

Q1: Planning in belief space

<https://forms.gle/fbVz3zCXcSBZErwu8>

Q2: Semantic state estimation

<https://forms.gle/oFvkhqtiawqrWvww5>

Q3: POMCP

<https://forms.gle/acZirDVCAcyKG9PTA>

Q4: Options

<https://forms.gle/hauZiQXJ9VPKj88p8>