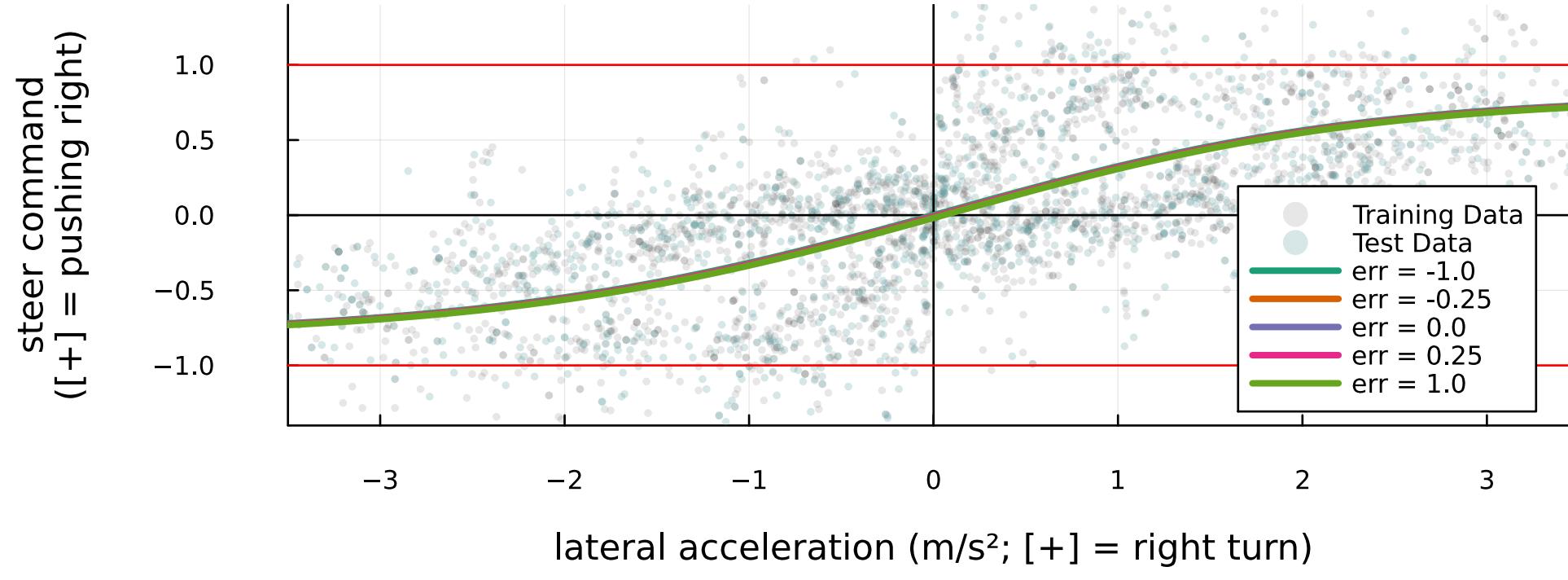


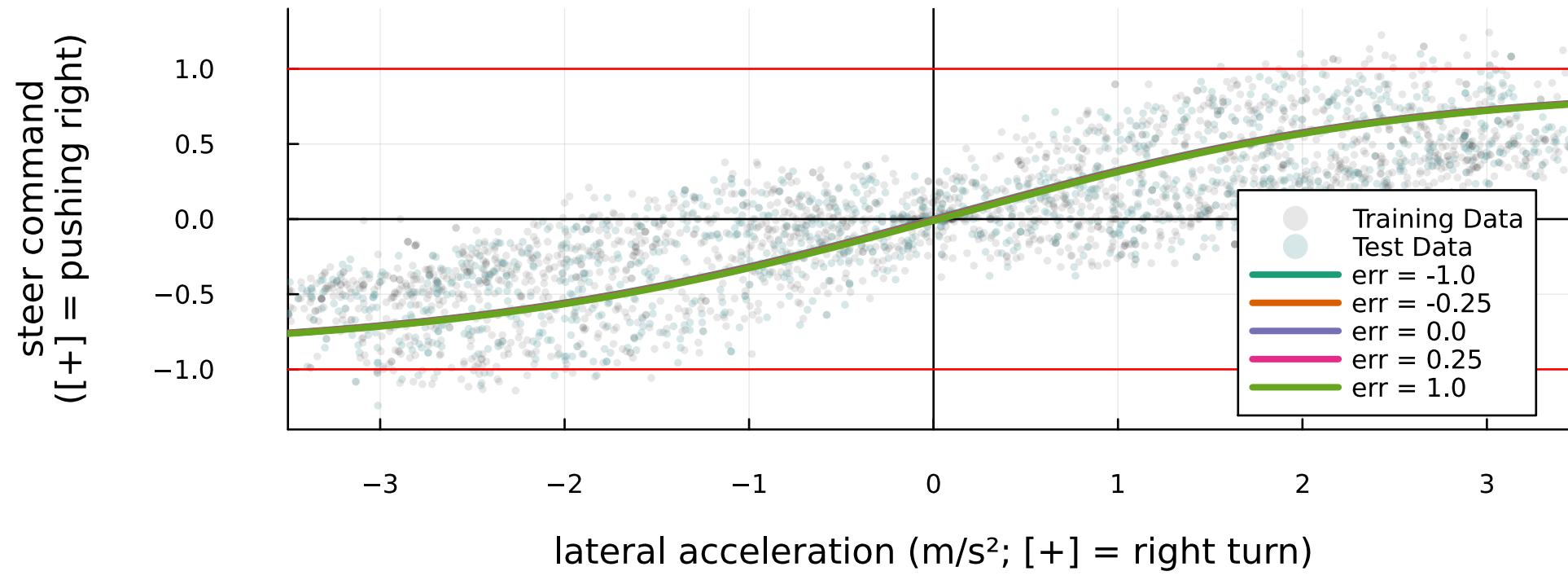
HYUNDAI IONIQ_6_torque_adjusted_eps
Lateral acceleration/jerk error response
0-13 mph w/ |roll| < 0.03



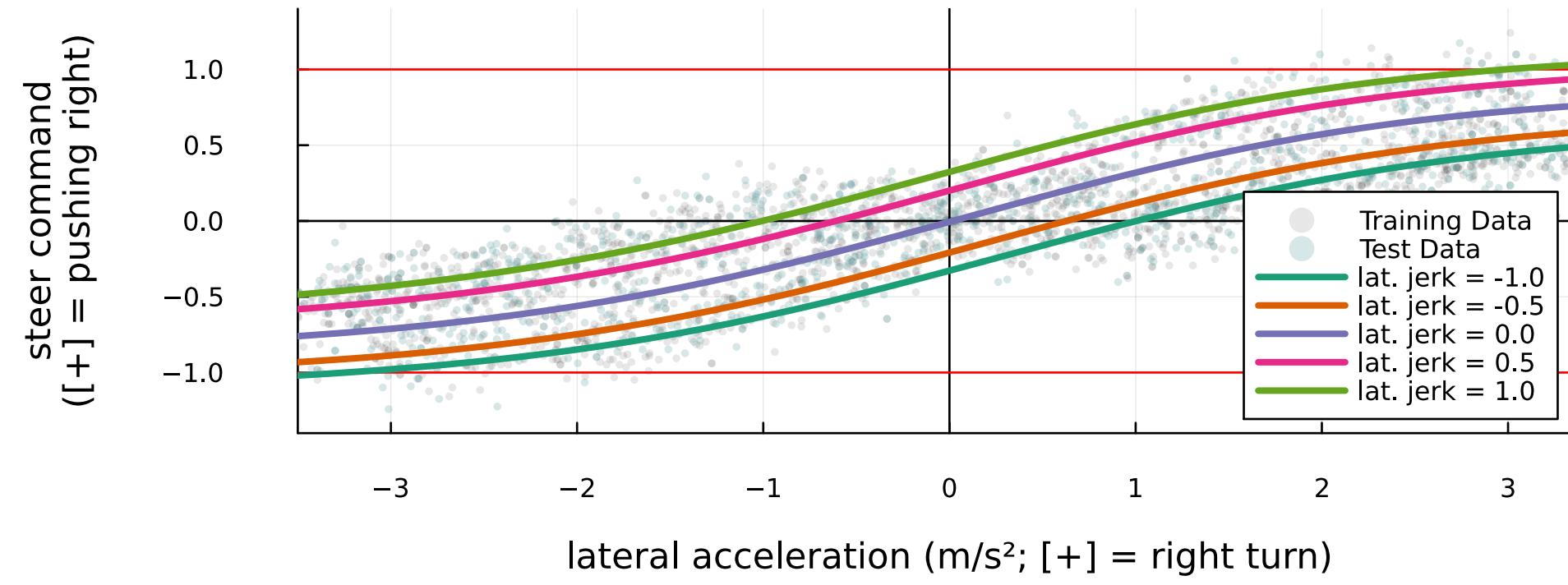
Model input: , v_ego, lateral_accel, lateral_jerk, roll, lateral_accel_m03, lateral_accel_m02, lateral_accel_m01, lateral_accel_p03, lateral_accel_p06, lateral_accel_p10, lateral_accel_p15, roll_m03, roll_m02, roll_m01, roll_p03, roll_p06, roll_p10, roll_p15
Lateral jerk response
0-13 mph @ |roll| < 0.03

Model test loss: 0.029
Roll compensation [+] = leaning to the right
0-13 mph w/ |lat jerk| < 0.2

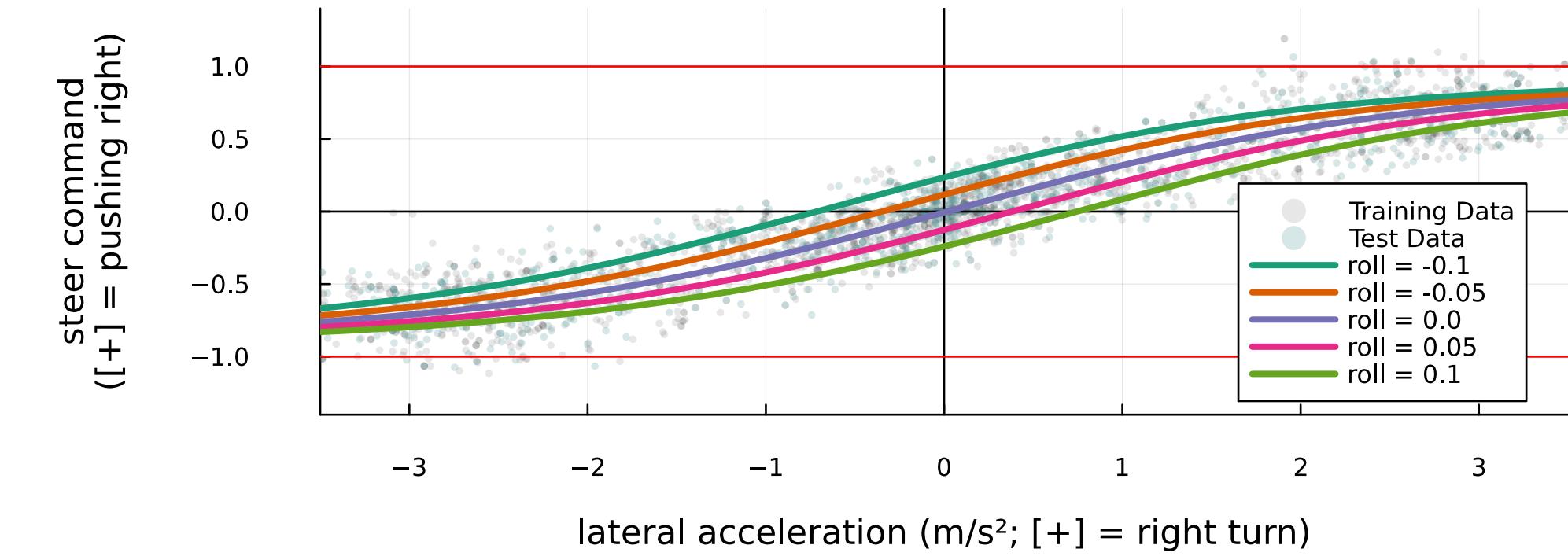
13-27 mph w/ |roll| < 0.03



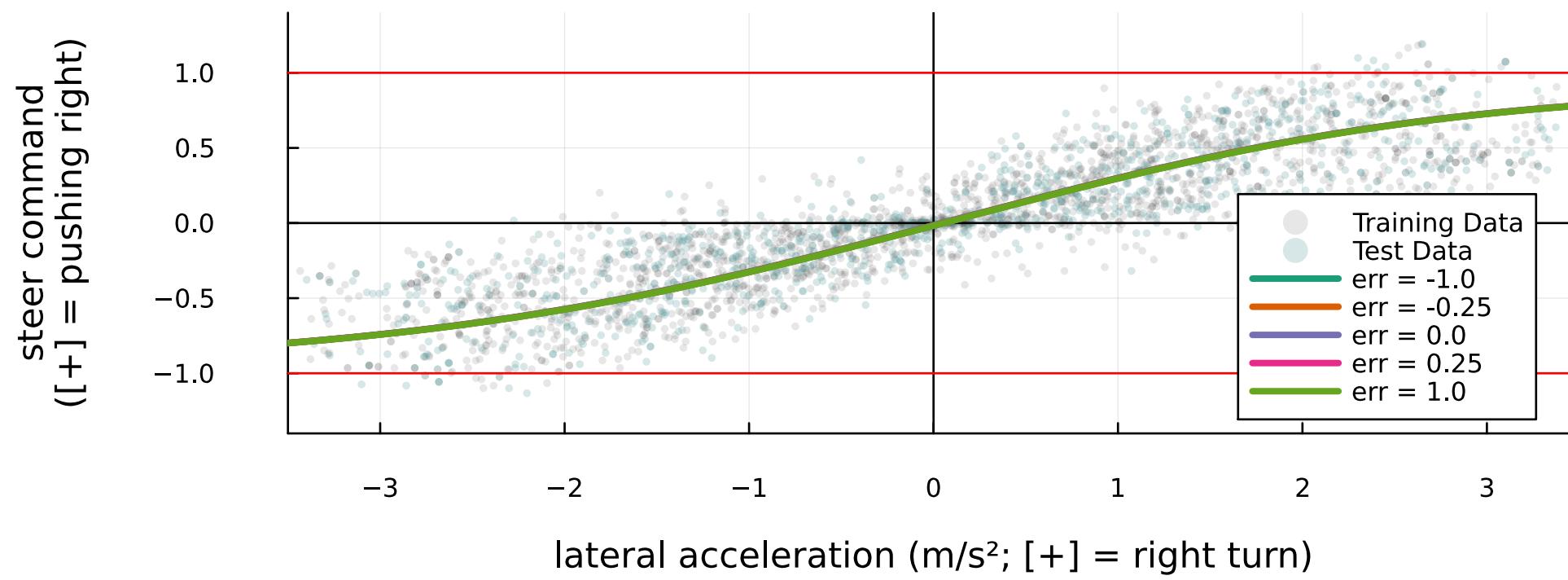
13-27 mph w/ |roll| < 0.03



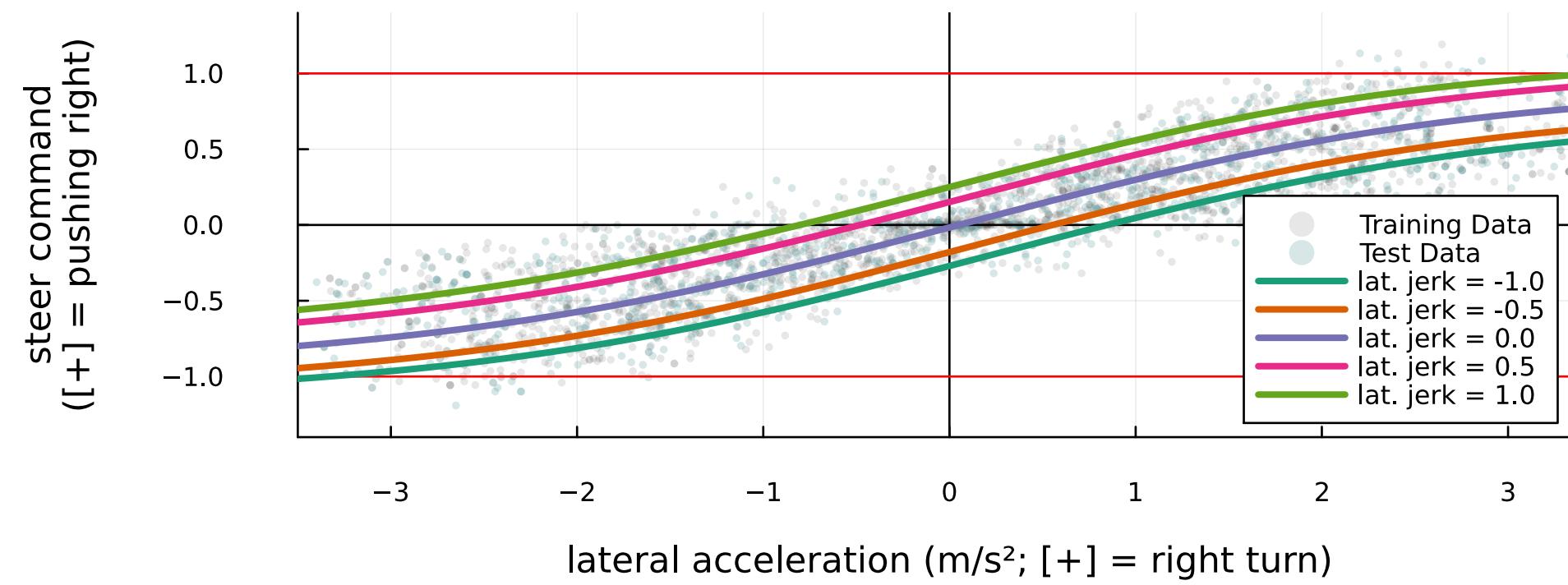
13-27 mph w/ |lat jerk| < 0.2



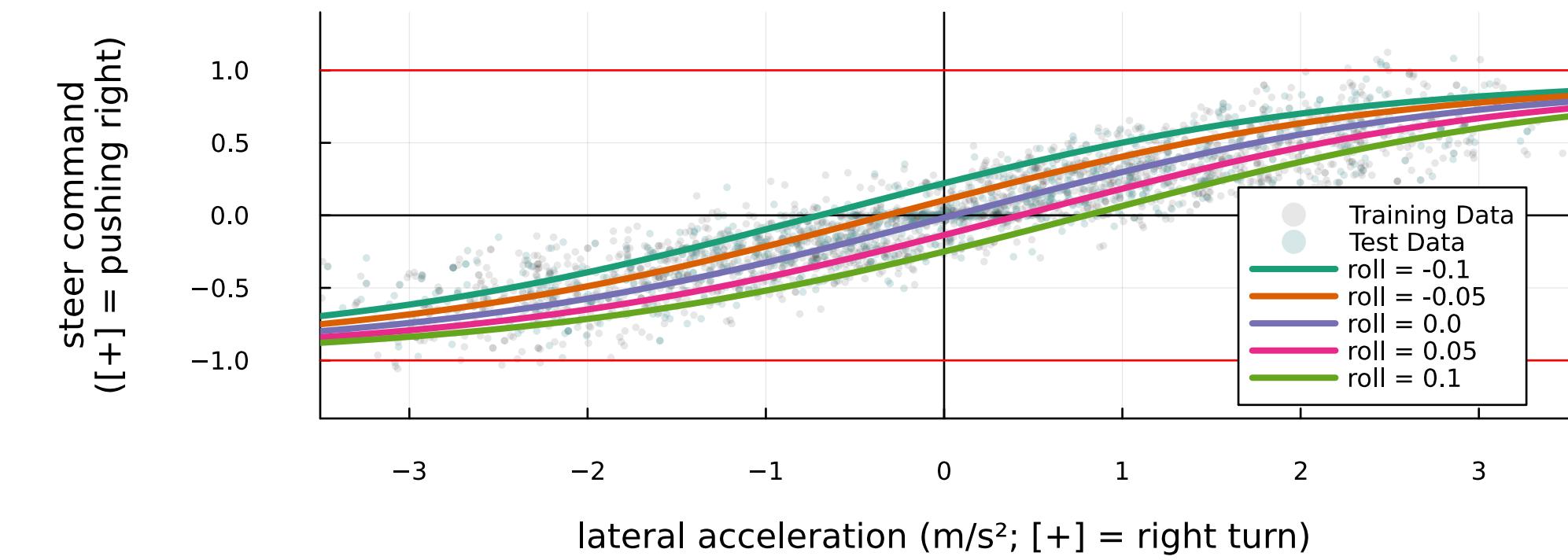
27-40 mph w/ |roll| < 0.03



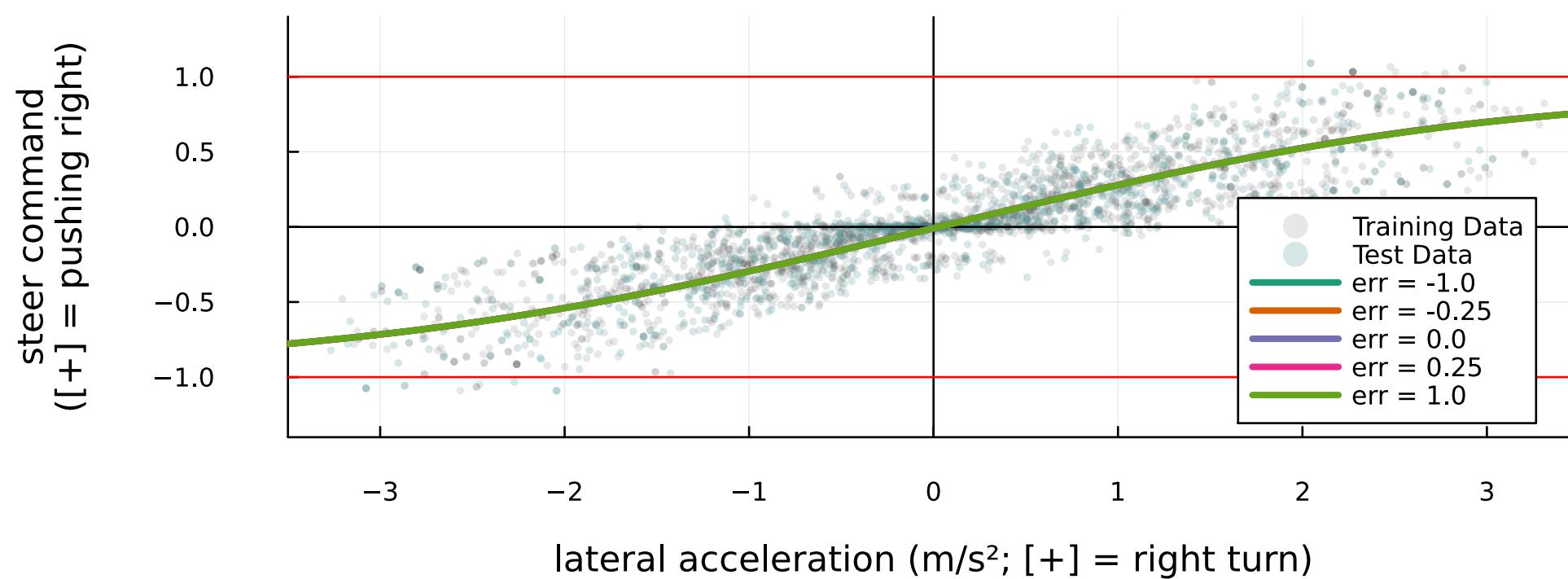
27-40 mph w/ |roll| < 0.03



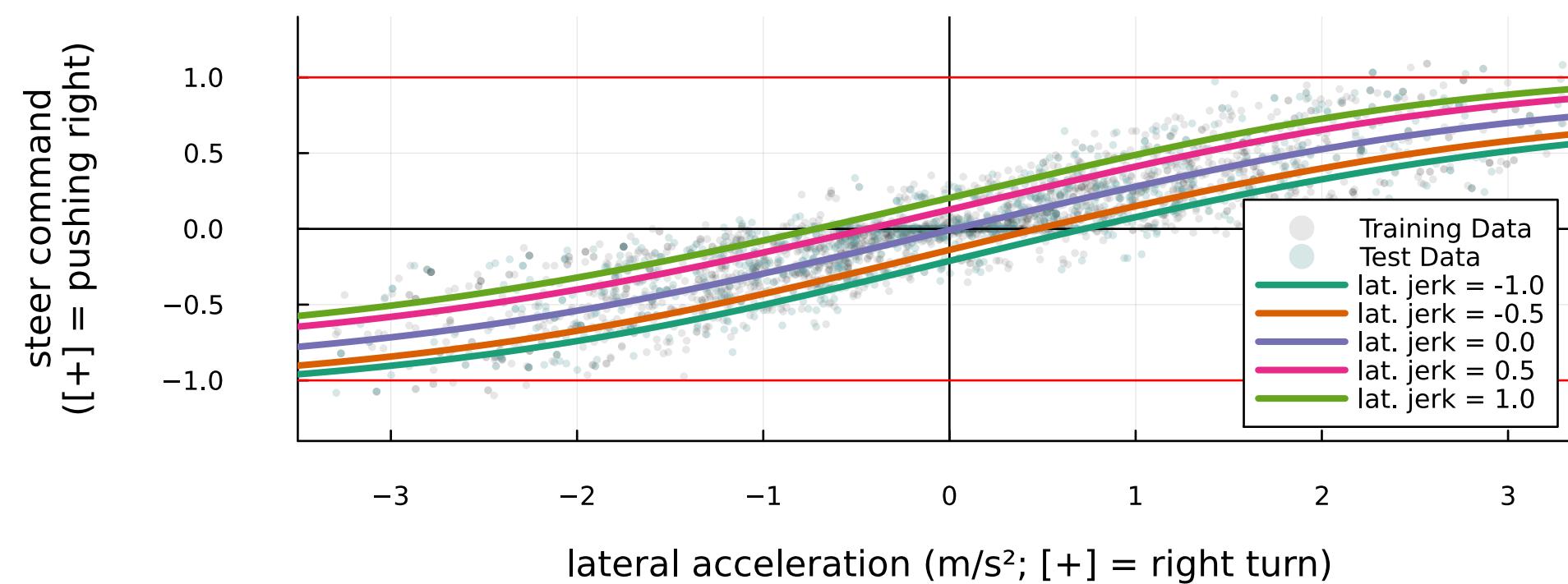
27-40 mph w/ |lat jerk| < 0.2



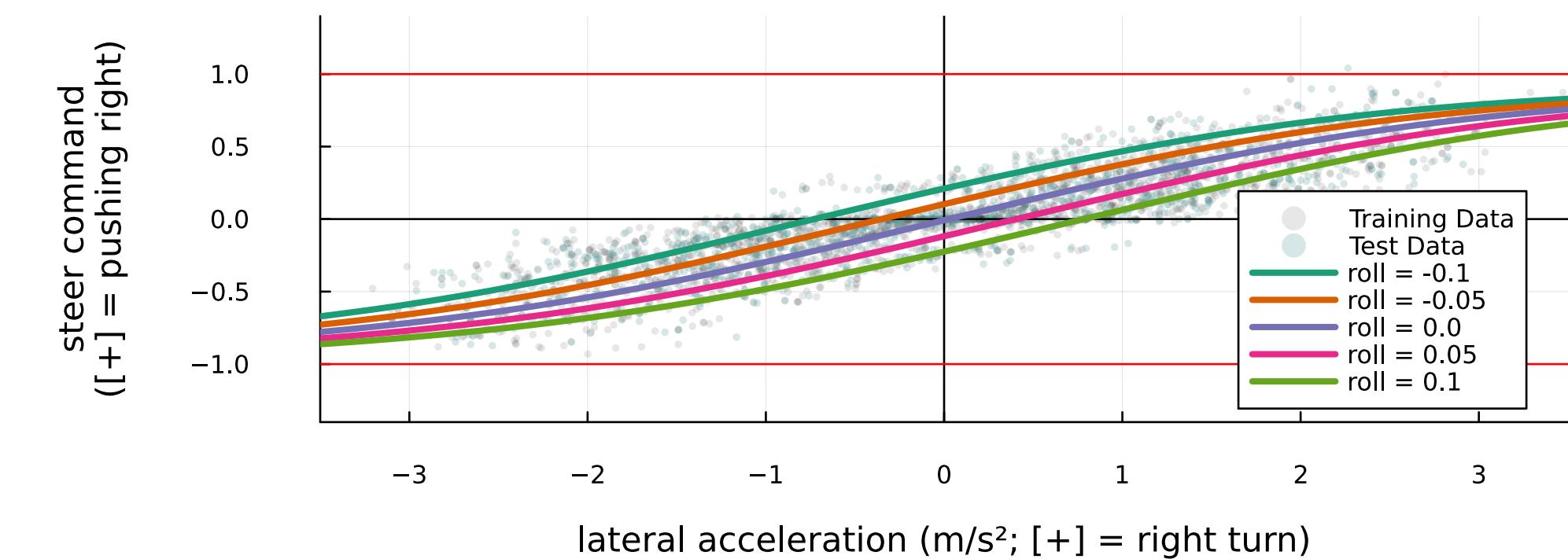
40-54 mph w/ |roll| < 0.03



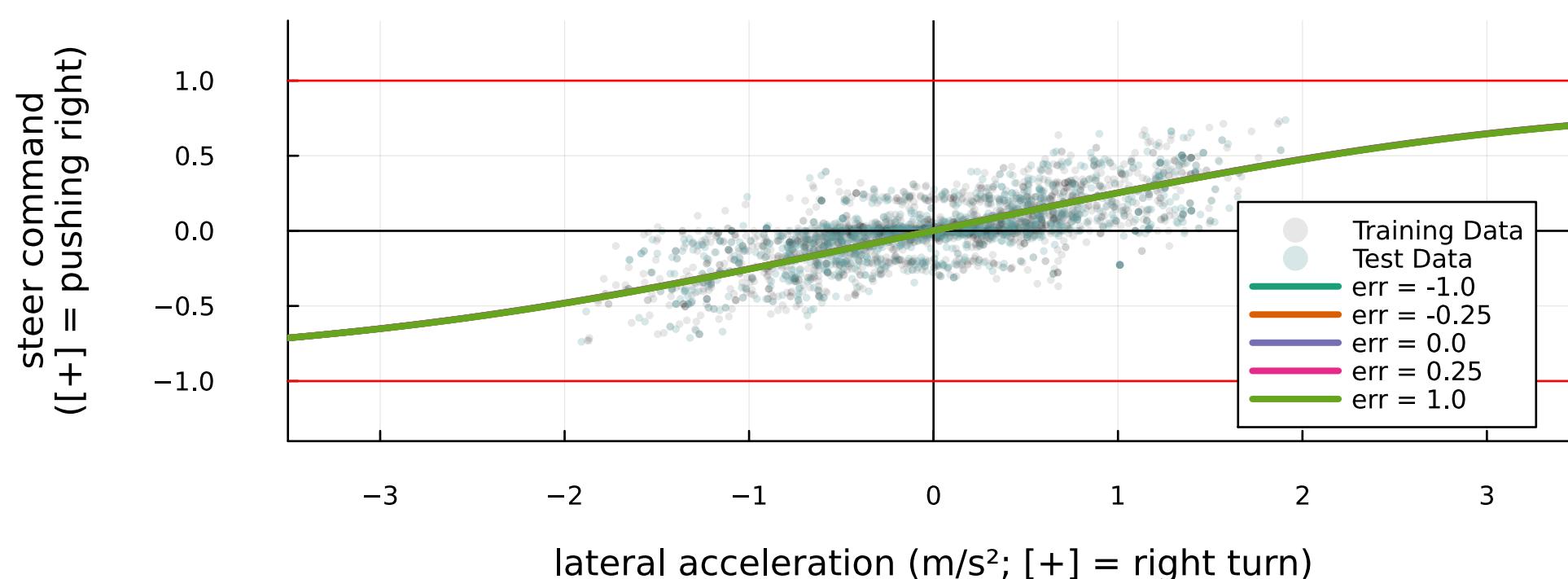
40-54 mph w/ |roll| < 0.03



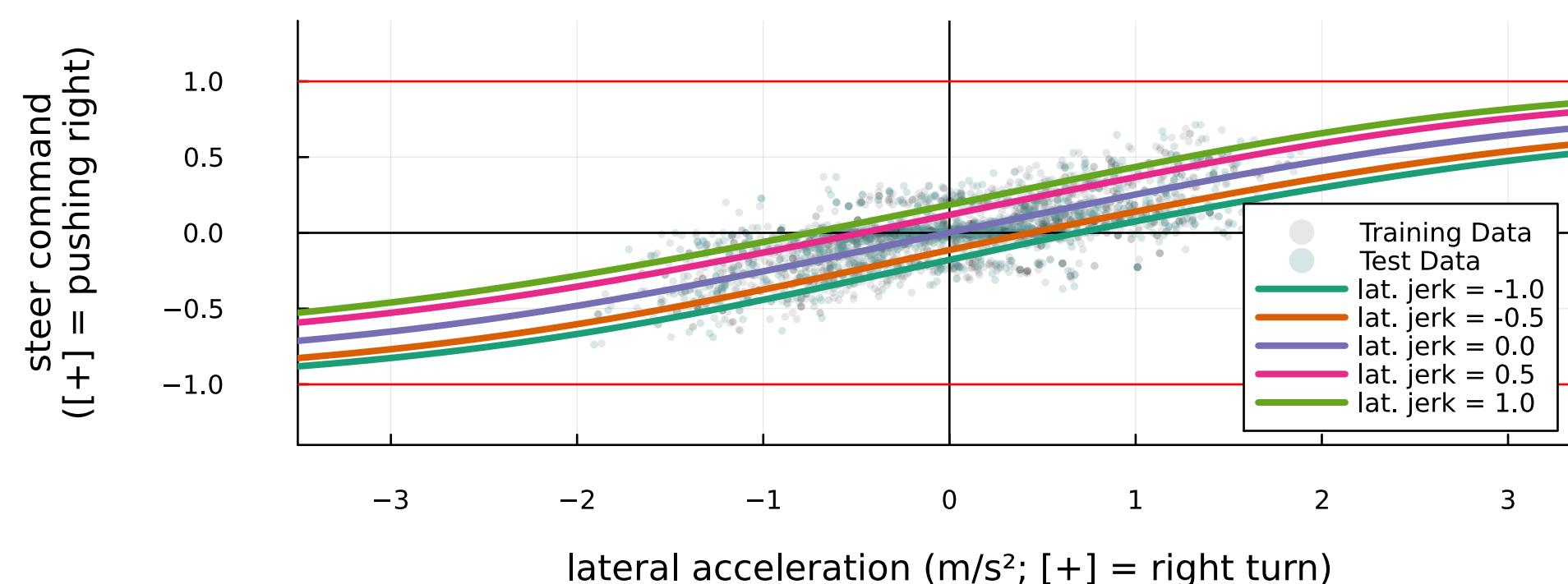
40-54 mph w/ |lat jerk| < 0.2



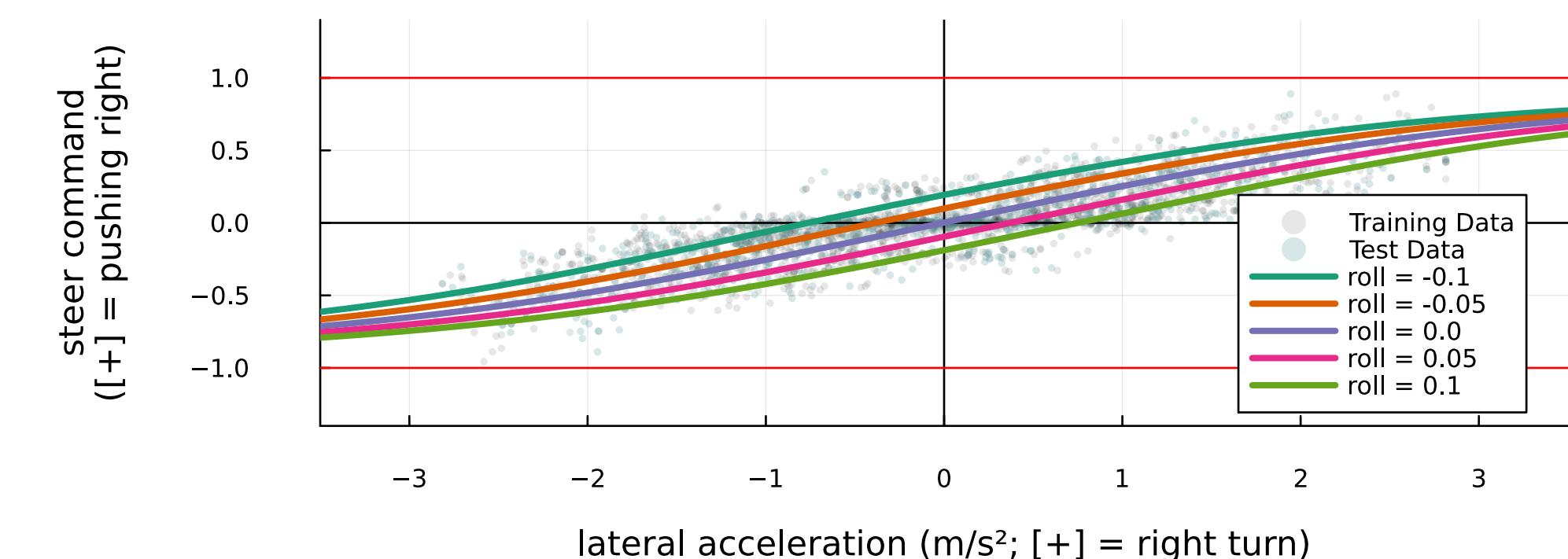
54-67 mph w/ |roll| < 0.03



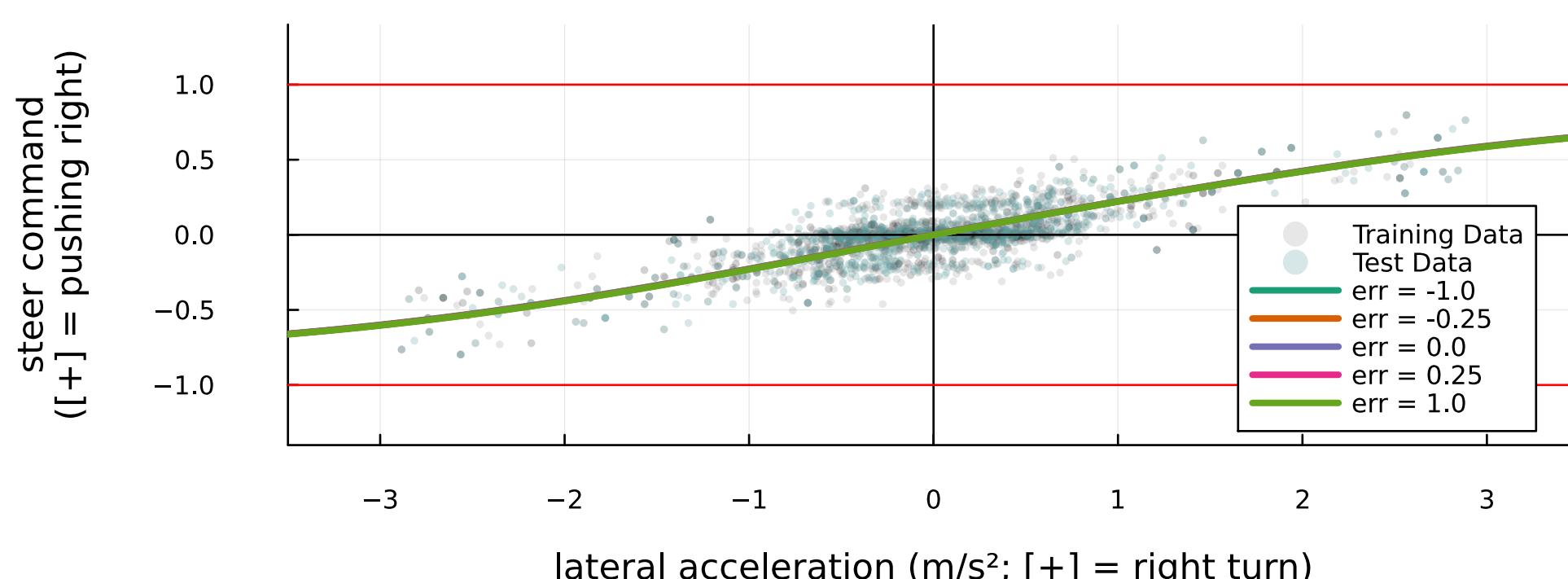
54-67 mph w/ |roll| < 0.03



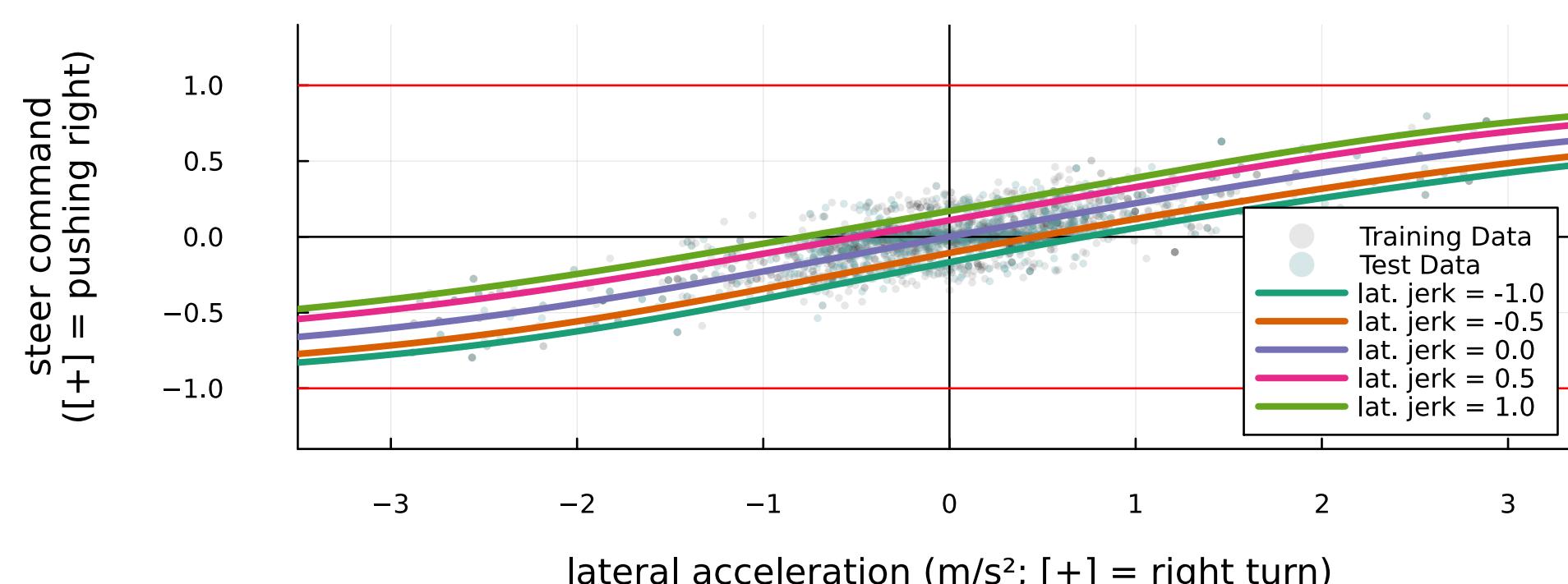
54-67 mph w/ |lat jerk| < 0.2



67-81 mph w/ |roll| < 0.03



67-81 mph w/ |roll| < 0.03



67-81 mph w/ |lat jerk| < 0.2

