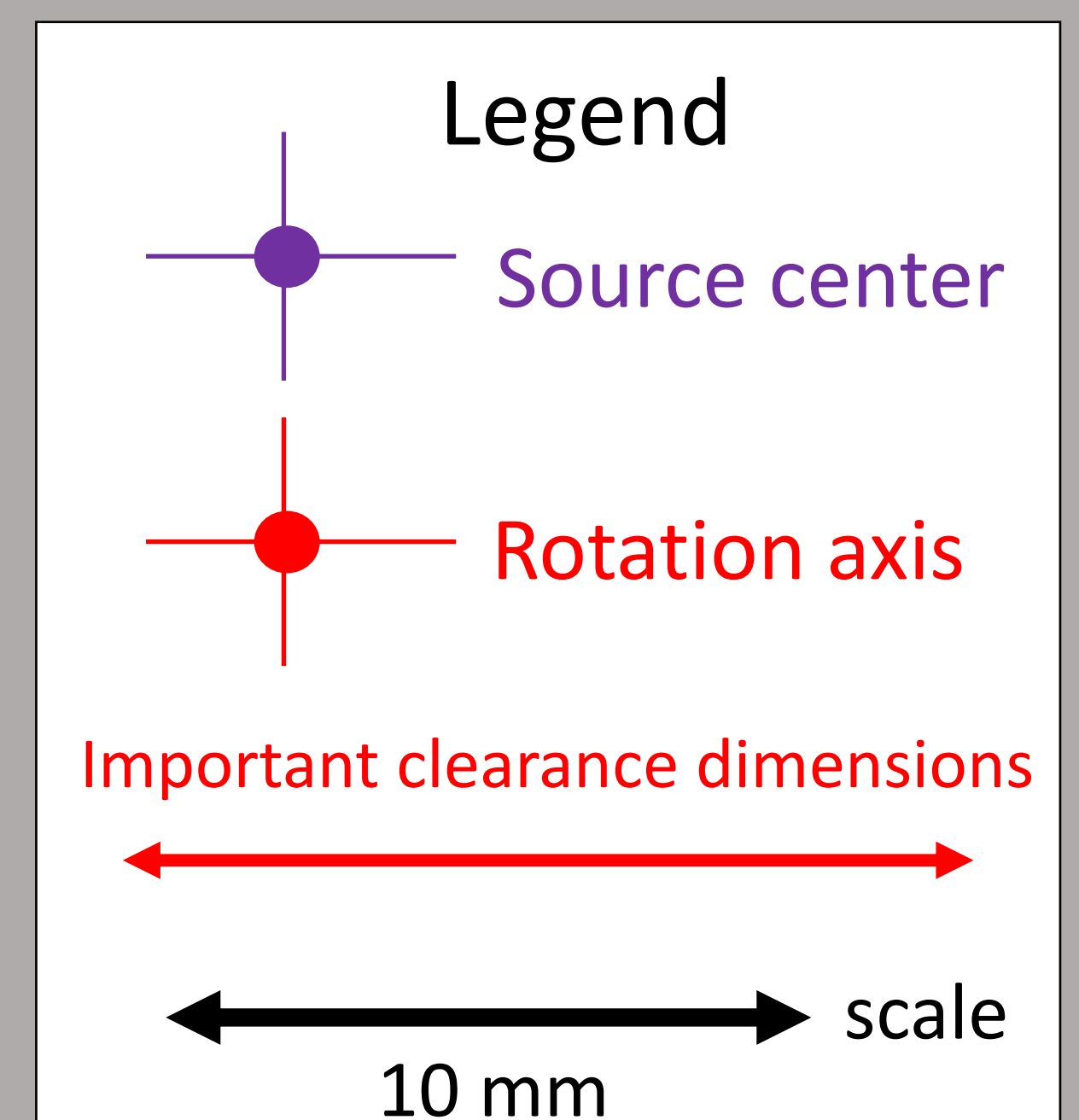
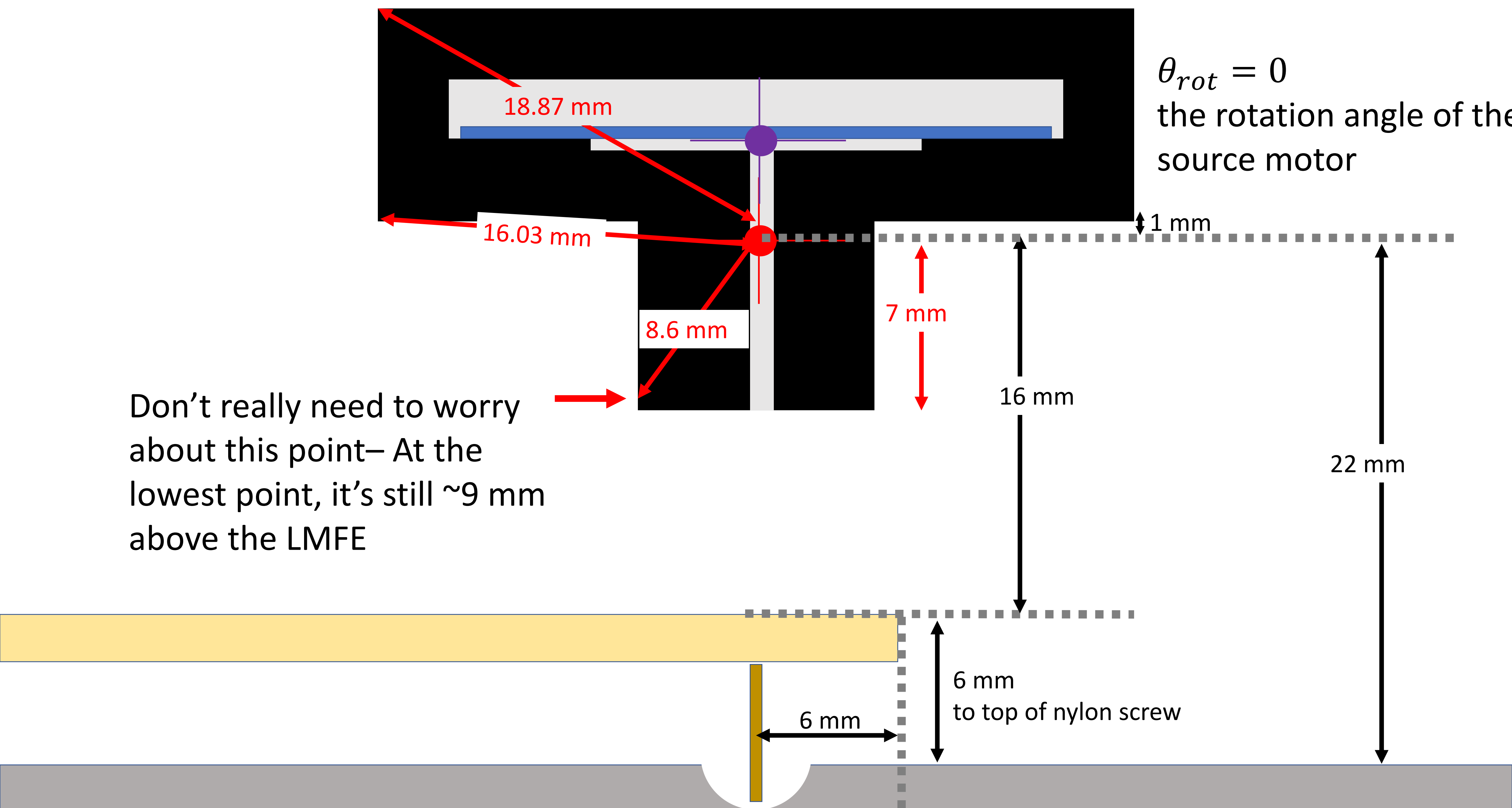


# Collimator clearances and rotation: OPPI



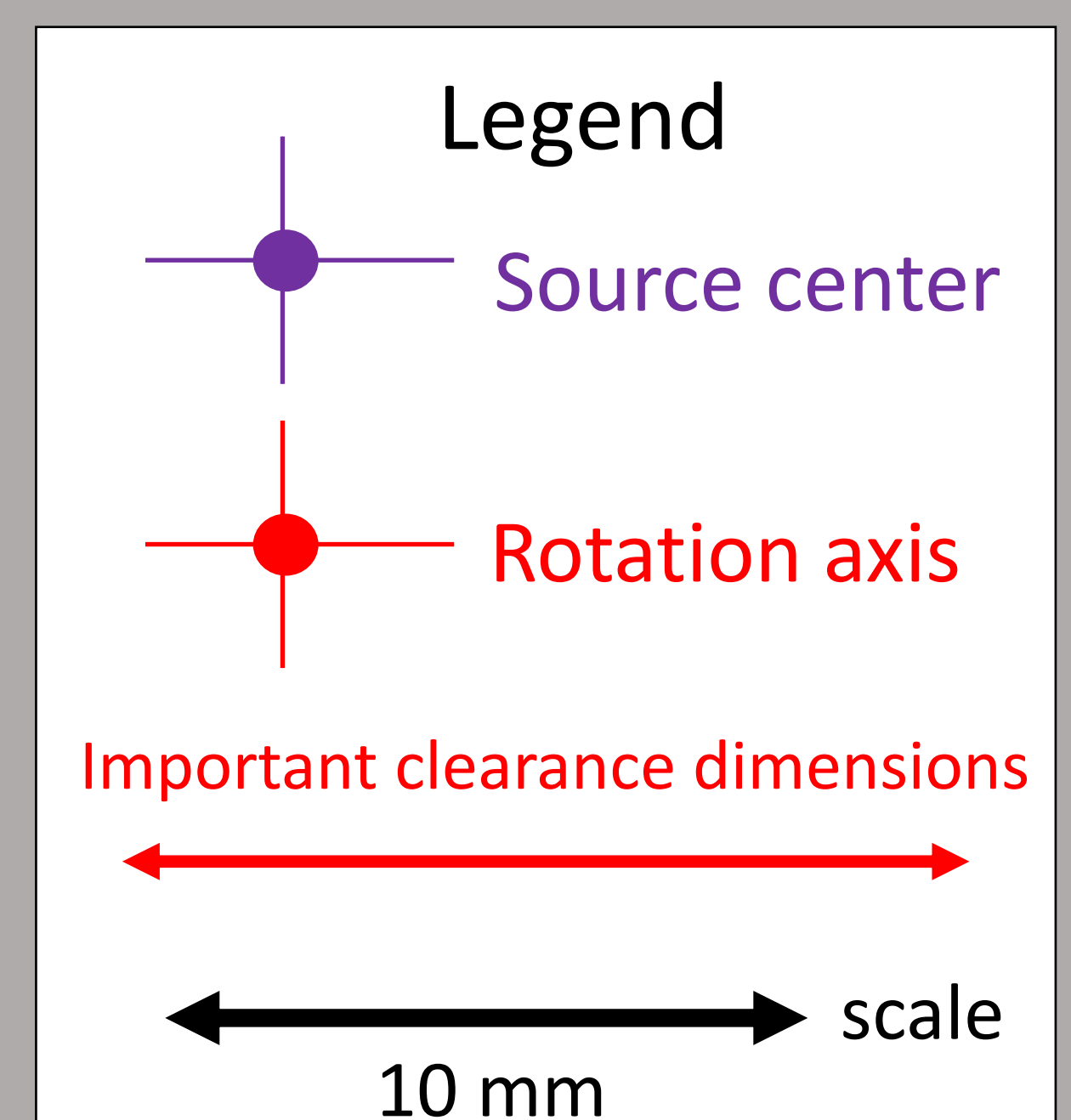
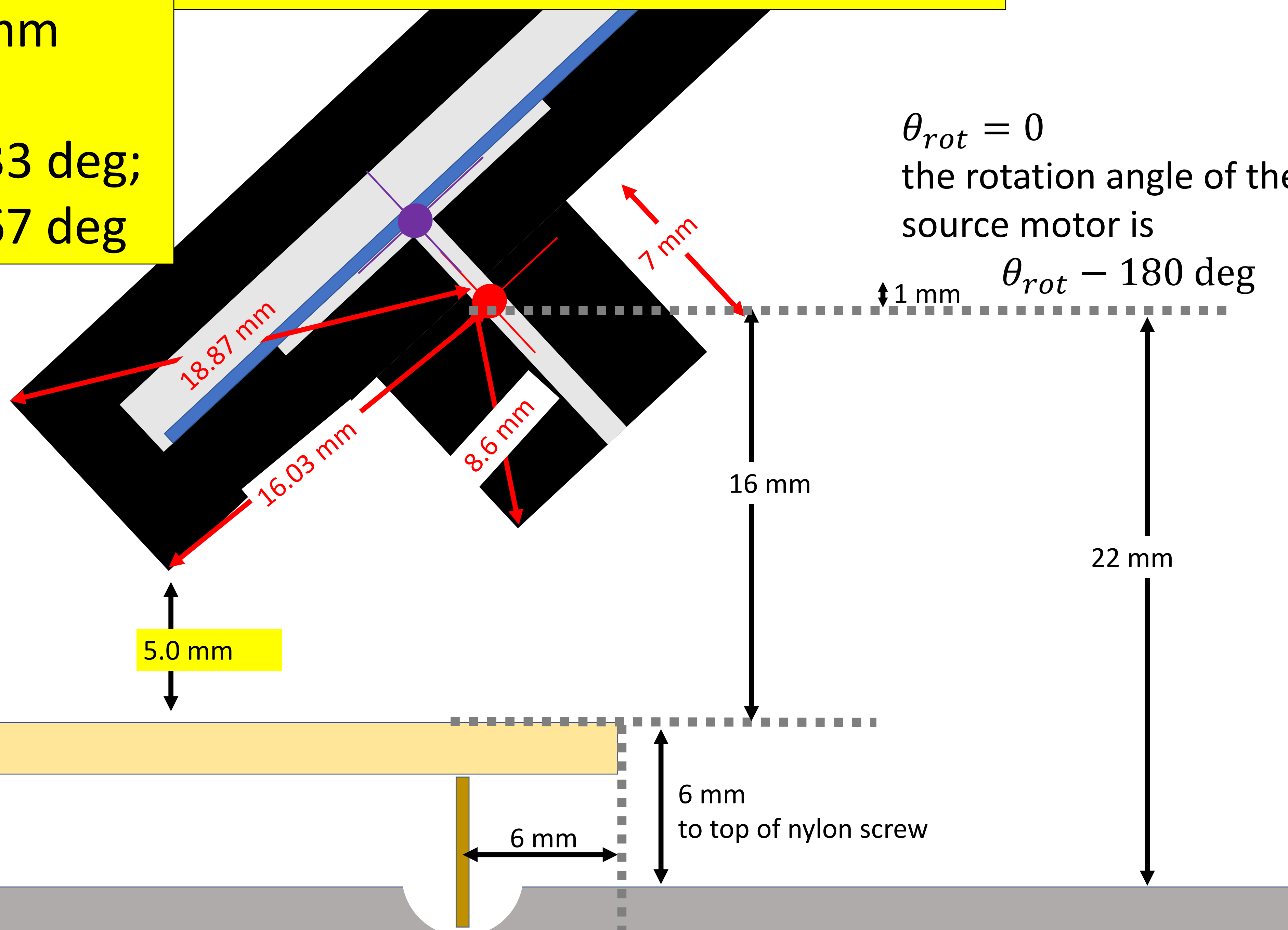
Scale: 1 mm real life = 1 cm in drawing

# Collimator clearances and rotation: OPPI

To maintain 5 mm  
clearance:

$$\theta_{rot\_max} = 43.33 \text{ deg};$$
$$\theta_{det\_min} = 46.67 \text{ deg}$$

Calculated using  
maxRotation()  
function within  
~/CAGE/sims/source  
\_placement.py



Scale: 1 mm real life = 1 cm in drawing

# Angle definitions

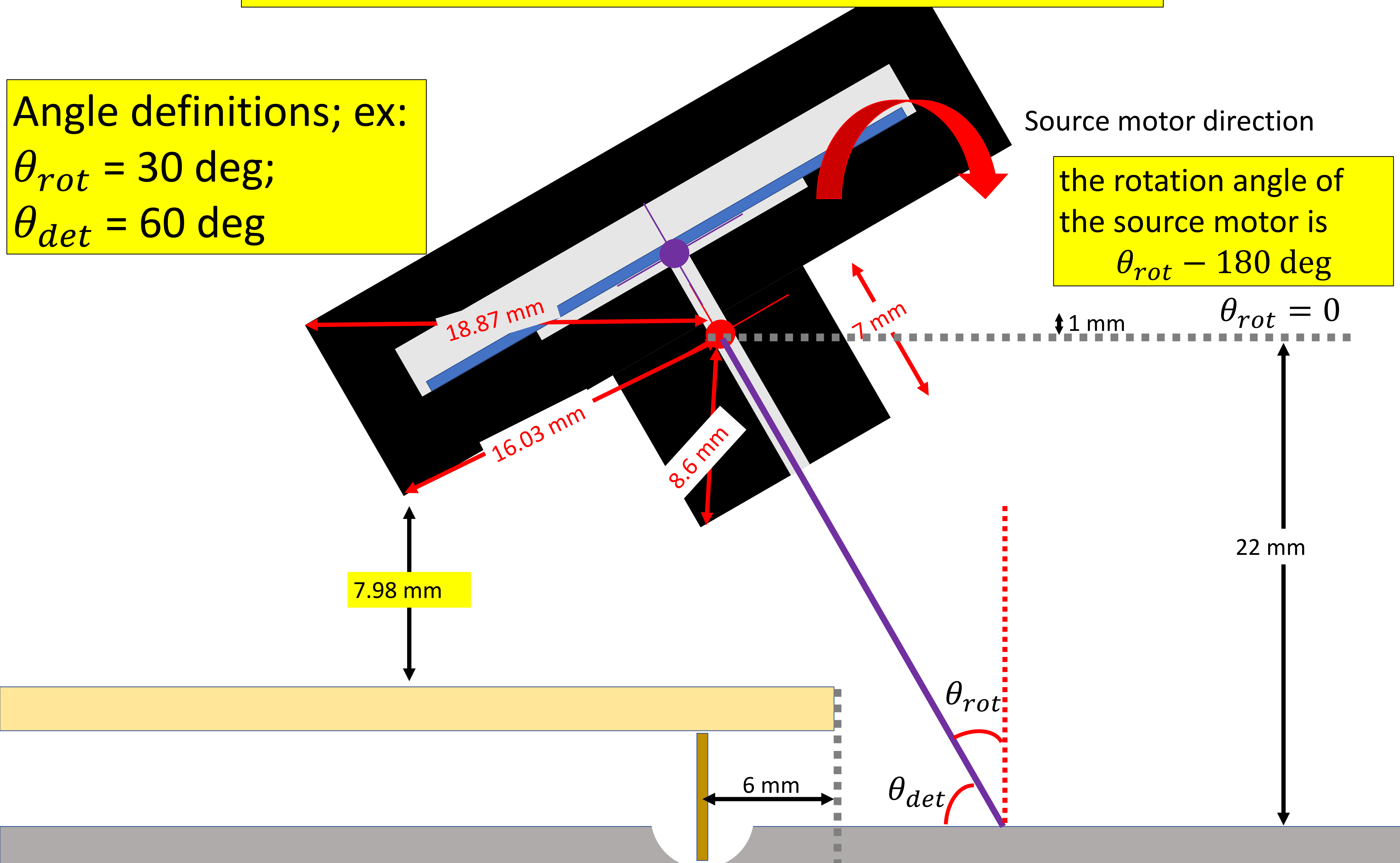
Angle definitions; ex:

$$\theta_{rot} = 30 \text{ deg;}$$

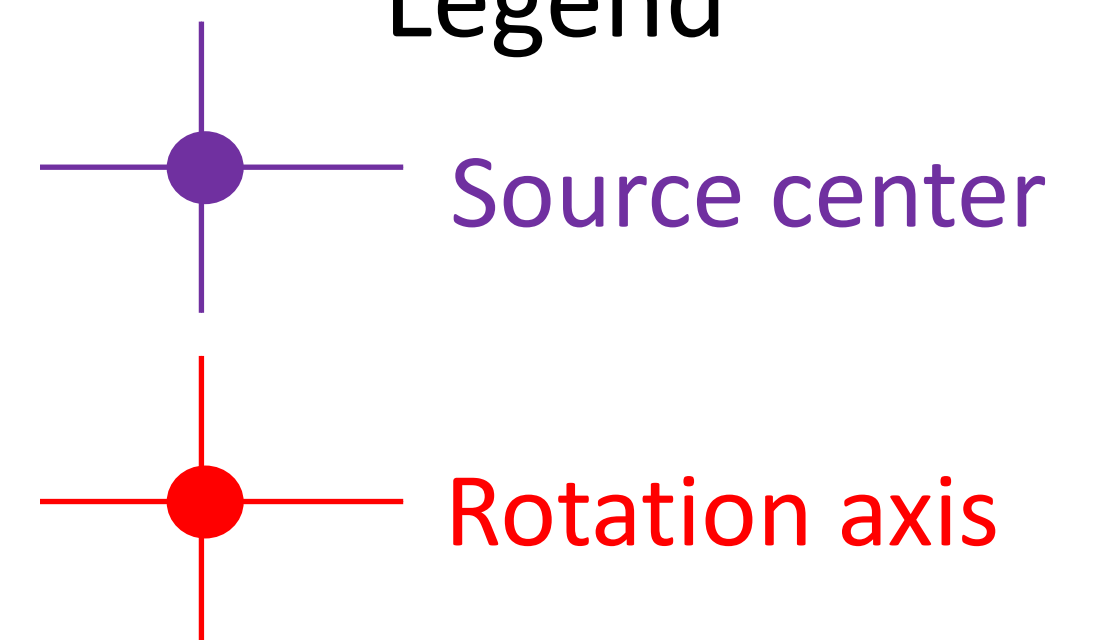
$$\theta_{det} = 60 \text{ deg}$$

Source motor direction

the rotation angle of  
the source motor is  
 $\theta_{rot} - 180 \text{ deg}$



## Legend



Important clearance dimensions



scale

10 mm

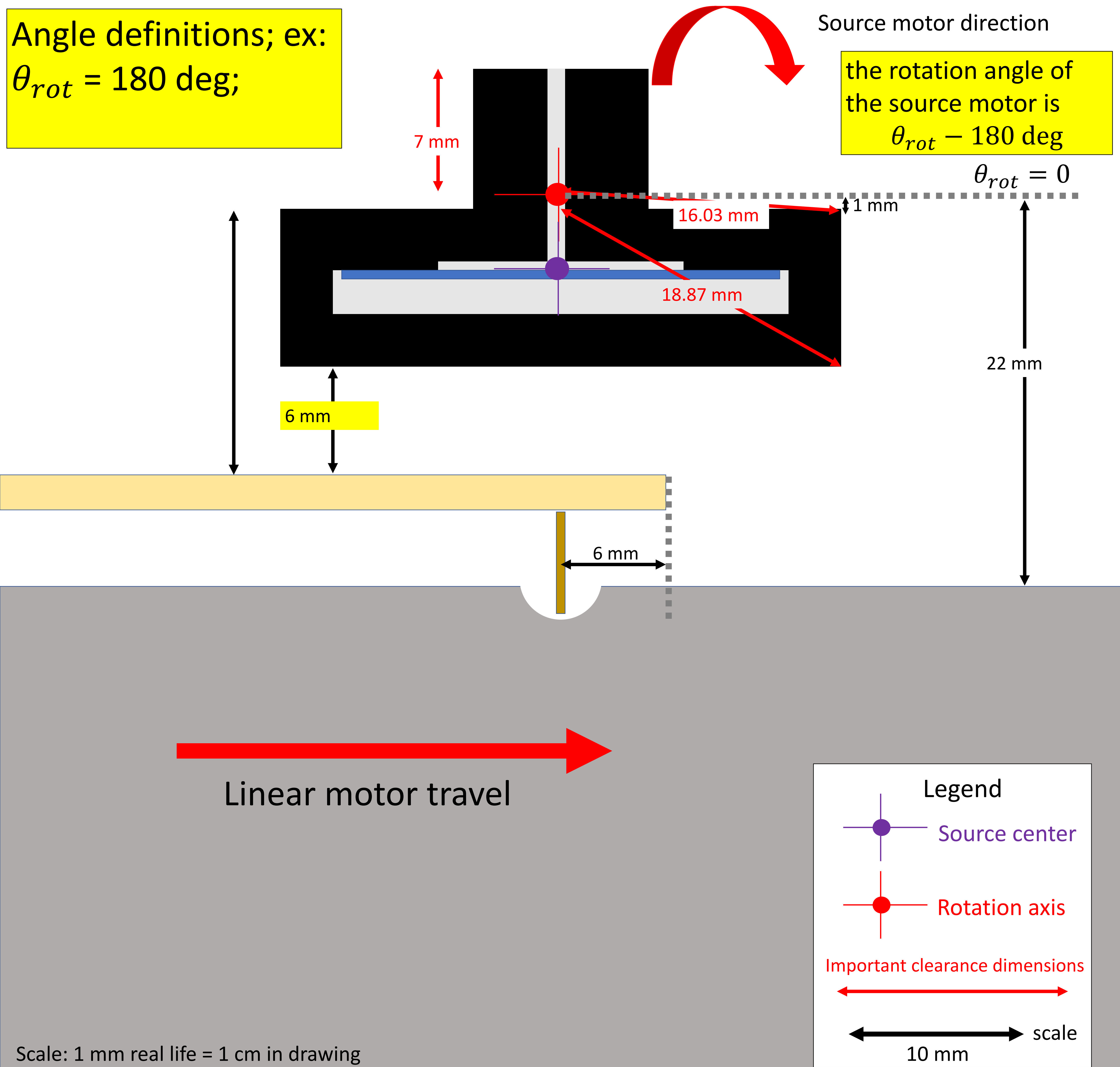
Scale: 1 mm real life = 1 cm in drawing

# Angle definitions: Parked on limit switch

-- zero source

Angle definitions; ex:  
 $\theta_{rot} = 180 \text{ deg}$

Source motor direction  
the rotation angle of  
the source motor is  
 $\theta_{rot} - 180 \text{ deg}$



# Angle definitions: --move source -90

$\theta_{rot} = 90 \text{ deg};$   
 $\theta_{det} = 0 \text{ deg}$

Source motor direction

the rotation angle of  
the source motor is  
 $\theta_{rot} - 180 \text{ deg}$

$\theta_{rot} = 0$

1 mm

22 mm

18.87 mm

16.03 mm

6 mm

Linear motor travel

Legend

Source center  
Rotation axis

Important clearance dimensions



scale

10 mm

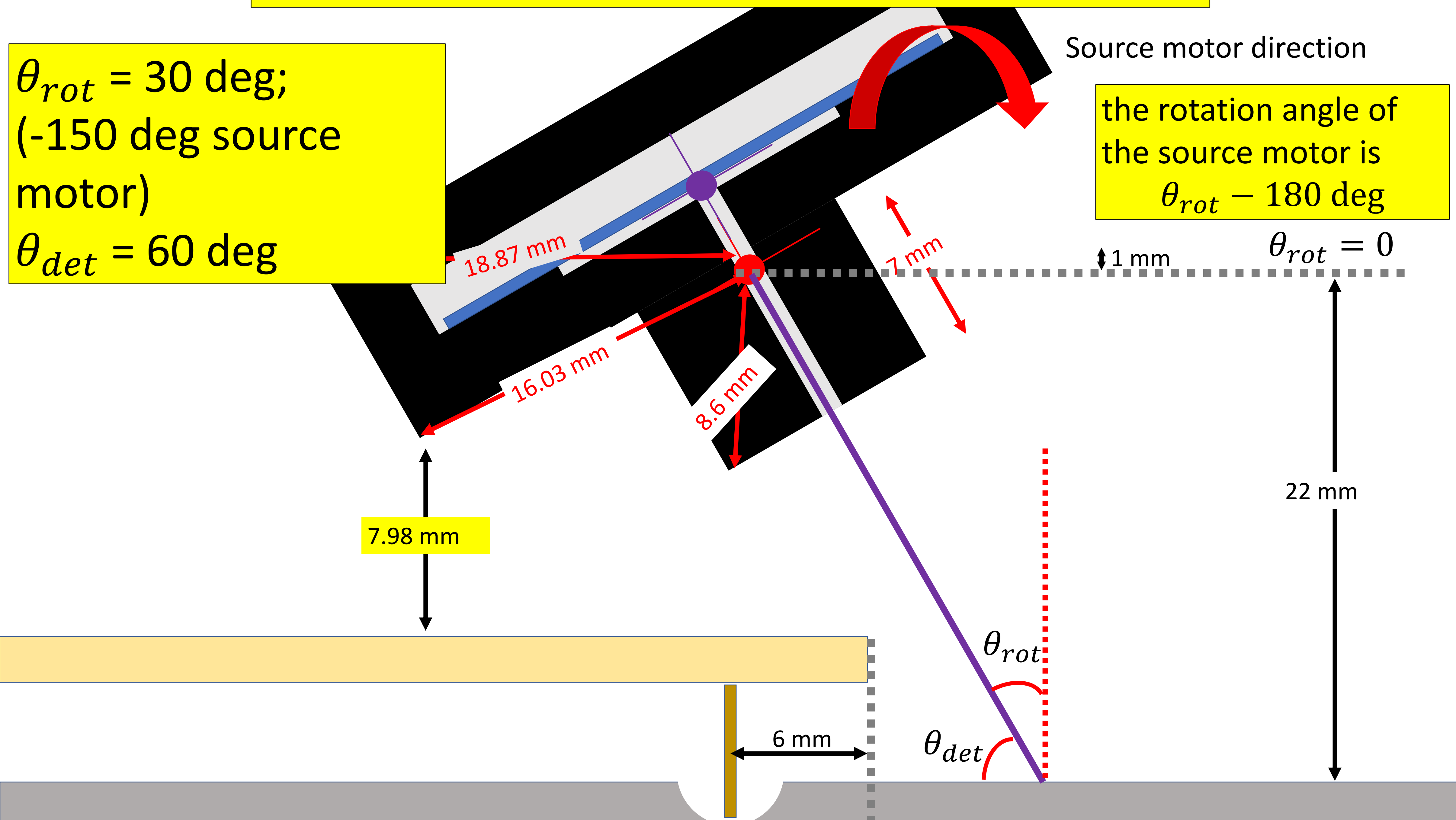
Scale: 1 mm real life = 1 cm in drawing

# Angle definitions: --move source -150

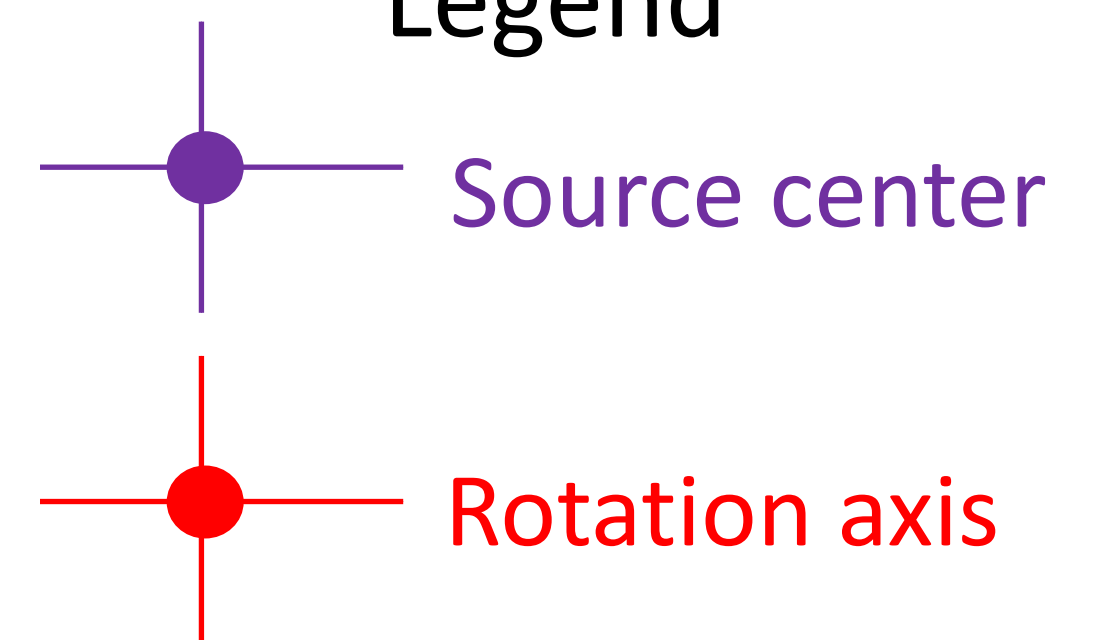
$\theta_{rot} = 30 \text{ deg};$   
(-150 deg source  
motor)  
 $\theta_{det} = 60 \text{ deg}$

Source motor direction

the rotation angle of  
the source motor is  
 $\theta_{rot} - 180 \text{ deg}$



## Legend



Important clearance dimensions



scale

10 mm

Scale: 1 mm real life = 1 cm in drawing



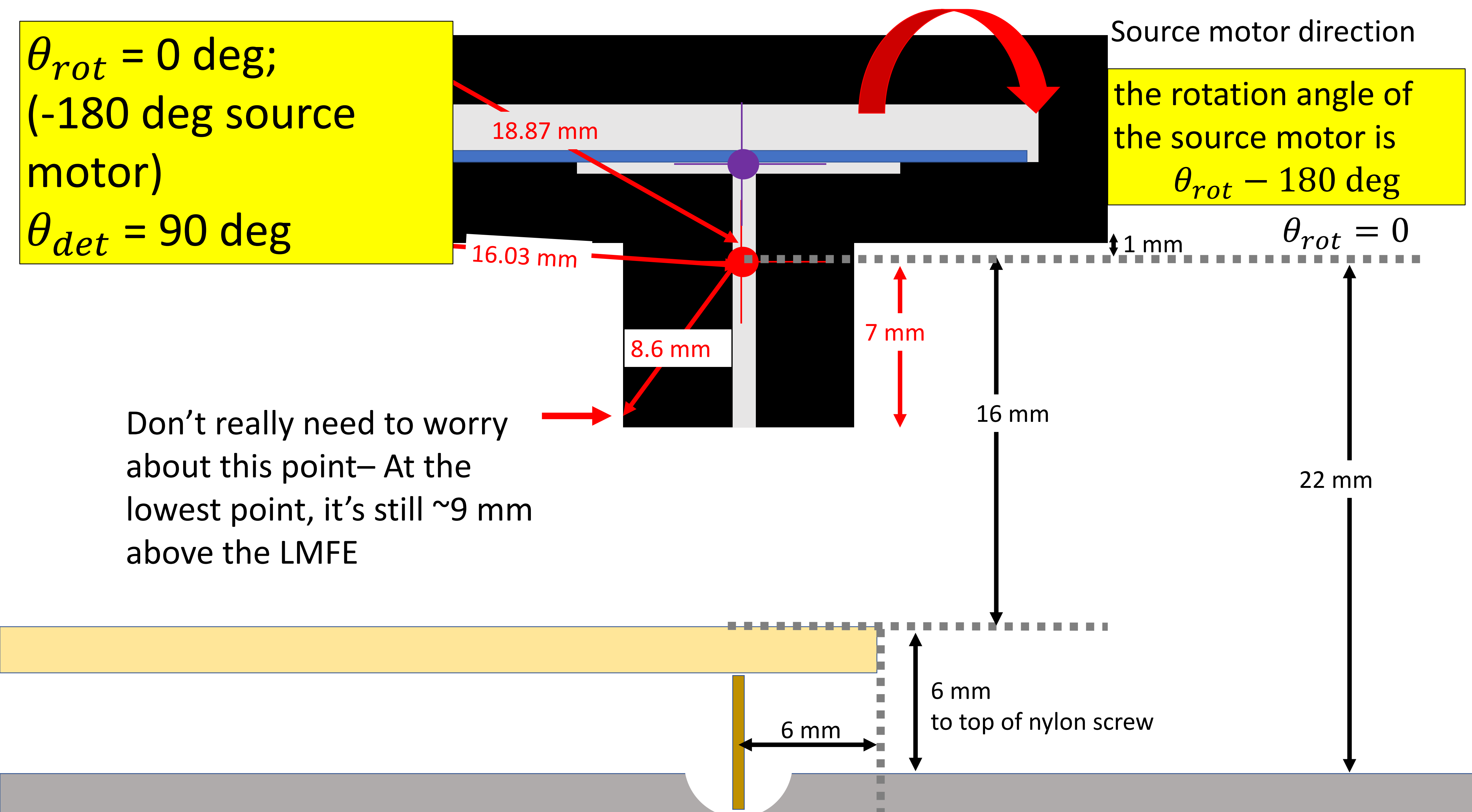
# Angle definitions: -180 (centered) --center source

$\theta_{rot} = 0$  deg;  
(-180 deg source  
motor)  
 $\theta_{det} = 90$  deg

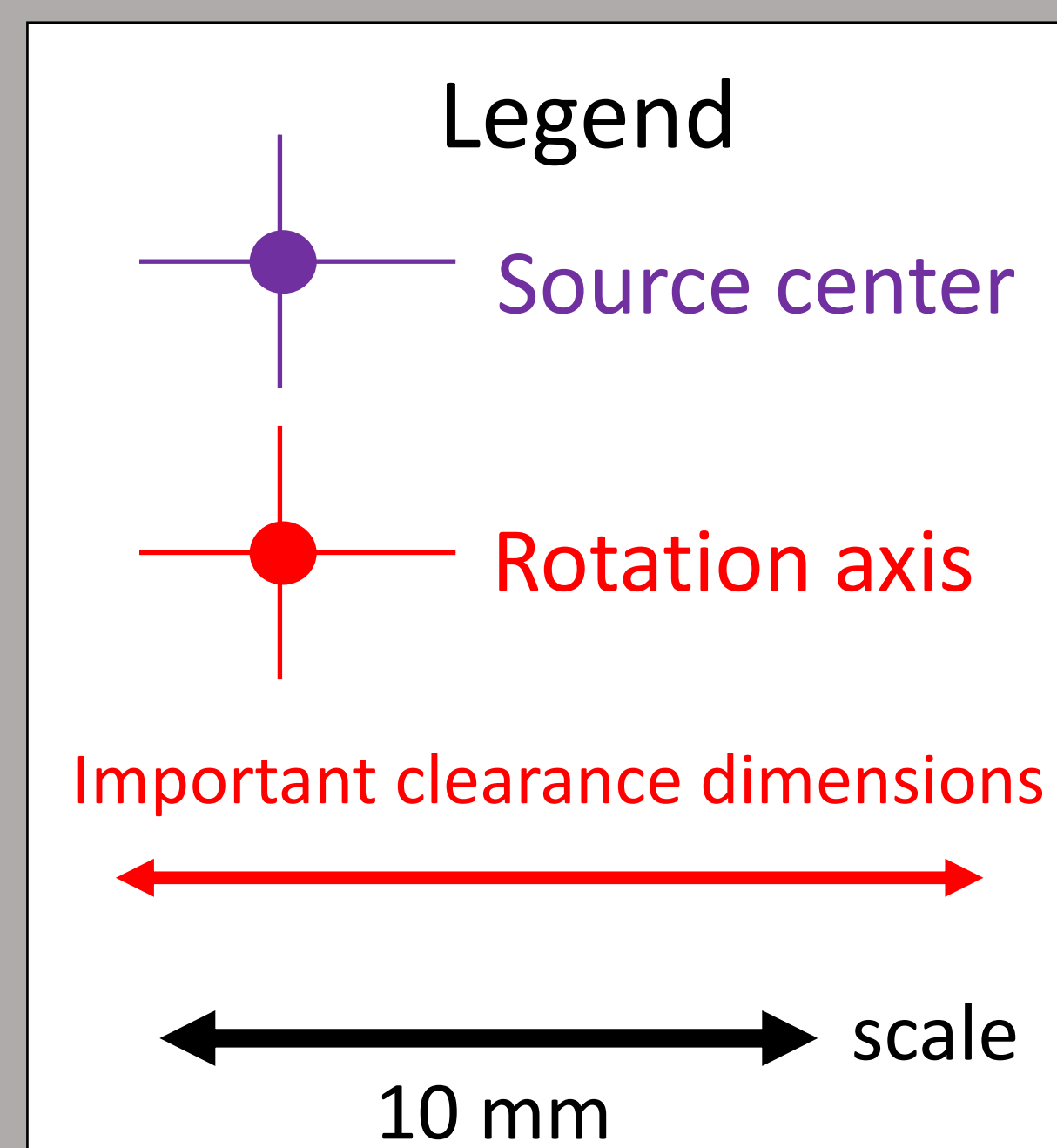
Source motor direction

the rotation angle of  
the source motor is  
 $\theta_{rot} - 180$  deg

Don't really need to worry  
about this point– At the  
lowest point, it's still ~9 mm  
above the LMFE



Linear motor travel



Scale: 1 mm real life = 1 cm in drawing

# Angle definitions: -205 (max) --move source -205

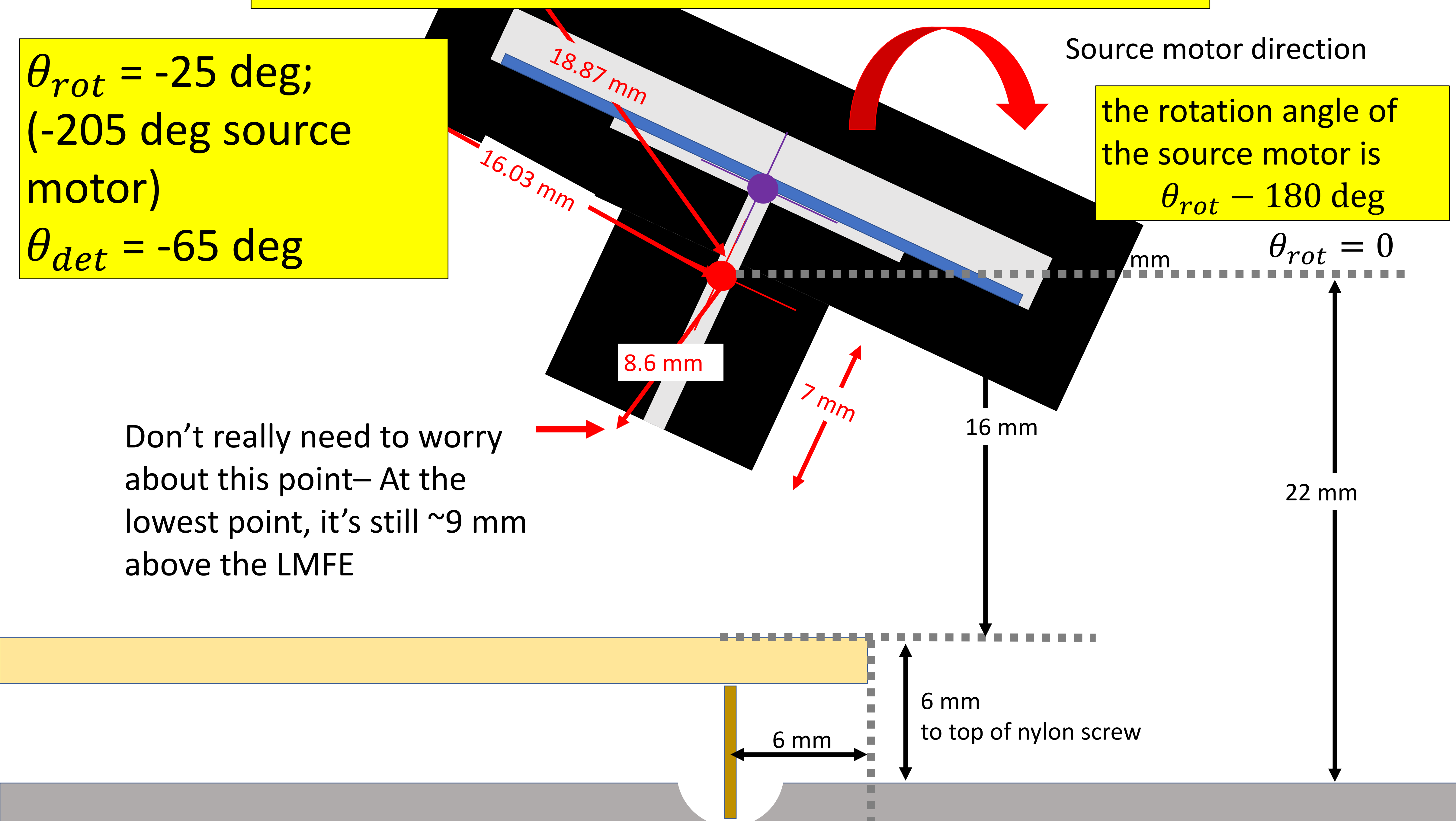
$\theta_{rot} = -25 \text{ deg};$   
(-205 deg source motor)  
 $\theta_{det} = -65 \text{ deg}$

Source motor direction

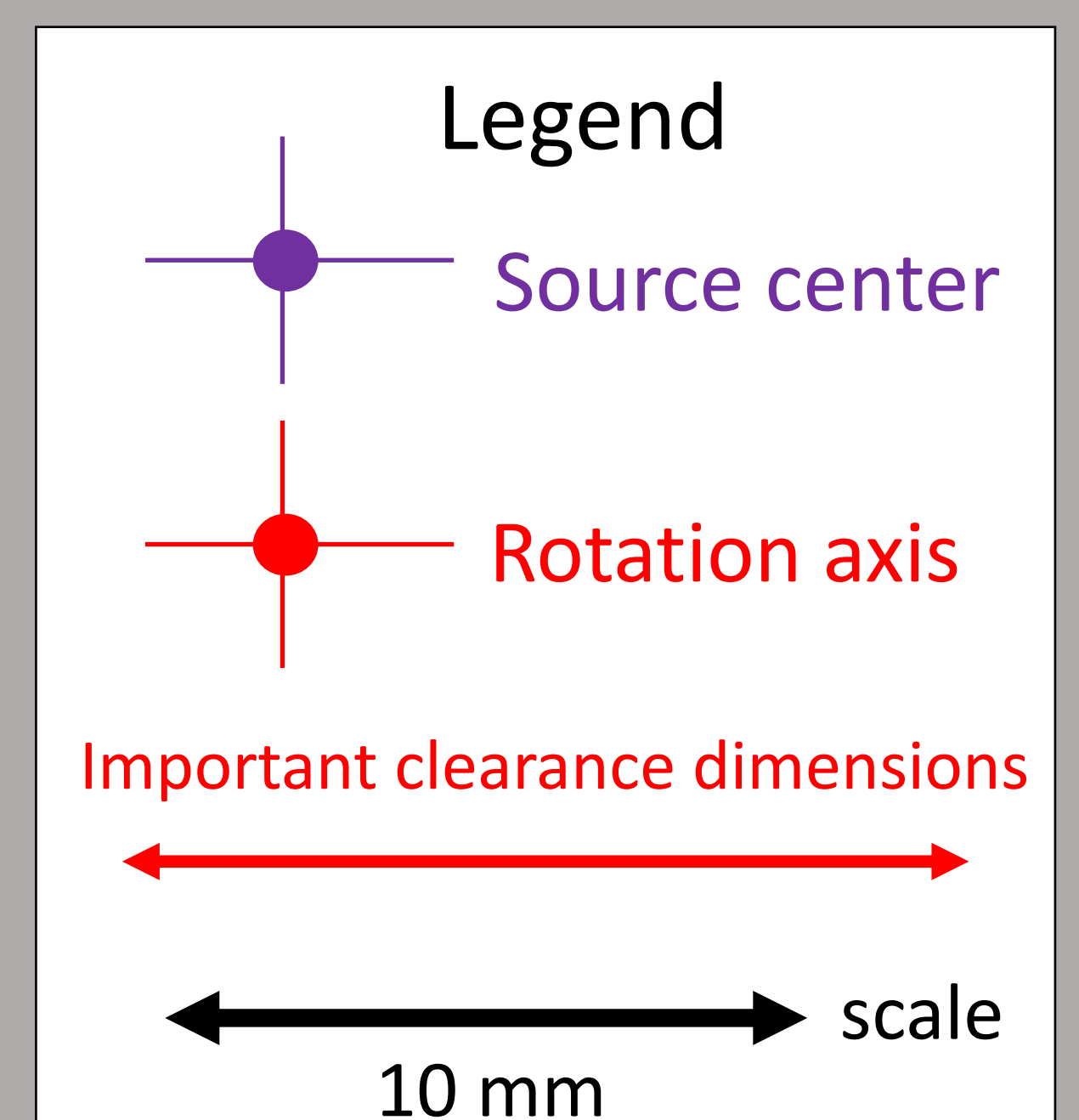
the rotation angle of the source motor is  
 $\theta_{rot} - 180 \text{ deg}$

$\theta_{rot} = 0$

Don't really need to worry about this point— At the lowest point, it's still ~9 mm above the LMFE



Linear motor travel



Scale: 1 mm real life = 1 cm in drawing