

Airlock

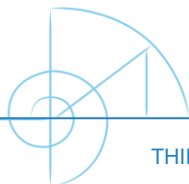
Specifying and implementing a Voter

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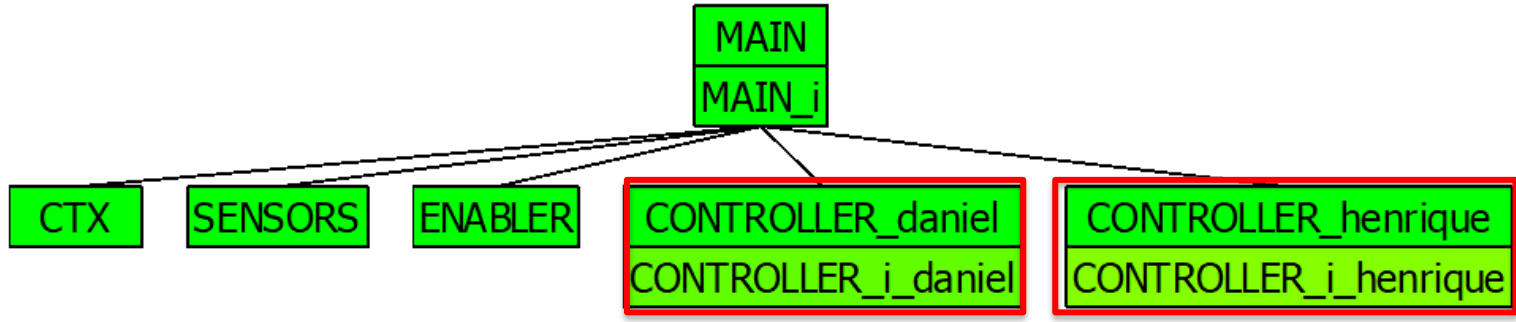
PART V

One Solution



Your turn

- Implement VOTER in MAIN_I [10 pt]
 - ▷ *CONTROLLER duplicated (thank you Daniel and Henrique !)*



```
operate =  
VAR act_d, auth_d, obj_d, act_h, auth_h, obj_h IN  
  update_sensors_states;  
  process_readers_daniel;  
  process_readers_henrique;  
  control_daniel;  
  control_henrique;  
  act_d, auth_d, obj_d <-- get_status_daniel;  
  act_h, auth_h, obj_h <-- get_status_henrique;  
  
  IF act_d = act_h & auth_d = auth_h & obj_d = obj_h THEN  
    action := act_d  
  ELSE  
    action := NONE  
  END  
END
```

Your turn

- **Optional:** What happens to the whole system if the controllers are functionally different? [1 pt]

It gets stuck.

- **Optional:** is it possible to adapt the voting principle to make it a bit more useful? [1 pt]

Apply the voting only on opening door and modify pressure actions. Define recovery procedure. Complete the specification of the operation to get a proof that the functional behaviour is correct

The End

► *Key facts*

- ▷ *How embedded systems are developed*
- ▷ *Hypotheses, safety architecture, specification, implementation*
- ▷ *Formal methods to help adding control*
- ▷ *Real systems are more complex:*
 - *Situation is never 100% known*
 - *Redundancy (sensors, actuators)*
 - *Safety critical “IF THEN ELSE” could take 2k loc*
 - *Human in the loop for maintenance operations*
 - *Timing constraints*

And now the final results ...