

Nodal Domains and Diffusion Processes

Jacob Denson

University of Wisconsin Madison

October 5, 2022

- Georgiev, Mukherjee, *Nodal Geometry, Heat Diffusion, and Brownian Motion*, Anal. PDE. **12** (2017), 133-148.

- Georgiev, Mukherjee, *Nodal Geometry, Heat Diffusion, and Brownian Motion*, Anal. PDE. **12** (2017), 133-148.
- Steinerberger, *Lower Bounds on Nodal Sets of Eigenfunctions via the Heat Flow*, Comm. Partial Differential Equations. **39** (2014), 2240-2261.

- Georgiev, Mukherjee, *Nodal Geometry, Heat Diffusion, and Brownian Motion*, Anal. PDE. **12** (2017), 133-148.
- Steinerberger, *Lower Bounds on Nodal Sets of Eigenfunctions via the Heat Flow*, Comm. Partial Differential Equations. **39** (2014), 2240-2261.
- Øksendal, *Stochastic Differential Equations*, Springer, 2003.
- Chung, *Green, Brown, and Probability and Brownian Motion*, World Scientific Publishing Company, 2002.

Nodal Domains

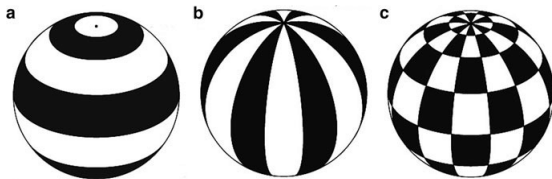
Goal

Study 'asymptotic geometry' of D_λ as $\lambda \rightarrow \infty$.

Nodal Domains

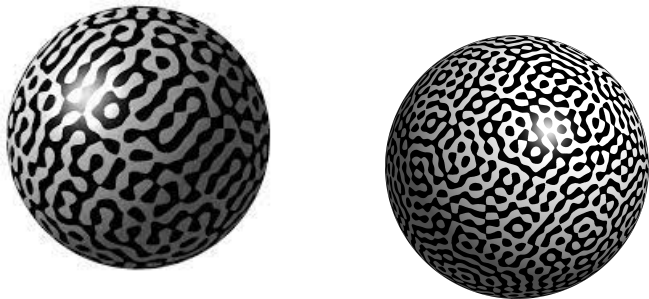
Goal

Study 'asymptotic geometry' of D_λ as $\lambda \rightarrow \infty$.



Credit: Yuri Skiba

Nodal Domains



Credit: *Alex Barnett*

Main Result

- **Theorem:** There is $c_M > 0$ such that for any 'good' k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

Main Result

- **Theorem:** There is $c_M > 0$ such that for any 'good' k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

- Consider the radius $1/\lambda$ tubular neighborhood

$$T_{1/\lambda}\Sigma = \bigcup_{x \in \Sigma} \{v \in (T_x \Sigma)^\perp : |v|_g \leq 1/\lambda\}.$$

The submanifold Σ is 'good' if the geodesic map $T_{1/\lambda}\Sigma \rightarrow N(\Sigma, 1/\lambda)$ is an embedding.

Main Result

- **Theorem:** There is $c_M > 0$ such that for any 'good' k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

- Consider the radius $1/\lambda$ tubular neighborhood

$$T_{1/\lambda}\Sigma = \bigcup_{x \in \Sigma} \{v \in (T_x \Sigma)^\perp : |v|_g \leq 1/\lambda\}.$$

The submanifold Σ is 'good' if the geodesic map $T_{1/\lambda}\Sigma \rightarrow N(\Sigma, 1/\lambda)$ is an embedding.

- Local condition: All principal curvatures of Σ are $\lesssim \lambda$.

Main Result

- **Theorem:** There is $c_M > 0$ such that for any ‘good’ k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

- Consider the radius $1/\lambda$ tubular neighborhood

$$T_{1/\lambda}\Sigma = \bigcup_{x \in \Sigma} \{v \in (T_x \Sigma)^\perp : |v|_g \leq 1/\lambda\}.$$

The submanifold Σ is ‘good’ if the geodesic map $T_{1/\lambda}\Sigma \rightarrow N(\Sigma, 1/\lambda)$ is an embedding.

- Local condition: All principal curvatures of Σ are $\lesssim \lambda$.
- But no cheating globally!

Main Result

- **Theorem:** There is $c_M > 0$ such that for any 'good' k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

Main Result

- **Theorem:** There is $c_M > 0$ such that for any 'good' k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

- There is $C_M > 0$ such that $D_\lambda \subset N(Z_\lambda, C_M/\lambda)$, contrasting this result.

Main Result

- **Theorem:** There is $c_M > 0$ such that for any ‘good’ k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

- There is $C_M > 0$ such that $D_\lambda \subset N(Z_\lambda, C_M/\lambda)$, contrasting this result.
- Proof Heuristic: Elliptic methods tend to give $O(1/\lambda)$ localized results. We study stochastic diffusions, which provide cool tools for analyzing eigenfunctions from an elliptic perspective!

Uncertainty Principle Type Thing?

- What would an analogous result look like on \mathbb{R}^d ?

Uncertainty Principle Type Thing?

- What would an analogous result look like on \mathbb{R}^d ?
- **Theorem:** Let D_λ be a nodal domain in \mathbb{R}^d . Then there is $c_d > 0$ such that if Σ is a finite union of $O(1/\lambda)$ -separated k dimensional planes, then D_λ is not contained in $N(\Sigma, c_d/\lambda)$.

Uncertainty Principle Type Thing?

- What would an analogous result look like on \mathbb{R}^d ?
- **Theorem:** Let D_λ be a nodal domain in \mathbb{R}^d . Then there is $c_d > 0$ such that if Σ is a finite union of $O(1/\lambda)$ -separated k dimensional planes, then D_λ is not contained in $N(\Sigma, c_d/\lambda)$.
- Stronger Result: D_λ should contain a ball of radius $O(1/\lambda)$ by the uncertainty principle.

Uncertainty Principle Type Thing?

- What would an analogous result look like on \mathbb{R}^d ?
- **Theorem:** Let D_λ be a nodal domain in \mathbb{R}^d . Then there is $c_d > 0$ such that if Σ is a finite union of $O(1/\lambda)$ -separated k dimensional planes, then D_λ is not contained in $N(\Sigma, c_d/\lambda)$.
- Stronger Result: D_λ should contain a ball of radius $O(1/\lambda)$ by the uncertainty principle.
- Version on Manifolds: Paper also proves that D_λ contains 'a large percentage' of a ball of radius $O(1/\lambda)$ using similar techniques.

Uncertainty Principle Type Thing?

- What would an analogous result look like on \mathbb{R}^d ?
- **Theorem:** Let D_λ be a nodal domain in \mathbb{R}^d . Then there is $c_d > 0$ such that if Σ is a finite union of $O(1/\lambda)$ -separated k dimensional planes, then D_λ is not contained in $N(\Sigma, c_d/\lambda)$.
- Stronger Result: D_λ should contain a ball of radius $O(1/\lambda)$ by the uncertainty principle.
- Version on Manifolds: Paper also proves that D_λ contains ‘a large percentage’ of a ball of radius $O(1/\lambda)$ using similar techniques.
- Related Methods: D_λ satisfies an ‘interior cone condition’ with angle $O(1/\lambda)$.

Continuous Stochastic Processes

- Three ways to view continuous stochastic processes:

Continuous Stochastic Processes

- Three ways to view continuous stochastic processes:
 - As Borel-measurable functions

$$X : \Omega \rightarrow C([0, \infty), M).$$

Continuous Stochastic Processes

- Three ways to view continuous stochastic processes:
 - As Borel-measurable functions

$$X : \Omega \rightarrow C([0, \infty), M).$$

- As a family of correlated random variables

$$\{X_t : \Omega \rightarrow M : t \in [0, \infty)\}.$$

Continuous Stochastic Processes

- Three ways to view continuous stochastic processes:
 - As Borel-measurable functions

$$X : \Omega \rightarrow C([0, \infty), M).$$

- As a family of correlated random variables

$$\{X_t : \Omega \rightarrow M : t \in [0, \infty)\}.$$

- As a law predicting future behaviour from present behaviour, i.e. by defining quantities such as

$$\mathbb{E}^x[f(X)] = \mathbb{E}[f(X)|X_0 = x].$$

Brownian Motion on \mathbb{R}^d

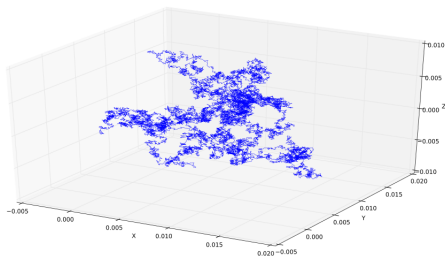
- Brownian motion is a stochastic process $\{B_t\}$ such that:

Brownian Motion on \mathbb{R}^d

- Brownian motion is a stochastic process $\{B_t\}$ such that:
 - For any $I = [t, s]$, given $B_t = x$, the random variable $\Delta_I B = B_s - B_t$ is normally distributed with mean x and variance $s - t$.

Brownian Motion on \mathbb{R}^d

- Brownian motion is a stochastic process $\{B_t\}$ such that:
 - For any $I = [t, s]$, given $B_t = x$, the random variable $\Delta_I B = B_s - B_t$ is normally distributed with mean x and variance $s - t$.
 - For any family of disjoint intervals $I_1, \dots, I_N \subset [0, \infty)$, with $I_k = [t_k, s_k]$, the random variables $\Delta_{I_k} B$ are independent from one another.



Credit: Shiyu Ji

Itô Diffusions

- An Itô Diffusion is like Brownian Motion, but diffusion is not radially symmetric.

Itô Diffusions

- An Itô Diffusion is like Brownian Motion, but diffusion is not radially symmetric.
- For each $x \in \mathbb{R}^d$, let $A(x)$ be a $d \times d$ positive semidefinite matrix. Then we have an Itô diffusion $\{X_t\}$ given in law by the 'Stochastic differential equation' $dX = A(X)dB$.

Itô Diffusions

- An Itô Diffusion is like Brownian Motion, but diffusion is not radially symmetric.
- For each $x \in \mathbb{R}^d$, let $A(x)$ be a $d \times d$ positive semidefinite matrix. Then we have an Itô diffusion $\{X_t\}$ given in law by the 'Stochastic differential equation' $dX = A(X)dB$.
- For practical purposes, we have

$$X_{t+\delta} - X_t \approx A(X_t)[B_{t+\delta} - B_t]$$

where the difference between the LHS and RHS is a random variable with mean $o(\delta)$, and variance $O(\delta)$.

Itô Diffusions

- An Itô Diffusion is like Brownian Motion, but diffusion is not radially symmetric.
- For each $x \in \mathbb{R}^d$, let $A(x)$ be a $d \times d$ positive semidefinite matrix. Then we have an Itô diffusion $\{X_t\}$ given in law by the 'Stochastic differential equation' $dX = A(X)dB$.
- For practical purposes, we have

$$X_{t+\delta} - X_t \approx A(X_t)[B_{t+\delta} - B_t]$$

where the difference between the LHS and RHS is a random variable with mean $o(\delta)$, and variance $O(\delta)$.

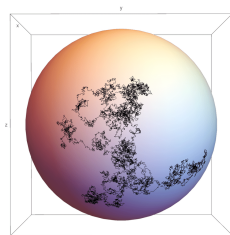
- Diffuses locally near x faster in directions where $A(x)$ has large eigenvalues.

Itô Diffusions

- Can define Itô diffusions on compact Riemannian manifolds M given a section $A : M \rightarrow \text{Hom}(TM)$ of positive definite matrices.

Itô Diffusions

- Can define Itô diffusions on compact Riemannian manifolds M given a section $A : M \rightarrow \text{Hom}(TM)$ of positive definite matrices.
- We can define Brownian motion on a Riemannian manifold such that Brownian motion diffuses at a unit speed along geodesics.



Credit: *Ma, Matveev, Pavlyukevich*

Connection to Elliptic Operators

- For any diffusion X , we can associate a semielliptic operator L , the *generator* of X , such that for $f \in C^\infty(M)$,

$$Lf(x) = \partial_t \{ \mathbb{E}^x[f(X_t)] \} |_{t=0} = \lim_{t \rightarrow 0^+} \frac{\mathbb{E}^x[f(X_t)] - f(x)}{t}.$$

Connection to Elliptic Operators

- For any diffusion X , we can associate a semielliptic operator L , the *generator* of X , such that for $f \in C^\infty(M)$,

$$Lf(x) = \partial_t \{ \mathbb{E}^x[f(X_t)] \} |_{t=0} = \lim_{t \rightarrow 0^+} \frac{\mathbb{E}^x[f(X_t)] - f(x)}{t}.$$

- Second order because paths of X are 'half differentiable'.

Connection to Elliptic Operators

- For any diffusion X , we can associate a semielliptic operator L , the *generator* of X , such that for $f \in C^\infty(M)$,

$$Lf(x) = \partial_t \{ \mathbb{E}^x[f(X_t)] \} |_{t=0} = \lim_{t \rightarrow 0^+} \frac{\mathbb{E}^x[f(X_t)] - f(x)}{t}.$$

- Second order because paths of X are 'half differentiable'.
- For Brownian motion (on \mathbb{R}^d or a manifold M), $L = \Delta/2$.

Connection to Elliptic Operators

- For any diffusion X , we can associate a semielliptic operator L , the *generator* of X , such that for $f \in C^\infty(M)$,

$$Lf(x) = \partial_t \{ \mathbb{E}^x[f(X_t)] \} |_{t=0} = \lim_{t \rightarrow 0^+} \frac{\mathbb{E}^x[f(X_t)] - f(x)}{t}.$$

- Second order because paths of X are 'half differentiable'.
- For Brownian motion (on \mathbb{R}^d or a manifold M), $L = \Delta/2$.
- 'Morally' apply the Fundamental Theorem of Calculus to get *Dynkin's Formula*

$$\mathbb{E}^x[f(X_T)] = f(x) + \mathbb{E}^x \left[\int_0^T (Lf)(X_s) ds \right].$$

Application: Escape Times

- In Dynkin's formula, T can be a 'stopping time', i.e. any $[0, \infty)$ valued function of X which doesn't 'predict the future', i.e. if T stops at a time t , it must only stop because of the properties of X on $[0, T]$, and not behaviour on (T, ∞) .

Application: Escape Times

- In Dynkin's formula, T can be a 'stopping time', i.e. any $[0, \infty)$ valued function of X which doesn't 'predict the future', i.e. if T stops at a time t , it must only stop because of the properties of X on $[0, T]$, and not behaviour on (T, ∞) .
- Given an open, bounded set U , let

$$T_U = \inf\{t : X_t \notin U\}$$

be the *escape time* of U .

Application: Escape Times

- In Dynkin's formula, T can be a 'stopping time', i.e. any $[0, \infty)$ valued function of X which doesn't 'predict the future', i.e. if T stops at a time t , it must only stop because of the properties of X on $[0, T]$, and not behaviour on (T, ∞) .
- Given an open, bounded set U , let

$$T_U = \inf\{t : X_t \notin U\}$$

be the *escape time* of U .

- If B is Brownian motion on \mathbb{R}^d , and U is the escape time of a ball of radius $R^{1/2}$ centered at x , $\mathbb{E}^x[T_U] = R/n$.

Application: Escape Times

- In Dynkin's formula, T can be a 'stopping time', i.e. any $[0, \infty)$ valued function of X which doesn't 'predict the future', i.e. if T stops at a time t , it must only stop because of the properties of X on $[0, T]$, and not behaviour on (T, ∞) .
- Given an open, bounded set U , let

$$T_U = \inf\{t : X_t \notin U\}$$

be the *escape time* of U .

- If B is Brownian motion on \mathbb{R}^d , and U is the escape time of a ball of radius $R^{1/2}$ centered at x , $\mathbb{E}^x[T_U] = R/n$.
- If B is Brownian motion on M , escape time will be slower if volume expands (negative curvature) and faster if volume contracts (positive curvature). This is irrelevant for the values $R = O(1/\lambda)$ that we care about.

Feynman Kac Formula

- Reverses Dynkin's Formula: Solves PDEs via Diffusions.

Feynman Kac Formula

- Reverses Dynkin's Formula: Solves PDEs via Diffusions.
- Physically Intuitive Situations:

Feynman Kac Formula

- Reverses Dynkin's Formula: Solves PDEs via Diffusions.
- Physically Intuitive Situations:
 - (1) If $\partial_t u = Lu$ on M with $u_0 = f$, then

$$u(x, t) = \mathbb{E}^x[f(X_t)].$$

Feynman Kac Formula

- Reverses Dynkin's Formula: Solves PDEs via Diffusions.
- Physically Intuitive Situations:

- (1) If $\partial_t u = Lu$ on M with $u_0 = f$, then

$$u(x, t) = \mathbb{E}^x[f(X_t)].$$

- (2) $\partial_t u = Lu$ on $D \subset M$ with $u_0 = f$ and $u = 0$ on ∂D ,

$$u(x, t) = \mathbb{E}^x[f(X_t)\chi_t],$$

where $\chi_t = \mathbb{I}(T_D > t)$ kills paths absorbed by ∂D .

Feynman Kac Formula

- Reverses Dynkin's Formula: Solves PDEs via Diffusions.
- Physically Intuitive Situations:

- (1) If $\partial_t u = Lu$ on M with $u_0 = f$, then

$$u(x, t) = \mathbb{E}^x[f(X_t)].$$

- (2) $\partial_t u = Lu$ on $D \subset M$ with $u_0 = f$ and $u = 0$ on ∂D ,

$$u(x, t) = \mathbb{E}^x[f(X_t)\chi_t],$$

where $\chi_t = \mathbb{I}(T_D > t)$ kills paths absorbed by ∂D .

- (3) If $Lv = 0$ on $D \subset M$ with $v = \phi$ on ∂D , then

$$v(x) = \mathbb{E}^x[\phi(X_{T_D})].$$

Feynman Kac Formula

- Reverses Dynkin's Formula: Solves PDEs via Diffusions.
- Physically Intuitive Situations:

- (1) If $\partial_t u = Lu$ on M with $u_0 = f$, then

$$u(x, t) = \mathbb{E}^x[f(X_t)].$$

- (2) $\partial_t u = Lu$ on $D \subset M$ with $u_0 = f$ and $u = 0$ on ∂D ,

$$u(x, t) = \mathbb{E}^x[f(X_t)\chi_t],$$

where $\chi_t = \mathbb{I}(T_D > t)$ kills paths absorbed by ∂D .

- (3) If $Lv = 0$ on $D \subset M$ with $v = \phi$ on ∂D , then

$$v(x) = \mathbb{E}^x[\phi(X_{T_D})].$$

- Can also solve $\partial_t u = Lu$ with $\partial u / \partial \eta = 0$ on ∂D using 'reflection on Brownian motion', but a little more technical with singularities.

The Proof

And now, back to our regularly scheduled programming

- **Theorem:** There is $c_M > 0$ such that for any ‘good’ k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

The Proof

And now, back to our regularly scheduled programming

- **Theorem:** There is $c_M > 0$ such that for any 'good' k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

- Assume $e_\lambda \geq 0$ on D_λ . Let $x^* = \operatorname{argmax}\{e_\lambda(x)\}$.

The Proof

And now, back to our regularly scheduled programming

- **Theorem:** There is $c_M > 0$ such that for any ‘good’ k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

- Assume $e_\lambda \geq 0$ on D_λ . Let $x^* = \operatorname{argmax}\{e_\lambda(x)\}$.
- Let $p(x, t)$ and $u(x, t)$ solve $\partial_t = \Delta$ with initial / boundary conditions:
 - $p_0 = 0$ and $p = 1$ on ∂D_λ .
 - $u_0 = e_\lambda$, and $u = 0$ on ∂D_λ .

The Proof

And now, back to our regularly scheduled programming

- **Theorem:** There is $c_M > 0$ such that for any 'good' k -dimensional submanifold Σ of M , then

$$N(\Sigma, c_M/\lambda) = \{x \in M : d(x, \Sigma) < c_M/\lambda\}$$

doesn't contain D_λ .

- Assume $e_\lambda \geq 0$ on D_λ . Let $x^* = \operatorname{argmax}\{e_\lambda(x)\}$.
- Let $p(x, t)$ and $u(x, t)$ solve $\partial_t = \Delta$ with initial / boundary conditions:
 - $p_0 = 0$ and $p = 1$ on ∂D_λ .
 - $u_0 = e_\lambda$, and $u = 0$ on ∂D_λ .
 - $p(x, t) = \mathbb{P}^x(T_D \geq t | X_0 = x)$.
 - $u(x, t) = \mathbb{E}[e_\lambda(B_t) \chi_t]$.

Thanks For Listening!