

Second Order Differential Equations Procedure

Given:

$$\begin{pmatrix} \ddot{x} \\ \ddot{y} \end{pmatrix} = \begin{pmatrix} \tilde{A} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$x(0) = x_0$$

$$y(0) = y_0$$

$$\dot{x}(0) = v_{0x}$$

$$\dot{y}(0) = v_{0y}$$

Step 1:

Solve for the eigenvalues and eigenvectors of \tilde{A}

$$\rightarrow \lambda_1, \lambda_2$$

$$\rightarrow \vec{s}_1, \vec{s}_2$$

Step 2:

Construct the matrix, \tilde{S} , with the eigenvectors of \tilde{A} as columns.

$$\tilde{S} = \begin{pmatrix} s_{1x} & s_{2x} \end{pmatrix}$$

$$S = \begin{pmatrix} S_{1y} & S_{2y} \end{pmatrix}$$

Step 3:

Construct the matrix, Λ ,
with the eigenvalues of \tilde{A}
as the diagonal elements.

$$\Lambda = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$$

Step 4:

Find the inverse of \tilde{S} ,

$$\tilde{S}^{-1}_{ij} = \frac{1}{\det(S)} \begin{pmatrix} S_{2y} & -S_{2x} \\ -S_{1y} & S_{1x} \end{pmatrix}$$

Step 5:

$$\text{Let } \ddot{r}_1 = \lambda_1 r_1$$

$$\text{Let } \ddot{r}_2 = \lambda_2 r_2$$

Case 1: $\lambda_i < 0$

$$r_i = C_i \sin \sqrt{\lambda_i} t + K_i \cos \sqrt{\lambda_i} t$$

Case 2: $\lambda_i > 0$

$$r_i = C_i e^{\sqrt{\lambda_i} t} + K_i e^{-\sqrt{\lambda_i} t}$$

Now, need to determine C_1, C_2, K_1, K_2 from initial conditions.

Step 6: Using that $\begin{pmatrix} r_1 \\ r_2 \end{pmatrix} = S_{inv} \begin{pmatrix} x \\ y \end{pmatrix}$

$$r_1(t) = \frac{1}{\det S} (S_{2y} x(t) - S_{2x} y(t))$$

$$r_2(t) = \frac{1}{\det S} (-S_{1y} x(t) + S_{1x} y(t))$$

① $\Rightarrow r_{10} = \frac{1}{\det S} (S_{2y} x_0 - S_{2x} y_0)$

② $\Rightarrow r_{20} = \frac{1}{\det S} (-S_{1y} x_0 + S_{1x} y_0)$

Evaluate
based on
Step 5
solutions!!

Using that $\begin{pmatrix} \dot{r}_1 \\ \dot{r}_2 \end{pmatrix} = S_{inv} \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix}$

$$\dot{r}_1(t) = \frac{1}{\det S} (S_{2y} \dot{x}(t) - S_{2x} \dot{y}(t))$$

$$\dot{r}_2(t) = \frac{1}{\det S} (-S_{1y} \dot{v}(t) + S_{1y} \dot{y}(t))$$

③ \Rightarrow $\dot{r}_{10} = \frac{1}{\det S} (S_{2y} V_{0x} - S_{2x} V_{0y})$

④ \Rightarrow $\dot{r}_{20} = \frac{1}{\det S} (-S_{1y} V_{0x} + S_{1y} V_{0y})$

Use ①, ②, ③, ④ to determine

$C_1, K_1, C_2, K_2 !! \rightarrow s(t), r(t)$

Step b: Using $\begin{pmatrix} x \\ y \end{pmatrix} = \tilde{S} \begin{pmatrix} r_1 \\ r_2 \end{pmatrix}$

$$x(t) = S_{1x} r_1(t) + S_{2x} r_2(t)$$

$$y(t) = S_{1y} r_1(t) + S_{2y} r_2(t)$$