MA 511 Solutions, Homework 1

1.3.17 We can subtract one copy of row one from row two to get

$$\begin{bmatrix} 1 & 4 & -2 & 1 \\ 0 & 3 & -4 & 5 \\ 0 & 3 & q & t \end{bmatrix}$$

and subtract one copy of the resulting row two from row three to get

$$\begin{bmatrix} 1 & 4 & -2 & 1 \\ 0 & 3 & -4 & 5 \\ 0 & 0 & q+4 & t-5 \end{bmatrix}.$$

This is a singular matrix when q = -4. If q = -4, then the bottom row represents the equation 0 = t - 5, and so there are infinitely many solutions when t = 5. When q = -4, t = 5, and z = 1, we get y = 3 from the second row and x = -9 from the first row, so the solution is (-9, 3, 1).

1.3.31 The augmented matrix for this system is

$$\begin{bmatrix} a & 2 & 3 & b_1 \\ a & a & 4 & b_2 \\ a & a & a & b_3 \end{bmatrix}.$$

Subtracting row two from row three, and then subsequently subtracting row one from row two, we get

$$\begin{bmatrix} a & 2 & 3 & b_1 \\ 0 & a-2 & 1 & b_2-b_1 \\ 0 & 0 & a-4 & b_3-b_2 \end{bmatrix}.$$

This matrix fails to have three pivots when a = 0, 2, or 4.

1.4.24 We have

$$E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}, \quad E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix},$$

which corresponds to the operations (1) subtract 4 copies of row 1 from row 2, (2) add 2 copies of row 1 to row 3, and (3) subtract two copies of (the new) row 2 from row 3. We have

$$M = E_{32}E_{31}E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 10 & -2 & 0 \end{bmatrix}.$$

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1.5.29 We have the decomposition

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a & a & a & a \\ 0 & b-a & b-a & b-a \\ 0 & 0 & c-b & c-b \\ 0 & 0 & 0 & d-c \end{bmatrix}.$$

In order to get four pivots, we need $a \neq 0$, $a \neq b$, $b \neq c$, and $c \neq d$.

1.5.38 We can write, to represent subtracting 3 of row one from row two and subsequently subtracting 1/(c-6) times the resulting row two from row three, that

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & \frac{1}{c-6} & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} A = \begin{bmatrix} 1 & 2 & 0 \\ 0 & c-6 & 1 \\ 0 & 0 & \frac{c-7}{c-6} \end{bmatrix},$$

whenever $c \neq 6$. This gives 3 pivots whenever $c \neq 6, 7$.

- 1.6.40 (a) True. A row of zeroes means there cannot be four pivots.
 - (b) False. Consider the 4x4 matrix of all 1's. Subtracting row three from row four results in a row of zeroes, which as in (a) means the matrix is not invertible.
 - (c) True. If A^{-1} exists, then $AA^{-1} = A^{-1}A = I$, so $A = (A^{-1})^{-1}$.
 - (d) True. We have that $A^{-1} = ((A^T)^T)^{-1} = ((A^T)^{-1})^T$, which exists since $(A^T)^{-1}$ exists.
- 1.6.41 If c=0, we have a row of zeroes, so it is not invertible. Otherwise, subtract 8/c times the second row from the third row to get

$$\begin{bmatrix} 2 & c & c \\ c & c & c \\ 0 & -1 & c - 8 \end{bmatrix}.$$

Next subtract c/2 times the first row from the second row to get

$$\begin{bmatrix} 2 & c & c \\ 0 & (2c - c^2)/2 & (2c - c^2)/2 \\ 0 & -1 & c - 8 \end{bmatrix}.$$

If c=2 or 0, then the middle row is all zeroes, so it is not invertible. Otherwise, add $2/(2c-c^2)$ times the second row to the third row to get

$$\begin{bmatrix} 2 & c & c \\ 0 & c/2 & c/2 \\ 0 & 0 & c-7 \end{bmatrix}.$$

If c = 7, this is not invertible. Thus c = 0, 2, 7 are the values of c for which the matrix is not invertible.

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1.6.56 We have

$$(A^2 - B^2)^T = (A^2)^T - (B^2)^T = (A^T)^2 - (B^T)^2 = A^2 - B^2,$$

so (a) is symmetric. Next,

$$[(A+B)(A-B)]^T = (A-B)^T (A+B)^T = (A-B)(A+B),$$

which is not generally equal to (A + B)(A - B), so (b) is not symmetric. Next,

$$(ABA)^T = A^T B^T A^T = ABA,$$

so (c) is symmetric. Finally, by the same method,

$$(ABAB)^T = BABA,$$

which is not generally equal to ABAB, so (d) is not symmetric.