



Predict the use of shared bicycles

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Deep Learning Foundation



Outline

1/ Introduction

2/ Theory of BPNN

3/ Dataset of the project

4/ Optimization



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1/ **Introduction**

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Back Propagation Neural Network

- Computing systems inspired by the biological neural networks that constitute animal brains

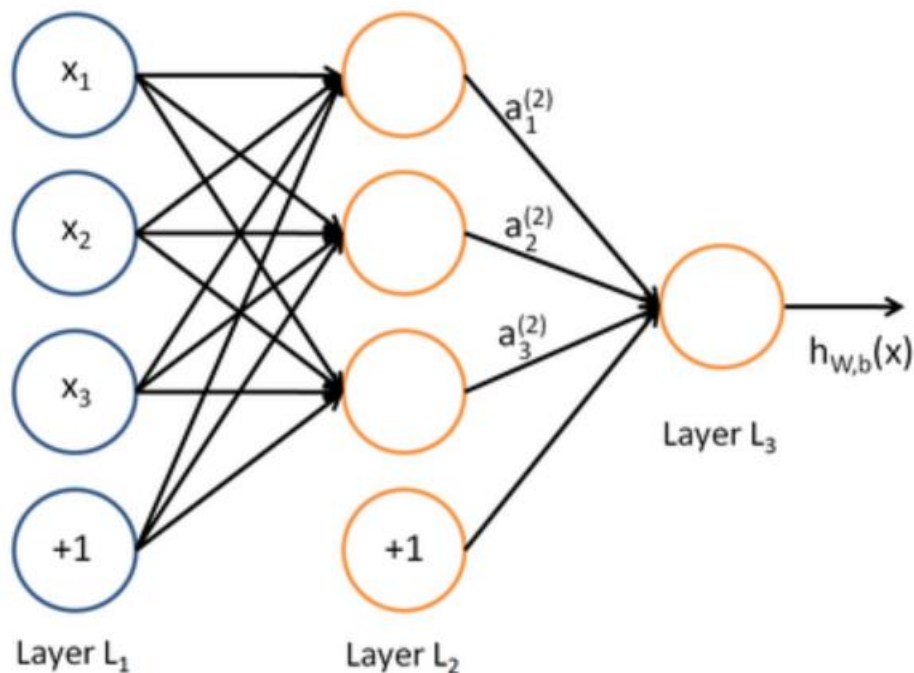


Fig.1 Figure of Three-layer Neural Network



Convolutional Neural Network (CNN)

卷积神经网络

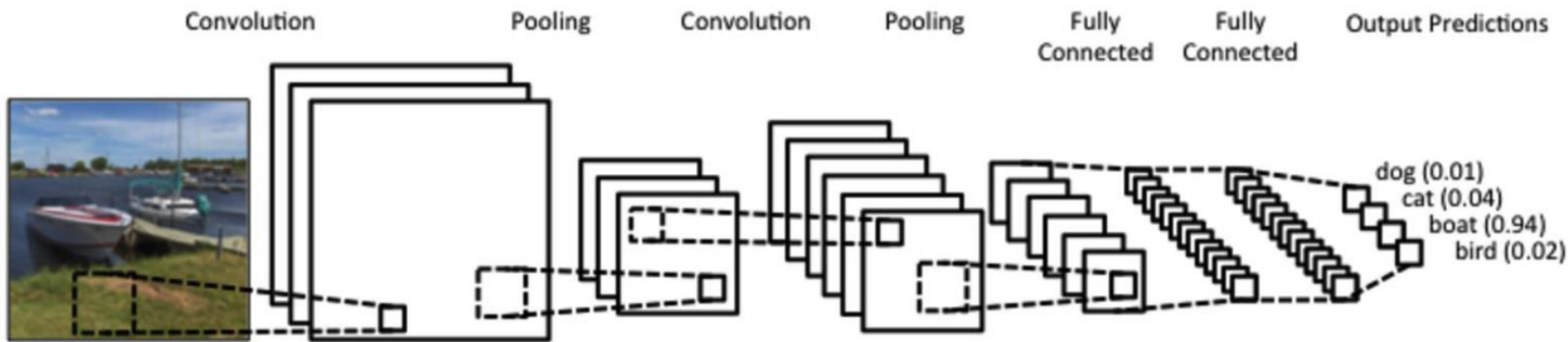


Fig.3 Convolutional neural network

Sensitive with image



Recurrent Neural Network(RNN)

递归神经网络

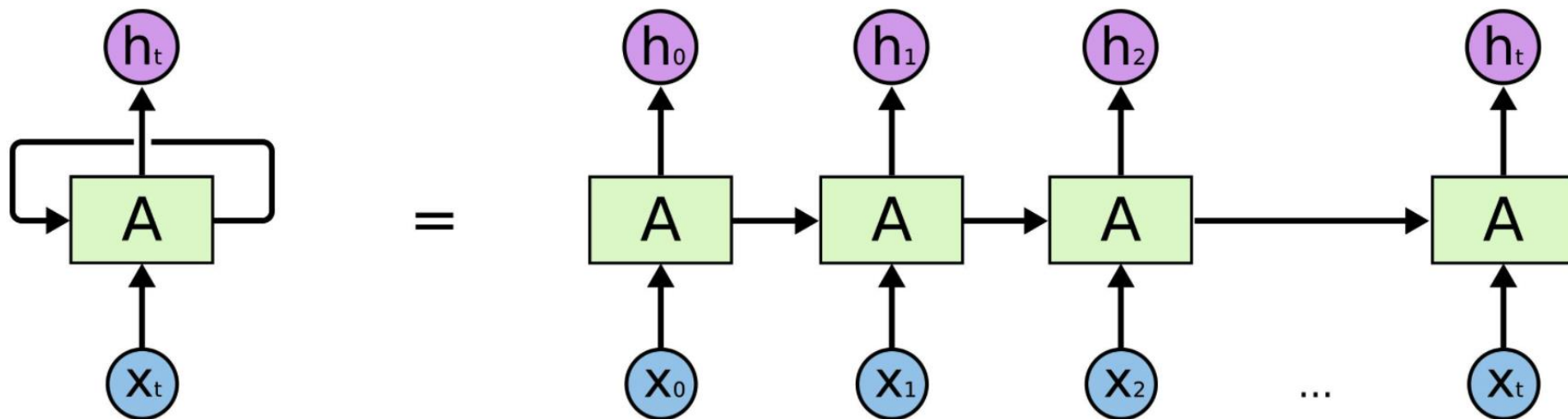


Fig.2 Recurrent Neural Network

Sensitive with sequential data



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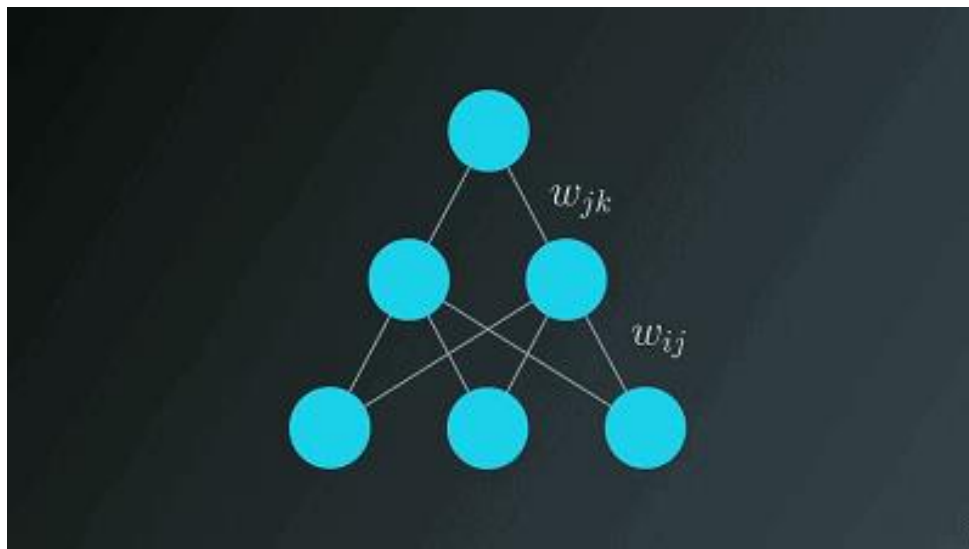
4/ Optimization



Back propagation neural network

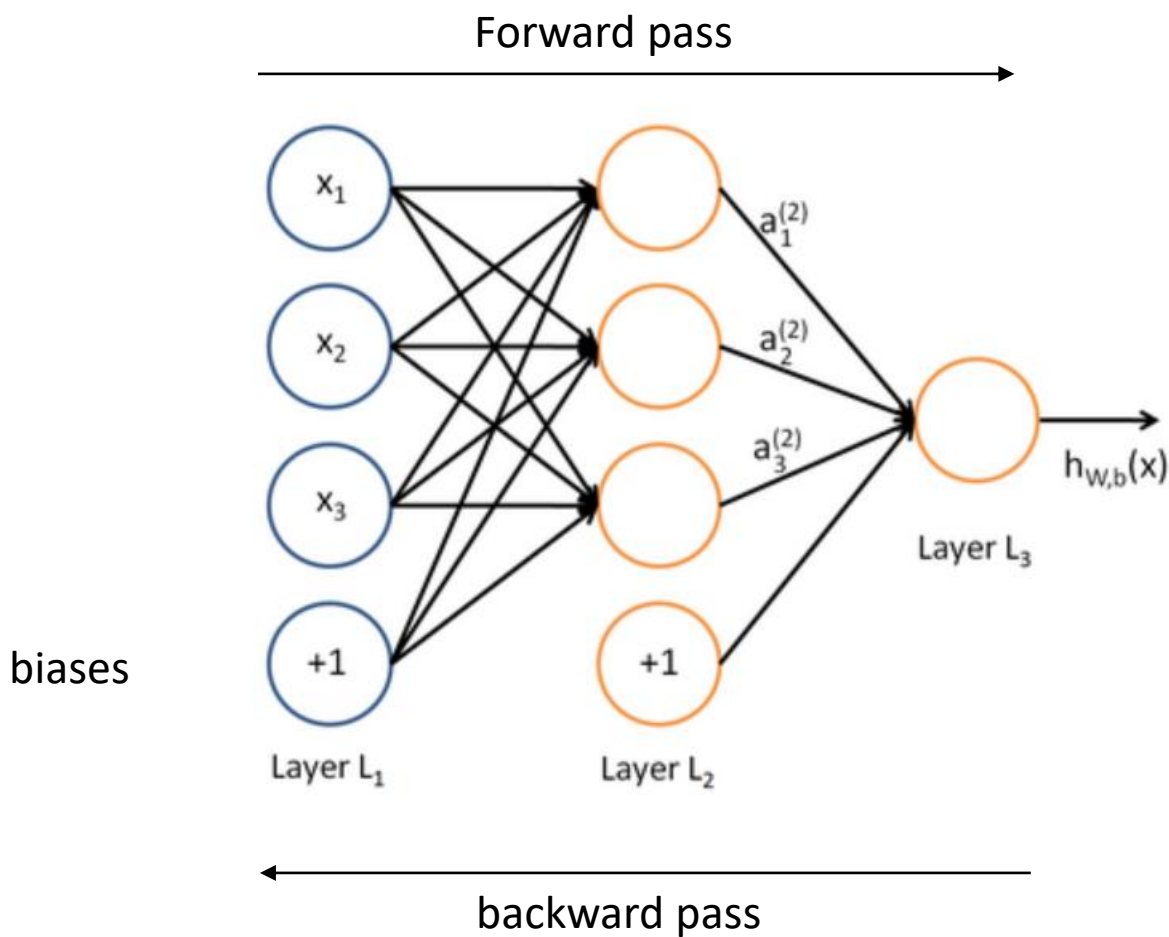
反向传播神经网络

实验要求：三层神经网络（输入层，隐藏层，输出层）



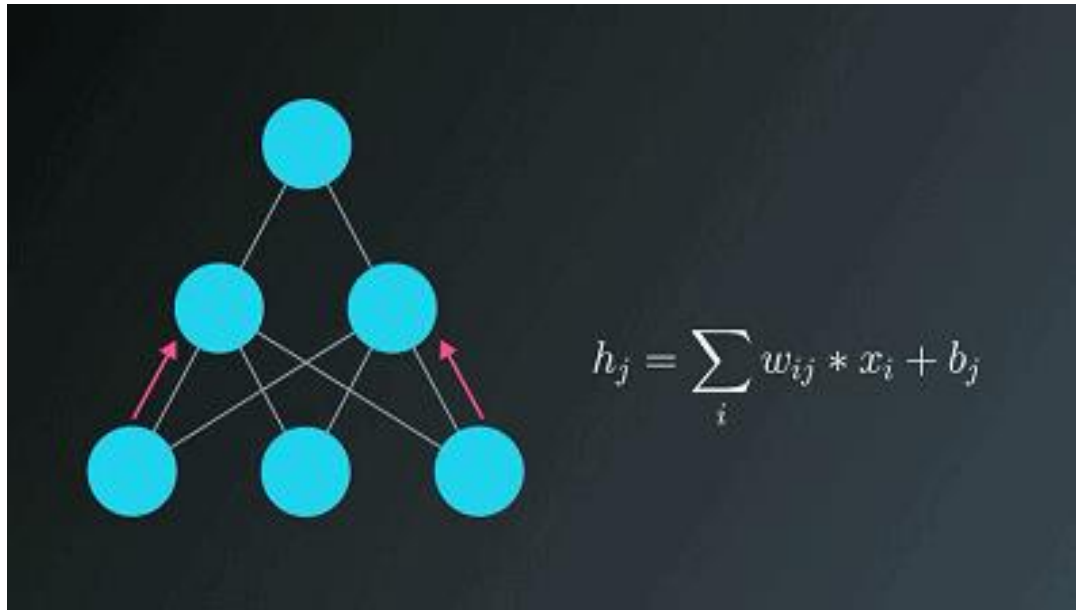


Back propagation neural network





Forward pass





Forward pass

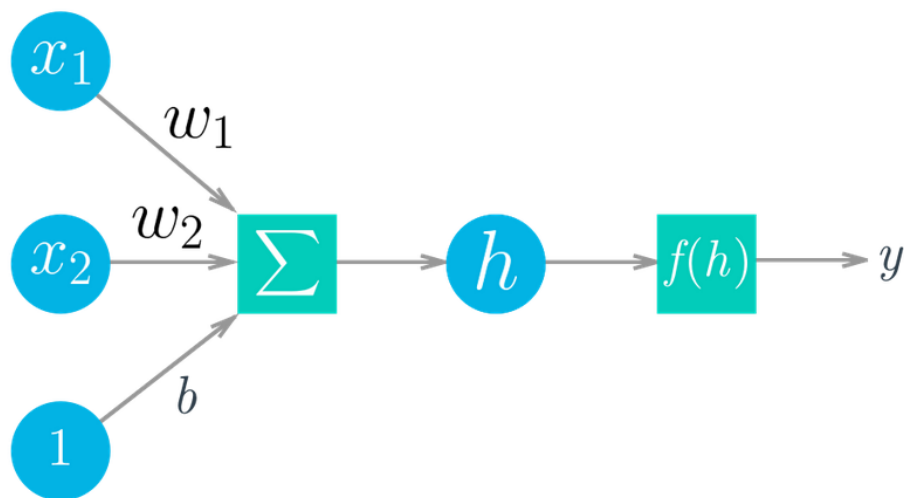


Fig.3 神经网络示意图

在这个架构中 $f(h)$ 称为激活函数，这个函数可以为很多不同的函数，例如如果让 $f(h) = h$ 。则网络的输出为：

$$y = \sum_i w_i x_i + b$$



Forward pass

将数据从 $(-\infty, \infty)$ 映射到 $(0,1)$

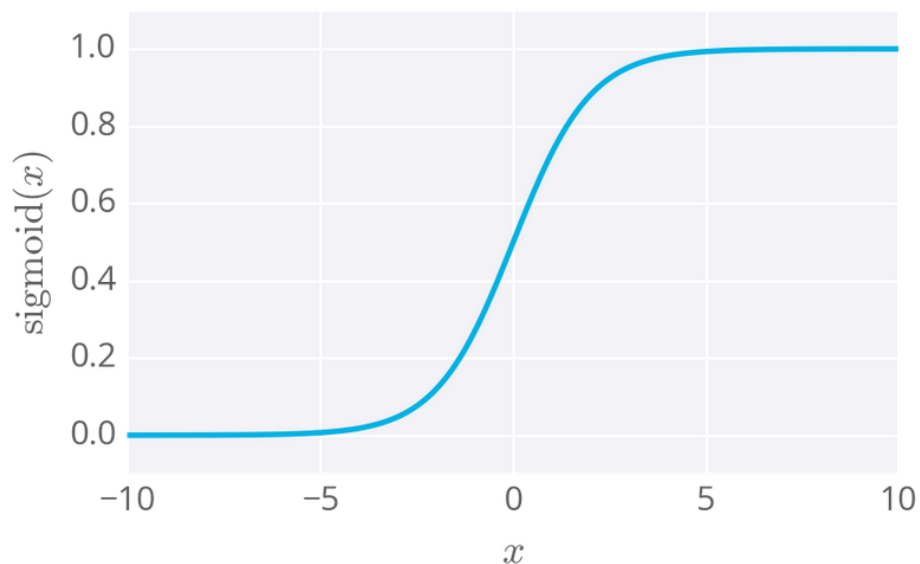


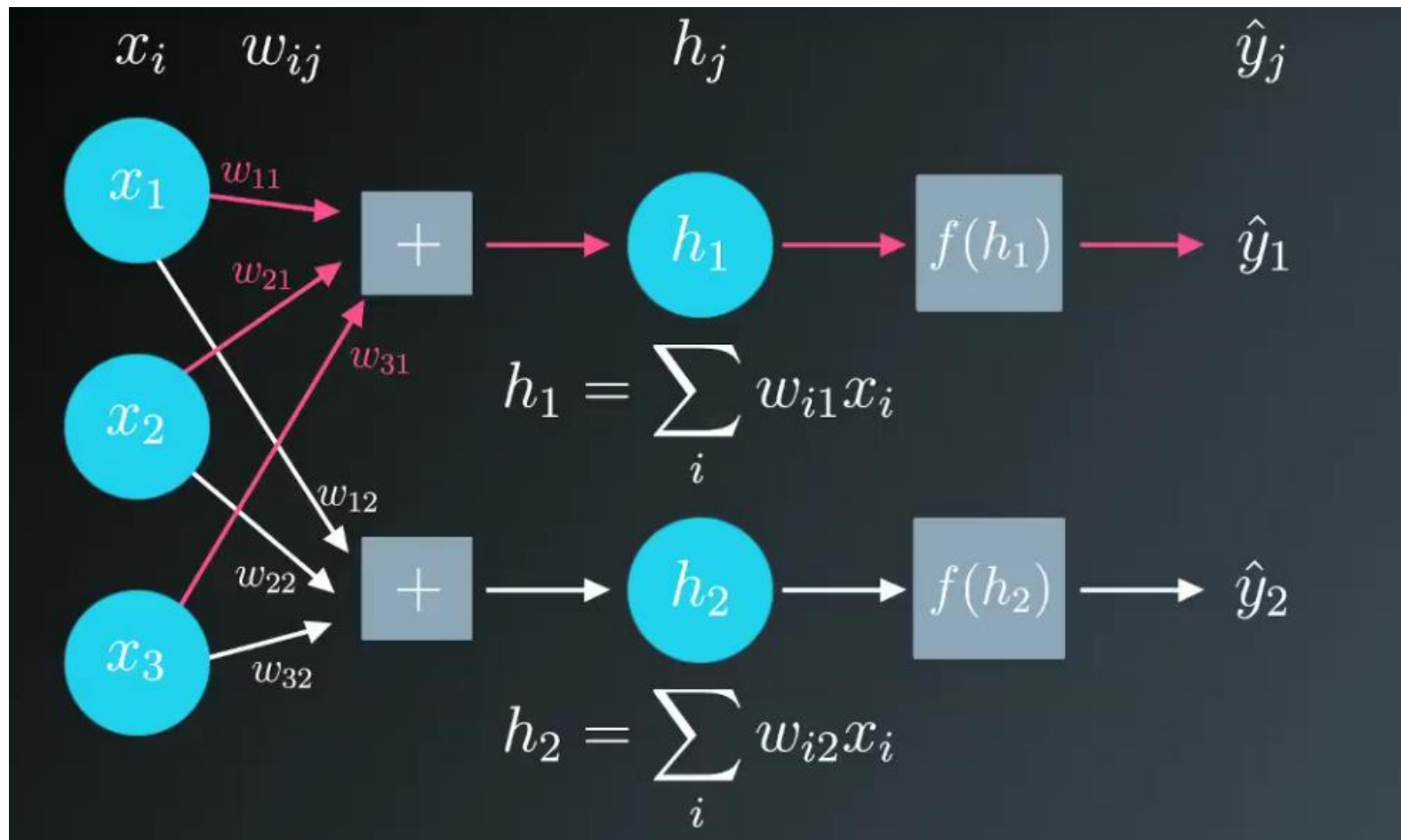
Fig.3 sigmoid函数

公式:

$$\text{sigmoid}(x) = 1 / (1 + e^{-x})$$



Forward pass





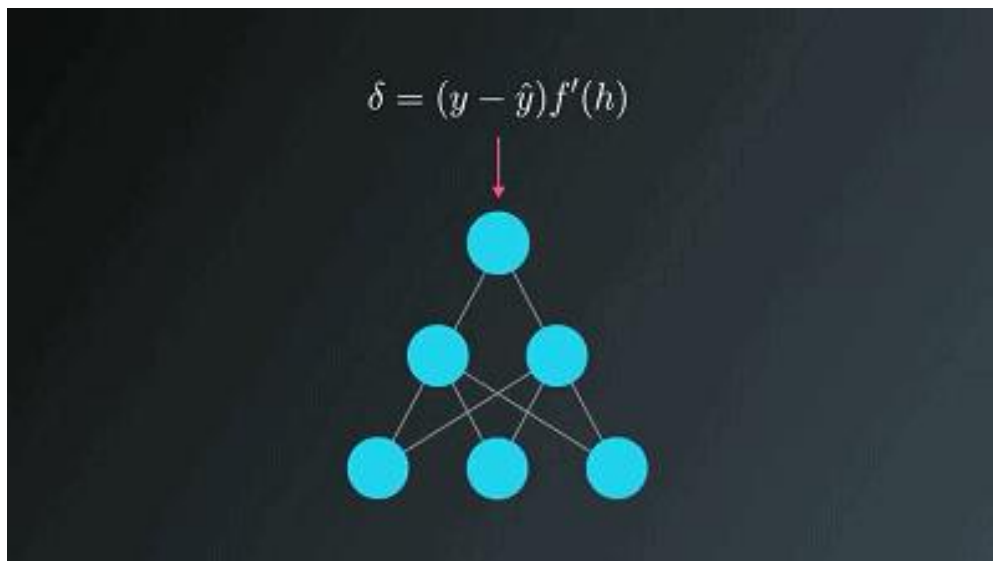
Forward pass

Loss function

$$\text{MSE} = \frac{1}{n} \sum_{i=1}^n (\hat{Y}_i - Y_i)^2$$



Backward pass





Backward pass

Loss function:

$$J(W, b) = \frac{1}{m} \sum_{i=1}^m J(W, b; x^i, y^i) + \frac{\lambda}{2} \sum_{l=1}^{n^l-1} \sum_{i=1}^{S_l} \sum_{j=1}^{S_{l+1}} \left(W_{ji}^{(l)} \right)^2$$

其中:

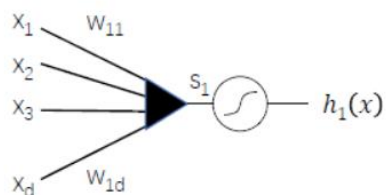
$$J(W, b; x, y) = \frac{1}{2} \|h_{wb}(x) - y\|^2$$



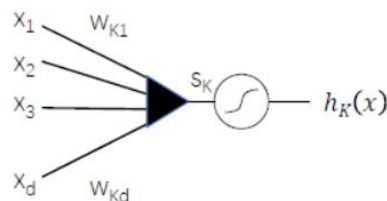
Backward pass

对于二分类问题，使用sigmoid函数。

对于K分类问题（ $K > 2$ ），使用softmax回归。



⋮



$$\left\{ \begin{array}{l} s_j = \sum_{i=1}^d w_{ji}x_i + \mathbf{w_{j0}x_0} = \sum_{i=0}^d w_{ji}x_{ji} = \mathbf{W_jx} \\ t_j(\mathbf{x}) = \exp(s_j) \\ p_j(y = j) = \frac{t_j(\mathbf{x})}{\sum_j t_j(\mathbf{x})} \end{array} \right. , \quad j \in [1, K]$$

简而言之：

$$p(y = j | \mathbf{x}, \mathbf{W_j}) = h_j(\mathbf{x}) = \text{softmax}(\mathbf{W_jx}) = \frac{\exp(\mathbf{W_jx})}{\sum_{i=1}^K \exp(\mathbf{W_ix})}$$



Backward pass

似然函数对比

假设数据集中有 N 个样本 $\{\mathbf{x}_1, \dots, \mathbf{x}_n\}$, 对应的标签集合为 $\{y_1, \dots, y_n\}$

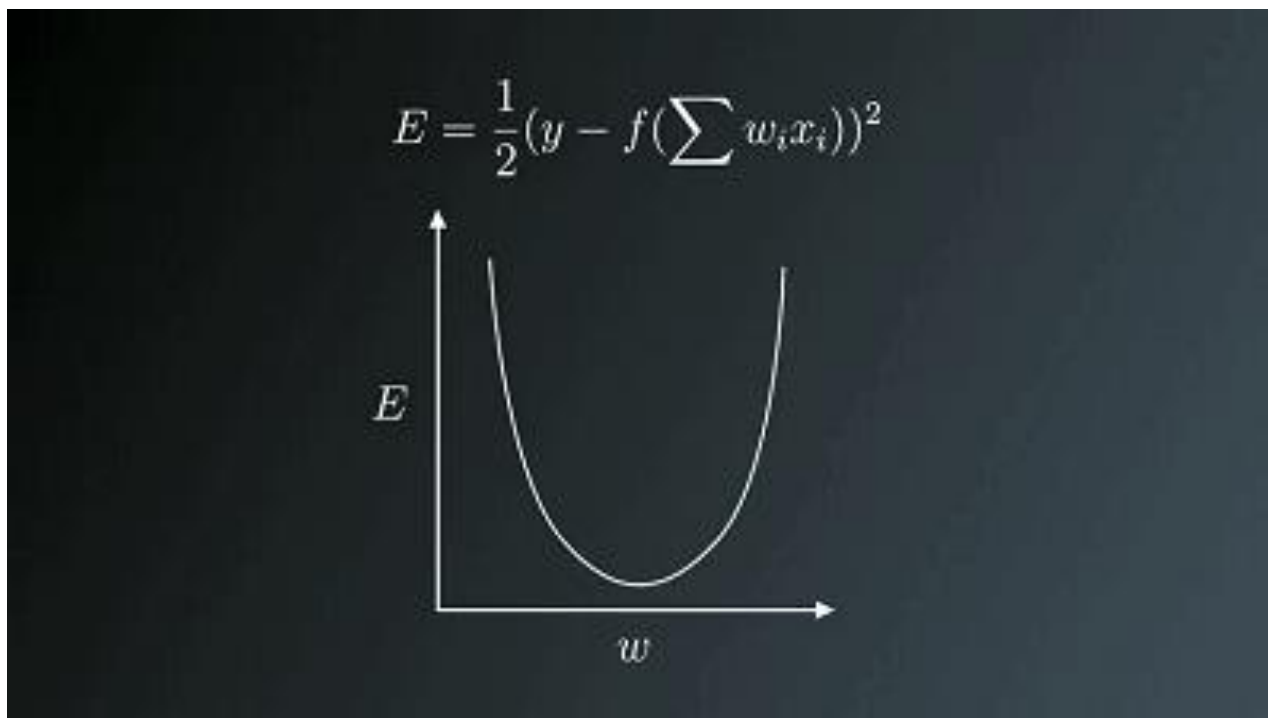
逻辑回归:
$$likelihood = \prod_{n=1}^N p(y_n | \mathbf{x}_n) = \prod_{n=1}^N h(\mathbf{x}_n)^{y_n} (1 - h(\mathbf{x}_n))^{1-y_n}$$

softmax回归:
$$likelihood = \prod_{n=1}^N p(y_n | \mathbf{x}_n) = \prod_{n=1}^N h(\mathbf{x}_n)^{y_n}$$

更新过程相似, 计算负对数似然, 并对权重求导数后使用梯度下降法更新。



Backward pass





Backward pass

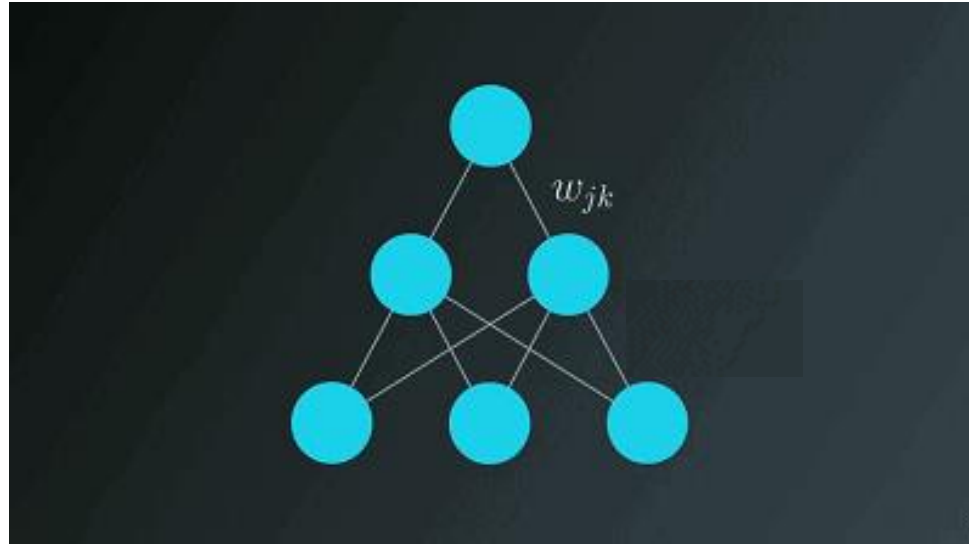
$$w_i = w_i + \Delta w_i$$

$$\Delta w_i \propto -\frac{\partial E}{\partial w_i} \longrightarrow \text{THE GRADIENT}$$

$$\Delta w_i = -\eta \frac{\partial E}{\partial w_i}$$



Backward pass





Backward pass

w_i 为最后一层权重

$$\frac{\partial E}{\partial w_i} = \frac{\partial}{\partial w_i} \frac{1}{2} (y - \hat{y})^2$$

$$= \frac{\partial}{\partial w_i} \frac{1}{2} (y - f(h))^2$$



通过链式求导

$$\frac{\partial}{\partial z} p(q(z)) = \frac{\partial p}{\partial q} \frac{\partial q}{\partial z}$$



Backward pass

$$\hat{y} = f(h) \text{ where } h = \sum_i w_i x_i$$

$$\frac{\partial E}{\partial w_i} = -(y - \hat{y}) \frac{\partial \hat{y}}{\partial w_i}$$

$$= -(y - \hat{y}) f'(h) \frac{\partial}{\partial w_i} \sum w_i x_i$$



Backward pass

$$\begin{aligned} & \frac{\partial}{\partial w_i} \sum_i w_i x_i \\ &= \frac{\partial}{\partial w_1} [w_1 x_1 + w_2 x_2 + \dots + w_n x_n] \\ &= x_1 + 0 + 0 + 0 + \dots \\ & \frac{\partial}{\partial w_i} \sum_i w_i x_i = x_i \end{aligned}$$



Backward pass

$$\frac{\partial E}{\partial w_i} = -(y - \hat{y}) f'(h) x_i$$



$$\delta = (y - \hat{y}) f'(h)$$

$$w_i = w_i + \eta \delta x_i$$



Backward pass

$h+1$ 层的误差为 δ_k^{h+1} ， h 层节点 j 的误差即为 $h+1$ 层误差乘以两层间的权重矩阵和激活函数的导数

$$\delta_j^h = \sum W_j \delta_k^{h+1} f'(h_j)$$

梯度下降与之前相同，只是用当前层的误差

$$\Delta w_{ij} = \eta \delta_j^h x_i$$



Backward pass

当 $f(x) = \text{sigmoid}(x)$ 时:

$$\begin{aligned}\frac{\partial E_d}{\partial \text{net}_j} &= \sum_{k \in \text{Downstream}(j)} \frac{\partial E_d}{\partial \text{net}_k} \frac{\partial \text{net}_k}{\partial \text{net}_j} \\&= \sum_{k \in \text{Downstream}(j)} -\delta_k \frac{\partial \text{net}_k}{\partial \text{net}_j} \\&= \sum_{k \in \text{Downstream}(j)} -\delta_k \frac{\partial \text{net}_k}{\partial a_j} \frac{\partial a_j}{\partial \text{net}_j} \\&= \sum_{k \in \text{Downstream}(j)} -\delta_k w_{kj} \frac{\partial a_j}{\partial \text{net}_j} \\&= \sum_{k \in \text{Downstream}(j)} -\delta_k w_{kj} a_j (1 - a_j) \\&= -a_j (1 - a_j) \sum_{k \in \text{Downstream}(j)} \delta_k w_{kj}\end{aligned}$$



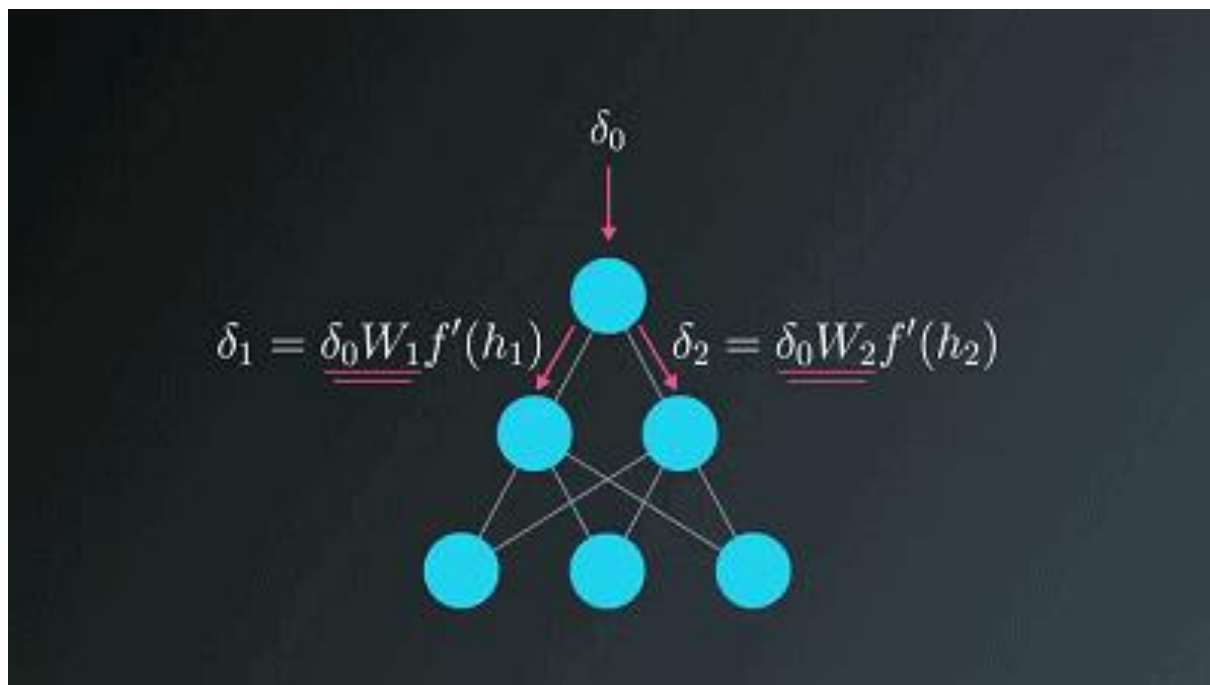
Backward pass

$$\begin{aligned}
 \frac{\partial J(W, b)}{\partial W_{ji}^{(l)}} &= \frac{1}{m} \sum_{t=1}^m \frac{\partial J(W, b; x^t, y^t)}{\partial W_{ji}^{(l)}} + \lambda W_{ji}^{(l)} \\
 &= \frac{1}{m} \sum_{t=1}^m \left(\frac{\partial J(W, b; x^t, y^t)}{\partial Z_j^{l+1}} \times \frac{\partial Z_j^{l+1}}{\partial W_{ji}^{(l)}} \right) + \lambda W_{ji}^{(l)} \\
 &= \frac{1}{m} \sum_{t=1}^m \left(\delta_j^{l+1} \times \frac{\partial Z_j^{l+1}}{\partial W_{ji}^{(l)}} \right) + \lambda W_{ji}^{(l)} \\
 &= \frac{1}{m} \sum_{t=1}^m \left(\delta_j^{l+1} \times \frac{\partial \left(\sum_{k=1}^S (W_{jk}^l a_k^l) + b_i^l \right)}{\partial W_{ji}^{(l)}} \right) + \lambda W_{ji}^{(l)} \\
 &= \frac{1}{m} \sum_{t=1}^m \left(\delta_j^{l+1} \times a_i^l \right) + \lambda W_{ji}^{(l)}
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial J(W, b)}{\partial b_i^l} &= \frac{1}{m} \sum_{t=1}^m \frac{\partial J(W, b; x^t, y^t)}{\partial b_i^l} \\
 &= \frac{1}{m} \sum_{t=1}^m \left(\frac{\partial J(W, b; x^t, y^t)}{\partial Z_j^{l+1}} \times \frac{\partial Z_j^{l+1}}{\partial b_i^l} \right) \\
 &= \frac{1}{m} \sum_{t=1}^m \left(\delta_j^{l+1} \times \frac{\partial Z_j^{l+1}}{\partial b_i^l} \right) \\
 &= \frac{1}{m} \sum_{t=1}^m \left(\delta_j^{l+1} \times \frac{\partial \left(\sum_{k=1}^S (W_{jk}^l a_k^l) + b_i^l \right)}{\partial b_i^l} \right) \\
 &= \frac{1}{m} \sum_{t=1}^m \left(\delta_j^{l+1} \right)
 \end{aligned}$$



Backward pass





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Background of the project

In this project, you'll build your first neural network and use it to predict daily bike rental ridership.

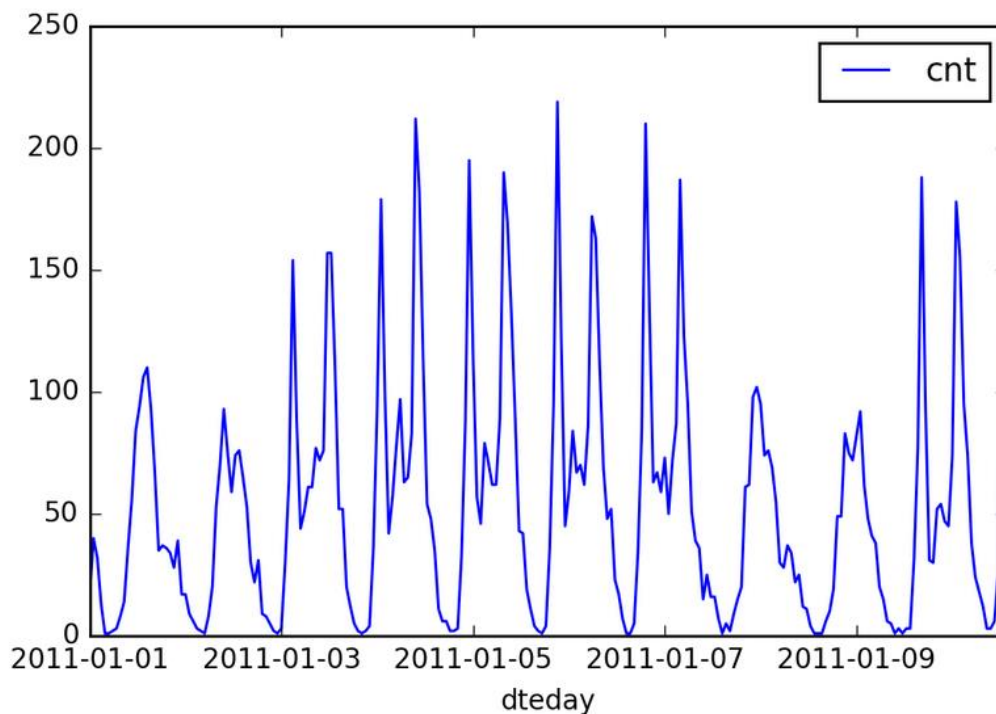


Fig. 4 Subset of the data



Load and prepare the data

```
In [2]: data_path = 'Bike-Sharing-Dataset/hour.csv'

rides = pd.read_csv(data_path)
```

```
In [3]: rides.head()
```

Out[3]:

	instant	dteday	season	yr	mnth	hr	holiday	weekday
0	1	2011-01-01	1	0	1	0	0	6
1	2	2011-01-01	1	0	1	1	0	6
2	3	2011-01-01	1	0	1	2	0	6
3	4	2011-01-01	1	0	1	3	0	6
4	5	2011-01-01	1	0	1	4	0	6

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Fig. 8 show the dataset



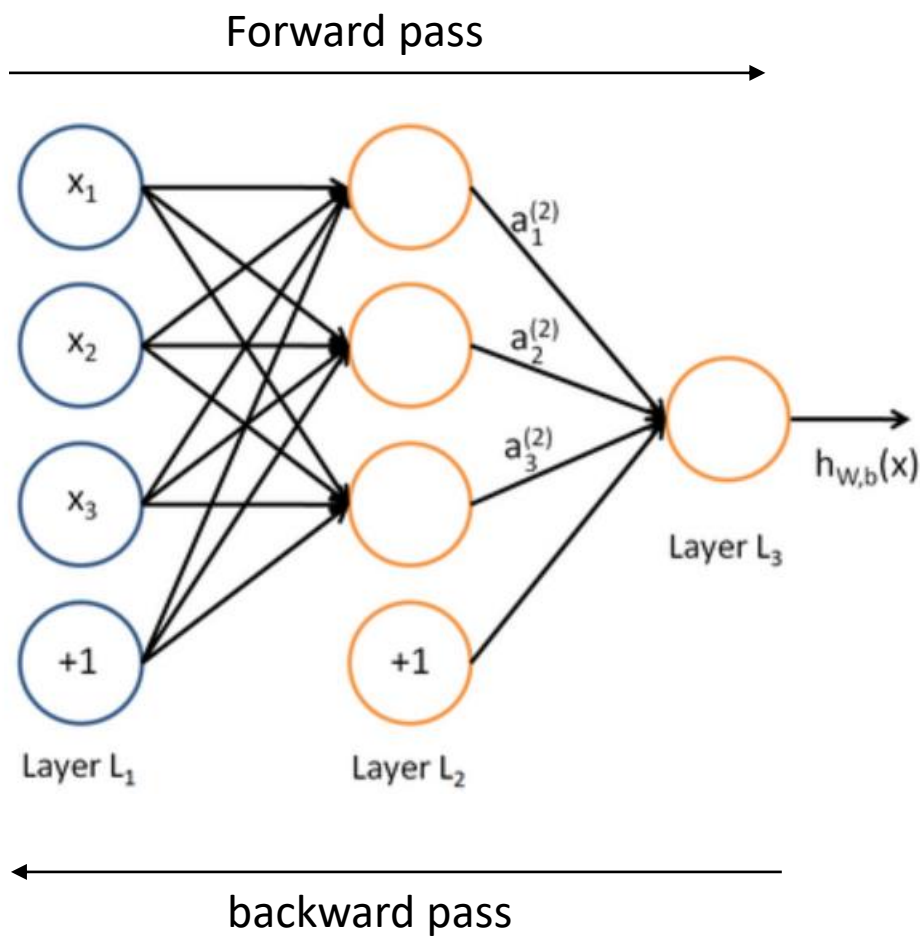
Build the Network

TODO list:

- 将所有权重进行随机初始化
- 把每一层权重更新的初始梯度设置为 0
 - 输入到隐藏层的权重更新是 $\Delta w_{ij} = 0$
 - 隐藏层到输出层的权重更新是 $\Delta W_j = 0$
- 对训练数据当中的每一个点
 - 让它正向通过网络, 计算输出 \hat{y}
 - 计算输出节点的误差梯度 $\delta^o = (y - \hat{y})f'(z)$ 这里 $z = \sum_j W_j a_j$ 是输出节点的输入。
 - 误差传播到隐藏层 $\delta_j^h = \delta^o W_j f'(h_j)$
 - 更新权重步长:
 - $\Delta W_j = \Delta W_j + \delta^o a_j$
 - $\Delta w_{ij} = \Delta w_{ij} + \delta_j^h a_i$
- 更新权重, 其中 η 是学习率, m 是数据点的数量:
 - $W_j = W_j + \eta \Delta W_j / m$
 - $w_{ij} = w_{ij} + \eta \Delta w_{ij} / m$
- 重复这个过程 e 代。



Training and Validating





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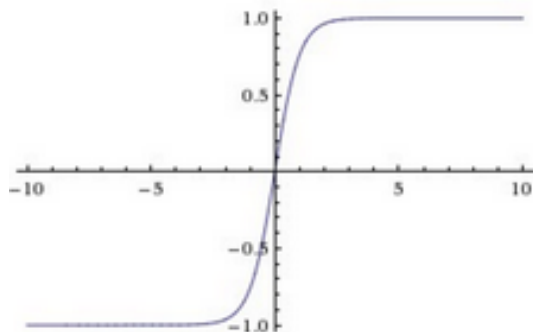


- L2正则化

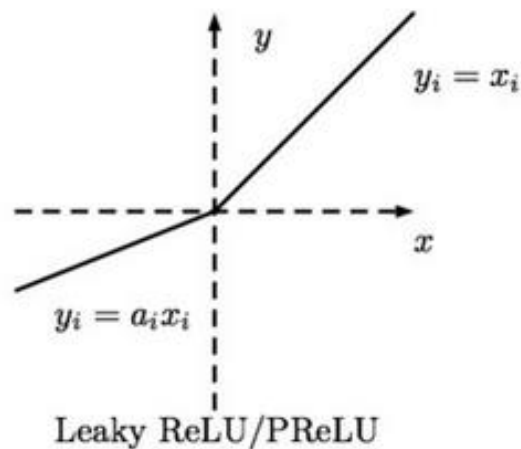
$$J(W, b) = \frac{1}{m} \sum_{i=1}^m J(W, b; x^i, y^i) + \frac{\lambda}{2} \sum_{l=1}^{n^l-1} \sum_{i=1}^{S_l} \sum_{j=1}^{S_{l+1}} \left(W_{ji}^{(l)} \right)^2$$

- 不同的激活函数

Tanh



Relu





- 数据预处理
- 多层深度神经网络
- 不同神经网络架构
- Mini-batch



任务布置

- 共享单车使用量预测任务
- 标签内容参考readme，包含时间、天气等信息
- 必须实现三层神经网络（输入层，隐藏层，输出层）
- 必须在给出的优化建议中任意选择一项实现
- 自己划分验证集（报告里说明是怎么分的）调整参数



思考题

- 尝试说明下其他激活函数的优缺点。
- 有什么方法可以实现传递过程中不激活所有节点？
- 梯度消失和梯度爆炸是什么？可以怎么解决？



实验要求

- 提交文件
 - 实验报告: 18*****_wangxiaoming.pdf。
 - 代码文件夹: 18*****_wangxiaoming。如果代码分成多个文件，最好写份readme
- DDL:
 - 报告: 10月22号 23:59:59
 - 验收: 10月23号 18:00:00



THANKS

