

Computation of B-spline Basis Functions:

The local support of B-spline basis functions suggests there must be an efficient means to compute them. Indeed, supposing that $\xi \in [\xi_l, \xi_{l+1})$, only basis functions:

$$N_{i,j} \quad \begin{array}{l} i = l-j, \dots, l \\ j = 0, \dots, p \end{array}$$

are non zero. Moreover, we have the relationships:

$$p=0: \quad N_{l,0} = 1$$

$$p=1: \quad N_{l,1} = \left(\frac{\xi - \xi_l}{\xi_{l+1} - \xi_l} \right) N_{l,0} = B_{2,l} N_{l,0}$$

$$N_{l-1,1} = \left(\frac{\xi_{l+1} - \xi}{\xi_{l+1} - \xi_l} \right) N_{l,0} = (1 - B_{2,l}) N_{l,0}$$

$$p=2: \quad N_{l,2} = \left(\frac{\xi - \xi_l}{\xi_{l+2} - \xi_l} \right) N_{l,1} = B_{3,l} N_{l,1}$$

$$\begin{aligned} N_{l-1,2} &= \left(\frac{\xi_{l+2} - \xi}{\xi_{l+2} - \xi_l} \right) N_{l,1} + \left(\frac{\xi - \xi_{l-1}}{\xi_{l+1} - \xi_{l-1}} \right) N_{l-1,1} \\ &= (1 - B_{3,l}) N_{l,1} + B_{3,l-1} N_{l-1,1} \end{aligned}$$

$$N_{l-2,2} = \left(\frac{\xi_{l+1} - \xi}{\xi_{l+1} - \xi_{l-1}} \right) N_{l-1,1} = (1 - B_{3,l-1}) N_{l-1,1}$$

$$p \geq 0: \quad N_{l,p} = B_{p,l} N_{l,p-1}$$

$$\begin{aligned} N_{l-k,p} &= (1 - B_{p,l-k+1}) N_{l-k+1,p-1} \\ &\quad + B_{p,l-k} N_{l-k,p-1} \end{aligned}$$

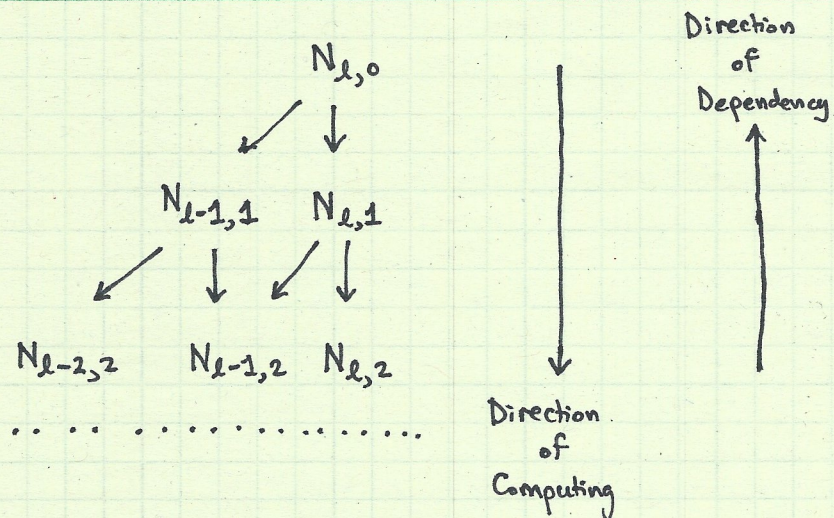
$$\text{for } k = 1, \dots, p-1$$

$$N_{l-p,p} = (1 - B_{p,l-p+1}) N_{l-p+1,p-1}$$

where:

$$B_{k,i} = \frac{\xi - \xi_i}{\xi_{i+k} - \xi_i}$$

This suggests we can compute all $\frac{1}{2} p(p+1)$ non zero basis functions in $O(p^2)$ time by exploiting the triangular scheme:



As opposed to our earlier algorithms, our new algorithm is not recursive but rather constructive. Pseudocode is listed below.

```

Function Compute Spline Basis ( $\xi$ )
begin
    find  $l$  s.t.  $\xi \in [\xi_l, \xi_{l+1})$  via binary search
    initialize  $N_{l,k} = 0$  for  $k = 0, \dots, p$  and  $i = l-k, \dots, l$ 
    set  $N_{l,0} = 1$ 
    for  $k = 1, \dots, p$ 
        for  $i = l-k+1, \dots, l$ 
            set  $B_{k,i} = (\xi - \xi_i) / (\xi_{i+k} - \xi_i)$ 
            update  $N_{i,k} += \alpha_{k,i} N_{i,k-1}$ 
            update  $N_{i-1,k} += (1 - \alpha_{k,i}) N_{i,k-1}$ 
        endloop
    endloop
    return basis functions and  $l$ 
end
    
```

Above, the notation $+=$ indicates:

$$x += y \Rightarrow x = x + y$$

The function Compute Spline Basis has a few redundant computations and memory accesses/updates, but it is still quite efficient. The NURBS Book by Piegl and Tiller has a more efficient algorithm but it is more difficult to digest.

3 / 3

The function Compute Spline Basis also suggests another means of computing the value of a B-spline curve.

```
function Compute Spline Curve ( $\xi$ )  
begin  
    call Compute Spline Basis ( $\xi$ )  
    return  $\vec{P}_{l-p} * N_{l-p,p} + \dots + \vec{P}_l * N_{l,p}$   
end
```

-2

We will also use Compute Spline Basis later to compute NURBS basis functions and NURBS curves.