0704 遺碩生論文 1~9 database 林野郊50725 test case

0708 projection feature. A SVM method for Projection features database 50 → 25 1 25 true forged 2 test rase 50 -> 25; 25 fraining test Y= 0.299 R+ 0.387 G+0. 114B (intensity) Y <220 ⇒ stroke 0~259 ≥220 >> background Po, Pz --- Pio (how many pixels To each slot bare stroke pixels) features: fe = Pe-mean(Pe) (Eq. (4)) exclude the features that almost equal to D test data training data fe = a (megh/Pe) 50 data, 10-features label features prediction model prediction mode) label Feature Vectors

projection <10 features exclude the features that are zero moment features B(m,n) = 1 for stroke 0 non-stroke $M_0 = \sum_{m \in \mathbb{Z}} \sum_{m \in \mathbb{Z$ $m_{a,b} = \sum_{m,n} \sum_{n} (m-m_0)^{a} (n-n_0)^{b} B(m,n)$ ZZB(M,N) SKEWNESS Mo, No, M2,0, M0,2, M1,1, M3,0, M2,1, M1,2, M0, Varian(e

atb=4 kurtosis

mean of the intensity of stroke pixels standard deviation

number of stroke pixels after k erosions = rk

number of stroke pixels

[nifial: Yo[m,n] = x [m,n] X[m,n] = 10 Ykt [m,n] & 8 Ykt [m,n+1.

Y[m,n] = 10 Ykt (m,n] AA [kt[") && Yk-([m,n+] && Yk-([m+1,n]) & Xk-[m-1, n] Yk-1 [m+1,n] & Xk-[m-1, n]



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Y , Y 2, Y 3

Y=0.299 R+0.387 G+0.114B

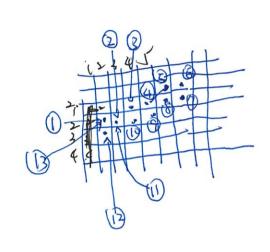
 m_{20} m_{11} m_{02} $f_n = \frac{50}{50}$ $f_{n,m}$ $f_n = \frac{50}{50}$ $f_n = \frac{5$

0.128

stroke pixels (xn, Yn) n=1,2, --- P $Z = \begin{bmatrix} \chi_1 - \chi_0 & \chi_1 - \chi_0 \\ \chi_2 - \chi_0 & \chi_2 - \chi_0 \end{bmatrix}$ $Z = \begin{bmatrix} \chi_1 - \chi_0 & \chi_2 - \chi_0 \\ \vdots & \vdots & \vdots \\ \chi_{p-\chi_0} & \chi_{p-\chi_0} \end{bmatrix}$ Z = Z = Z = Z = Z $2xz = \chi_0$ 76= mean(7n) PCA (principle component analysis) Yo = mean(yn) if NI > 72 = EDE ergenvalues (0/1) 3 features (1,0) OD: 較水平位勺 eigenvector $\theta = \arccos \frac{\vec{V}_1 \cdot \vec{V}_2}{\|\vec{V}_1\| \|\vec{V}_1\|}$ (+ πV) 2 horizantal 3) Avertical



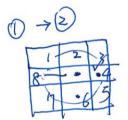




Initial: leftest upper pixe)
reference direction:
previos pixe)

(TO 1 = 1 the first nix

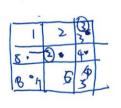
(If it is the first pixe), the reference direction is left

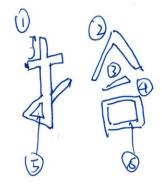


sort the sorrounding 8 pixels

Select the stroke pixel without the smallest vank

When returning to the first pixel the confour is completed





Boundary pixels A(m,n)=1

but one of A(m±1, n) & A(m, m±1) is 0

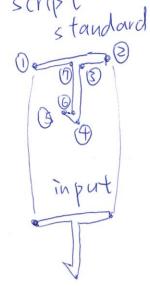
All the boundary pixels should be numbered.

(xn, xn): the nth pixel on the contour 0812 打倒 corner d=10~15 $(0) \quad \theta_{n} = \frac{(x_{n-d} - x_{n}, y_{n-d} - y_{n}), (x_{n+d} - x_{n}, y_{n+d} - y_{n})}{(x_{n-d} - x_{n})^{2} + (y_{n-d} - y_{n})^{2} + (y_{n+d} - y_{n})^{2} + (y_{n+d} - y_{n})^{2}}$ A DE arccos BA BC>
|| BAII || BCII PO

If $\theta_n < \theta_{n+m} \quad m \in E-10, 107$ $(2) \theta_n < \frac{3}{4}\pi \quad \frac{5}{6}\pi$ then θ_n is a corner

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select a standard script



1) normalized coordinate

$$m_{10} = \frac{m_{1} - m_{1}}{m_{1}}$$
, $n_{10} = \frac{m_{2} - n_{1}}{2} + n_{11}$
 $m_{11} = m_{11} = \frac{m_{11} - m_{11}}{m_{11}}$, $n_{12} = \frac{m_{11} - m_{12}}{m_{12} - m_{13}}$
 $m_{11} = m_{11} = \frac{m_{11} - m_{12}}{m_{12} - m_{13}}$
 $m_{12} = m_{11} = \frac{m_{11} - m_{12}}{m_{12} - m_{13}}$
 $m_{12} = m_{11} = \frac{m_{11} - m_{12}}{m_{12} - m_{13}}$

(M,n): original coordinate

The number of pixels whose m coordinate than m

tatal number of pixels

tatal number of pixels

standard ms, ns Orms Ms corners Mi, hi, rmit ruiz Input (orners

dist: \((\hat{m}_s - \hat{m}_t)^2 + (\hat{n}_s - \hat{n}_t)^2 + \((r_{m,s} - r_{m,t})^2 + (r_{m,s} - r_{m,t})^2 \)

0826 N=X direction (3) m= jy Ø(m,n) $B(m,n) \times \Phi(m,n)$ $\overline{\Phi}(m,n) = \underline{m + a \cdot n \cdot n - j \cdot m}$ = angle 189×189 binarized $\Phi(0,0) = 0$ stroke image arctan(Im() + cosotisin o $\int \dots + \lambda_2(\operatorname{dist}(\phi_{in}(m,n) - \phi_{rop}(m,n))$ dist(\$\phi_{\text{in}}(m,n) - \psi ref(m,n)) = min(| \$\phi_{\text{in}}(m,n) - \psi_{\text{ref}}(m,n)| , 27- | \signal = (m, n) - \signal rep(m,n) |) end point doinly matches end point turning point only matches turning point observe the training data, select only the corners that can well match TO LO LET turning points (i) If P corners are chosen (Xm, Ym) m=1, 2, ..., P (ZP) features (Xm, Ym) m=1, 2, ..., P (ZP) features (Xm, Ym) (