API Documentation

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Variables Package pyFAI

1 Package pyFAI

1.1 Modules

- _geometry (Section 2, p. 3)
- azimuthalIntegrator (Section 3, p. 4)
- bilinear (Section 4, p. 21)
- detectors (Section 5, p. 22)
- geometry (Section 6, p. 31)
- geometryRefinement (Section 7, p. 44)
- histogram (Section 8, p. 48)
- ocl_azim (Section 9, p. 49)
- ocl_azim_lut (Section 10, p. 50)
- peakPicker (Section 11, p. 52)
- reconstruct (Section 12, p. 58)
- refinment2D (Section 13, p. 59)
- relabel (Section 14, p. 61)
- spline: This is piece of software aims to manipulate spline files for geometric corrections of the 2D detectors using cubic-spline (Section 15, p. 62)
- splitBBox (Section 16, p. 67)
- splitBBoxLUT (Section 17, p. 68)
- splitPixel (Section 18, p. 69)
- utils (Section 19, p. 70)

1.2 Variables

Name	Description
version	Value: '0.7.8'
logger	Value: logging.getLogger("pyFAIinit")
package	Value: 'pyFAI'

2 Module pyFAI._geometry

2.1 Variables

Name	Description
package	Value: 'pyFAI'
test	Value: {}

3 Module pyFAI.azimuthalIntegrator

Date: 02/07/2012

Author: Jerome Kieffer

Contact: Jerome.Kieffer@ESRF.eu

Copyright: European Synchrotron Radiation Facility, Grenoble, France

License: GPLv3+

3.1 Variables

Name	Description
_status	Value: 'beta'
logger	Value:
	<pre>logging.getLogger("pyFAI.azimuthalIntegrator")</pre>
ocl	Value: OpenCL devic
package	Value: 'pyFAI'

3.2 Class AzimuthalIntegrator

Known Subclasses: pyFAI.geometryRefinement.GeometryRefinement

This class is an azimuthal integrator based on P. Boesecke's geometry and histogram algorithm by Manolo S. del Rio and V.A Sole

All geometry calculation are done in the Geometry class

3.2.1 Methods

 $_$ init $_$ (self, dist=1, poni1=0, poni2=0, rot1=0, rot2=0, rot3=0, pixel1=1, pixel2=1, splineFile=None)

 $x._init_(...)$ initializes x; see help(type(x)) for signature

Parameters

dist: distance sample - detector plan (orthogonal distance, not along the

beam), in meter.

poni1: coordinate of the point of normal incidence along the detector's

first dimension, in meter

poni2: coordinate of the point of normal incidence along the detector's

second dimension, in meter

rot1: first rotation from sample ref to detector's ref, in radians

rot2: second rotation from sample ref to detector's ref, in radians

rot3: third rotation from sample ref to detector's ref, in radians

pixel1: pixel size of the fist dimension of the detector, in meter

pixel2: pixel size of the second dimension of the detector, in meter

splineFile: file containing the geometric distortion of the detector. Overrides

the pixel size.

Overrides: object.__init__

$\mathbf{reset}(self)$

Reset azimuthal integrator in addition to other arrays.

Overrides: pyFAI.geometry.Geometry.reset

makeMask(self, data, mask=None, dummy=None, delta_dummy=None, invertMask=None)

Combines a mask

For the mask: 1 for good pixels, 0 for bas pixels

Parameters

data: input array of
mask: input mask

dummy: value of dead pixels

delta_dumy: precision of dummy pixels

invertMask: to force inversion of the input mask

 $\mathbf{xrpd_numpy}(self,\ data,\ nbPt,\ filename = \mathtt{None},\ correctSolidAngle = \mathtt{True},\ tthRange = \mathtt{None},\ mask = \mathtt{None},\ dummy = \mathtt{None},\ delta_dummy = \mathtt{None})$

Calculate the powder diffraction pattern from a set of data, an image. Numpy implementation

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt: number of points in the output pattern

(type=integer)

filename: file to save data in

(type=string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type = (float, float), optional)

mask: array (same size as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels
delta_dummy: precision for dummy value

Return Value

(2theta, I) in degrees

 $\mathbf{xrpd_cython}(self,\ data,\ nbPt,\ filename = \mathtt{None},\ correctSolidAngle = \mathtt{True},\ tthRange = \mathtt{None},\ mask = \mathtt{None},\ dummy = \mathtt{None},\ delta_dummy = \mathtt{None},\ pixelSize = \mathtt{None})$

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt: number of points in the output pattern

(type=integer)

filename: file to save data in

(type=string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of the 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type = (float, float), optional)

mask: array (same size as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels
delta_dummy: precision for dummy value

Return Value

(2theta, I) in degrees

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation

TODO: add in the cython part a dark and a flat images to be corrected on the fly. Flat should be combined with solid-angle

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt: number of points in the output pattern

(type=integer)

filename: file to save data in ascii format 2 column

(type=string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of the 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type = (float, float), optional)

chiRange: The lower and upper range of the chi angle. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type=(float, float), optional)

mask: array (same siza as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels delta_dummy: precision for dummy value

dark: dark noise image

dark: dark noise image flat: flat field image

Return Value

(2theta, I) in degrees

Calculate the powder diffraction pattern from a set of data, an image.

Cython implementation

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt: number of points in the output pattern

(type=integer)

filename: file to save data in

(type=string)

mask: array (same siza as image) with 0 for masked pixels, and 1 for

valid pixels

dummy: value for dead/masked pixels
delta_dummy: precision for dummy value

Return Value

(2theta, I) in degrees

 $\mathbf{xrpd}(self, data, nbPt, filename = \mathtt{None}, correctSolidAngle = \mathtt{True}, tthRange = \mathtt{None}, chiRange = \mathtt{None}, mask = \mathtt{None}, dummy = \mathtt{None}, delta_dummy = \mathtt{None}, dark = \mathtt{None}, flat = \mathtt{None})$

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation

TODO: add in the cython part a dark and a flat images to be corrected on the fly. Flat should be combined with solid-angle

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt: number of points in the output pattern

(type=integer)

filename: file to save data in ascii format 2 column

(type = string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of the 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type = (float, float), optional)

chiRange: The lower and upper range of the chi angle. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type=(float, float), optional)

mask: array (same siza as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels
delta_dummy: precision for dummy value

dark: dark noise image
flat: flat field image

Return Value

(2theta, I) in degrees

 $\begin{array}{l} \mathbf{xrpd_OpenCL}(self,\ data,\ nbPt,\ filename= \texttt{None},\ correctSolidAngle= \texttt{True},\ tthRange= \texttt{None},\ mask= \texttt{None},\ dummy= \texttt{None},\ delta_dummy= \texttt{None},\ devicetype= \texttt{'gpu'},\ useFp64= \texttt{True},\ platformid= \texttt{None},\ deviceid= \texttt{None},\ safe= \texttt{True}) \end{array}$

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt: number of points in the output pattern

(type=integer)

filename: file to save data in ascii format 2 column

(type = string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of the 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type = (float, float), optional)

chiRange: The lower and upper range of the chi angle. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type=(float, float), optional, disabled for now)

mask: array (same siza as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels

delta_dummy: precision for dummy value OpenCL specific parameters:

devicetype: "cpu" or "gpu" or "all" or "def"

useFp64: shall histogram be done in double precision (adviced)

platformid: platform number deviceid: device number

safe: set to false if you think your GPU is already set-up

correctly (2theta, mask, solid angle...)

Return Value

(2theta, I) in degrees

(type=2-tuple of 1D arrays)

setup_LUT(self, shape, nbPt, mask=None, tthRange=None, chiRange=None)

 $\mathbf{xrpd_LUT}(self, data, nbPt, filename = \mathtt{None}, correctSolidAngle = \mathtt{True}, tthRange = \mathtt{None}, chiRange = \mathtt{None}, mask = \mathtt{None}, dummy = \mathtt{None}, delta_dummy = \mathtt{None}, safe = \mathtt{True})$

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation using a Look-Up Table.

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt: number of points in the output pattern

(type=integer)

filename: file to save data in ascii format 2 column

(type=string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of the 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type = (float, float), optional)

chiRange: The lower and upper range of the chi angle. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type=(float, float), optional, disabled for now)

mask: array (same siza as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels

delta_dummy: precision for dummy value LUT specific parameters:

safe: set to false if you think your GPU is already set-up

correctly (2theta, mask, solid angle...)

Return Value

(2theta, I) in degrees

 $\begin{array}{l} \mathbf{xrpd_LUT_OCL}(self,\ data,\ nbPt,\ filename = \mathtt{None},\ correctSolidAngle = \mathtt{True},\\ tthRange = \mathtt{None},\ chiRange = \mathtt{None},\ mask = \mathtt{None},\ dummy = \mathtt{None},\ delta_dummy = \mathtt{None},\\ safe = \mathtt{True},\ devicetype = \mathtt{`all'},\ platformid = \mathtt{None},\ deviceid = \mathtt{None}) \end{array}$

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation using a Look-Up Table.

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt: number of points in the output pattern

(type=integer)

filename: file to save data in ascii format 2 column

(type = string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of the 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type = (float, float), optional)

chiRange: The lower and upper range of the chi angle. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type=(float, float), optional, disabled for now)

mask: array (same siza as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels

delta_dummy: precision for dummy value LUT specific parameters: safe: set to false if you think your GPU is already set-up

correctly (2theta, mask, solid angle...) OpenCL specific

parameters:

devicetype: can be "all", "cpu" or "gpu"

Return Value

(2theta, I) in degrees

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Pure numpy implementation (VERY SLOW !!!)

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt2Th: number of points in the output pattern in the Radial (horizontal)

axis (2 theta)

nbPtChi: number of points in the output pattern along the Azimuthal

(vertical) axis (chi)

(type=integer)

filename: file to save data in

(type=string)

mask: array (same siza as image) with 0 for masked pixels, and 1 for

valid pixels

dummy: value for dead/masked pixels
delta_dummy: precision for dummy value

nbPt: (type=integer)

Return Value

azimuthaly regrouped data, 2theta pos and chipos

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Cython implementation: fast but incaccurate

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt2Th: number of points in the output pattern in the Radial (horizontal)

axis (2 theta)

nbPtChi: number of points in the output pattern along the Azimuthal

(vertical) axis (chi)

 $(type{=}integer)$

filename: file to save data in

(type=string)

mask: array (same siza as image) with 0 for masked pixels, and 1 for

valid pixels

dummy: value for dead/masked pixels
delta_dummy: precision for dummy value

nbPt: (type=integer)

Return Value

azimuthaly regrouped data, 2theta pos and chipos

 $\begin{array}{l} \mathbf{xrpd2_splitBBox}(self,\ data,\ nbPt2Th,\ nbPtChi=360,\ filename=\mathtt{None},\\ correctSolidAngle=\mathtt{True},\ tthRange=\mathtt{None},\ chiRange=\mathtt{None},\ mask=\mathtt{None},\ dummy=\mathtt{None},\\ delta_dummy=\mathtt{None}) \end{array}$

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Split pixels according to their coordinate and a bounding box

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt2Th: number of points in the output pattern in the Radial

(horizontal) axis (2 theta)

nbPtChi: number of points in the output pattern along the

Azimuthal (vertical) axis (chi)

(type=integer)

filename: file to save data in

(type=string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of the 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type=(float, float), optional)

chiRange: The lower and upper range of the azimuthal angle. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type = (float, float), optional)

mask: array (same siza as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels delta_dummy: precision for dummy value

nbPt: (type=integer)

Return Value

azimuthaly regrouped data, 2theta pos. and chi pos.

 $\begin{array}{l} \mathbf{xrpd2_splitPixel}(self,\ data,\ nbPt2Th,\ nbPtChi = 360,\ filename = \mathtt{None}, \\ correctSolidAngle = \mathtt{True},\ tthRange = \mathtt{None},\ chiRange = \mathtt{None},\ mask = \mathtt{None},\ dummy = \mathtt{None}, \\ delta_dummy = \mathtt{None}) \end{array}$

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Split pixels according to their corner positions

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt2Th: number of points in the output pattern in the Radial

(horizontal) axis (2 theta)

nbPtChi: number of points in the output pattern along the

Azimuthal (vertical) axis (chi)

(type=integer)

filename: file to save data in

(type=string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of the 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type = (float, float), optional)

chiRange: The lower and upper range of the azimuthal angle. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type = (float, float), optional)

mask: array (same siza as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels
delta_dummy: precision for dummy value

nbPt: (type=integer)

Return Value

azimuthaly regrouped data, 2theta pos. and chi pos.

 $\mathbf{xrpd2}(self,\ data,\ nbPt2Th,\ nbPtChi=360,\ filename=\mathtt{None},\ correctSolidAngle=\mathtt{True},\ tthRange=\mathtt{None},\ chiRange=\mathtt{None},\ mask=\mathtt{None},\ dummy=\mathtt{None},\ delta_dummy=\mathtt{None})$

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Split pixels according to their coordinate and a bounding box

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt2Th: number of points in the output pattern in the Radial

(horizontal) axis (2 theta)

nbPtChi: number of points in the output pattern along the

Azimuthal (vertical) axis (chi)

(type=integer)

filename: file to save data in

(type=string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

tthRange: The lower and upper range of the 2theta. If not provided,

range is simply (data.min(), data.max()). Values outside

the range are ignored.

(type=(float, float), optional)

chiRange: The lower and upper range of the azimuthal angle. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type = (float, float), optional)

mask: array (same siza as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels
delta_dummy: precision for dummy value

nbPt: (type=integer)

Return Value

azimuthaly regrouped data, 2theta pos. and chi pos.

 $\begin{tabular}{ll} \mathbf{saxs}(self,\ data,\ nbPt,\ filename= \verb|None|,\ correctSolidAngle= \verb|True|,\ variance= \verb|None|,\ qRange= \verb|None|,\ chiRange= \verb|None|,\ mask= \verb|None|,\ dummy= \verb|None|,\ delta_dummy= \verb|None|,\ method= \verb|'bbox'|) \end{tabular}$

Calculate the azimuthal integrated Saxs curve

Multi algorithm implementation (tries to be bullet proof)

Parameters

data: 2D array from the CCD camera

(type=ndarray)

nbPt: number of points in the output pattern

(type=integer)

filename: file to save data to

(type=string)

correctSolidAngle: if True, the data are devided by the solid angle of each

pixel

(type=boolean)

variance: array containing the variance of the data

(type=ndarray)

qRange: The lower and upper range of the setter vector q. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type = (float, float), optional)

chiRange: The lower and upper range of the chi angle. If not

provided, range is simply (data.min(), data.max()).

Values outside the range are ignored.

(type = (float, float), optional)

mask: array (same siza as image) with 0 for masked pixels, and 1

for valid pixels

dummy: value for dead/masked pixels
delta_dummy: precision for dummy value

method: can be "numpy", "cython", "BBox" or "splitpixel"

Return Value

azimuthaly regrouped data, 2theta pos. and chi pos.

(type=3-tuple of ndarrays)

makeHeaders(self, hdr='#')

Return Value

a string to be used for headers

save1D(self, filename, dim1, I, error=None, dim1_unit='2th_deg')

save2D(self, filename, I, dim1, dim2, dim1_unit='2th')

$Inherited\ from\ pyFAI.geometry.Geometry(Section\ 6.2)$

repr(), calcfrom1d(), chi(), chiArray(), chi_corner(), cornerArray(), cornerQArray(), del_chia(), del_dssa(), del_qa(), del_ttha(), delta2Theta(), deltaChi(), deltaQ(), diffSolidAngle(), getFit2D(), getPyFAI(), get_chia(), get_correct_solid_angle_for_spline(), get_dist(), get_dssa(), get_pixel1(), get_pixel2(), get_poni1(), get_poni2(), get_qa(), get_rot1(), get_rot2(), get_rot3(), get_spline(), get_splineFile(), get_ttha(), get_wavelength(), load(), oversampleArray(), polarization(), qArray(), qCornerFunct(), qFunction(), read(), save(), setChiDiscAtPi(), setChiDiscAtZero(), setFit2D(), setOversampling(), setPyFAI(), set_chia(), set_correct_solid_angle_for_spline(), set_dist(), set_dssa(), set_pixel1(), set_pixel2(), set_poni1(), set_poni2(), set_qa(), set_rot1(), set_rot2(), set_rot3(), set_spline(), set_splineFile(), set_ttha(), set_wavelength(), sload(), solidAngleArray(), tth(), tth_corner(), twoThetaArray(), write()

Inherited from object

3.2.2 Properties

Name	Description		
Inherited from pyFAI.geometric	Inherited from pyFAI.geometry.Geometry (Section 6.2)		
chia, correct_SA_spline, dist, dssa, pixel1, pixel2, poni1, poni2, qa, rot1,			
rot2, rot3, spline, splineFile, ttha, wavelength			
Inherited from object			
class			

4 Module pyFAI.bilinear

Date: 21/12/2011

Author: Jerome Kieffer

 ${\bf Contact:}\ {\tt jerome.kieffer@esrf.fr}$

Copyright: 2011, ESRF

License: GPLv3

4.1 Variables

Name	Description
package	Value: 'pyFAI'
test	Value: {}

5 Module pyFAI.detectors

Date: 12/04/2012

Author: $J \times 3 \times 4$ Kieffer

Contact: Jerome.Kieffer@ESRF.eu

Copyright: European Synchrotron Radiation Facility, Grenoble, France

License: GPLv3+

5.1 Variables

Name	Description
status	Value: 'beta'
logger	Value:
	<pre>logging.getLogger("pyFAI.detectors")</pre>
package	Value: 'pyFAI'

5.2 Class Detector

object pyFAI.detectors.Detector

Known Subclasses: pyFAI.detectors.FReLoN, pyFAI.detectors.Fairchild, pyFAI.detectors.Pilatus Generic class representing a 2D detector

5.2.1 Methods

__init__(self, pixel1=None, pixel2=None, splineFile=None)
x.__init__(...) initializes x; see help(type(x)) for signature
Overrides: object.__init__ extit(inherited documentation)

__repr__(self)
repr(x)
Overrides: object.__repr__ extit(inherited documentation)

get_splineFile(self)

set_splineFile(self, splineFile)

 $\mathbf{get_binning}(self)$

 $set_binning(self, bin_size=(1, 1))$

getPyFAI(self)

getFit2D(self)

setPyFAI(self, **kwarq)

setFit2D(self)

calc_cartesian_positions(self, d1=None, d2=None)

Calculate the position of each pixel center in cartesian coordinate and in meter of a couple of coordinates. The half pixel offset is taken into account here !!!

Parameters

d1: ndarray of dimension 1 or 2 containing the Y pixel positions

d2: ndarray of dimension 1 or 2 containing the X pixel positions

Return Value

2-arrays of same shape as d1 & d2 with the position in meter d1 and d2 must have the same shape, returned array will have the same shape.

$\mathbf{get_mask}(self)$

Should return a generic mask for the detector

Inherited from object

5.2.2 Properties

Name	Description
splineFile	

continued on next page

Name	Description
binning	
Inherited from object	
class	

5.3 Class Pilatus

object —

pyFAI.detectors.Detector —

pyFAI.detectors.Pilatus

Known Subclasses: pyFAI.detectors.Pilatus1M, pyFAI.detectors.Pilatus2M, pyFAI.detectors.Pilatus6M Pilatus detector: generic description

5.3.1 Methods

```
__init__(self, pixel1=0.000172, pixel2=0.000172)

x.__init__(...) initializes x; see help(type(x)) for signature

Overrides: object.__init__ extit(inherited documentation)
```

```
get_mask(self)
Returns a generic mask for Pilatus detecors...
Overrides: pyFAI.detectors.Detector.get_mask
```

$Inherited\ from\ pyFAI. detectors. Detector (Section\ 5.2)$

```
_repr_(), calc_cartesian_positions(), getFit2D(), getPyFAI(), get_binning(), get_splineFile(), setFit2D(), setPyFAI(), set_binning(), set_splineFile()
```

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

5.3.2 Properties

Name	Description
Inherited from pyFAI.detectors.Detector (Section 5.2)	

continued on next page

Name	Description
binning, splineFile	
Inherited from object	
class	

5.3.3 Class Variables

Name	Description
MODULE_SIZE	Value: (195, 487)
MODULE_GAP	Value: (17, 7)

5.4 Class Pilatus1M

```
object —

pyFAI.detectors.Detector —

pyFAI.detectors.Pilatus —

pyFAI.detectors.Pilatus1M
```

Pilatus 1M detector

5.4.1 Methods

```
__init__(self, pixel1=0.000172, pixel2=0.000172)
x.__init__(...) initializes x; see help(type(x)) for signature
Overrides: object.__init__ extit(inherited documentation)
```

Inherited from pyFAI.detectors.Pilatus(Section 5.3)

get_mask()

$Inherited\ from\ pyFAI.detectors.Detector(Section\ 5.2)$

```
_repr_(), calc_cartesian_positions(), getFit2D(), getPyFAI(), get_binning(), get_splineFile(), setFit2D(), setPyFAI(), set_binning(), set_splineFile()
```

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

5.4.2 Properties

Name	Description
Inherited from pyFAI.detectors.Detector (Section 5.2)	
binning, splineFile	
Inherited from object	
_class	

5.4.3 Class Variables

Name	Description
Inherited from pyFAI.detectors.Pilatus (Section 5.3)	
MODULE_GAP, MODULE_SIZE	

5.5 Class Pilatus2M

```
object —

pyFAI.detectors.Detector —

pyFAI.detectors.Pilatus —

pyFAI.detectors.Pilatus2M
```

Pilatus 2M detector

5.5.1 Methods

```
__init__(self, pixel1=0.000172, pixel2=0.000172)

x.__init__(...) initializes x; see help(type(x)) for signature

Overrides: object.__init__ extit(inherited documentation)
```

$Inherited\ from\ pyFAI. detectors. Pilatus (Section\ 5.3)$

```
get_mask()
```

Inherited from pyFAI.detectors.Detector(Section 5.2)

```
_repr_(), calc_cartesian_positions(), getFit2D(), getPyFAI(), get_binning(), get_splineFile(), setFit2D(), setPyFAI(), set_binning(), set_splineFile()
```

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

5.5.2 Properties

Name	Description
Inherited from pyFAI.detectors.Detector (Section 5.2)	
binning, splineFile	
Inherited from object	
_class	

5.5.3 Class Variables

Name	Description
Inherited from pyFAI.detectors.Pilatus (Section 5.3)	
MODULE_GAP, MODULE_SIZE	

5.6 Class Pilatus6M

```
object —

pyFAI.detectors.Detector —

pyFAI.detectors.Pilatus —

pyFAI.detectors.Pilatus6M
```

Pilatus 6M detector

5.6.1 Methods

```
__init__(self, pixel1=0.000172, pixel2=0.000172)
x.__init__(...) initializes x; see help(type(x)) for signature
Overrides: object.__init__ extit(inherited documentation)
```

Inherited from pyFAI.detectors.Pilatus(Section 5.3)

get_mask()

Inherited from pyFAI.detectors.Detector(Section 5.2)

repr(), calc_cartesian_positions(), getFit2D(), getPyFAI(), get_binning(), get_splineFile(), setFit2D(), setPyFAI(), set_binning(), set_splineFile()

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

5.6.2 Properties

Name	Description
Inherited from pyFAI.detectors.Detector (Section 5.2)	
binning, splineFile	
Inherited from object	
class	

5.6.3 Class Variables

Name	Description
Inherited from pyFAI.detectors.Pilatus (Section 5.3)	
MODULE_GAP, MODULE_SIZE	

5.7 Class Fairchild

object —

pyFAI.detectors.Detector —

pyFAI.detectors.Fairchild

Fairchild Condor 486:90 detector

5.7.1 Methods

```
__init__(self, pixel1=1.5e-05, pixel2=1.5e-05)
x.__init__(...) initializes x; see help(type(x)) for signature
Overrides: object.__init__ extit(inherited documentation)
```

$Inherited\ from\ pyFAI. detectors. Detector (Section\ 5.2)$

```
_repr_(), calc_cartesian_positions(), getFit2D(), getPyFAI(), get_binning(), get_mask(), get_splineFile(), setFit2D(), setPyFAI(), set_binning(), set_splineFile()
```

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

5.7.2 Properties

Name	Description
Inherited from pyFAI.detectors.Detector (Section 5.2)	
binning, splineFile	
Inherited from object	
class	

5.8 Class FReLoN

```
object —

pyFAI.detectors.Detector —

pyFAI.detectors.FReLoN
```

FReLoN detector (spline mandatory to correct for geometric distortion)

5.8.1 Methods

```
__init__(self, splineFile)
x.__init__(...) initializes x; see help(type(x)) for signature
Overrides: object.__init__ extit(inherited documentation)
```

Inherited from pyFAI.detectors.Detector(Section 5.2)

```
_repr_(), calc_cartesian_positions(), getFit2D(), getPyFAI(), get_binning(), get_mask(), get_splineFile(), setFit2D(), setPyFAI(), set_binning(), set_splineFile()
```

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

5.8.2 Properties

Name	Description
Inherited from pyFAI.detectors.Detector (Section 5.2)	
binning, splineFile	
Inherited from object	
class	

6 Module pyFAI.geometry

Date: 09/06/2012

Author: Jerome Kieffer

Contact: Jerome.Kieffer@ESRF.eu

Copyright: European Synchrotron Radiation Facility, Grenoble, France

License: GPLv3+

6.1 Variables

Name	Description
_status	Value: 'beta'
logger	Value:
	<pre>logging.getLogger("pyFAI.geometry")</pre>
package	Value: 'pyFAI'

6.2 Class Geometry

object —

pyFAI.geometry.Geometry

Known Subclasses: pyFAI.azimuthalIntegrator.AzimuthalIntegrator

This class is an azimuthal integrator based on P. Boesecke's geometry and histogram algorithm by Manolo S. del Rio and V.A Sole

Detector is assumed to be corrected from "raster orientation" effect.

It is not addressed here but rather in the Detector object or at read time.

Considering there is no tilt:

Detector fast dimension (dim2) is supposed to be horizontal (dimension X of the image) Detector slow dimension (dim1) is supposed to be vertical, upwards (dimension Y of the interest The third dimension is chose such as the referential is orthonormal, so dim3 is along in

Demonstration of the equation done using Mathematica.

Axis 1 is along first dimension of detector (when not tilted), this is the slow dimension

```
x1=\{1,0,0\}
Axis 2 is along second dimension of detector (when not tilted), this is the fast dimensi
Axis 3 is along the incident X-Ray beam
      x3=\{0,0,1\}
We define the 3 rotation around axis 1, 2 and 3:
      rotM2 = RotationMatrix[rot2,x2] = \{\{cos[rot2],0,sin[rot2]\},\{0,1,0\},\{-sin[rot2],0,cos[rot2]\},\{0,1,0\},\{-sin[rot2],0,cos[rot2]\},\{0,1,0\},\{-sin[rot2],0,cos[rot2]\},\{0,1,0\},\{-sin[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[rot2],0,cos[
      rotM3 = RotationMatrix[rot3,x3] = \{\{cos[rot3], -sin[rot3], 0\}, \{sin[rot3], cos[rot3], 0\}, \{cos[rot3], 0\}, \{c
Rotations of the detector are applied first Rot around axis 1, then axis 2 and finally a
      R = rotM3.rotM2.rotM1
                   = \{\{\cos[\text{rot2}] \cos[\text{rot3}], \cos[\text{rot3}] \sin[\text{rot1}] \sin[\text{rot2}] - \cos[\text{rot1}] \sin[\text{rot3}], \cos[\text{rot1}] \cos[\text{rot3}] \}
                                         {cos[rot2] sin[rot3],cos[rot1] cos[rot3]+sin[rot1] sin[rot2] sin[rot3],-cos[rot3]
                                        {-sin[rot2],cos[rot2] sin[rot1],cos[rot1] cos[rot2]}}
In Python notation:
PForm[R.x1] = [cos(rot2)*cos(rot3), cos(rot2)*sin(rot3), -sin(rot2)]
PForm[R.x2] = [cos(rot3)*sin(rot1)*sin(rot2) - cos(rot1)*sin(rot3), cos(rot1)*cos(rot3) + cos(rot3)*sin(rot3) + cos(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*sin(rot3)*
PForm[R.x3] = [\cos(rot1)*\cos(rot3)*\sin(rot2) + \sin(rot1)*\sin(rot3), -(\cos(rot3)*\sin(rot1))
* Coordinates of the Point of Normal Incidence:
      PONI = R.\{0,0,L\}
      PForm[PONI] = [L*(cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3)),
                                                                                                 L*(-(\cos(\cot 3)*\sin(\cot 1)) + \cos(\cot 1)*\sin(\cot 2)*\sin(\cot 3)), L*\cos(\cot 1)*\cos(\cot 1)
* Any pixel on detector plan at coordinate (d1, d2) in meters. Detector is at z=L
      P = \{d1, d2, L\}
      PForm[R.P] = [t1, t2, t3] =
                                                                              = [d1*cos(rot2)*cos(rot3) + d2*(cos(rot3)*sin(rot1)*sin(rot2) - cos(rot1)*sin(rot2)]
                                                                                                 d1*cos(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + d2*(cos(rot3) + d2*(cos
                                                                                                 d2*cos(rot2)*sin(rot1) - d1*sin(rot2) + L*cos(rot1)*cos(rot2)
* Distance sample (origin) to detector point (d1,d2)
      FForm[Norm[R.P]] = sqrt(pow(Abs(L*cos(rot1)*cos(rot2) + d2*cos(rot2)*sin(rot1) - d1*sin(rot1) + d2*cos(rot2)*sin(rot1) + d2*cos(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*sin(rot2)*
                                                                                                                                 pow(Abs(d1*cos(rot2)*cos(rot3) + d2*(cos(rot3)*sin(rot1)*sin(rot2) -
                                                                                                                                 L*(cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3))),2) +
                                                                                                                                 pow(Abs(d1*cos(rot2)*sin(rot3) + L*(-(cos(rot3)*sin(rot1)) + cos(rot3)*sin(rot1)) + cos(rot3)*sin(rot3) + L*(-(cos(rot3)*sin(rot3)) + Cos(rot3)*sin(rot3)) + Cos(rot3)*sin(rot3) + Cos(rot3)*sin(rot3)*sin(rot3)*sin(rot3) + Cos(rot3)*sin(rot3) + Cos(rot3)*sin(rot3) + Cos(rot3)*sin(rot3)
                                                                                                                                  d2*(\cos(\cot 1)*\cos(\cot 3) + \sin(\cot 1)*\sin(\cot 2)*\sin(\cot 3))),2))
* cos(2theta) is defined as (R.P component along x3) over the distance from origin to da
      tth = ArcCos [-(R.P).x3/Norm[R.P]]
      FForm[tth] = Arccos((-(L*cos(rot1)*cos(rot2)) - d2*cos(rot2)*sin(rot1) + d1*sin(rot2))/
```

```
sqrt(pow(Abs(L*cos(rot1)*cos(rot2) + d2*cos(rot2)*sin(rot1) - d1*sin
pow(Abs(d1*cos(rot2)*cos(rot3) + d2*(cos(rot3)*sin(rot1)*sin(rot2)
L*(cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3))),2) +
pow(Abs(d1*cos(rot2)*sin(rot3) + L*(-(cos(rot3)*sin(rot1)) + cos(r
d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3))),2)))
```

```
* tan(2theta) is defined as sqrt(t1**2 + t2**2) / t3

tth = ArcTan2 [sqrt(t1**2 + t2**2) , t3]
```

Getting 2theta from it's tangeant seems both more precise (around beam stop very far from Currently there is a swich in the method to follow one path or the other.

```
* Tangeant of angle chi is defined as (R.P component along x1) over (R.P component along chi = ArcTan[((R.P).x1) / ((R.P).x2)]

FForm[chi] = ArcTan2(d1*cos(rot2)*cos(rot3) + d2*(cos(rot3)*sin(rot1)*sin(rot2) - cos(rot1)*cos(rot1)*sin(rot2) + sin(rot1)*sin(rot3)),

d1*cos(rot2)*sin(rot3) + L*(-(cos(rot3)*sin(rot1)) + cos(rot1)*sin(rot2)*sin(rot3)))
```

6.2.1 Methods

 $_$ init $_$ (self, dist=1, poni1=0, poni2=0, rot1=0, rot2=0, rot3=0, pixel1=1, pixel2=1, splineFile=None, detector=None)

Parameters

dist: distance sample - detector plan (orthogonal distance,

not along the beam), in meter.

poni1: coordinate of the point of normal incidence along the

detector's first dimension, in meter

poni2: coordinate of the point of normal incidence along the

detector's second dimension, in meter

rot1: first rotation from sample ref to detector's ref, in

radians

rot2: second rotation from sample ref to detector's ref, in

radians

rot3: third rotation from sample ref to detector's ref, in

radians

pixel1: pixel size of the fist dimension of the detector, in meter

pixel2: pixel size of the second dimension of the detector, in

meter

splineFile: file containing the geometric distortion of the detector.

Overrides the pixel size.

Overrides: object._init__

 $_$ repr $_$ (self)

repr(x)

Overrides: object._repr_ extit(inherited documentation)

tth(self, d1, d2, param=None, path='cython')

Calculates the 2theta value for the center of a given pixel (or set of pixels)

Parameters

d1: position(s) in pixel in first dimension (c order)

(type=scalar or array of scalar)

d2: position(s) in pixel in second dimension (c order)

(type=scalar or array of scalar)

path: can be "cos", "tan" or "cython" @return 2theta in radians

Return Value

floar or array of floats.

qFunction(self, d1, d2, param=None, path='cython')

Calculates the q value for the center of a given pixel (or set of pixels) in nm-1

q = 4pi/lambda sin(2theta / 2)

Parameters

d1: position(s) in pixel in first dimension (c order)

(type=scalar or array of scalar)

d2: position(s) in pixel in second dimension (c order)

(type=scalar or array of scalar @return q in in nm^(-1))

Return Value

float or array of floats.

qArray(self, shape)

Generate an array of the given shape with q(i,j) for all elements.

qCornerFunct(self, d1, d2)

calculate the q_vector for any pixel corner

tth_corner(self, d1, d2)

Calculates the 2theta value for the corner of a given pixel (or set of pixels)

Parameters

```
d1: position(s) in pixel in first dimension (c order)
```

(type=scalar or array of scalar)

d2: position(s) in pixel in second dimension (c order)

(type=scalar or array of scalar @return 2theta in radians)

Return Value

floar or array of floats.

twoThetaArray(self, shape)

Generate an array of the given shape with two-theta(i,j) for all elements.

$\mathbf{chi}(self, d1, d2, path='cython')$

Calculate the chi (azimuthal angle) for the centre of a pixel at coordinate d1,d2 which in the lab ref has coordinate: X1 = p1*cos(rot2)*cos(rot3) + p2*(cos(rot3)*sin(rot1)*sin(rot2) - cos(rot1)*sin(rot3)) - L*(cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3)) X2 = p1*cos(rot2)*sin(rot3) - L*(-(cos(rot3)*sin(rot1)) +

 $\cos(\cot 1)^*\sin(\cot 2)^*\sin(\cot 3)) + p2^*(\cos(\cot 1)^*\cos(\cot 3) + \sin(\cot 1)^*\sin(\cot 2)^*\sin(\cot 3))$ X3 = -(L*cos(\tau 1)^*\cos(\tau 1)) +

p2*cos(rot2)*sin(rot1) - p1*sin(rot2) hence tan(Chi) = X2 / X1

Parameters

d1: pixel coordinate along the 1st dimention (C convention)

(type=float or array of them)

d2: pixel coordinate along the 2nd dimention (C convention)

(type=float or array of them)

path: can be "tan" (i.e via numpy) or "cython"

Return Value

chi, the azimuthal angle in rad

chi_corner(self, d1, d2)

Calculate the chi (azimuthal angle) for the corner of a pixel at coordinate d1,d2 which in the lab ref has coordinate: X1 = p1*cos(rot2)*cos(rot3) + p2*(cos(rot3)*sin(rot1)*sin(rot2) - cos(rot1)*sin(rot3)) - L*(cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3)) X2 = p1*cos(rot2)*sin(rot3) - L*(-(cos(rot3)*sin(rot1)) + cos(rot1)*sin(rot2)*sin(rot3)) + p2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3)) X3 = -(L*cos(rot1)*cos(rot2)) + p2*cos(rot2)*sin(rot1) - p1*sin(rot2) hence <math>tan(Chi) = X2 / X1

Parameters

d1: pixel coordinate along the 1st dimention (C convention)

(type=float or array of them)

d2: pixel coordinate along the 2nd dimention (C convention)

(type=float or array of them)

Return Value

chi, the azimuthal angle in rad

chiArray(self, shape)

Generate an array of the given shape with chi(i,j) (azimuthal angle) for all elements.

cornerArray(self, shape)

Generate a 3D array of the given shape with (i,j) (azimuthal angle) for all elements.

cornerQArray(self, shape)

Generate a 3D array of the given shape with (i,j) (azimuthal angle) for all elements.

delta2Theta(self, shape)

Generate a 3D array of the given shape with (i,j) with the max distance between the center and any corner in 2 theta

deltaChi(self, shape)

Generate a 3D array of the given shape with (i,j) with the max distance between the center and any corner in chi-angle

deltaQ(self, shape)

Generate a 3D array of the given shape with (i,j) with the max distance between the center and any corner in q_vector

diffSolidAngle(self, d1, d2)

calulate the solid angle of the current pixels

solidAngleArray(self, shape)

Generate an array of the given shape with the solid angle of the current element two-theta(i,j) for all elements.

save(self, filename)

Save the refined parameters.

Parameters

filename: name of the file where to save the parameters

(type=string)

write(self, filename)

Save the refined parameters.

Parameters

filename: name of the file where to save the parameters

(type=string)

sload(cls, filename)

A static method combining the constructor and the loader from a

Parameters

filename: name of the file to load

(type=string)

Return Value

instance of Gerometry of AzimuthalIntegrator set-up with the parameter from the file.

load(self, filename)

Load the refined parameters from a file.

Parameters

filename: name of the file to load

(type=string)

read(self, filename)

Load the refined parameters from a file.

Parameters

filename: name of the file to load

(type=string)

getPyFAI(self)

return the parameter set from the PyFAI geometry as a dictionary

setPyFAI(self, **kwargs)

set the geometry from a pyFAI-like dict

getFit2D(self)

return a dict with parameters compatible with fit2D geometry

 $\mathbf{setFit2D}(self, directDist, centerX, centerY, tilt=0.0, tiltPlanRotation=0.0, pixelX=None, pixelY=None, splineFile=None)$

Set the Fit2D-like parameter set: For geometry description see HPR 1996 (14) pp-240

Parameters

direct: direct distance from sample to detector along

the incident beam (in millimeter as in fit2d)

tilt: tilt in degrees

tiltPlanRotation: Rotation (in degrees) of the tilt plan arround

the Z-detector axis * 0deg -> Y does not move, +X goes to Z<0 * 90deg -> X does not move, +Y goes to Z<0 * 180deg -> Y does not move, +X goes to Z>0 * 270deg -> X does not move,

+Y goes to Z>0

pixelX, pixelY: as in fit2d they ar given in micron, not in meter

centerX, centerY: pixel position of the beam center

splineFile: name of the file containing the spline

setChiDiscAtZero(self)

Set the position of the discontinuity of the chi axis between 0 and 2pi. By default it is between pi and -pi

setChiDiscAtPi(self)

Set the position of the discontinuity of the chi axis between -pi and +pi. This is the default behavour

setOversampling(self, iOversampling)

set the oversampling factor

oversampleArray(self, myarray)

polarization(self, shape, factor=0.98)

Calculate the polarization correction according to the polarization factor:

Parameters

factor: (Ih-Iv)/(Ih+Iv): varies between 0 (no polarization) and 1

(where division by 0 could occure) @return 2D array with

polarization correction array (intensity/polarisation)

 $\mathbf{get_ttha}(self)$

```
\mathbf{reset}(self)
reset most arrays that are cached: used when a parameter changes.
calcfrom1d(self, tth, I, shape=None, mask=None, dim1_unit='2th_deg')
Computes a 2D image from a 1D integrated profile
Parameters
    tth: 1D array with 2theta in degrees
          scattering intensity @return 2D image reconstructed
set_dist(self, value)
\mathbf{get\_dist}(self)
set_poni1(self, value)
get_poni1(self)
set_poni2(self, value)
\mathbf{get\_poni2}(self)
set_rot1(self, value)
get_rot1(self)
set_rot2(self, value)
get_rot2(self)
set_rot3(self, value)
get_rot3(self)
set_wavelength(self, value)
get_wavelength(self)
```

set_ttha(self, value)
$\mathbf{del_ttha}(self)$
$\mathbf{get_chia}(self)$
set_chia(self, value)
Set_cma(setj, value)
$\mathbf{del_chia}(self)$
$\mathbf{get_dssa}(\mathit{self})$
set_dssa(self, value)
$\mathbf{del_dssa}(\mathit{self})$
$\mathbf{get}_{-}\mathbf{qa}(self)$
$set_{-}qa(self, value)$
$del_{-}qa(self)$
$\mathbf{get_pixel1}(self)$
set_pixel1(self, pixel1)
$\mathbf{get_pixel2}(self)$
act nivel2(colf nimel0)
set_pixel2(self, pixel2)
$\boxed{\mathbf{get_splineFile}(\mathit{self})}$
set_splineFile(self, splineFile)
1 (1.19) (F)
$\mathbf{get_spline}(\mathit{self})$
set_spline(self, spline)
$[\mathtt{get_correct_solid_angle_for_spline}(self)]$

${\bf set_correct_solid_angle_for_spline}(\mathit{self}, \mathit{value})$

$Inherited\ from\ object$

6.2.2 Properties

Name	Description
dist	
poni1	
poni2	
rot1	
rot2	
rot3	
wavelength	
ttha	2theta array in cache
chia	chi array in cache
dssa	solid angle array in cache
qa	Q array in cache
pixel1	
pixel2	
splineFile	
spline	
correct_SA_spline	
Inherited from object	
class	

7 Module pyFAI.geometryRefinement

Date: 23/12/2011

Author: Jerome Kieffer

Contact: Jerome.Kieffer@ESRF.eu

Copyright: European Synchrotron Radiation Facility, Grenoble, France

License: GPLv3+

7.1 Variables

Name	Description	
status	Value: 'development'	
logger	Value:	
	logging.getLogger("pyFAI.geometryRefinement	.t")
ROCA	Value: '/opt/saxs/roca'	
package	Value: 'pyFAI'	

7.2 Class GeometryRefinement

```
object —

pyFAI.geometry.Geometry —

pyFAI.azimuthalIntegrator.AzimuthalIntegrator —
```

pyFAI.geometryRefinement.GeometryRefineme

7.2.1 Methods

```
-_init__(self, data, dist=1, poni1=None, poni2=None, rot1=0, rot2=0, rot3=0, pixel1=1, pixel2=1, splineFile=None)

x.__init__(...) initializes x; see help(type(x)) for signature

Parameters

data: ndarray float64 shape = n, 3 col0: pos in dim0 (in pixels) col1: pos in dim1 (in pixels) col2: associated tth value (in rad)

Overrides: object.__init__
```

residu1(self, param, d1, d2, tthRef)
residu2(self, param, d1, d2, tthRef)
$\mathbf{refine1}(self)$
refine2 (self, maxiter=1000000)
simplex(self, maxiter=1000000)
anneal(self, maxiter=1000000)
chi2(self, param=None)
$\mathbf{roca}(self)$
run roca to optimise the parameter set
set_dist_max(self, value)
$get_dist_max(self)$
gct_dist_max(scy)
set_dist_min(self, value)
1. 1
$\mathbf{get_dist_min}(self)$
set_poni1_min(self, value)
$get_poni1_min(self)$
set_poni1_max(self, value)
met nonil mov(self)
$get_poni1_max(self)$
set_poni2_min(self, value)
${f get_poni2_min}(self)$
set_poni2_max(self, value)

$\boxed{\mathbf{get_poni2_max}(\mathit{self})}$
set_rot1_min(self, value)
$\boxed{\mathbf{get_rot1_min}(\mathit{self})}$
set_rot1_max(self, value)
$\boxed{\mathbf{get_rot1_max}(\mathit{self})}$
set_rot2_min(self, value)
${\tt get_rot2_min}(\mathit{self})$
set_rot2_max(self, value)
$\boxed{\mathbf{get_rot2_max}(\mathit{self})}$
set_rot3_min(self, value)
$\mathbf{get_rot3_min}(\mathit{self})$
set_rot3_max(self, value)
$\boxed{\mathbf{get_rot3_max}(\mathit{self})}$

Inherited from pyFAI.azimuthalIntegrator.AzimuthalIntegrator(Section 3.2)

makeHeaders(), makeMask(), reset(), save1D(), save2D(), saxs(), setup_LUT(), xrpd(), xrpd2(), xrpd2_histogram(), xrpd2_numpy(), xrpd2_splitBBox(), xrpd2_splitPixel(), xrpd_LUT_OCL(), xrpd_OpenCL(), xrpd_cython(), xrpd_numpy(), xrpd_splitBBox(), xrpd_splitPixel()

Inherited from pyFAI.geometry.Geometry(Section 6.2)

repr(), calcfrom1d(), chi(), chiArray(), chi_corner(), cornerArray(), cornerQArray(), del_chia(), del_dssa(), del_qa(), del_ttha(), delta2Theta(), deltaChi(), deltaQ(), diffSolidAngle(), getFit2D(), getPyFAI(), get_chia(), get_correct_solid_angle_for_spline(), get_dist(), get_dssa(), get_pixel1(), get_pixel2(), get_poni1(), get_poni2(), get_qa(), get_rot1(), get_rot2(), get_spline(), get_splineFile(), get_ttha(), get_wavelength(), load(), oversampleArray(), polarization(), qArray(), qCornerFunct(), qFunction(), read(), save(), setChiDiscAtPi(), setChiDiscAtZero(), setFit2D(), setOversampling(),

setPyFAI(), set_chia(), set_correct_solid_angle_for_spline(), set_dist(), set_dssa(), set_pixel1(), set_pixel2(), set_poni1(), set_poni2(), set_qa(), set_rot1(), set_rot2(), set_rot3(), set_spline(), set_splineFile(), set_ttha(), set_wavelength(), sload(), solidAngleArray(), tth(), tth_corner(), twoThetaArray(), write()

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

7.2.2 Properties

Name	Description	
dist_max		
dist_min		
poni1_min		
poni1_max		
poni2_min		
poni2_max		
rot1_min		
rot1_max		
rot2_min		
rot2_max		
rot3_min		
rot3_max		
Inherited from pyFAI.geometry.Geometry (Section 6.2)		
chia, correct_SA_spline, dist, dssa, pixel1, pixel2, poni1, poni2, qa, rot1,		
rot2, rot3, spline, splineFile, ttha, wavelength		
Inherited from object		
class		

8 Module pyFAI.histogram

Date: 20120916

Author: Jerome Kieffer

Name	Description
_package	Value: 'pyFAI'
test	Value: {}

$9 \quad Module \ pyFAI.ocl_azim$

Date: 03/07/2012

Author: Jerome Kieffer

 ${\bf Contact:}\ {\tt jerome.kieffer@esrf.fr}$

 ${\bf Copyright:}\ 2012,\ {\bf ESRF},\ {\bf Grenoble}$

License: GPLv3

Name	Description
package	Value: 'pyFAI'
test	Value: {}
lock	Value: <threadingsemaphore at<="" object="" th=""></threadingsemaphore>
	0x206f290>
ocl	Value: OpenCL devic

10 Module pyFAI.ocl_azim_lut

Date: 18/10/2012

Author: Jerome Kieffer

Contact: jerome.kieffer@esrf.fr

Copyright: 2012, ESRF, Grenoble

License: GPLv3

10.1 Variables

Name	Description
ocl	Value: OpenCL devic
package	Value: 'pyFAI'

10.2 Class OCL_LUT_Integrator

object — pyFAI.ocl_azim_lut.OCL_LUT_Integrator

10.2.1 Methods

 $_$ init $_$ (self, lut, devicetype='all', platformid=None, deviceid=None, checksum=None)

 $x_{-init_{-}(...)}$ initializes x; see help(type(x)) for signature

Parameters

lut: array of uint32 - float32 with shape (nbins, lut_size) with

indexes and coefficients

checksum: pre - calculated checksum to prevent re - calculating it:)

Overrides: object.__init__

__del__(self)
Destructor: release all buffers

$get_nr_threads(self, size=None, ws=None)$

calculate the number of threads, multiple of workgroup-size and greater than bins

$$\label{eq:lone} \begin{split} & \textbf{integrate}(\textit{self}, \textit{data}, \textit{dummy} = \texttt{None}, \textit{delta_dummy} = \texttt{None}, \textit{dark} = \texttt{None}, \\ & \textit{flat} = \texttt{None}, \textit{solidAngle} = \texttt{None}, \textit{polarization} = \texttt{None}) \end{split}$$

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

10.2.2 Properties

Name	Description
Inherited from object	
class	

11 Module pyFAI.peakPicker

Date: 23/12/2011

Author: $J \times 3 \times 4$ Kieffer

Contact: Jerome.Kieffer@ESRF.eu

Copyright: European Synchrotron Radiation Facility, Grenoble, France

License: GPLv3+

11.1 Variables

Name	Description
status	Value: 'development'
logger	Value:
	<pre>logging.getLogger("pyFAI.peakPicker")</pre>
TARGET_SIZE	Value: 1024
package	Value: 'pyFAI'

11.2 Class PeakPicker

object — pyFAI.peakPicker.PeakPicker

11.2.1 Methods

 $__init__(self, strFilename, reconst = \texttt{False})$

x.__init__(...) initializes x; see help(type(x)) for signature

Parameters

reconst: shall negative values be reconstucted (wipe out problems

with pilatus gaps)

Overrides: object.__init__

 $\mathbf{gui}(\mathit{self}, \mathit{log} = \mathtt{False})$

Parameters

log: show z in log scale

load(self, filename)

load a filename and plot data on the screen (if GUI)

display_points(self)

onclick(self, event)

readFloatFromKeyboard(self, text, dictVar)

Read float from the keyboard

Parameters

text: string to be displayed

dictVar: dict of this type: {1: [set_dist_min],3: [set_dist_min,

set_dist_guess, set_dist_max]}

finish(self, filename=None)

Ask the 2theta values for the given points

contour(self, data)

Parameters

data:

massif_contour(self, data)

Parameters

data:

closeGUI(self)

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

11.2.2 Properties

Name	Description
Inherited from object	
_class	

11.3 Class ControlPoints

object — pyFAI.peakPicker.ControlPoints

This class contains a set of control points with (optionaly) their diffrection 2Theta angle

11.3.1 Methods

```
__init__(self, filename=None)

x.__init__(...) initializes x; see help(type(x)) for signature

Overrides: object.__init__ extit(inherited documentation)
```

```
-_repr__(self)
repr(x)
Overrides: object.__repr__ extit(inherited documentation)
```

```
\_len\_(self)
```

```
\frac{\mathbf{check}(\mathit{self})}{\mathbf{check} \text{ internal consistency of the class}}
```

```
\frac{\mathbf{reset}(self)}{\mathbf{remove all stored values and resets them to default}}
```

```
append(self, points, angle=None)
Parameters
    point: list of points
    angle: 2-theta angle in radians
```

```
append_2theta_deg(self, points, angle=None)
Parameters
   point: list of points
   angle: 2-theta angle in degrees
```

pop(self, idx=None)

Remove the set of points at given index (by default the last)

Parameters

idx: poistion of the point to remove

save(self, filename)

Save a set of control points to a file

Parameters

filename: name of the file

Return Value

None

load(self, filename)

load all control points from a file

 $\mathbf{getList}(self)$

Retrieve the list of control points suitable for geometry refinement

readAngleFromKeyboard(self)

Ask the 2theta values for the given points

setWavelength(*self*, *value*=None)

getWavelength(self)

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

11.3.2 Properties

Name	Description
wavelength	
Inherited from object	
class	

11.4 Class Massif

object ___ pyFAI.peakPicker.Massif

A massif is defined as an area around a peak, it is used to find neighbouring peaks

11.4.1 Methods

```
__init__(self, data=None)
x.__init__(...) initializes x; see help(type(x)) for signature
Overrides: object.__init__
```

```
\frac{\mathbf{nearest\_peak}(\mathit{self}, x)}{\text{@returns the coordinates of the nearest peak}}
```

```
\frac{\text{calculate\_massif}(\textit{self}, \textit{x})}{\text{defines a map of the massif around x and returns the mask}}
```

```
\label{eq:contour} \begin{aligned} & \textbf{find\_peaks}(\textit{self}, \textit{x}, \textit{nmax} \texttt{=} \texttt{200}, \textit{annotate} \texttt{=} \texttt{None}, \textit{massif\_contour} \texttt{=} \texttt{None}, \\ & \textit{stdout} \texttt{=} \texttt{sys.stdout}) \end{aligned}
```

All in one function that finds a maximum from the given seed (x) then calculates the region extension and extract position of the neighboring peaks.

Parameters

x: seed for the calculation, input coordinates

nmax: maximum number of peak per region

annotate: call back method taking number of points +

coordinate as input.

massif_contour: callback to show the contour of a massif with the

given index.

stdout: this is the file where output is written by default.

Return Value list of peaks

initValleySize(self)

$\mathbf{getValleySize}(self)$

setValleySize(self, size)

delValleySize(self)

 $\frac{\mathbf{getBinnedData}(\mathit{self})}{\mathbf{@return\ binned\ data}}$

 $\mathbf{getMedianData}(self)$

 $|\mathbf{getBluredData}(\mathit{self})|$

 ${f getLabeledMassif}(\mathit{self}, \mathit{pattern} = {f None})$

Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

11.4.2 Properties

Name	Description
valley_size	Defines the minimum distance between two
	massifs
Inherited from object	
class	

12 Module pyFAI.reconstruct

Name	Description
package	Value: 'pyFAI'
test	Value: {}

13 Module pyFAI.refinment2D

Date: 23/08/2012

Author: $J\xc3\xa9r\xc3\xb4me$ Kieffer

Contact: Jerome.Kieffer@ESRF.eu

Copyright: European Synchrotron Radiation Facility, Grenoble, France

License: GPLv3+

13.1 Variables

Name	Description
status	Value: 'beta'
logger	Value:
	logging.getLogger("pyFAI.refinment2D")
package	Value: 'pyFAI'

13.2 Class Refinment2D

object pyFAI.refinment2D.Refinment2D

refine the parameters from image itself ...

13.2.1 Methods

__init__(self, img, ai=None)
x.__init__(...) initializes x; see help(type(x)) for signature
Overrides: object.__init__

 $\mathbf{get_shape}(self)$

reconstruct(self, tth, I)

Reconstruct a perfect image according to 2th / I given in input

Parameters

tth: 2 theta array

I: intensity array

 $\mathbf{diff}_{\mathbf{L}}\mathbf{tth}_{\mathbf{X}}(self, dx=0.1)$

 $diff_{tth_{tilt}(self, dx=0.1)}$

 $diff_Fit2D(self, axis='all', dx=0.1)$

scan_centerX(self, width=1.0, points=10)

scan_tilt(self, width=1.0, points=10)

scan_Fit2D(self, width=1.0, points=10, axis='tilt', dx=0.1)

Inherited from object

__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()

13.2.2 Properties

Name	Description
shape	
Inherited from object	
class	

14 Module pyFAI.relabel

Date: 20120916

Author: Jerome Kieffer

Contact: Jerome.kieffer@esrf.fr

License: GPLv3+

Name	Description
package	Value: 'pyFAI'
_status	Value: 'stable'
test	Value: {}

15 Module pyFAI.spline

This is piece of software aims to manipulate spline files for geometric corrections of the 2D detectors using cubic-spline

Author: $J \times 3 \times 4$ Kieffer

Contact: Jerome.Kieffer@esrf.eu

Copyright: European Synchrotron Radiation Facility, Grenoble, France

License: GPLv3+

15.1 Variables

Name	Description
package	Value: 'pyFAI'

15.2 Class Spline

This class is a python representation of the spline file Those file represent cubic splines for 2D detector distortions and makes heavy use of fitpack (dierckx in netlib) — A Python-C wrapper to FITPACK (by P. Dierckx). FITPACK is a collection of FORTRAN programs for curve and surface fitting with splines and tensor product splines. See http://www.cs.kuleuven.ac.be/cwis/research or http://www.netlib.org/dierckx/index.html

15.2.1 Methods

init(self, filename=None)
this is the constructor of the Spline class, for

$__\mathbf{repr}__(self)$

zeros(self, xmin=0.0, ymin=0.0, xmax=2048.0, ymax=2048.0, pixSize=None)

defines a spline file with no (zero) displacement.

Parameters

xmin: minimum coordinate in x, usually zero

(type = float)

xmax: maximum coordinate in x (+1) usually 2048

(type=float)

ymin: minimum coordinate in y, usually zero

(type=float)

ymax: maximum coordinate y (+1) usually 2048

(type = float)

zeros_like(self, other)

defines a spline file with no (zero) displacement with the same shape as the other one given.

Parameters

other: another Spline

(type = Spline)

read(self, filename)

read an ascii spline file from file

Parameters

filename: name of the file containing the cubic spline distortion file

(type=string)

comparison(self, ref, verbose=False)

Compares the current spline distortion with a reference

Parameters

ref: another spline file

Return Value

True or False depending if the splines are the same or not

spline2array(self, timing=False)

calculates the displacement matrix using fitpack bisplev(x, y, tck, dx = 0, dy = 0)

Evaluate a bivariate B-spline and its derivatives. Return a rank-2 array of spline function values (or spline derivative values) at points given by the cross-product of the rank-1 arrays x and y. In special cases, return an array or just a float if either x or y or both are floats.

splineFuncX(self, x, y)

calculates the displacement matrix using fitpack for the X direction

Parameters

- x: numpy array repesenting the points in the x direction
- y: numpy array repesenting the points in the y direction

Return Value

displacement matrix for the X direction

 $(type=numpy\ arrays)$

splineFuncY(self, x, y)

calculates the displacement matrix using fitpack for the Y direction

Parameters

- x: numpy array repesenting the points in the x direction
- y: numpy array repesenting the points in the y direction

Return Value

displacement matrix for the Y direction

(type=numpy array)

array2spline(self, smoothing=1000, timing=False)

calculates the spline coefficients from the displacements matrix using fitpack

writeEDF(self, basename)

save the distortion matrices into a couple of files called basename-x.edf and basename-y.edf

Class Spline Module pyFAI.spline

write(self, filename)

save the cubic spline in an ascii file usable with Fit2D or SPD

Parameters

 ${\tt filename}\colon$ name of the file containing the cubic spline distortion file

(type=string)

tilt(self, center=(0.0, 0.0), tiltAngle=0.0, tiltPlanRot=0.0,
distanceSampleDetector=1.0, timing=False)

The tilt method apply a virtual tilt on the detector, the point of tilt is given by the center

Parameters

center: position of the point of tilt, this point

will not be moved.

(type=2tuple of floats)

tiltAngle: the value of the tilt in degrees

(type=float in the range [-90:+90]

degrees)

tiltPlanRot: the rotation of the tilt plan with the Ox

axis (0 deg for y axis invariant, 90 deg

for x axis invariant)

(type=Float in the range [-180:180])

distanceSampleDetector: the distance from sample to detector in

meter (along the beam, so distance from

sample to center)

(type = float)

Return Value

tilted Spline instance

(type=Spline)

setPixelSize(self, pixelSize)

sets the size of the pixel from a 2-tuple of floats expressed in meters.

Parameters

pixelSize: (type=2-tuple of float)

$\mathbf{getPixelSize}(\mathit{self})$

Return Value

the size of the pixel from a 2D detector (type=2-tuple of floats expressed in meter.)

 $\mathbf{bin}(self, binning = None)$

16 Module pyFAI.splitBBox

Name	Description
package	Value: 'pyFAI'
test	Value: {}

17 Module pyFAI.splitBBoxLUT

Name	Description
package	Value: 'pyFAI'
test	Value: {}

18 Module pyFAI.splitPixel

Name	Description
package	Value: 'pyFAI'
test	Value: {}

19 Module pyFAI.utils

19.1 Functions

timeit(func)

gaussian_filter(input, sigma, mode='reflect', cval=0.0)

2-dimensional Gaussian filter implemented with FFTw

Parameters

input: input array to filter

(type=array-like)

sigma: standard deviation for Gaussian kernel. The standard

deviations of the Gaussian filter are given for each axis as a sequence, or as a single number, in which case it is equal for

all axes.

(type=scalar or sequence of scalars)

mode: {'reflect', 'constant', 'nearest', 'mirror', 'wrap'}, optional The

"mode" parameter determines how the array borders are handled, where "cval" is the value when mode is equal to

'constant'. Default is 'reflect'

cval: scalar, optional Value to fill past edges of input if "mode" is

'constant'. Default is 0.0

expand(input, sigma, mode='constant', cval=0.0)

Expand array a with its reflection on boundaries

Parameters

a: 2D array

sigma: float or 2-tuple of floats

mode: "constant","nearest" or "reflect"

cval: filling value used for constant, 0.0 by default

Functions Module pyFAI.utils

relabel(label, data, blured, max_size=None)

Relabel limits the number of region in the label array. They are ranked relatively to their $\max(I0)$ - $\max(blur(I0)$

Parameters

label: a label array coming out of

scipy.ndimage.measurement.label

data: an array containing the raw data

blured: an array containing the blured data

max_size: the max number of label wanted @return array like label

averageImages(listImages, output=None, threshold=0.1, minimum=None, maximum=None, darks=None, flats=None)

Takes a list of filenames and create an average frame discarding all saturated pixels.

Parameters

listImages: list of string representing the filenames

output: name of the optional output file

threshold: what is the upper limit? all pixel $> \max^*(1-\text{threshold})$

are discareded.

minimum: minimum valid value or True

maximum: maximum valid value

darks: list of dark current images for subtraction

flats: list of flat field images for division

boundingBox(img)

Tries to guess the bounding box around a valid massif

Parameters

img: 2D array like

Return Value

4-typle (d0_min, d1_min, d0_max, d1_max)

Variables Module pyFAI.utils

removeSaturatedPixel(ds, threshold=0.1, minimum=None, maximum=None)

Parameters

ds: a dataset as ndarray

threshold: what is the upper limit? all pixel $> \max^*(1-\text{threshold})$

are discareded.

minimum: minumum valid value (or True for auto-guess)

maximum: maximum valid value

Return Value

another dataset

binning(inputArray, binsize)

Parameters

inputArray: input ndarray

binsize: int or 2-tuple representing the size of the binning

Return Value

binned input ndarray

unBinning(binnedArray, binsize)

Parameters

binnedArray: input ndarray

binsize: 2-tuple representing the size of the binning

Return Value

unBinned input ndarray

Name	Description
logger	Value: logging.getLogger("pyFAI.utils")
timelog	Value: logging.getLogger("pyFAI.timeit")
package	Value: 'pyFAI'

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