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Project Overview:

This code provides an implementation for Binary Trees, Binary Search Trees (BSTs), and Heap operations. It includes functions to perform basic operations like insertion, deletion, search, and traversal for trees and heaps.

Description of Each Functionality

Includes and using namespace std

```
1  #include <iostream>
2  #include <vector>
3  #include <queue>
4  #include <algorithm>
5  using namespace std;
```

- **#include <iostream>**: Enables input/output operations using cin, cout.
- **#include <vector>**: Used for dynamic arrays.
- **#include <queue>**: Allows the use of queues (FIFO) and priority queues.
- **#include <algorithm>**: Provides utility functions like swap.
- **using namespace std;**: Avoids prefixing std:: for standard functions like cout.

Node Structure

```
6
7  // Node structure
8  struct Node {
9      int data;
10     Node *left, *right;
11     Node(int data) : data(data), left(nullptr), right(nullptr) {}
12 };
```

- **data**: Stores the value of the node.
- **left, right**: Pointers to the left and right children.
- **Constructor**: Initializes data and sets left and right to nullptr.

Binary Tree Operations

Insert a node

```
13
14  // Function to insert a node into a Binary Tree
15  void insertBinaryTree(Node*& root, int data) {
16      if (root == nullptr) {
17          root = new Node(data);
18          return;
19      }
20      queue<Node*> q;
21      q.push(root);
22      while (!q.empty()) {
23          Node* temp = q.front();
24          q.pop();
25          if (!temp->left) {
26              temp->left = new Node(data);
27              break;
28          } else {
29              q.push(temp->left);
30          }
31          if (!temp->right) {
32              temp->right = new Node(data);
33              break;
34          } else {
35              q.push(temp->right);
36          }
37      }
```



- Inserts a new node in the first available position using level-order traversal.
- If root is nullptr, create a new root node.
- Otherwise, use a queue to traverse the tree level by level and insert the node in the first available position.

Tree Traversals

Pre-order Traversal: Root → Left → Right

```
38
39 // Preorder Traversal for Binary Tree
40 void preorderBinaryTree(Node* root) {
41     if (root) {
42         cout << root->data << " ";
43         preorderBinaryTree(root->left);
44         preorderBinaryTree(root->right);
45     }
46 }
```

In-order Traversal: Left → Root → Right

```
47
48 // Inorder traversal for Binary Tree (Sorted order)
49 void inorderBinaryTree(Node* root) {
50     if (root) {
51         inorderBinaryTree(root->left); // Recurse on left subtree
52         cout << root->data << " "; // Visit the root
53         inorderBinaryTree(root->right); // Recurse on right subtree
54     }
55 }
```

Post-order Traversal: Left → Right → Root

```
56
57 // Postorder Traversal for Binary Tree
58 void postorderBinaryTree(Node* root) {
59     if (root) {
60         postorderBinaryTree(root->left);
61         postorderBinaryTree(root->right);
62         cout << root->data << " ";
63     }
64 }
```

Search in a Binary Tree

```
66 // Search in Binary Tree
67 Node* searchBinaryTree(Node* root, int data) {
68     if (!root) return nullptr;
69     if (root->data == data) return root;
70     Node* leftSearch = searchBinaryTree(root->left, data);
71     if (leftSearch) return leftSearch;
72     return searchBinaryTree(root->right, data);
73 }
```

- Searches for a node with the given data using recursion.



Delete a Node

Delete the deepest node

```
75 // Delete the deepest node
76 void deleteDeepestNode(Node* root, Node* deepNode) {
77     queue<Node*> q;
78     q.push(root);
79     while (!q.empty()) {
80         Node* temp = q.front();
81         q.pop();
82         if (temp->left) {
83             if (temp->left == deepNode) {
84                 delete temp->left;
85                 temp->left = nullptr;
86                 return;
87             }
88             q.push(temp->left);
89         }
90         if (temp->right) {
91             if (temp->right == deepNode) {
92                 delete temp->right;
93                 temp->right = nullptr;
94                 return;
95             }
96             q.push(temp->right);
97         }
98     }
99 }
```

Delete a specific node

```
100 // Delete a node in Binary Tree
101 void deleteNodeBinaryTree(Node*& root, int data) {
102     if (!root) return;
103     if (!root->left && !root->right) {
104         if (root->data == data) {
105             delete root;
106             root = nullptr;
107         }
108         return;
109     }
110     queue<Node*> q;
111     q.push(root);
112     Node* targetNode = nullptr;
113     Node* temp = nullptr;
114     while (!q.empty()) {
115         temp = q.front();
116         q.pop();
117         if (temp->data == data) targetNode = temp;
118         if (temp->left) q.push(temp->left);
119         if (temp->right) q.push(temp->right);
120     }
121     if (targetNode) {
122         targetNode->data = temp->data;
123         deleteDeepestNode(root, temp);
124     }
125 }
126 }
```

- Finds the deepest node and swaps its value with the node to delete.
- Deletes the deepest node.

Binary Search Tree (BST) Operations

Insert a Node

```
127 // Insert into Binary Search Tree
128 void insertBST(Node*& root, int data) {
129     if (!root) {
130         root = new Node(data);
131         return;
132     }
133     if (data < root->data)
134         insertBST(root->left, data);
135     else
136         insertBST(root->right, data);
137 }
138 }
```

- Places smaller values in the left subtree and larger values in the right subtree.



Delete a Node

```
177 // Delete a node in BST
178 Node* deleteNodeBST(Node* root, int data) {
179     if (!root) return nullptr;
180     if (data < root->data)
181         root->left = deleteNodeBST(root->left, data);
182     else if (data > root->data)
183         root->right = deleteNodeBST(root->right, data);
184     else {
185         if (!root->left) {
186             Node* temp = root->right;
187             delete root;
188             return temp;
189         } else if (!root->right) {
190             Node* temp = root->left;
191             delete root;
192             return temp;
193         }
194         Node* successor = root->right;
195         while (successor->left) successor = successor->left;
196         root->data = successor->data;
197         root->right = deleteNodeBST(root->right, successor->data);
198     }
199     return root;
200 }
```

- Handles three cases: node with no child, one child, or two children.

Heap Operations

Heapify Function

```
201 // Custom heapify function
202 void heapify(vector<int>& arr, int n, int i) {
203     int largest = i; // Initialize largest as root
204     int left = 2 * i + 1; // Left child
205     int right = 2 * i + 2; // Right child
206
207     // If left child is larger than root
208     if (left < n && arr[left] > arr[largest])
209         largest = left;
210
211     // If right child is larger than largest so far
212     if (right < n && arr[right] > arr[largest])
213         largest = right;
214
215     // If largest is not root
216     if (largest != i) {
217         swap(arr[i], arr[largest]);
218
219         // Recursively heapify the affected subtree
220         heapify(arr, n, largest);
221     }
222 }
223 }
```

- This function is used to maintain the heap property (for a max-heap: every parent node must be larger than its children).
- arr: The array representing the heap.
- n: Size of the heap (or sub-heap).
- i: The current root node being checked.

Key Steps:

1. Assume the current node (i) is the largest.
2. Check its left ($2*i+1$) and right ($2*i+2$) children, updating largest if a child is larger.
3. If the largest value is not at the root, swap and recursively call heapify.

Build Heap

```
223 }
224
225 void buildHeap(vector<int>& arr) {
226     int n = arr.size();
227     // Index of the last non-leaf node
228     int startIdx = (n / 2) - 1;
229
230     // Perform reverse level order traversal
231     // from the last non-leaf node and heapify each node
232     for (int i = startIdx; i >= 0; i--) {
233         heapify(arr, n, i);
234     }
235 }
```



- Non-leaf nodes start at index $(n/2 - 1)$.
- Heapify every node from the last non-leaf node to the root.

Heapify Operations

```
236
237 void heapifyOperations() {
238     vector<int> values;
239     int value;
240     cout << "Enter values to heapify (enter -1 to stop): ";
241     while (cin >> value && value != -1) {
242         values.push_back(value);
243     }
244
245     buildHeap(values);
246
247     cout << "Heapified array: ";
248     for (int v : values) {
249         cout << v << " ";
250     }
251     cout << endl;
252 }
```

- Reads input values, builds a max-heap, and prints the heapified array.
- Input values are collected in a vector.
- buildHeap is called to convert the array into a max-heap.
- The resulting array is printed.

Min-Heap and Max-Heap Operations

Min-Heap

```
254 // Min-Heap Operations
255 void minHeapOperations() {
256     priority_queue<int, vector<int>, greater<int>> minHeap;
257     int value;
258     cout << "Enter values for Min-Heap (enter -1 to stop): ";
259     while (cin >> value && value != -1) {
260         minHeap.push(value);
261     }
262     cout << "Min-Heap elements: ";
263     while (!minHeap.empty()) {
264         cout << minHeap.top() << " ";
265         minHeap.pop();
266     }
267     cout << endl;
268 }
```

Max-Heap

```
269
270 // Max-Heap Operations
271 void maxHeapOperations() {
272     priority_queue<int> maxHeap;
273     int value;
274     cout << "Enter values for Max-Heap (enter -1 to stop): ";
275     while (cin >> value && value != -1) {
276         maxHeap.push(value);
277     }
278     cout << "Max-Heap elements: ";
279     while (!maxHeap.empty()) {
280         cout << maxHeap.top() << " ";
281         maxHeap.pop();
282     }
283     cout << endl;
284 }
```

- Min-Heap: Maintains the smallest element at the root.
- Max-Heap: Maintains the largest element at the root.
- priority_queue is used to efficiently manage heaps in C++.
- greater<int> creates a min-heap; the default is a max-heap.



Main Function

```
286 int main() {
287     Node* binaryTreeRoot = nullptr;
288     Node* bstRoot = nullptr;
289     int input;
290 }
```

- Perform operations for binary trees, BSTs, and heaps interactively.
- Users input data for each structure and view the results.

Binary Tree Operations

Building the Binary Tree

```
290 // Binary Tree Operations
291 cout << "Build your Binary Tree:\n";
292 while (cout << "Enter node data (-1 to stop): ", cin >> input, input != -1) {
293     insertBinaryTree(binaryTreeRoot, input);
294 }
295 }
```

- This loop prompts the user to enter node data for the Binary Tree until the user enters -1.
- insertBinaryTree(binaryTreeRoot, input) is a function (not defined in the provided code) that inserts the input value into the Binary Tree.

Traversal of the Binary Tree

```
296
297 cout << "In-order (Binary Tree): ";
298 inorderBinaryTree(binaryTreeRoot);
299 cout << endl;
300 cout << "Preorder (Binary Tree): ";
301 preorderBinaryTree(binaryTreeRoot);
302 cout << "\nPostorder (Binary Tree): ";
303 postorderBinaryTree(binaryTreeRoot);
304 cout << endl;
```

These are three different tree traversal methods:

- In-order: Left subtree, root, right subtree.
- Preorder: Root, left subtree, right subtree.
- Postorder: Left subtree, right subtree, root.

The functions inorderBinaryTree(), preorderBinaryTree(), and postorderBinaryTree() would perform the respective traversals on the Binary Tree and print the results.

Searching for a Value in the Binary Tree

```
305
306 // Search for a value in the binary tree
307 cout << "Enter value to search in Binary Tree: ";
308 cin >> input;
309 Node* result = searchBinaryTree(binaryTreeRoot, input);
310 if (result) {
311     cout << "Value found in the Binary Tree!\n";
312 } else {
313     cout << "Value not found in the Binary Tree.\n";
314 }
```

- The user is prompted to enter a value to search for in the Binary Tree.
- searchBinaryTree(binaryTreeRoot, input) searches the Binary Tree for the value entered. If the value is found, a message is displayed; otherwise, a different message is shown.

Deleting a Value from the Binary Tree

```
315
316 // Delete a value from the binary tree
317 cout << "Enter value to delete from Binary Tree: ";
318 cin >> input;
319 deleteNodeBinaryTree(binaryTreeRoot, input);
320
321 cout << "Binary Tree after deletion: ";
322 preorderBinaryTree(binaryTreeRoot);
323 cout << endl;
```



- The user is prompted to enter a value to delete from the Binary Tree.
- `deleteNodeBinaryTree(binaryTreeRoot, input)` deletes the node with the specified value from the Binary Tree.
- After deletion, the Binary Tree is displayed using a preorder traversal.

Binary Search Tree (BST) Operations

Building the BST

```
326 // BST Operations
327 cout << "\nBuild your Binary Search Tree:\n";
328 while (cout << "Enter node data (-1 to stop): ", cin >> input, input != -1) {
329     insertBST(bstRoot, input);
330 }
```

- Similar to the Binary Tree, the user is prompted to enter data to build the Binary Search Tree (BST) until -1 is entered.
- `insertBST(bstRoot, input)` inserts the input into the BST.

Traversal of the BST

```
331 cout << "Inorder (BST): ";
332 inorderBST(bstRoot);
333 cout << "\nPreorder (BST): ";
334 preorderBST(bstRoot);
335 cout << "\nPostorder (BST): ";
336 postorderBST(bstRoot);
337 cout << endl;
338
```

- The same traversal methods are used for the BST (`inorderBST()`, `preorderBST()`, `postorderBST()`), displaying the results for the BST.

Searching for a Value in the BST

```
338
339 // Search for a value in the BST
340 cout << "Enter value to search in BST: ";
341 cin >> input;
342 result = searchBST(bstRoot, input);
343 if (result) {
344     cout << "Value found in the BST!\n";
345 } else {
346     cout << "Value not found in the BST.\n";
347 }
```

- The user is prompted to enter a value to search for in the BST.
- `searchBST(bstRoot, input)` performs the search, and if the value is found, a message is displayed.

Deleting a Value from the BST

```
348
349 // Delete a value from the BST
350 cout << "Enter value to delete from BST: ";
351 cin >> input;
352 bstRoot = deleteNodeBST(bstRoot, input);
353 cout << "BST after deletion: ";
354 preorderBST(bstRoot);
355 cout << endl;
356
```

- The user is prompted to enter a value to delete from the BST.
- `deleteNodeBST(bstRoot, input)` deletes the node with the specified value.
- After deletion, the BST is displayed using a preorder traversal.



Heap Operations

```
358 // heapify/Heap Operations
359 heapifyOperations();
360 minHeapOperations();
361 maxHeapOperations();
```

These functions are placeholders for heap-related operations. Typically, these could involve:

- `heapifyOperations()`: Operations related to transforming an array into a heap.
- `minHeapOperations()`: Operations related to maintaining a Min-Heap (e.g., inserting or deleting nodes).
- `maxHeapOperations()`: Operations related to maintaining a Max-Heap (e.g., inserting or deleting nodes).

Return Statement

```
362
363 return 0;
364 }
365
```

- The program ends by returning 0, signaling successful execution.

Sample Output

```
C:\Users\TinTin\OneDrive\De: X + v
Build your Binary Tree:
Enter node data (-1 to stop): 1
Enter node data (-1 to stop): 2
Enter node data (-1 to stop): 3
Enter node data (-1 to stop): 4
Enter node data (-1 to stop): 5
Enter node data (-1 to stop): -1
In-order (Binary Tree): 4 2 5 1 3
Preorder (Binary Tree): 1 2 4 5 3
Postorder (Binary Tree): 4 5 2 3 1
Enter value to search in Binary Tree: 2
Value found in the Binary Tree!
Enter value to delete from Binary Tree: 3
Binary Tree after deletion: 1 2 4 5

Build your Binary Search Tree:
Enter node data (-1 to stop): 1
Enter node data (-1 to stop): 2
Enter node data (-1 to stop): 3
Enter node data (-1 to stop): 4
Enter node data (-1 to stop): 5
Enter node data (-1 to stop): -1
Inorder (BST): 1 2 3 4 5
Preorder (BST): 1 2 3 4 5
Postorder (BST): 5 4 3 2 1
Enter value to search in BST: 4
Value found in the BST!
Enter value to delete from BST: 2
BST after deletion: 1 3 4 5
Enter values to heapify (enter -1 to stop): 1
2
3
4
5
-1
Heapified array: 5 4 3 1 2
Enter values for Min-Heap (enter -1 to stop): 1
2
3
4
5
-1
Min-Heap elements: 1 2 3 4 5
Enter values for Max-Heap (enter -1 to stop): 1
2
3
4
5
-1
Max-Heap elements: 5 4 3 2 1

Process returned 0 (0x0)   execution time : 50.182 s
Press any key to continue.
```