$$J^{2} = h[s(t)] + \int_{0}^{t} g[s(\omega, u(t)]dt = \frac{1}{t} \int_{0}^{t} f(s)^{2} dt \qquad h[s(t)] = h[v(t), o(t)] = 0$$

$$\begin{cases}
S = (\rho, v, o) & S = \frac{1}{2}(S, u) = (v, o, j) & u = j \\
S(0) = (\theta_{0}, v_{0}, o_{0}) \\
S(1) = (\theta_{1}, 1, 1) & S_{1}(1) = \rho_{1}
\end{cases}$$

$$H(S, u, \lambda) = g(S, u) + \lambda^{T} + (S, u) = \frac{1}{t} \int_{0}^{t} + \lambda_{1} v + \lambda_{2} h + \lambda_{3} j$$

$$\lambda = -V_{3} + (S^{*}, u^{*}, \lambda) = (0, -\lambda_{1}, -\lambda_{2})$$

$$\lambda(t) = \begin{bmatrix} \lambda_{1}(t) \\ \lambda_{3}(t) \end{bmatrix} = \frac{1}{t} \begin{bmatrix} -\nu \lambda_{1} \\ \nu \lambda_{1} + \nu \end{pmatrix} \begin{bmatrix} -\nu \lambda_{2} \\ \nu \lambda_{2} + \nu \end{bmatrix}$$

$$\frac{\partial H(S^{*}, j, \lambda)}{\partial j} = \frac{1}{t} + \lambda_{3} = 0$$

$$\Rightarrow J^{*} = -\frac{1}{t} \lambda_{3} = \frac{1}{t} \alpha t^{2} + \rho_{2} t^{2} + \frac{1}{t} t^{2} + \frac{\rho_{2}}{t^{2}} t^{2} + vot + \rho_{3}$$

$$\frac{\partial^{3}}{\partial t} = \frac{1}{t} \lambda_{3} + \frac{1}{t} \lambda_{3} + \frac{1}{t} \lambda_{4} + \frac{1}{t} \lambda_{5} + \frac{\rho_{2}}{t^{2}} t^{2} + vot + vo$$

$$\lambda^{3}(t) = \frac{1}{t} \frac{\partial h(S^{*}(t))}{\partial v} = 0 \Rightarrow \rho = -\alpha T$$

$$\lambda_{3}(t) = \frac{\partial h(S^{*}(t))}{\partial v} = 0 \Rightarrow \gamma = \frac{1}{t} dt^{2}$$

$$\rho^{*}(t) = \rho_{1}$$

$$J = -\int_{0}^{T} j(t)^{2} dt = -\int_{0}^{T} -da^{2}t^{4} + \beta^{2}t^{2} + \gamma^{2} + \alpha\beta t^{3} + a\gamma t^{2} + L\beta \gamma t dt$$

$$= 1^{2} + PTT + \frac{1}{3}P^{2}T + \frac{1}{3}aTT^{2} + \frac{1}{4}aPT^{3} + \frac{1}{12}a^{2}T^{4}$$

$$= 100 \frac{dP}{T0} - 100 \frac{dP}{T0} + \frac{900}{3} \frac{dP}{T0} + \frac{100}{3} \frac{dP}{T0} - 100 \frac{dP}{T0} + 100 \frac{dP}{T0}$$