

Boundary Value Problems: Galerkin's Method

Galerkin's method consists of constructing finite-dimensional approximations of \mathcal{J} and \mathcal{V} , denoted as \mathcal{J}^h and \mathcal{V}^h respectively. Strictly speaking, these will be subsets:

$$\mathcal{J}^h \subset \mathcal{J}$$

$$\mathcal{V}^h \subset \mathcal{V}$$

We will further characterize \mathcal{J}^h by requiring that if we have a given function $g^h \in \mathcal{J}^h$, such that $g^h|_{\Gamma_D} = g$, then for every $u^h \in \mathcal{J}^h$, there exists a unique $v^h \in \mathcal{V}^h$ such that:

$$u^h = v^h + g^h$$

Then, Galerkin's method is stated as follows:

$$(G) \begin{cases} \text{Find } u^h = v^h + g^h, \text{ where } v^h \in \mathcal{V}^h, \text{ such that:} \\ a(w^h, u^h) = L(w^h) \quad \forall w^h \in \mathcal{V}^h \end{cases}$$

We can rewrite the variational form of Galerkin's method as:

$$a(w^h, v^h) = L(w^h) - a(w^h, g^h)$$

\updownarrow
 Unknown
Information

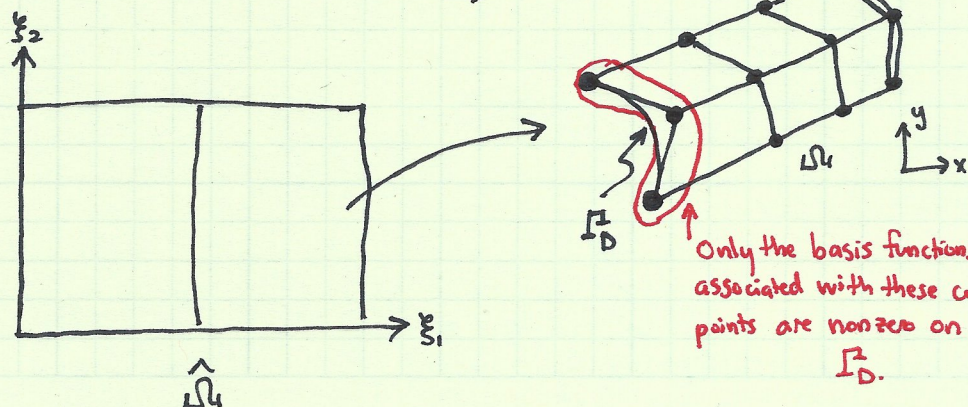
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In isogeometric analysis, we identify \mathcal{V}^h and \mathcal{J}^h as NURBS spaces:

$$\mathcal{V}^h := \left\{ w^h \in \mathcal{V} : w^h(\vec{x}) = \sum_{i=1}^n N_i(\vec{x}) c_i \right\}$$

$$\mathcal{J}^h := \left\{ u^h \in \mathcal{J} : u^h(\vec{x}) = \sum_{i=1}^n N_i(\vec{x}) d_i \right\}$$

Recall that the support of NURBS functions are highly localized, and hence there are very few functions that are nonzero on Γ_D .



Without loss of generality, let us suppose that there exists an integer $n_{eq} < n$ such that:

$$N_i|_{\Gamma_D} = 0 \quad \forall i = 1, \dots, n_{eq}$$

Then:

$$\gamma^h := \{ w^h : w^h = \sum_{i=1}^{n_{eq}} N_i(\vec{x}) c_i \} \quad \text{Completely free}$$

Moreover, we can choose g^h such that $g_1 = \dots = g_{n_{eq}} = 0$:

$$g^h(\vec{x}) = \sum_{i=n_{eq}+1}^n N_i(\vec{x}) g_i$$

Then, we have that:

$$u^h(\vec{x}) = \sum_{i=1}^n N_i(\vec{x}) d_i = \underbrace{\sum_{i=1}^{n_{eq}} N_i(\vec{x}) d_i}_{\text{Unknown}} + \underbrace{\sum_{i=n_{eq}+1}^n N_i(\vec{x}) g_i}_{\text{Known}} = v^h + g^h$$

$v^h \in V^h$

If we plug our expressions for u^h and w^h into the Galerkin formulation, we obtain:

$$a\left(\sum_{i=1}^{n_{eq}} N_i c_i, \sum_{j=1}^{n_{eq}} N_j d_j\right) = L\left(\sum_{i=1}^{n_{eq}} N_i c_i\right) - a\left(\sum_{i=1}^{n_{eq}} N_i c_i, g^h\right)$$

Exploiting linearity, we find:

$$\sum_{i=1}^{n_{eq}} \underbrace{c_i}_{\text{Free}} \left(\sum_{j=1}^{n_{eq}} a(N_i, N_j) d_j - L(N_i) + a(N_i, g^h) \right) = 0$$

As c_i is arbitrary for $i=1, \dots, n_{eq}$, we have:

$$\sum_{j=1}^{n_{eq}} a(N_i, N_j) d_j = L(N_i) - a(N_i, g^h) \quad \text{for } i=1, \dots, n_{eq}$$

Now, suppose we define:

$$K_{ij} = a(N_i, N_j)$$

$$F_i = L(N_i) - a(N_i, g^h)$$

and:

$$\underline{\underline{K}} = [K_{ij}]$$

$$\underline{F} = [F_i]$$

$$\underline{d} = [d_i]$$

Then we have the matrix problem:

$$\boxed{\underline{\underline{K}} \underline{d} = \underline{F}}$$

for the unknown control variables $\underline{d} = [d_i]$. Due to the finite element method's historical origins in finite element analysis of structures, we call:

$$\underline{\underline{K}} = \text{stiffness matrix}$$

$$\underline{d} = \text{displacement vector}$$

$$\underline{F} = \text{force vector}$$

We solve for the control variables as:

$$\underline{d} = \underline{\underline{K}}^{-1} \underline{F}$$

and then we finally obtain our desired discrete approximation of the temperature field as:

$$u^h(\vec{x}) = \sum_{i=1}^{n_{eq}} N_i(\vec{x}) \underset{\substack{\uparrow \\ \text{Solved for!}}}{d_i} + \sum_{i=n_{eq}+1}^n N_i(\vec{x}) \underset{\substack{\uparrow \\ \text{Dirichlet data}}}{g_i}$$