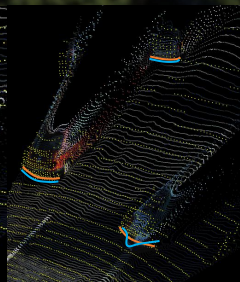
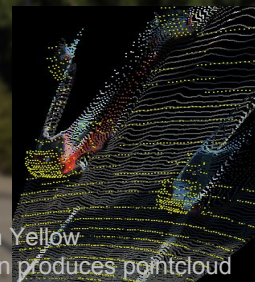
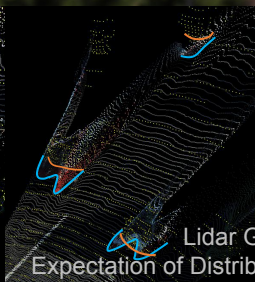
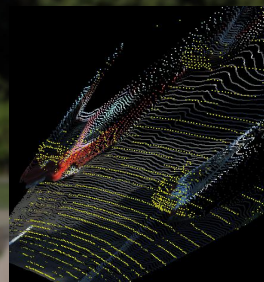
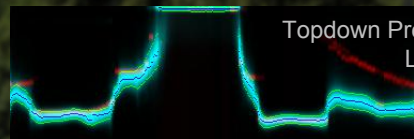


Per Pixel Depth Distribution  
Predicted from Monocular  
RGB

Used to Drive the  
Adaptive Light  
Curtain Laser

Pixel Depth corrected over  
Time from Light Curtain  
Measurements



Lidar GT in Yellow  
Expectation of Distribution produces pointcloud