

## Programming Assignment 2

Assigned: February 23

Due: March 11, 4:59:59 PM.

## 1 Introduction

In this assignment you will implement distance vector routing. As in the previous projects, you will implement a *virtual* network on top of UDP. In this virtual network, Unix processes will again represent network nodes, though this time each node will use *separate* ports to maintain links between nodes. Though the configuration file format allows nodes to be spread across multiple hosts, we will only test with nodes on `localhost`.

Section 2 of this document describes the skeleton code we are giving you, as well as the format of the route dissemination packets your submission must adhere to. Section 3 describes specifically how we will call the executable and the behavior we expect it to adhere to.

The format to define our network is specified using a scenario file. An example scenario file and associated network is shown in Figure 1.

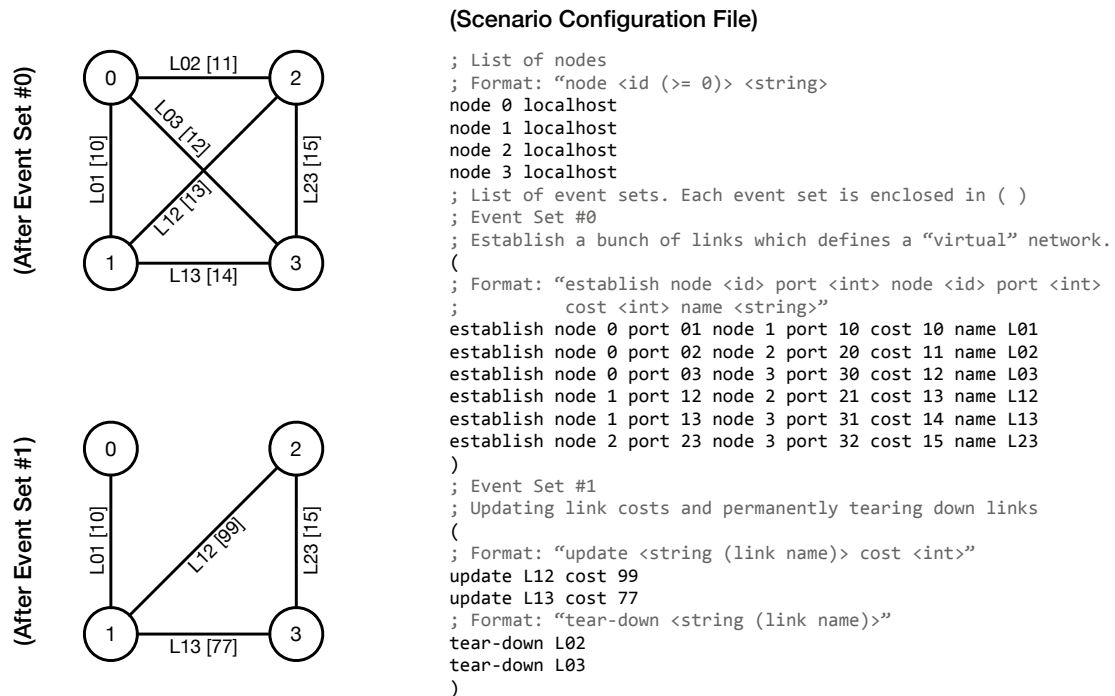


Figure 1: Sample scenario configuration file and the two relevant states of the network after the respective event set is executed. All lines represent virtual links between nodes, which are labeled by their link name and cost.

## 1.1 What is in a scenario file?

The scenario file defines the set of nodes and a set of event sets. An event set consists of a set of events that affect the links in the network<sup>1</sup>. There are three types of events: establishment of a link, tear-down of a link and updating the of cost of a link. All events in an event set are *executed sequentially without any delay*. How event sets are ordered is configurable — for this assignment, your task is to run the distance vector algorithm for a fixed amount of time before executing events in the next event set. Thus, your code can be structured as follows:

```
boolean nextSET ← true ; Global variable
alarmHandler() { ; Called every timeout number of seconds
    nextSET ← true;
}
...
do
    if (nextSET is true)
        es ← ⟨ next event set ⟩
        ⟨ dispatch all events in es ⟩ ; This will cause changes to the links in the network
        nextSET ← false;
    ⟨ execute Distance Vector protocol ⟩ ⇐ Your primary task
while ⟨ there are more event sets to process ⟩
```

Obviously, you don't have to follow this blueprint, but this is one possible way.

## 2 Implementation

### 2.1 Scenario Configuration File

The format of the scenario file is as follows:

- The scenario file begins by listing all the virtual nodes in the network and may contain up to 256 virtual nodes. Virtual nodes are declared as follows:

```
node ⟨ node-id ⟩ ⟨ host ⟩
```

The node id is an unsigned integer and corresponds to the virtual node identifier (must be unique). The host will *always* be `localhost`.

- After the virtual nodes are defined, the scenario file consists of a set of event sets. Event sets themselves consist of events and are delimited by “(” and “)”. Thus, the rest of the scenario file looks like this:

```
( ⟨ set of events ⟩ ) ... ( ⟨ set of events ⟩ )
```

- There are three types of events in an event set. An event set may contain an arbitrary number of events of any given type in any given order. (Of course, the events must be consistent, i.e. an event cannot refer to a node or a link that does not exist.) Specifics of events are as follows:

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<sup>1</sup>Unless otherwise noted, we mean the virtual network when we say network

- The establish event establishes a new link in the network. The syntax is as follows:

```
establish node < node-id > port < integer > node < node-id > port < integer >
cost < integer > name < string >
```

This command will establish a link between the two nodes (and associated port numbers) whose node ids are specified. These nodes must already exist and the port numbers must not have been used before to define a link. The link has a cost given as an unsigned integer and a “name” specified as a string. All subsequent actions on this link will just use this string to identify the link. Hence, link names must be globally unique.

- The following event is used to tear down an existing link:

```
tear-down < string >
```

Once again, the named link must already exist.

- Lastly, the cost of a link can be changed:

```
update < string > cost < integer >
```

The string should identify an existing link and the cost should be positive.

- A scenario file can also contain comments guarded by “;”.

## 2.2 Route Dissemination Packets

Routes are disseminated using an advertisement packet with the following structure:

```
0 0 0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 2 2 2 2 2 2 2 2 2 3 3
0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1
+-----+-----+-----+-----+-----+-----+-----+-----+
|  type      |  version      |          Num. Updates          |
+-----+-----+-----+-----+-----+-----+-----+-----+
|  dest_0     |          min_cost_0          |
+-----+-----+-----+-----+-----+-----+-----+-----+
|  dest_1     |          min_cost_1          |
+-----+-----+-----+-----+-----+-----+-----+-----+
|                                     |
|          .....                   |
+-----+-----+-----+-----+-----+-----+-----+-----+
|  dest_n     |          min_cost_n          |
+-----+-----+-----+-----+-----+-----+-----+-----+
```

**Type:** Set to 0x7 for this assignment.

**Version:** Set to 0x1.

**Num. Updates:** Number of distance vector pairs in this advertisement. This must be more than zero for all legal advertisements.

**Dest:** Assume the advertisement is from node *a* to node *b* and the **Dest** field is *c*. This advertisement therefore informs node *b* of the minimum cost of sending a message to node *c* through node *a*. Or, equivalently, the cost of sending a message from node *a* to node *c*.

**Cost:** Using the terminology from above, the cost field corresponds to the actual cost of the route to destination *c* as advertised by node *a* (to node *b*).

## 2.3 Source Code

A substantial part of the source code will be given to you so you can concentrate on developing the distance vector part. Please clone the starter code for this project from:

<http://ter.ps/417p2>

You are required to use either the `select` or `poll` system calls to multiplex reading from multiple descriptors. Since your virtual process will have multiple links incident upon it, it can receive a message from any link. If the node just does a `read` or `recvfrom` from any link, the process will be blocked until something actually arrives on that link. The UNIX (system) calls `select` and `poll` allow you to wait on multiple descriptors, and you should use this facility to implement your virtual node.

### 2.3.1 Parser

You will be given a `flex` and `bison`<sup>2</sup> parser which will parse the configuration file and automatically create a global node-to-hostname mapping and a two-dimensional local event structure that maps to the set of event sets. The interface is in the form of the `ruparse()` (route update parse) function, which populates the `g_el` global variable. You must call the `parser_init` function before calling `ruparse` as shown below.

```
char *sc_file;
extern int ruparse();
int main (int argc, char *argv[])
{
    parse_arg(argc, argv);

    parser_init(sc_file); // sc_file contains the name of the scenario file
    ruparse(); // output stored in g_el global variable
    .....
}
```

The `ruparse` function creates a two-dimensional event list. Each `column` in the 2-D event list corresponds to an event set in the scenario file. Note that once you call the parser using `ruparse`, you **never** have to bother with the scenario file again and you never have to call `ruparse` again. All the information in the scenario file has been read into the event list.

Each element of the event set is an `struct es` (struct event set). The definition of the event set is as follows:

```
struct es{
    struct es *next; // to create the 2-d list
    struct es *prev;

    e_type ev;       // ev is one of establish, tear_down or update
    int peer0, port0, peer1, port1;
    int cost;
    char *name;
};
```

Eventually, you will have to *dispatch* these events. We discuss dispatching events in Section 2.3.4. The parser resides in `*ru*` files, and the event set is defined in the `es.[c|h]` files.

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<sup>2</sup>If you don't know anything about parsing, don't worry, you will not be required to do anything with `flex` or `bison` for this assignment.

### 2.3.2 Nodes and Links

As the parser runs, it also creates a set of nodes to hostname mappings. This mapping can be accessed by using the `(char*) gethostbyname(int node)` function defined in `n2h*` files. The node id must be defined in order for `gethostbyname` to return anything meaningful. However, because all hosts will be “localhost” for this project, accessing this mapping will likely be unnecessary.

In each dispatch of an event set (column), the **local link set** (set of all links with the local node as an endpoint) should be updated when necessary. Your routing algorithm will then use it to collect distance vector information, and update its routing table. The local link set has the following structure:

```
struct link {
    struct link *next; // next entry
    struct link *prev; // prev entry
    node peer0, peer1; // link peers
    int port0, port1;
    int sockfd0;       // if peer0 is itself, local port is bound
    int sockfd1;       // if peer1 is itself, local port is bound
    cost c;            // cost
    char *name;        // name of the link
};
```

The methods to access the link set are:

```
int create_ls(); // initialization

int add_link(node peer0, int port0, node peer1, int port1,
            cost c, char *name);

int del_link(char *n);

struct link *ud_link(char *n, int cost);

struct link *find_link(char *n);

void print_link(struct link* i); // print info about a single link
void print_ls(); // prints entire link set
```

You must call `create_ls` to initialize the link set at a node. The `add_link`, `del_link`, and `ud_link` functions mutate the link set. The `print_link` and `print_ls` print information about a given link or the entire set at the node.

**Note well:** When a link is added into the local link set, socket(s) corresponding to the link are **not** automatically allocated. You must write the code to associate the sockets yourself. Note that you can obtain a link structure using the `find_link` function.

Link sets are defined in `ls.*`.

### 2.3.3 Routing Table

We provide a set of routines to manipulate routing tables. The methods to maintain routing tables are:

```
int create_rt();
int add_rte(node n, cost c, node nh);
int update_rte(node n, cost c, node nh);
int del_rte(node n);
```

```
struct rte *find_rte(node n);

void print_rte(struct rte* i);
void print_rt();
```

The function `create_rt` must be called to create a routing table at a node. The functions `add_rte`, `update_rte`, and `del_rte` are used to add, update, and delete individual routing table entries. For example, a call to `update_rte` will specify the cost  $c$  of routing to destination  $n$  by following next hop  $nh$ . The logging functions `print_rte` and `print_rt` print individual table entries and the entire table, respectively.

The function `find_rte` is used to find an entry for a specific destination.

### 2.3.4 Dispatching events

After the event list is created, you have to *dispatch* functions for each event in the event sets. As we said before, all the functions in a single event set will be executed sequentially. (Note that the event set at a node will only contain events that pertain to this node — events at remote nodes that are in the scenario file are not added to the event set at the local node). The event set code, as distributed in the skeleton, already defines the `walk_el` function that traverses the event list and the `dispatch_event` function that modifies the link set as appropriate.

## 3 Command-line options and logging

Your executable should be located in the `bin` directory and take in the following three command-line options:

```
bin/rt -n <node_id> [-f <scenario_file>] [-u update-time] [-t time-between-event-sets] [-v]
```

The `-n` option is mandatory and specifies the node id; the optional `-f` parameter specifies a scenario file (default `config`), and the optional `-t` parameter specifies how long to wait between executing event sets (default 30 seconds). The `-u` option specifies how long to wait (in seconds) before sending out distance vector updates; this should default to 3 seconds.

If the `-v` (verbose) option is not present, your code should print to `stdout` the routing table after each event set is executed. Further, your code should also log each event in the event set that it acts upon and each routing update that changes the routing table.

If the `-v` option is present, the routing table should be dumped after each event set is executed and after every routing update (whether or not it changes the routing table entries).

## 4 Additional Requirements

1. Your code must be submitted as a series of commits that are pushed to the origin/master branch of your Git repository. We consider your latest commit prior to the due date/time to represent your submission.
2. You must provide a Makefile that is included along with the code that you commit. We will run ‘make’ inside the root directory, which must produce an ‘rt’ located in the ‘bin’ subdirectory.
3. You must submit code that compiles in the provided vagrant VM, otherwise your assignment will not be graded.
4. As with all of your assignments in the class this semester, you are not allowed to work in teams or to copy code from any source.
5. In order to successfully compile, you will need to install the `bison` and `flex` software packages. Most package managers should have these, and the Vagrant VM has them installed automatically.