For each temporal vector $\mathbf{x}_{l,h,p}$ (Q or K), sample $\boldsymbol{\eta}_{l,h,p} \sim \mathcal{N}(\mathbf{0}, \sigma_{l,h}^2 \mathbf{I})$ and apply

$$\mathbf{x}'_{l,h,p} = \mathbf{x}_{l,h,p} + \alpha_{l,h}(\boldsymbol{\eta}_{l,h,p} - \mathbf{x}_{l,h,p}) = (1 - \alpha_{l,h})\mathbf{x}_{l,h,p} + \alpha_{l,h}\boldsymbol{\eta}_{l,h,p}. \quad (19)$$

Writeback mask:

$$\mathbf{X}^{\text{out}} = \mathbf{X} + \mathbf{M}_{\text{vid}} \odot \mathbf{M}_{\text{tmp}} \odot (\mathbf{X}' - \mathbf{X}), \quad (20)$$

where \mathbf{M}_{vid} selects valid video tokens and \mathbf{M}_{tmp} selects temporal channels.

Proposition 1 (Covariance dynamics under SPECTRA). *Assume $\boldsymbol{\eta}$ is independent isotropic Gaussian. Then*

$$\boldsymbol{\Sigma}'_{l,h} = (1 - \alpha_{l,h})^2 \boldsymbol{\Sigma}_{l,h} + \alpha_{l,h}^2 \sigma_{l,h}^2 \mathbf{I}. \quad (21)$$

Eq. (21) contracts dominant modes and lifts weak modes, which flattens the spectrum and improves coverage robustness. With truncated rank r , per-layer overhead is

$$\mathcal{O}(H N_v d_t r) \quad (22)$$

plus linear-time interpolation. In practice, this is modest because the module is temporal-only and prefill-only.

6 Experiments

This section is reserved and will be filled later.

7 Limitations

Our analysis is second-order and does not explicitly model higher-order token interactions. The current derivation also assumes isotropic Gaussian anchors; richer anchor distributions may improve adaptivity. Finally, while temporal-only intervention is theoretically motivated, very high-motion scenes may benefit from joint temporal-spatial adaptation.

8 Conclusion

We presented a mechanism-first account of long-video attention collapse in mRoPE-based VLMs. The analysis shows that finite-support phase effects induce cross-block coupling, which sharpens spectra and compresses coverage. Based on this chain, SPECTRA provides a training-free, architecture-preserving temporal intervention with explicit covariance-level behavior. The framework is designed to be directly testable in experiments and extensible to stronger adaptive variants.