

ECE 351 DSP: Assignment 1

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Total: 30 points

Submission deadline: During class on 18.09.2024

A word on the notation: I shall represent finite duration causal signals as arrays. For example, $x[n] = [1, 2, 3]$ means $x[0] = 1$, $x[1] = 2$, and $x[2] = 3$, and $x[n] = 0$ for all other n .

Coding has to be done in Python. MATLAB codes will be marked zero.

1) Let $z = x + jy$. Are the following regions on the complex plane ROC of some z-transform? Justify.

a) $2 < x^2 + y^2 < 3$.

b) $2x^2 + 3y^2 > 5$.

c) $2x^2 + 2y^2 < 1$.

[1.5+1.5+1.5=4.5 points]

Solution: a) Yes. This is the annular region between the circles centred at the origin with radii $\sqrt{2}$ and $\sqrt{3}$ respectively. b) No. This region represents the exterior of an ellipse. c) Yes. This region is the interior of the circle centred at the origin with radius $\frac{1}{\sqrt{2}}$. ■

2) Consider the LTI system with impulse response

$$h[n] = \begin{cases} \frac{n^n}{3^{1+2n}}, & \text{if } n \geq 0 \\ 0, & \text{otherwise.} \end{cases}$$

a) Which of the three possible shapes does the ROC of $h[n]$ have?

b) Does the ROC include the unit circle?

[2+4=6 points]

Solution: a) We note that $h[n] = 0$ for $n < 0$ and hence the ROC is the outside of a circle centred at origin.

b) To check this, we need to check if the LTI system is stable, i.e., if $\sum_{n=-\infty}^{\infty} |h[n]|$ converges. To do so, we employ the root test, and note that $(|h[n]|)^{\frac{1}{n}} = \frac{1}{9} n 3^{-\frac{1}{n}}$. So, $\lim_{n \rightarrow \infty} (|h[n]|)^{\frac{1}{n}} = \infty > 1$, and hence $\sum_{n=-\infty}^{\infty} |h[n]|$ diverges. So the unit circle is not contained within the ROC. ■

3) Consider the LTI system with the difference equation

$$y[n] = 5y[n-1] - 8y[n-2] + 4y[n-3] + x[n] + x[n-1] + x[n-2] - 4x[n-4].$$

- Find the transfer function $H(z)$.
- Write a Python code to print and plot the poles and zeros of $H(z)$.
- Compute $h[n]$.

Note: You can get the poles of $H(z)$ from the python code in step b). The poles are integers, so do round-off the poles returned by the python code to the nearest integer.

- Does the ROC of $h[n]$ include the unit circle?

[2+3+6+1=12 points]

Solution: a) By taking z -transform, the difference equation becomes $Y(z)(1 - 5z^{-1} + 8z^{-2} - 4z^{-3}) = X(z)(1 + z^{-1} + z^{-2} - 4z^{-4})$. Thus,

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1 + z^{-1} + z^{-2} - 4z^{-4}}{1 - 5z^{-1} + 8z^{-2} - 4z^{-3}}.$$

- From the Python code, there is a second order pole at 2 and a first order pole at one. Hence,

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1 + z^{-1} + z^{-2} - 4z^{-4}}{(1 - 2z^{-1})^2(1 - z^{-1})}.$$

Notice that the denominator polynomial has degree lower than the numerator polynomial. So, by Euclidean division, we have $H(z) = 2 + z^{-1} + U(z)$, where

$$U(z) = \frac{-1 + 10z^{-1} - 10z^{-2}}{(1 - 2z^{-1})^2(1 - z^{-1})}.$$

So,

$$\frac{U(z)}{z} = \frac{-z^2 + 10z - 10}{(z - 2)^2(z - 1)} = \frac{A}{z - 1} + \frac{B}{z - 2} + \frac{C}{(z - 2)^2}.$$

Using the method of partial fractions, we have $A = (z - 1)\frac{U(z)}{z}|_{z=1} = -1$. Also, $C = (z - 2)^2\frac{U(z)}{z}|_{z=2} = 6$. To get B , we use

$$\begin{aligned} B &= \frac{d}{dz}(z - 2)^2 \frac{U(z)}{z} \Big|_{z=2} \\ &= \frac{d}{dz} \frac{-z^2 + 10z - 10}{z - 1} \Big|_{z=2} \\ &= \frac{(z - 1)(-2z + 10) - (-z^2 + 10z - 10)}{(z - 1)^2} \Big|_{z=2} \\ &= 0. \end{aligned}$$

So, we have

$$H(z) = 2 + z^{-1} - \frac{z}{z - 1} + \frac{6z}{(z - 2)^2}.$$

Hence, using the formulas given in class, $h[n] = v[n] - u[n] + 3n2^n u[n-1]$, where $v[n] = [2, 1]$.

d) Note that $H(z)$ has poles at both $z = 1$, and $z = 2$. Then, the ROC cannot contain these points. So, it cannot contain the unit circle. ■

- 4) Consider the signal $x[n] = [1, 2, 3, 4, 5]$. Define $Y(k) = X(\frac{\pi}{2}k)$ for $k = 0, 1, 2, 3$, where $X(\omega)$ is the DTFT of $x[n]$. Now consider the sequence $y[n]$, for $n = 0, 1, 2, 3$, obtained by taking the 4-point IDFT of $Y(k)$, $k = 0, 1, 2, 3$. What is $y[n]$? [3 points]

Solution: Note that the 4-point IDFT will produce $y[n] = x_p[n] = \sum_{l=-\infty}^{\infty} x[n - 4l]$. Note that when $n = 0, 1, 2, 3$, the only signals in the above sum that have non-zero values are $x[n]$ and $x[n+4]$. Adding these two, we get $y[n] = [6, 2, 3, 4]$. ■

- 5) Consider the signal $x[n] = \cos(2\sqrt{3}\pi n)$.

- a) Is $x[n]$ periodic?
 b) Consider the LTI system with impulse response $h[n] = u[n]$. Find the output $y[n]$ obtained by passing $x[n]$ through this system.

[1+3.5=4.5 points]

Solution: a) No, because $\sqrt{3}$ is irrational.

b) Here, $H(z) = \frac{1}{1-z^{-1}}$, and so

$$\begin{aligned} H(\omega) &= \frac{1}{1 - e^{-j\omega}} \\ &= \frac{1}{1 - \cos \omega + j \sin \omega}. \end{aligned}$$

So,

$$\begin{aligned} |H(\omega)| &= \frac{1}{\sqrt{(1 - \cos \omega)^2 + \sin^2 \omega}} \\ &= \frac{1}{\sqrt{2 - 2 \cos \omega}} \\ &= \frac{1}{\sqrt{4 \sin^2 \frac{\omega}{2}}} \\ &= \frac{1}{2 \sin \frac{\omega}{2}}, \end{aligned}$$

and

$$\begin{aligned}
 \angle H(\omega) &= \pi - \tan^{-1} \left(\frac{\sin \omega}{1 - \cos \omega} \right) \\
 &= \pi - \tan^{-1} \left(\frac{2 \sin \frac{\omega}{2} \cos \frac{\omega}{2}}{2 \sin^2 \frac{\omega}{2}} \right) \\
 &= \pi - \tan^{-1} \cot \frac{\omega}{2} \\
 &= \pi - \frac{\pi}{2} + \frac{\omega}{2} \\
 &= \frac{\pi}{2} + \frac{\omega}{2}.
 \end{aligned}$$

So, $y[n] = |H(2\sqrt{3}\pi)| \cos(2\sqrt{3}\pi n + \angle H(2\sqrt{3}\pi)) = \frac{1}{2 \sin(\sqrt{3}\pi)} \cos(2\sqrt{3}\pi n + \frac{\pi}{2} + \sqrt{3}\pi)$. ■