

## MODEL 852 DIGITAL SONAR HEAD

## MODEL 852 DIGITAL ECHO SOUNDER

### DATA STORAGE FILE FORMAT (.852)

When recording the sonar and/or echo sounder data to a **.852** file, the following bytes are appended and saved to the file every 'shot':

Byte #	Description
0 to 99	<b>File Header</b> (100 Bytes)
100 to 111	<b>Sonar / Echo Sounder Return Data Header</b> (12 Bytes)
112 to xxxx	<b>Sonar / Echo Sounder Return Echo Data</b> (0, 252 or 500 Bytes) xxxx = 112+above number Byte xxxx always = <b>0xFC</b> (Termination Byte from sonar or echo sounder)
xxxx+1 to yyyy	<b>Zero Fill</b> yyyy = 127, 383 or 639

### FILE HEADER

Bytes 0 through 99 contain the following **File Header** information:

- 0      **ASCII '8'**
- 1      **ASCII '5'**
- 2      **ASCII '2'**
  
- 3      **nToReadIndex** - Index for Number of Data Bytes  
          0 = 0 Data Bytes (IPX data)  
          2 = 252 Data Bytes (IMX data)  
          3 = 500 Data Bytes (IGX data)
  
- 4-5    **Total Bytes** - number of bytes that are written to the disk for this shot

Byte 4								Byte 5							
7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
128 (for IPX), 384 (for IMX) or 640 (for IGX)															

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6-7      **nToRead** - Number of Bytes from the sonar or echo sounder

Byte 6								Byte 7							
7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
13 (for IPX), 265 (for IMX) or 513 (for IGX)															

8-19      **Date** - null terminated date string (12 bytes)  
**"DD-MMM-YYYY"**

20-28      **Time** - null terminated time string (9 bytes)  
**"HH:MM:SS"**

29-32      **Hundredth of Seconds** - null terminated string (4 bytes)  
**".hh"**

33-36      **Reserved** – always 0

37      **Dir, Xdcr, Mode, Step**

For Sonar Head (Head ID = 0x10):

Byte 37							
7	6	5	4	3	2	1	0
<b>Dir</b>	<b>Xdcr</b>	<b>Mode</b>			<b>Step Size</b>		
0=ccw	0=Dn	0 = Sector (IGX)			0 = 2.25 Deg (Slow)		
1=cw	1=Up	1 = Polar (IMX)			1 = 4.5 Deg (Fast)		

For Echo Sounder (Head ID = 0x11):

Byte 37							
7	6	5	4	3	2	1	0
<b>N/A</b>	<b>N/A</b>	<b>Mode</b>			<b>N/A</b>		
0	0	0 = IGX			0		
		1 = IMX					

38      **Start Gain**  
0 to 40 in 1 dB increments

39      **(Sector Size)/3**

For Sonar Head (Head ID = 0x10):  
0 to 102 = 0 to 306 Degrees in 3 degree increments

For Echo Sounder (Head ID = 0x11):  
Reserved – always 0

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40      **(Train Angle)/3**

For Sonar Head (Head ID = 0x10):

10 to 130 = -180 to +180 Degrees in 3 degree increments

70 = 0 degrees

For Echo Sounder (Head ID = 0x11):

Reserved – always 0

41      **Reserved** – always 0

42      **Reserved** – always 20

43      **Reserved** – always 9

44      **Pulse Length**  
1 to 250 in microseconds

45      **Profile**  
0 = Off  
1 = Points Only  
2 = Low Mix  
3 = Medium Mix  
4 = High Mix

46-47      **Sound Velocity**

Byte 46								Byte 47							
7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
V	Sound Velocity (in meters/second) * 10														

If 'V' = 0, Sound Velocity = 1500.0 m/s

If 'V' = 1, Sound Velocity = [((Byte 46 & 0x7F)<<8) | (Byte 47)]/10.0

48-79      **User Text** - null terminated text string (32 bytes)

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### **80-81 ROV Depth**

Byte 80								Byte 81							
7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
D	ROV Depth * 10														

If 'D' = 0, ROV Depth not available

If 'D' = 1, ROV Depth = [((Byte 80 & 0x7F)<<8) | (Byte 81)]/10

### **82 ROV Depth Units**

'M' = Meters

'F' = Feet

### **83-84 ROV Heading**

Byte 83								Byte 84							
7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
H	ROV Heading * 10														

If 'H' = 0, ROV Heading not available

If 'H' = 1, ROV Heading = [((Byte 83 & 0x7F)<<8) | (Byte 84)]/10

### **85-86 ROV Turns Counter**

Byte 85								Byte 86							
7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
T	ROV Turns Counter + 100														

If 'T' = 0, ROV Turns Counter not available

If 'T' = 1, ROV Turns Counter = [((Byte 85 & 0x7F)<<8) | (Byte 86)] - 100

### **87 Operating Frequency**

For Sonar Head (Head ID = 0x10):

0 = 675kHz

1 = 850kHz

For Echo Sounder (Head ID = 0x11):

0 = 675kHz

### **88 Head ID**

0x10 = Sonar Head

0x11 = Echo Sounder

### **89-99 Reserved - always 0**

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### **SONAR / ECHO SOUNDER RETURN DATA HEADER SONAR / ECHO SOUNDER RETURN ECHO DATA ZERO FILL**

The following bytes contain the **Sonar / Echo Sounder Return Data** that is acquired directly from the sonar head or echo sounder serial COM port (refer to the Model 852 Serial Interface Specification):

If Header is ASCII '**IPX**':

Bytes 100 through 112 (13 bytes)  
Bytes 113 through 127 (15 bytes – **Zero Fill**)

If Header is ASCII '**IMX**':

**8-Bit**  
Bytes 100 through 364 (265 bytes)  
Bytes 365 through 383 ( 19 bytes - **Zero Fill**)

If Header is ASCII '**IGX**':

**8-Bit**  
Bytes 100 through 612 (513 bytes)  
Bytes 613 through 639 ( 27 bytes - **Zero Fill**)