



Tecnológico
de Monterrey

Campus Ciudad de México
Escuela de Ingeniería y Ciencias
Departamento de Ingeniería Mecatrónica

KAG Engineering Project II

ITS
IMD

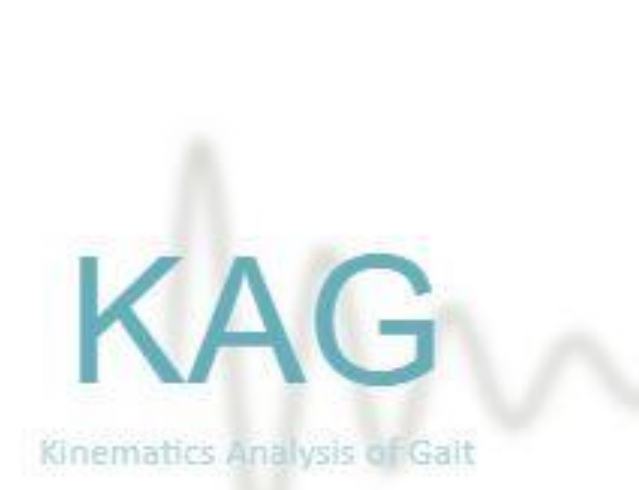
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Background

Nowadays, according to a study carried out by Hospital San Angel Inn, 50% of falls are due to a problem derived from walking problems.

The systems that are used to analyze this Problem are very expensive, not available, or is necessary that the patient needs to be in a closed space for the analysis, also, the calibration of these systems are related to an external reference.



Xsens

Kinescan/IBV
Sistema de análisis de movimiento

Objectives

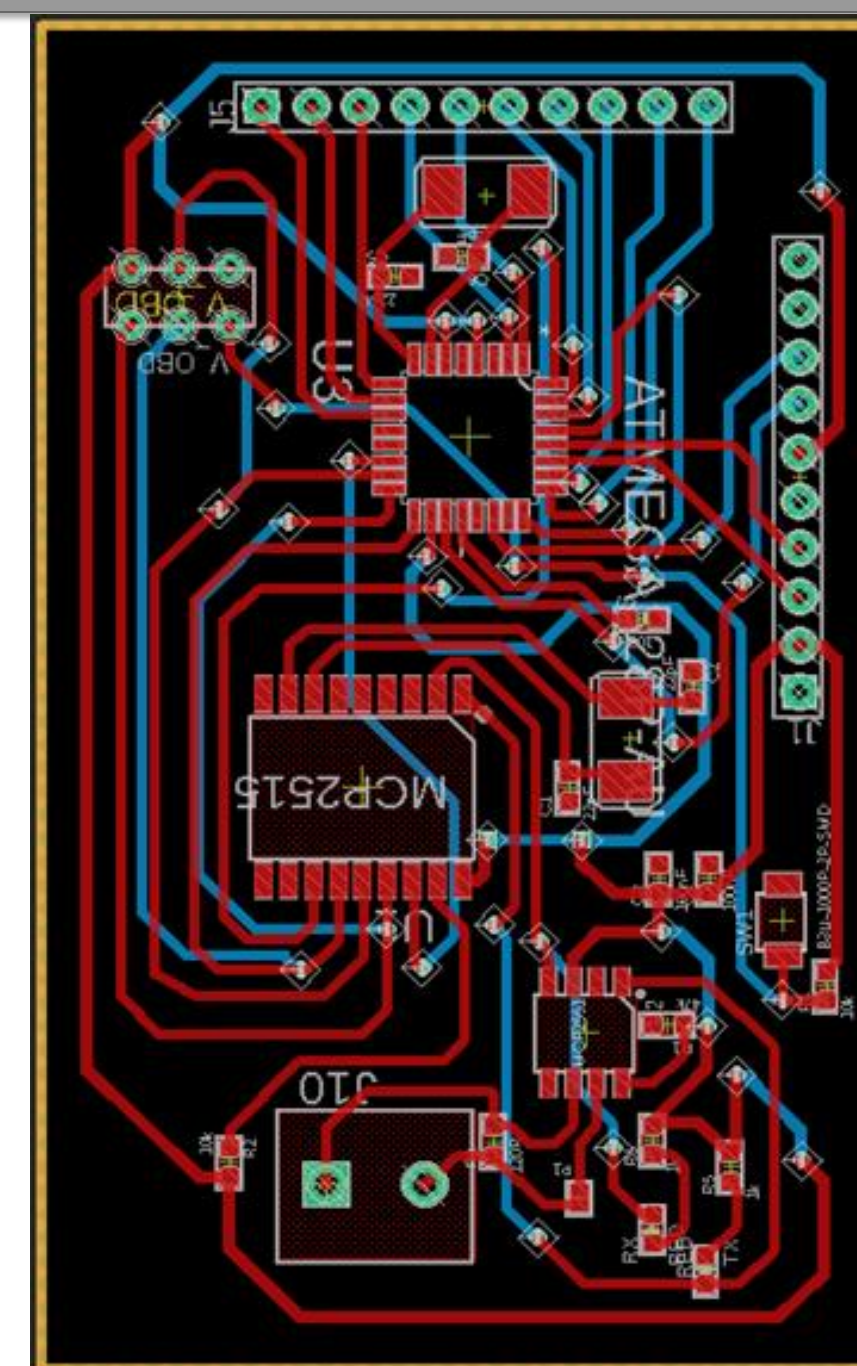
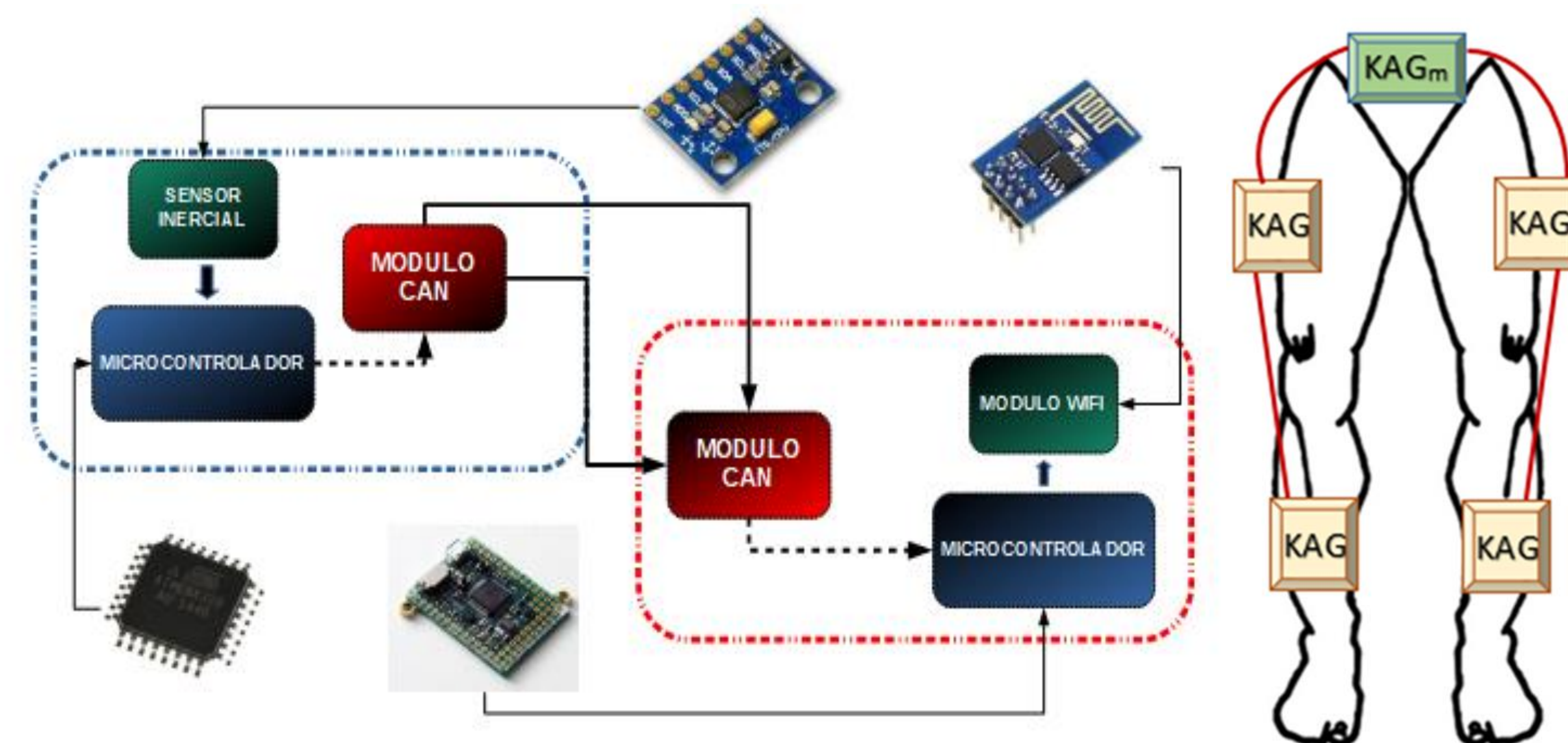
General objective

- Design a portable system of acquisition, communication and processing of physiological parameters for the implementation on an exoskeleton.

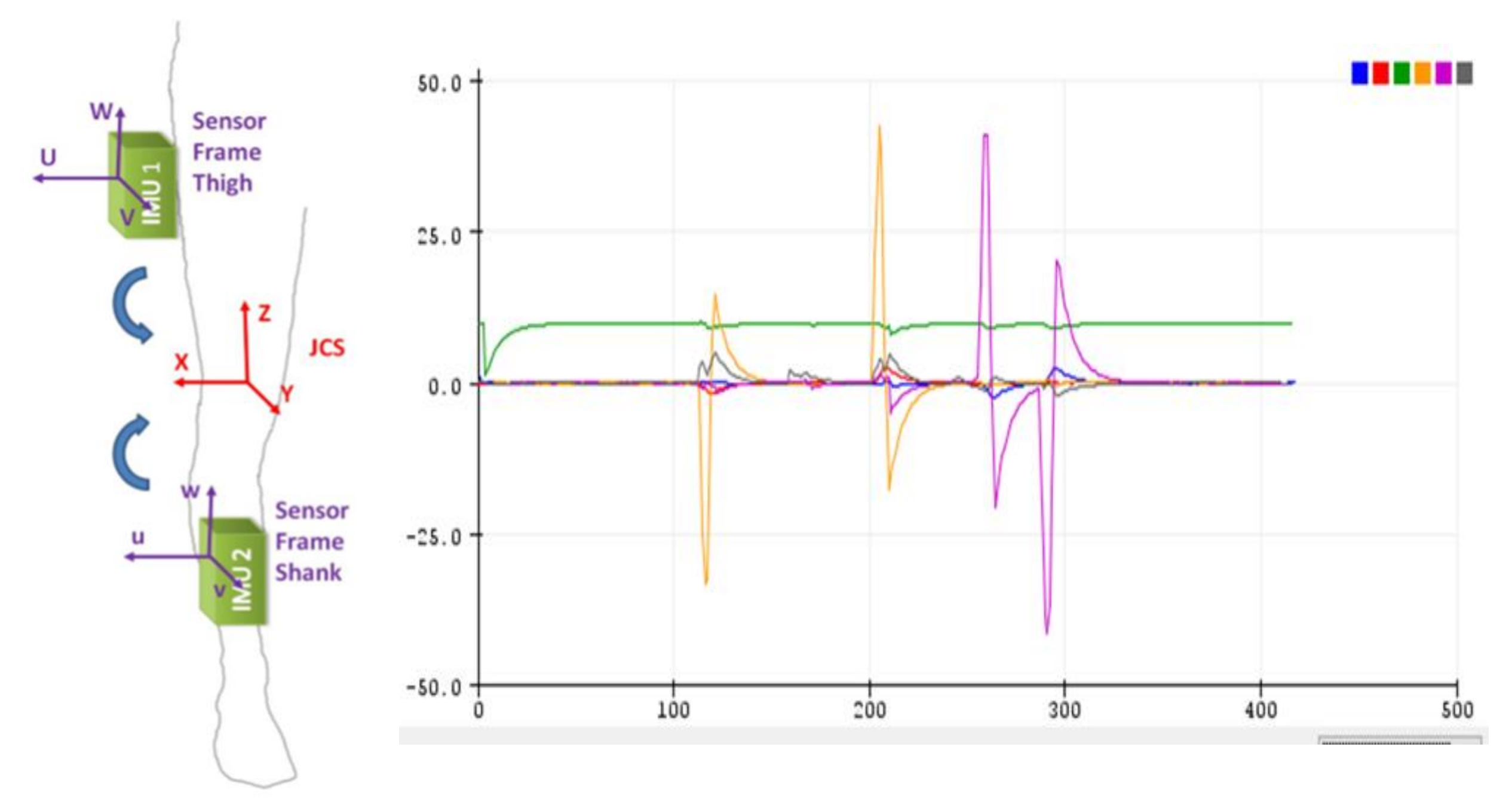
Specific objectives

- Design an electronic system that allows the acquisition of various sensors (inertial sensors).
- Design a general communication network for the acquisition and transmission of data.
- Develop a data reading and processing algorithm for the estimation of the joint range of the knee.

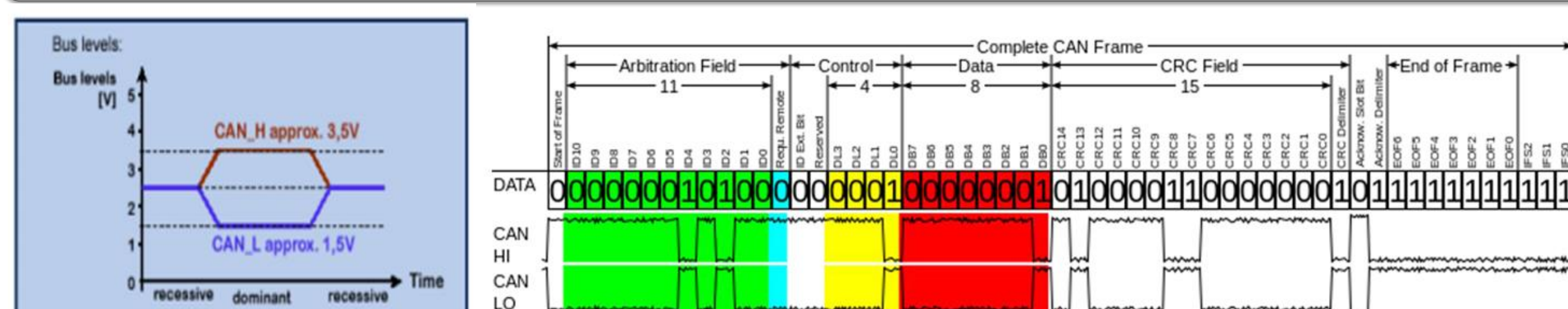
Solution design



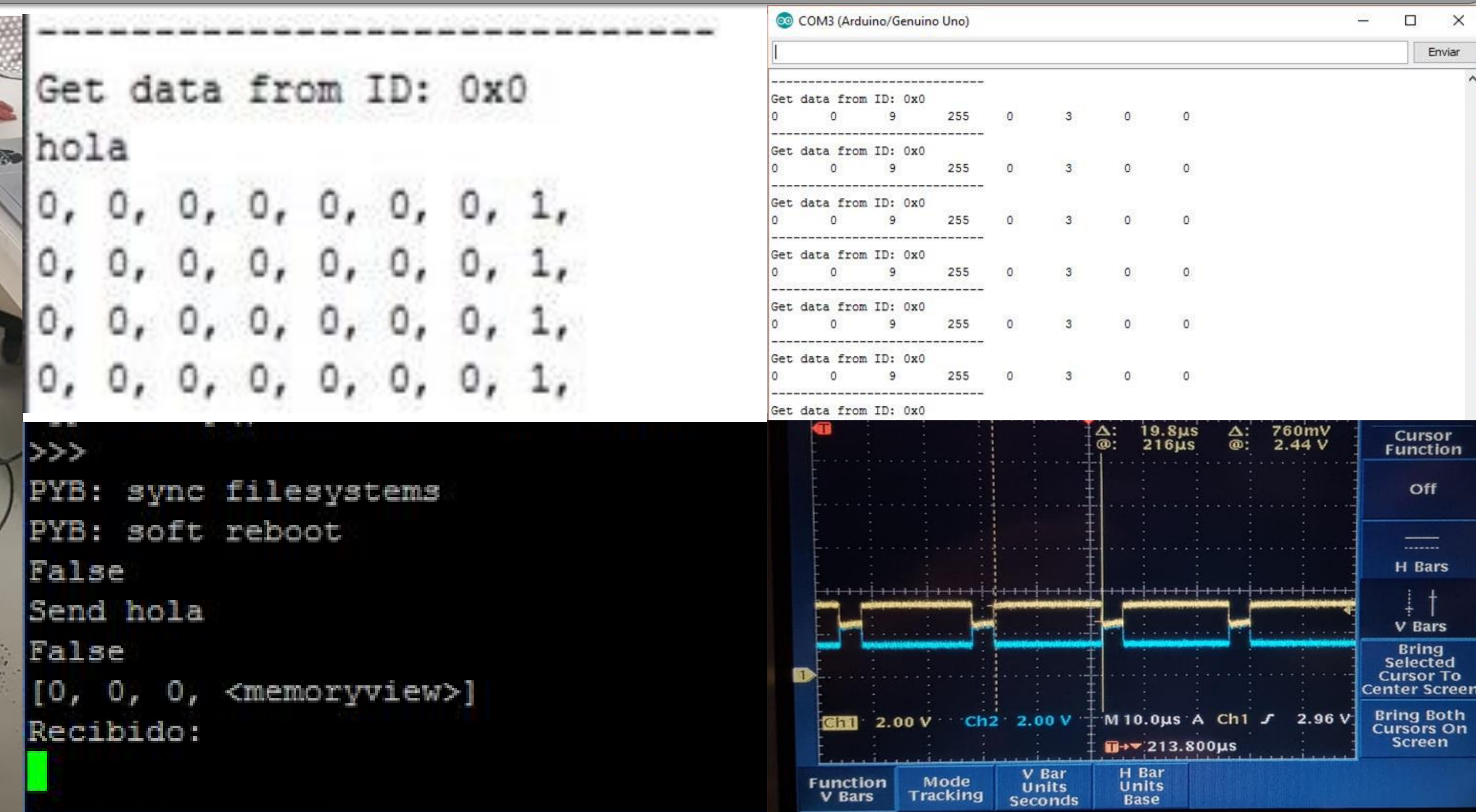
Pre-processing



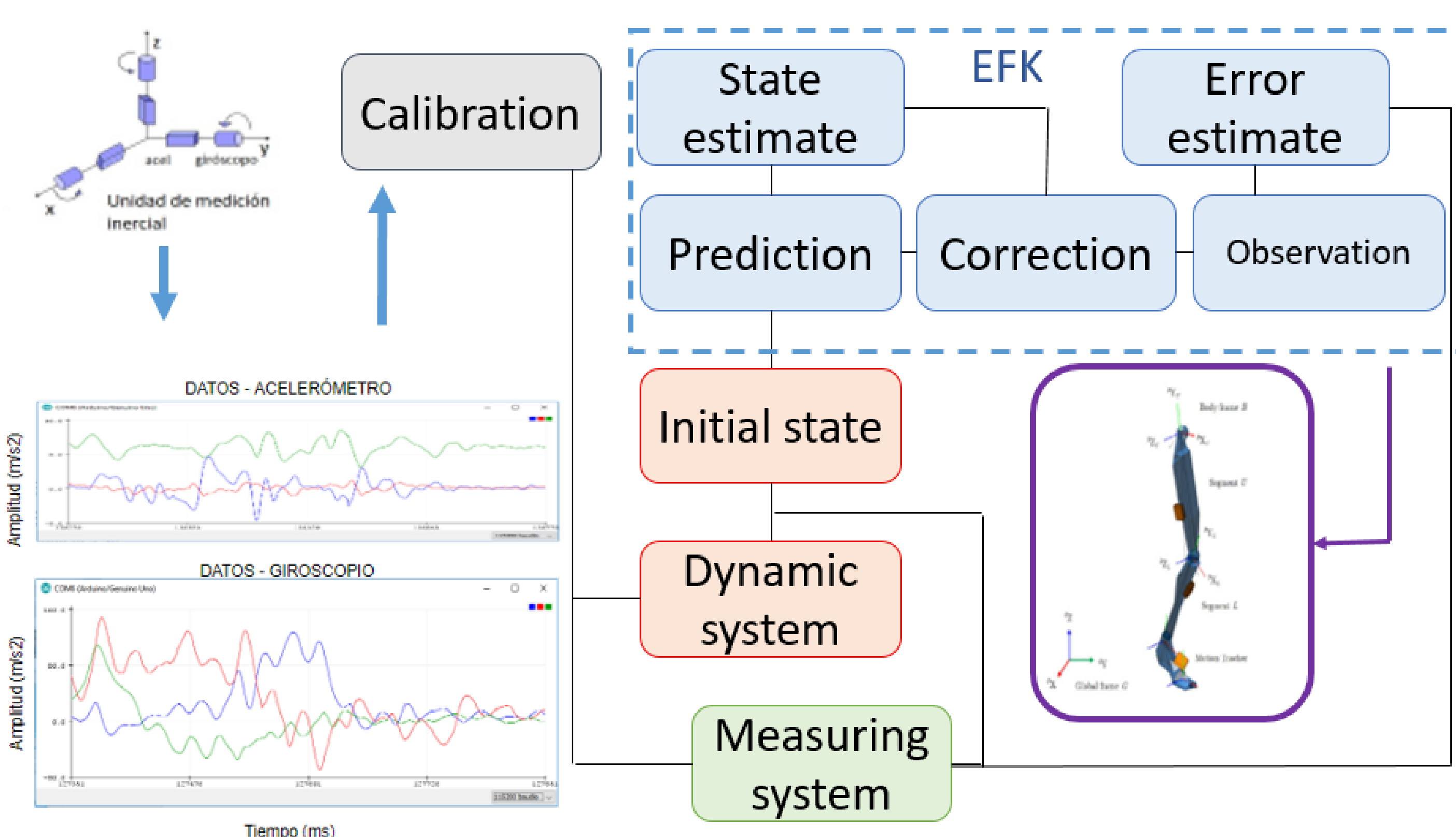
Communication



Results



Processing



Future work

- Compare and validate the response of the system propose with a reference system like vicon cameras.
- Optimization of the data processing algorithm in the Pyboard 1.1.
- Wireless transmission of the data processed.

Ethical dilemmas

- The long processing time can generate wrong results in the estimation of the parameters of knee joint range measurement.

Conclusions

An electronic system was designed and built successfully, that allows the acquisition and communication of data from various sensors.

An algorithm was developed successfully, that allows the acquisition, communication and processing of data from inertial sensors, giving as a result the knee angle.

Tests were carried out implementing the Kalman algorithm on the acquired data of inertial sensors.

The system designed was **96.14% cheaper** than the current ones in the market.