Assistive Robots for Blind Travelers







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Motivation

- 1+ billion people worldwide have some form of disability (WHO)
- Mobility tied strongly to employment, social inclusion, and personal independence

Approach

- Explores three principal research areas in the context of assistive robots for blind travelers:
 - 1) Accessible interfaces for assistive robots
 - Assistive interaction between humans and robots
 - Effective cooperation between a variety of human-robot and robot teams



Illustration of assistive robots interacting with blind travelers

Results to date

Identified high value robot task, functional constraints, and challenges specific to urban travel



Interaction with stakeholders

 Accessible interfaces necessary to allow blind travelers to effectively communicate with all platforms

