Minimum Spanning Trees

Let's prove something

 Prove: In an undirected graph, removing an edge from a cycle does not disconnect the graph (as in, the connected components remain identical)

Let's talk about trees

• Defn: A tree is an undirected acyclic graph

• Prove: A tree with n nodes has n-1 edges

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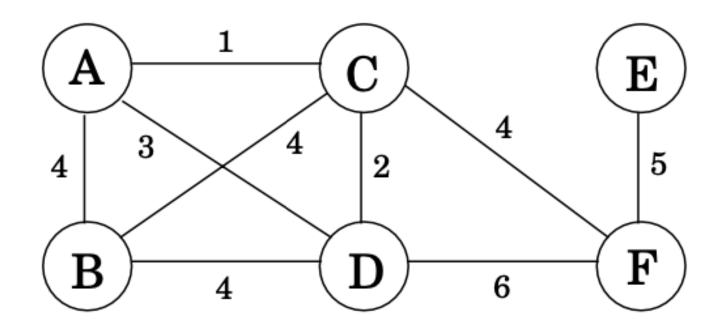
Prove: Any connected undirected graph G = (V,E), with |E| = |V| - 1 is a tree

• Prove: An undirected graph is a tree if and only if there is a unique path between any pair of nodes.

Minimum Spanning Trees

• Defn: A minimum spanning tree (MST) of a weighted undirected graph G is a tree that spans G and that has the minimum total weight of all spanning trees of G.

Problem: Find a minimum spanning tree



• Definition: A cut of a graph G is a partition of the vertices of G into two groups: S and V-S.

Cut property Suppose edges X are part of a minimum spanning tree of G = (V, E). Pick any subset of nodes S for which X does not cross between S and V - S, and let e be the lightest edge across this partition. Then $X \cup \{e\}$ is part of some MST.

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Figure 5.2 $T \cup \{e\}$. The addition of e (dotted) to T (solid lines) produces a cycle. This cycle must contain at least one other edge, shown here as e', across the cut (S, V - S).

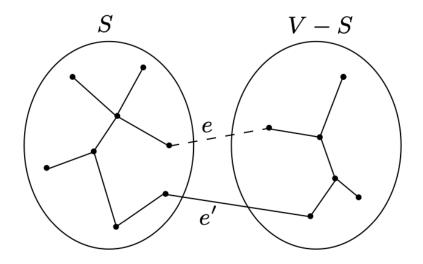


Figure 5.4 Kruskal's minimum spanning tree algorithm.

```
procedure kruskal(G,w)
Input: A connected undirected graph G=(V,E) with edge weights w_e
Output: A minimum spanning tree defined by the edges X

for all u \in V:
   makeset(u)

X = \{\}
Sort the edges E by weight for all edges \{u,v\} \in E, in increasing order of weight:
   if \mathrm{find}(u) \neq \mathrm{find}(v):
   add edge \{u,v\} to X
\mathrm{union}(u,v)
```

makeset(x): create a singleton set containing just x.

find(x): to which set does x belong?

union(x, y): merge the sets containing x and y.

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So, what is the cost of this?

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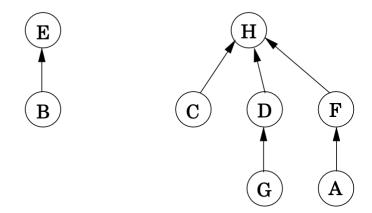
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union(x, y): merge the sets containing x and y.

Cost depends on the cost of each of these. And what does the cost of such things typically rely on?

$\frac{\texttt{procedure makeset}}{\pi(x) = x}$ rank(x) = 0 $\frac{\texttt{function find}}{\texttt{while } x \neq \pi(x): \ x = \pi(x)}$

Figure 5.5 A directed-tree representation of two sets $\{B,E\}$ and $\{A,C,D,F,G,H\}$.



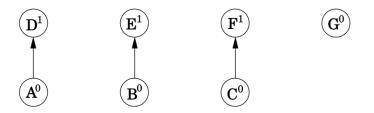
```
\begin{array}{l} {\tt procedure\ union}(x,y) \\ r_x = {\tt find}(x) \\ r_y = {\tt find}(y) \\ {\tt if\ } r_x = r_y {\tt :} \quad {\tt return} \\ {\tt if\ } {\tt rank}(r_x) > {\tt rank}(r_y) {\tt :} \\ \pi(r_y) = r_x \\ {\tt else:} \\ \pi(r_x) = r_y \\ {\tt if\ } {\tt rank}(r_x) = {\tt rank}(r_y) : \quad {\tt rank}(r_y) = {\tt rank}(r_y) + 1 \end{array}
```

Figure 5.6 A sequence of disjoint-set operations. Superscripts denote rank.

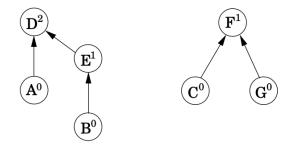
After $makeset(A), makeset(B), \dots, makeset(G)$:



After union(A, D), union(B, E), union(C, F):



After union(C, G), union(E, A):



After union(B,G):

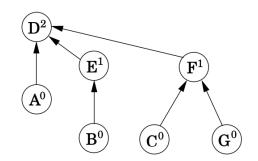


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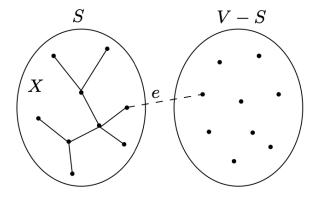
    union(u, v)
```

So, what is the cost of this?

```
X=\{\ \} (edges picked so far) repeat until |X|=|V|-1: pick a set S\subset V for which X has no edges between S and V-S let e\in E be the minimum-weight edge between S and V-S X=X\cup\{e\}
```

Cut property tells us that any algorithm that conforms to this greedy schema is guaranteed to work.

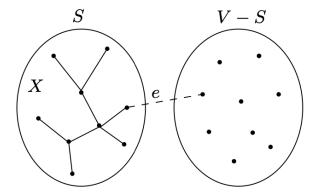
Figure 5.8 Prim's algorithm: the edges X form a tree, and S consists of its vertices.



growing to include the vertex $v \not \in S$ of smallest cost:

$$cost(v) = \min_{u \in S} w(u, v).$$

Figure 5.8 Prim's algorithm: the edges *X* form a tree, and *S* consists of its vertices.

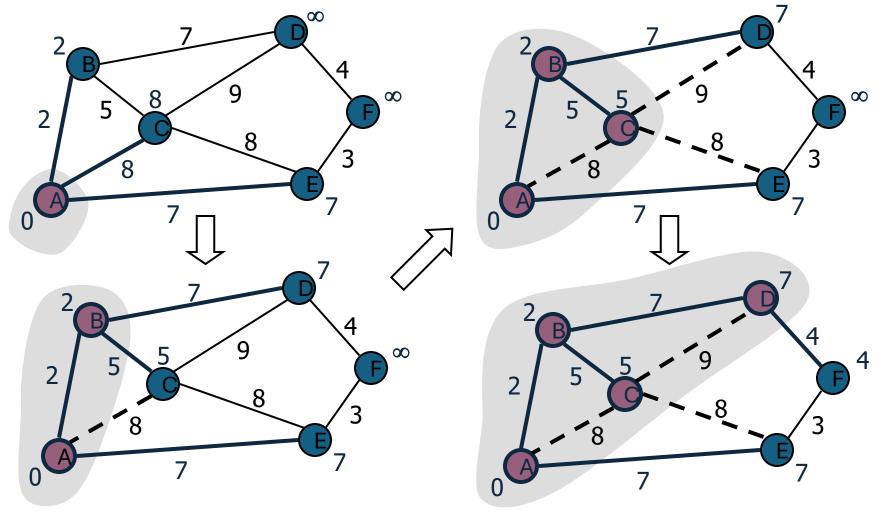


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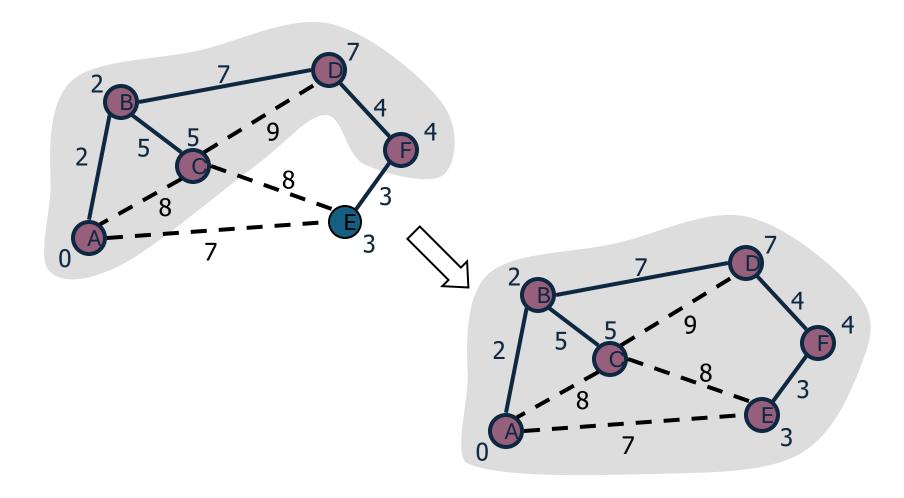
Does this look familiar?

Example



CS 315 20

Example (contd.)



CS 315 21

Figure 5.9 Top: Prim's minimum spanning tree algorithm. Below: An illustration of Prim's algorithm, starting at node A. Also shown are a table of cost/prev values, and the final MST. procedure prim(G, w)A connected undirected graph G = (V, E) with edge weights w_e Input: A minimum spanning tree defined by the array prev Output: for all $u \in V$: $\mathtt{cost}(u) = \infty$ prev(u) = nilPick any initial node u_0 $cost(u_0) = 0$ $H = \mathtt{makequeue}(V)$ (priority queue, using cost-values as keys) while H is not empty: $v = \mathtt{deletemin}(H)$ for each $\{v,z\} \in E$: if cost(z) > w(v, z): cost(z) = w(v, z)prev(z) = vdecreasekey(H, z)