- a) Linear or Non-Linear
- b) Static or Dynamic
- c) Stable or Unstable
- d) Causal or Mon-Causal
- e) Time invariant or time variant

Sol a) for dinear

for
$$9/p \times 1_1(t)$$
 $y_1(t) = at^2 x_1(t) + bt x_1(t-4)$

for an $4/p \times x_2(t)$
 $y_2(t) = at^2 x_2(t) + bt x_2(t-4)$

i weighted sum of off's.

reighted sum
$$9^{9/8}$$
.

 $py_1(t) + 9^{1}y_2(t) = pat^2 n_1(t) + pbt x_1(t-4)$
 $+ qat^2 n_2(t) + qbt n_2(t-4)$
 $+ qat^2 n_2(t) + qbt n_2(t-4)$

$$= at^{2} \left[p n_{1}(t) + q n_{2}(t) \right] + b + \left[p n_{1}(t-4) + q n_{2}(t-4) \right]$$

The Op due to neighted sum Jup's is: $y_3(t) = T[p_{n_1}(t) + q_{n_2}(t)] = at^2[p_{n_1}(t) + q_{n_2}(t)]$

$$y_3(t) = T[p_{n_1}(t) + q_{n_2}(t)] = ac[p_{n_1}(t-4) + q_{n_2}(t-4)] + bt[p_{n_1}(t-4) + q_{n_2}(t-4)]$$

- B) As the of p defends on part inputs. So it requires a memory. Hence, the system is Dynamic
- Stable or Unstable

 y(t) = at2 x(t) + bt x(t-4)

 if we take Bounded Typ lets' say x(t) = 1 & x(t-4) = 1

 then

 y(t) = at2 + bt (ie) y(t) is unbounded

 : System's unstable.
- As the Ofp depends only on the present & past inputs, and do not depend upon future Ip's.

 The System is Causal.
- Time-invariant or time variant $y(t) = T[\alpha(t)] = at^2 \alpha(t) + bt \alpha(t-4)$ The off due to the duayed by Tric is $y(t,T) = T[\alpha(t-T)] = y(t)|_{\alpha(t)} = \alpha(t-T)$ $= at^2 \alpha(t-T) + bt \alpha(t-4-T)$ The off delayed by Tracond is: $= a(t-T)^2 \alpha(t-T) + y(t-T) + y(t-T) = y(t)|_{t=t-T} = b(t-T) \alpha(t-T-4)$ = a(t-T) + y(t-T) + y(t-T) = a(t-T) + y(t-T) + y(t-T)